EXPERIMENT NO. 06

CODE:

set topo

[new Topography]

#EXPERIMENT NO. 06 #AIM: To simulate a wireless sensor network using NS2/NSG2 with TCP-FTP **#NAME: YOGENDRA TOPRE** #ROLL NO: 68 #6th SEM [B] Simulation parameters setup set val(chan) Channel/WirelessChannel ;# channel type set val(prop) Propagation/TwoRayGround ;# radio-propagation model set val(netif) Phy/WirelessPhy ;# network interface type set val(mac) Mac/802_11 ;# MAC type set val(ifq) Queue/DropTail/PriQueue ;# interface queue type set val(II) LL ;# link layer type set val(ant) Antenna/OmniAntenna :# antenna model set val(ifqlen) 50 ;# max packet in ifq set val(nn) ;# number of mobilenodes ;# routing protocol set val(rp) DSDV set val(x) 550 ;# X dimension of topography set val(y) 550 ;# Y dimension of topography set val(stop) 10.0 ;# time of simulation end Initialization #Create a ns simulator set ns [new Simulator] #Setup topography object

```
$topo load_flatgrid $val(x) $val(y)
create-god $val(nn)
#Open the NS trace file
set tracefile [open out.tr w]
$ns trace-all $tracefile
#Open the NAM trace file
set namfile [open out.nam w]
$ns namtrace-all $namfile
$ns namtrace-all-wireless $namfile $val(x) $val(y)
set chan [new $val(chan)];#Create wireless channel
Mobile node parameter setup
$ns node-config -adhocRouting $val(rp) \
         -IIType
                   $val(II) \
         -macType
                      $val(mac) \
         -ifqType
                    $val(ifq) \
         -ifqLen
                    $val(ifqlen) \
         -antType
                     $val(ant) \
         -propType
                     $val(prop) \
                     $val(netif) \
         -phyType
                     $chan \
         -channel
         -topolnstance $topo \
         -agentTrace ON \
         -routerTrace ON \
                      ON \
         -macTrace
         -movementTrace ON
#
     Nodes Definition
#Create 3 nodes
set n0 [$ns node]
```

```
$n0 set X_ 255
$n0 set Y_ 296
$n0 set Z_ 0.0
$ns initial_node_pos $n0 20
set n1 [$ns node]
$n1 set X_ 360
$n1 set Y_ 192
$n1 set Z_ 0.0
$ns initial_node_pos $n1 20
set n2 [$ns node]
$n2 set X_ 209
$n2 set Y_ 167
$n2 set Z_ 0.0
$ns initial_node_pos $n2 20
     Generate movement
$ns at 0.5 " $n0 setdest 350 350 30 "
$ns at 0.5 " $n1 setdest 400 400 30 "
$ns at 0.5 " $n2 setdest 450 450 30 "
     Agents Definition
#Setup a TCP connection
set tcp0 [new Agent/TCP]
$ns attach-agent $n0 $tcp0
set sink2 [new Agent/TCPSink]
$ns attach-agent $n2 $sink2
$ns connect $tcp0 $sink2
$tcp0 set packetSize_ 1500
#Setup a TCP connection
set tcp1 [new Agent/TCP]
$ns attach-agent $n0 $tcp1
```

```
set sink3 [new Agent/TCPSink]
$ns attach-agent $n1 $sink3
$ns connect $tcp1 $sink3
$tcp1 set packetSize_ 1500
```

```
#
      Applications Definition
#Setup a FTP Application over TCP connection
set ftp0 [new Application/FTP]
$ftp0 attach-agent $tcp0
$ns at 1.0 "$ftp0 start"
$ns at 2.0 "$ftp0 stop"
#Setup a FTP Application over TCP connection
set ftp1 [new Application/FTP]
$ftp1 attach-agent $tcp1
$ns at 1.0 "$ftp1 start"
$ns at 2.0 "$ftp1 stop"
#
      Termination
#Define a 'finish' procedure
proc finish {} {
  global ns tracefile namfile
  $ns flush-trace
  close $tracefile
  close $namfile
  exec nam out.nam &
  exit 0
}
for {set i 0} {$i < $val(nn) } { incr i } {
  $ns at $val(stop) "\$n$i reset"
```

```
}
$ns at $val(stop) "$ns nam-end-wireless $val(stop)"
$ns at $val(stop) "finish"
$ns at $val(stop) "puts \"done\"; $ns halt"
$ns run
```

OUTPUT:



