

Lecture 16 Stability and Matrix Norms

In this lecture we introduce matrix norms as a way to understand the amount in which a matrix blows up an error. Consider an approximation of $A\mathbf{x}$ given by

$$A(\mathbf{x} + \Delta\mathbf{x})$$

where A is $n \times m$, \mathbf{x} is $m \times 1$ and $\Delta\mathbf{x}$ is $m \times 1$ representing a small perturbation of \mathbf{x} . This is, assume for a suitable norm that

$$\|\Delta\mathbf{x}\| \leq \epsilon$$

The error of this approximation is precisely

$$A(\mathbf{x} + \Delta\mathbf{x}) - A\mathbf{x} = A(\Delta\mathbf{x})$$

We want a way to measure $\|A(\Delta\mathbf{x})\|$. This will be accomplished by defining an induced matrix norm.

Induced matrix norms

Suppose A is an $n \times m$ matrix, and consider two norms $\|\mathbf{v}\|_X$ for $\mathbf{v} \in \mathbb{R}^m$ and $\|\cdot\|_Y$ on \mathbb{R}^n . For example, they could both be the 2-norm, both be the ∞ -norm, or a mixture of the two. These two norms induce a norm on matrices:

$$\|A\|_{X \rightarrow Y} \triangleq \sup_{\mathbf{v}: \|\mathbf{v}\|_X = 1} \|A\mathbf{v}\|_Y$$

That is, take the supremum of $\|A\mathbf{v}\|_Y$ over the set of all vectors \mathbf{v} whose X -norm is one.

When we use the same vector norm for the domain and range, we specify only one space

$$\|A\|_X \triangleq \|A\|_{X \rightarrow X}$$

For the induced 2, 1, and ∞ -norm we use

$$\|A\|_2, \|A\|_1 \quad \text{and} \quad \|A\|_\infty.$$

Induced matrix norms are norms

In lectures we saw that it is easy to prove that induced norms are norms: they satisfy three properties

1. $\|cA\| = |c| \|A\|$
2. $\|A + B\| \leq \|A\| + \|B\|$
3. $\|A\| = 0 \Rightarrow A = 0$

The last property was shown using an equivalent definition of the induced norm:

$$\|A\| = \sup_{\mathbf{v}} \frac{\|A\mathbf{v}\|}{\|\mathbf{v}\|}$$

This follows since we can scale \mathbf{v} by its norm so that it has unit norm, that is, $\frac{\mathbf{v}}{\|\mathbf{v}\|}$ has unit norm. Then

$$\sup_{\mathbf{v}} \frac{\|A\mathbf{v}\|}{\|\mathbf{v}\|} = \sup_{\mathbf{v}} \left\| A \frac{\mathbf{v}}{\|\mathbf{v}\|} \right\| \leq \sup_{\mathbf{v}: \|\mathbf{v}\|=1} \|A\mathbf{v}\| = \|A\|$$

This combined with the trivial case

$$\sup_{\mathbf{v}} \frac{\|A\mathbf{v}\|}{\|\mathbf{v}\|} \geq \sup_{\mathbf{v}: \|\mathbf{v}\|=1} \frac{\|A\mathbf{v}\|}{\|\mathbf{v}\|} = \sup_{\mathbf{v}: \|\mathbf{v}\|=1} \|A\mathbf{v}\| = \|A\|$$

Extra properties of induced norms

We also have the following two additional proper

Induced 2-norm

Induced norms define the "length" of a matrix by how much they magnify vectors. We can visualize this in 2D for the induced 2-norm $\|A\|_2$, taking a random 2 x 2 matrix.

In [55]:

```
using PyPlot
```

```
A=rand(2,2)
```

Out[55]:

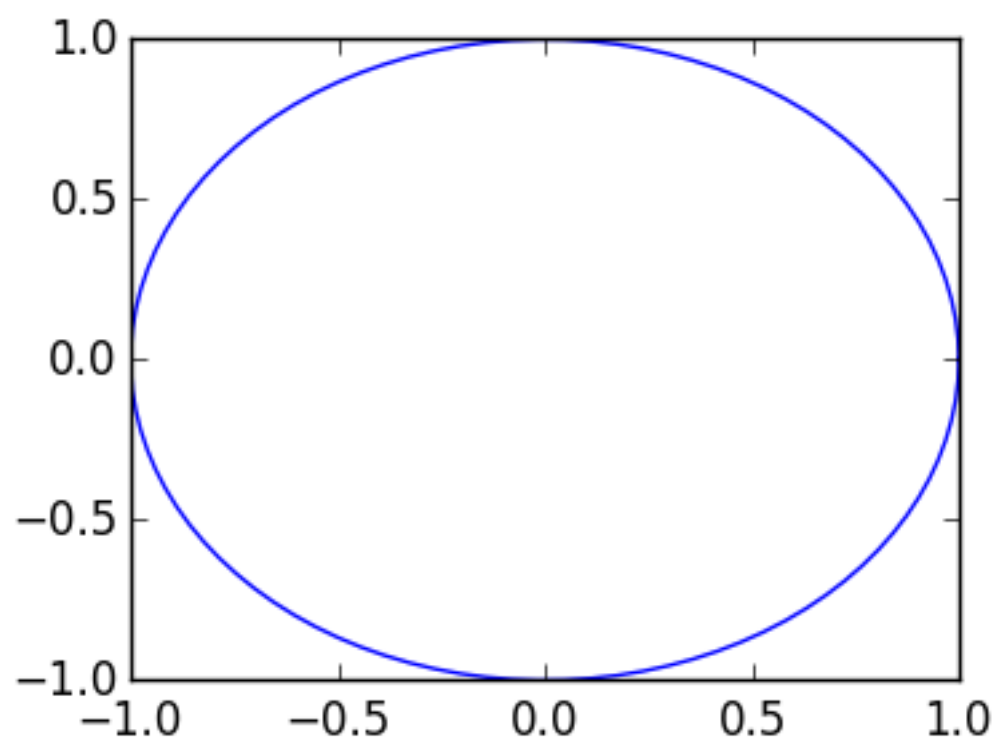
```
2x2 Array{Float64,2}:
 0.692806  0.330373
 0.809566  0.617713
```

The set $\{\mathbf{v} : \|\mathbf{v}\|_2 = 1\}$ is the unit circle:

In [56]:

```
t=linspace(0.,2 $\pi$ ,100)
x=cos(t)
y=sin(t)

plot(x,y);
```

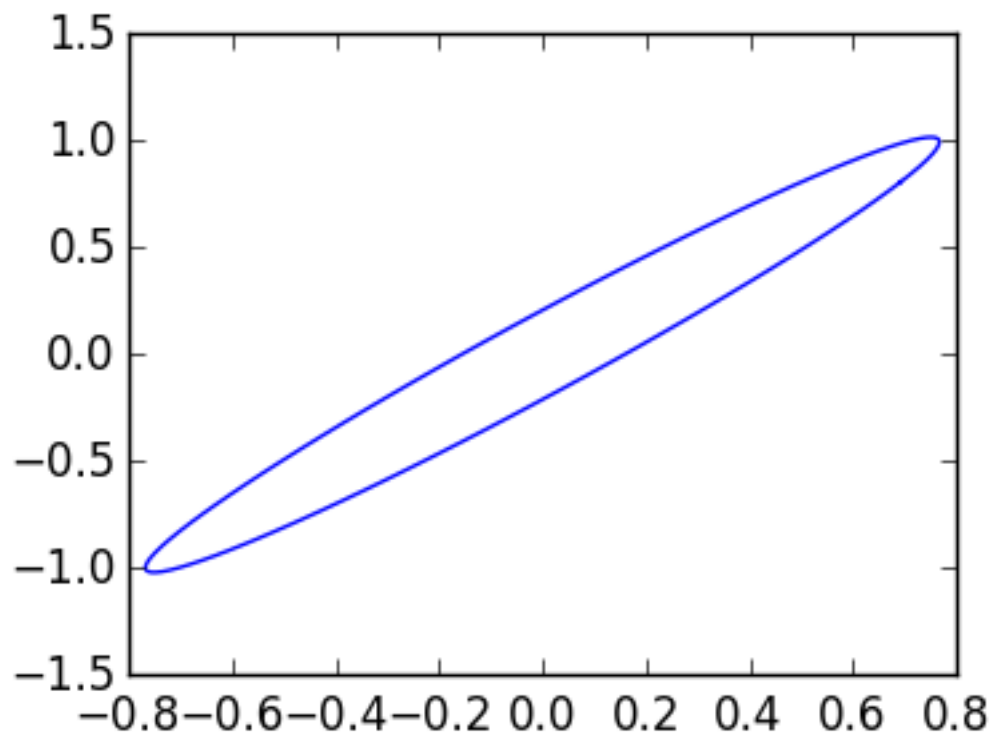


For each \mathbf{v} in the circle, we see where $A\mathbf{v}$ is mapped to:

In [57]:

```
Ax=copy(x)
Ay=copy(y)

for k=1:length(x)
    Ax[k],Ay[k]=A*[x[k],y[k]]
end
plot(Ax,Ay);
```



Out[57]:

```
1-element Array{Any,1}:
 PyObject <matplotlib.lines.Line2D object at 0x30b8eebd0>
```

The induced norm of A is then the maximum value of $\|A\mathbf{v}\|_2$. This is calculated using the inbuilt norm function:

In [58]:

```
norm(A)
```

Out[58]:

```
1.268895038744742
```

Induced ∞ -norm

We can do the same experiment to visualize the ∞ -norm. Here we use the notation $[\mathbf{v};\mathbf{w};\mathbf{z}]$ where \mathbf{v} , \mathbf{w} and \mathbf{z} are Vectors to concatenate:

In [60]:

```
v=[1,2,3]
w=[5,6,7]
z=[9,8,5]

[v;w;z]
```

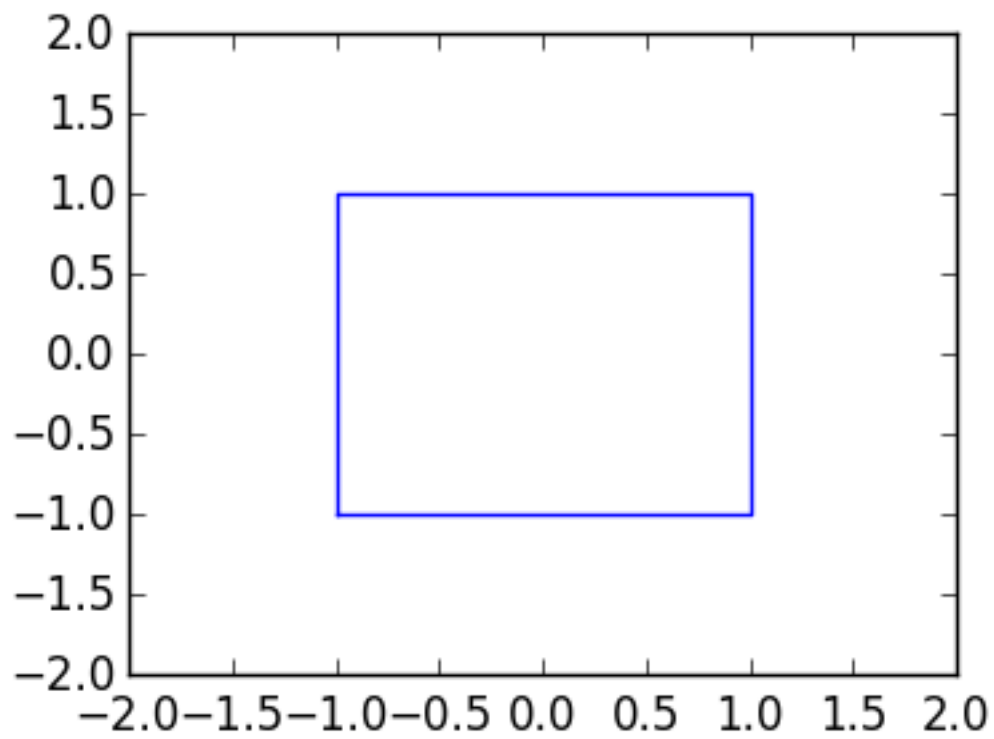
Out[60]:

```
9-element Array{Int64,1}:
 1
 2
 3
 5
 6
 7
 9
 8
 5
```

We begin by plotting the set $\{\mathbf{v} : \|\mathbf{v}\|_{\infty} = 1\}$, which is the unit square.

In [62]:

```
x=[linspace(-1.,1.,100);  ones(100);  
   linspace(1.,-1,100);  
   -ones(100)  
]  %; concatnates vectors  
y=[-ones(100);               linspace(-1.,1.,100);  
   ones(100);  
   linspace(1.,-1.,100)  
]  
  
plot(x,y);  
  
axis([-2,2,-2,2]);
```

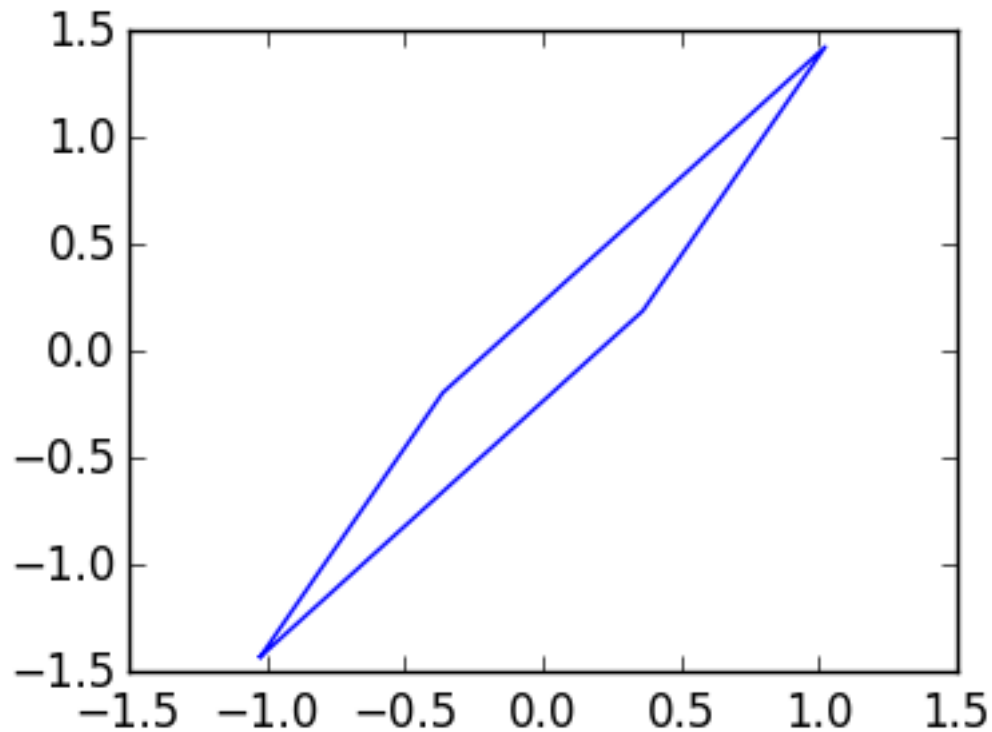


We multiply this new set of vectors by A and plot the result.

In [63]:

```
Ax=copy(x)
Ay=copy(y)

for k=1:length(x)
    Ax[k],Ay[k]=A*[x[k],y[k]]
end
plot(Ax,Ay);
```



To calculate $\|A\|_{\infty}$, we need to measure the maximum value in the ∞ norm. The built-in function `norm(A, Inf)` does this.

In [64]:

```
norm(A, Inf)
```

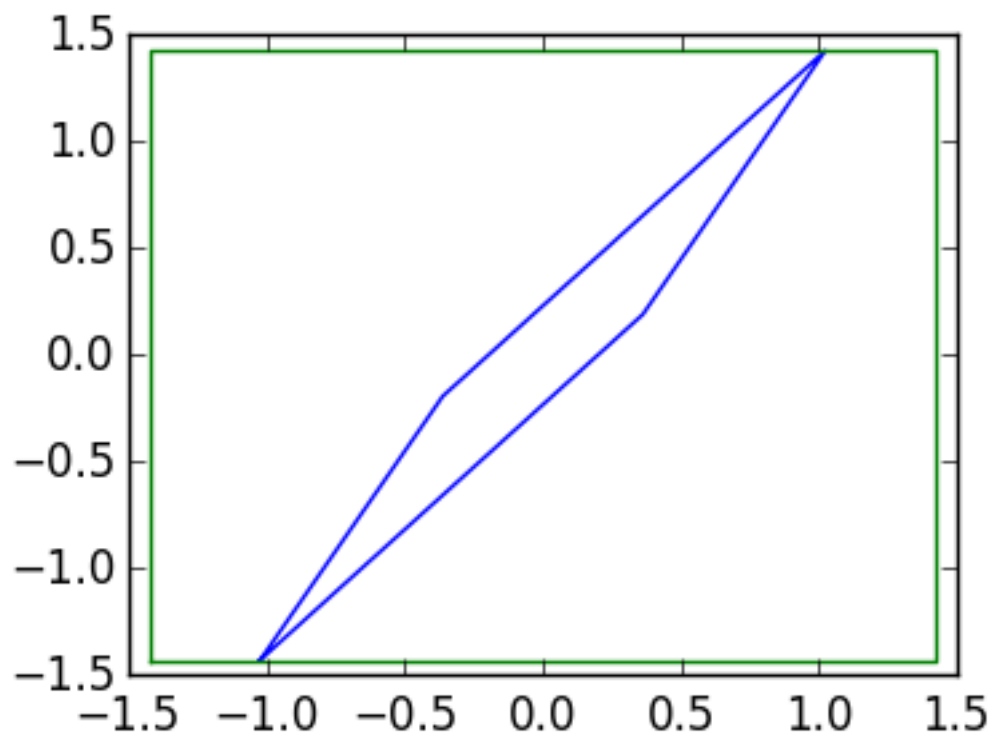
Out[64]:

```
1.4272791819737858
```

We can visualize this by drawing the unit square scaled by this norm, and showing that it passes through the largest point:

In [66]:

```
nrm $\infty$ =norm(A,Inf)
plot(Ax,Ay)
plot(nrm $\infty$ *x,nrm $\infty$ *y)
```



Out[66]:

```
1-element Array{Any,1}:
 PyObject <matplotlib.lines.Line2D object at 0x30bd8ffd0>
```

Induced ∞ to 2 norm

We can also use two different norms, for example,

$$\|A\|_{\infty \rightarrow 2}$$

measures how large the unit square is mapped to, measuring in the 2-norm.

There is no inbuilt command for calculating matrix norms when the norms differ. However, we can *approximate* it by finding the maximum of all vectors we used to plot the unit square:

In [69]:

```
nrm $\infty$ to2=0.0
for k=1:length(x)
    Av=[Ax[k],Ay[k]]
    nrm $\infty$ to2 = max(nrm $\infty$ to2, norm(Av))
end

nrm $\infty$ to2
```

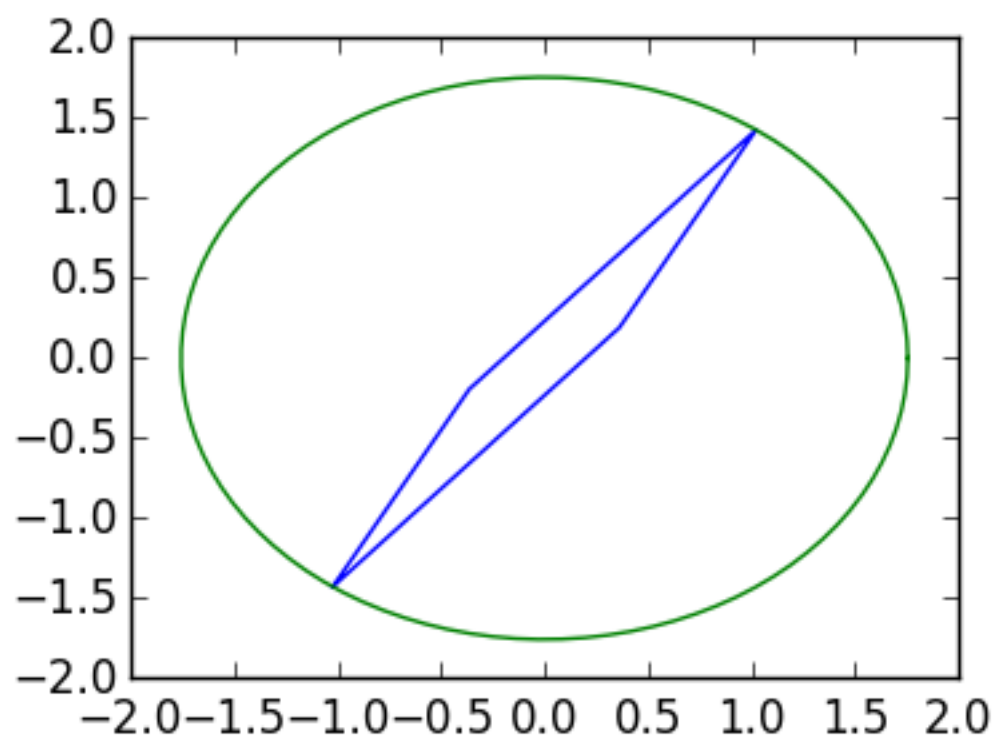
Out[69]:

```
1.7561382947071715
```


This matches:

In [70]:

```
plot(Ax,Ay)
plot(nrm∞to2*cos(t),nrm∞to2*sin(t))
```



Out[70]:

```
1-element Array{Any,1}:
PyObject <matplotlib.lines.Line2D object at 0x30b0a0490>
```

Norms measure how much a vector is magnified

We return to our original problem:

$$\|\Delta \mathbf{x}\| \leq \epsilon$$

The error of this approximation is precisely

$$A(\mathbf{x} + \Delta \mathbf{x}) - A\mathbf{x} = A(\Delta \mathbf{x})$$

In [3]:

```
x=rand(2)
ε=0.0001
Δx=ε*rand(2)
x̄=x+Δx      # x̄ is x perturbed by Δx
norm(x-x̄)
```

Out[3]:

```
7.286987817147542e-5
```

Multiplication by A magnifies the error by at most $\|A\|$:

In [5]:

```
A=rand(2,2)
norm(A*x-A*x̄) ≤ norm(x-x̄)*norm(A)
```

Out[5]:

true

This holds true even if norm of A is large:

In [6]:

```
A=[1. 1000.; 0. 1.0]
norm(A)
```

Out[6]:

1000.0009999990001

In [7]:

```
norm(A*x-A*x̄) ≤ ε*norm(A)
```

Out[7]:

true