

Deep Neural Network for Image Classification: Application

Build and apply a deep neural network to supervised learning.

Packages

Let's first import all the packages that you will need during this assignment.

- [numpy](#) is the fundamental package for scientific computing with Python.
- [matplotlib](#) is a library to plot graphs in Python.
- [h5py](#) is a common package to interact with a dataset that is stored on an H5 file.
- [PIL](#) and [scipy](#) are used here to test your model with your own picture at the end.
- `dnn_app_utils` provides the functions implemented in the "Building your Deep Neural Network: Step by Step" assignment to this notebook.
- `np.random.seed(1)` is used to keep all the random function calls consistent. It will help us grade your work.

```
import time
import numpy as np
import h5py
import matplotlib.pyplot as plt
import scipy
from PIL import Image
from scipy import ndimage
from dnn_app_utils_v3 import *

%matplotlib inline
plt.rcParams['figure.figsize'] = (5.0, 4.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

%load_ext autoreload
%autoreload 2

np.random.seed(1)
```

Dataset

We use the name "Cat vs non-Cat" dataset.

- a training set of `m_train` images labelled as cat (1) or non-cat (0)
- a test set of `m_test` images labelled as cat and non-cat
- each image is of shape `(num_px, num_px, 3)` where 3 is for the 3 channels (RGB).

```
train_x_orig, train_y, test_x_orig, test_y, classes = load_data()
```

```
# Explore your dataset
m_train = train_x_orig.shape[0]
num_px = train_x_orig.shape[1]
m_test = test_x_orig.shape[0]

print ("Number of training examples: " + str(m_train))
print ("Number of testing examples: " + str(m_test))
print ("Each image is of size: (" + str(num_px) + ", " + str(num_px) + ", 3)")
print ("train_x_orig shape: " + str(train_x_orig.shape))
print ("train_y shape: " + str(train_y.shape))
print ("test_x_orig shape: " + str(test_x_orig.shape))
print ("test_y shape: " + str(test_y.shape))
```

```
# Reshape the training and test examples
train_x_flatten = train_x_orig.reshape(train_x_orig.shape[0], -1).T
test_x_flatten = test_x_orig.reshape(test_x_orig.shape[0], -1).T

# Standardize data to have feature values between 0 and 1.
train_x = train_x_flatten/255.
test_x = test_x_flatten/255.
|
print ("train_x's shape: " + str(train_x.shape))
print ("test_x's shape: " + str(test_x.shape))
```

12,288 equals $64 \times 64 \times 3$ which is the size of one reshaped image vector.

Architecture of your model

Now that you are familiar with the dataset, it is time to build a deep neural network to distinguish cat images from non-cat images.

You will build two different models:

- A 2-layer neural network
- An L-layer deep neural network

You will then compare the performance of these models, and also try out different values for L.

Let's look at the two architectures.

2-layer neural network

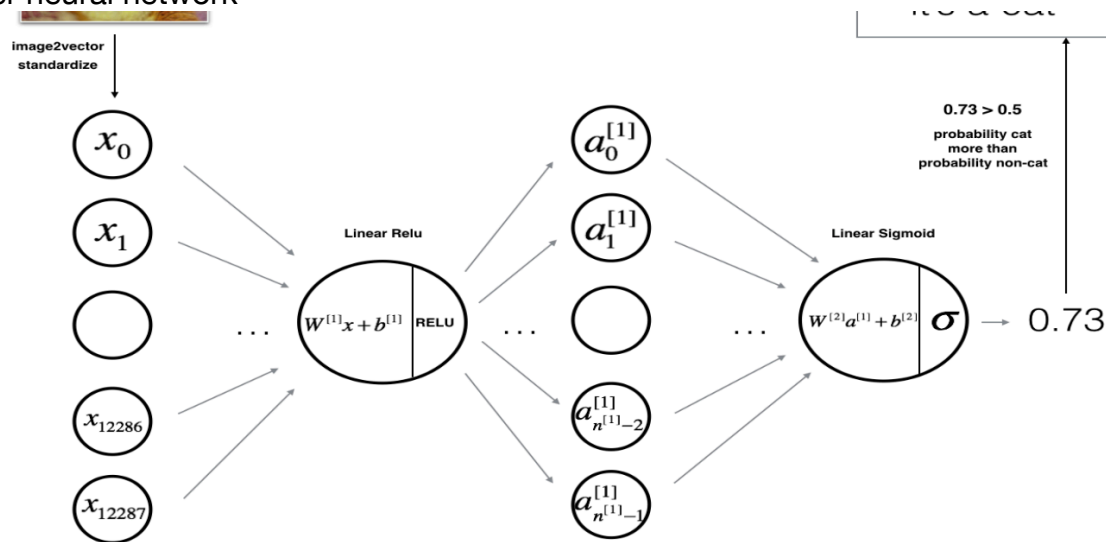


Figure 2: 2-layer neural network.

The model can be summarized as: **INPUT -> LINEAR -> RELU -> LINEAR -> SIGMOID -> OUTPUT.**

Detailed Architecture of figure 2:

- The input is a (64,64,3) image which is flattened to a vector of size (12288, 1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ of size $(n^{[1]}, 12288)$.
- You then add a bias term and take its relu to get the following vector: $[a_0^{[1]}, a_1^{[1]}, \dots, a_{n^{[1]}-1}^{[1]}]^T$.
- You then repeat the same process.
- You multiply the resulting vector by $W^{[2]}$ and add your intercept (bias).
- Finally, you take the sigmoid of the result. If it is greater than 0.5, you classify it to be a cat.

General methodology

As usual you will follow the Deep Learning methodology to build the model:

1. Initialize parameters / Define hyperparameters
2. Loop for num_iterations:
 - a. Forward propagation
 - b. Compute cost function
 - c. Backward propagation
 - d. Update parameters (using parameters, and grads from backprop)
4. Use trained parameters to predict labels

Let's now implement those two models!

```

### CONSTANTS DEFINING THE MODEL ###
n_x = 12288      # num_px * num_px * 3
n_h = 7
n_y = 1
layers_dims = (n_x, n_h, n_y)

```

```

# GRADED FUNCTION: two_layer_model

```

```

def two_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000, print_cost=False):
    """
    Implements a two-layer neural network: LINEAR->RELU->LINEAR->SIGMOID.

    Arguments:
    X -- input data, of shape (n_x, number of examples)
    Y -- true "label" vector (containing 1 if cat, 0 if non-cat), of shape (1, number of examples)
    layers_dims -- dimensions of the layers (n_x, n_h, n_y)
    num_iterations -- number of iterations of the optimization loop
    learning_rate -- learning rate of the gradient descent update rule
    print_cost -- If set to True, this will print the cost every 100 iterations

    Returns:
    parameters -- a dictionary containing W1, W2, b1, and b2
    """

    np.random.seed(1)
    grads = {}
    costs = []      # to keep track of the cost
    m = X.shape[1]  # number of examples
    (n_x, n_h, n_y) = layers_dims

    # Initialize parameters dictionary, by calling one of the functions you'd previously implemented

    parameters = None

    # Get W1, b1, W2 and b2 from the dictionary parameters.
    W1 = parameters["W1"]
    b1 = parameters["b1"]
    W2 = parameters["W2"]
    b2 = parameters["b2"]

```

```

# Loop (gradient descent)

for i in range(0, num_iterations):

    # Forward propagation: LINEAR -> RELU -> LINEAR -> SIGMOID. Inputs: "X, W1, b1, W2, b2". Output: "A1, cache.

    A1, cache1 = None
    A2, cache2 = None

    # Compute cost

    cost = None

    # Initializing backward propagation
    dA2 = - (np.divide(Y, A2) - np.divide(1 - Y, 1 - A2))

    # Backward propagation. Inputs: "dA2, cache2, cache1". Outputs: "dA1, dW2, db2; also dA0 (not used), dW1, d

    dA1, dW2, db2 = None
    dA0, dW1, db1 = None

    # Set grads['dW1'] to dW1, grads['db1'] to db1, grads['dW2'] to dW2, grads['db2'] to db2
    grads['dW1'] = dW1
    grads['db1'] = db1
    grads['dW2'] = dW2
    grads['db2'] = db2

    # Update parameters.

    parameters = None

    # Retrieve W1, b1, W2, b2 from parameters
    W1 = parameters["W1"]
    b1 = parameters["b1"]
    W2 = parameters["W2"]
    b2 = parameters["b2"]

    # Print the cost every 100 training example
    if print_cost and i % 100 == 0:
        print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
    if print_cost and i % 100 == 0:
        costs.append(cost)

# plot the cost

plt.plot(np.squeeze(costs))
plt.ylabel('cost')
plt.xlabel('iterations (per hundreds)')
plt.title("Learning rate =" + str(learning_rate))
plt.show()

return parameters

```

Run the cell below to train your parameters. See if your model runs. The cost should be decreasing. It may take up to 5 minutes to run 2500 iterations. Check if the "Cost after iteration 0" matches the expected output below, if not click on the square (■) on the upper bar of the notebook to stop the cell and try to find your error.

```
parameters = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y), num_iterations = 2500, print_cost=True)
```

```
predictions_test = predict(test_x, test_y, parameters)
```

```
predictions_train = predict(train_x, train_y, parameters)
```

```
# GRADED FUNCTION: L_layer_model

def L_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iterations = 3000, print_cost=False):#lr was 0.009
    """
    Implements a L-layer neural network: [LINEAR->RELU]*(L-1)->LINEAR->SIGMOID.

    Arguments:
    X -- data, numpy array of shape (number of examples, num_px * num_px * 3)
    Y -- true "label" vector (containing 0 if cat, 1 if non-cat), of shape (1, number of examples)
    layers_dims -- list containing the input size and each layer size, of length (number of layers + 1).
    learning_rate -- learning rate of the gradient descent update rule
    num_iterations -- number of iterations of the optimization loop
    print_cost -- if True, it prints the cost every 100 steps

    Returns:
    parameters -- parameters learnt by the model. They can then be used to predict.
    """
    np.random.seed(1)
    costs = [] # keep track of cost
    # Parameters initialization. (= 1 line of code)
    parameters = None
    # Loop (gradient descent)
    for i in range(0, num_iterations):
        # Forward propagation: [LINEAR -> RELU]*(L-1) -> LINEAR -> SIGMOID.
        AL, caches = None
        # Compute cost.
        cost = None
        # Backward propagation
        grads = None
        # Update parameters.
        parameters = None
        # Print the cost every 100 training example
        if print_cost and i % 100 == 0:
            print ("Cost after iteration %i: %f" % (i, cost))
        if print_cost and i % 100 == 0:
            costs.append(cost)

    # plot the cost
    plt.plot(np.squeeze(costs))
    plt.ylabel('cost')
    plt.xlabel('iterations (per hundreds)')
    plt.title("Learning rate =" + str(learning_rate))
    plt.show()

    return parameters
```

You will now train the model as a 4-layer neural network.

Run the cell below to train your model. The cost should decrease on every iteration. It may take up to 5 minutes to run 2500 iterations. Check if the "Cost after iteration 0" matches the expected output below, if not click on the square (■) on the upper bar of the notebook to stop the cell and try to find your error.

```
parameters = L_layer_model(train_x, train_y, layers_dims, num_iterations = 2500, print_cost = True)
```

```
pred_train = predict(train_x, train_y, parameters)
```

```
: pred_test = predict(test_x, test_y, parameters)
```