Process Synchronization (II)

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Semaphore

An abstract data type \square Semaphore S – integer variable Two standard operations to access S: wait() and signal() \square Originally called P() and V()Can only be accessed via two (atomic) operations wait (S) { while ($S \le 0$); //blocked S---; signal (S) { S++;

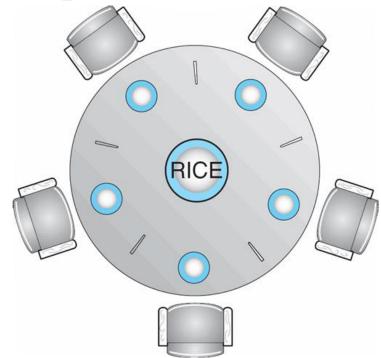
Usage of Semaphores

- Binary semaphore integer value S can range only between 0 and 1
 - Also known as mutex (i.e., mutual exclusive) locks
 - Provides mutual exclusion (the following is pseudo code)

```
Semaphore mutex; // initialized to 1 wait (mutex); ... Critical Section ... signal (mutex); ... remainder section ...
```

Counting semaphore – integer value can range over an unrestricted domain

Dining-Philosophers Problem



- Shared data
 - Bowl of rice (data set)
 - Semaphore chopstick [5] initialized to 1

Dining-Philosophers Problem

The structure of Philosopher i:

```
wait (chopstick[i]);
wait (chopStick[ (i + 1) % 5] );
... eat...
signal (chopstick[i]);
signal (chopstick[ (i + 1) % 5] );
... think...
```

POSIX Semaphores

- Two types of semaphores
 - Unnamed semaphores
 - Volatile
 - Storage is allocated by user program
 - Named semaphores
 - Permanent (like named Pipe (FIFO))
 - Storage is allocated by the OS
 - Defined in <semaphore.h>
 - Provided by Linux (You can use it on pyrite)

Unnamed Semaphores

Initialize a semaphore:

int sem_init(sem_t *sem, int pshared, unsigned value)

- sem: pointer to a sem_t structure allocated by user program
- pshared=0 if the sem is shared by threads in the same proc; otherwise, the sem can be shared by multiple processes (the sem_t structure should be allocated in the memory block shared by these processes)
- value: initial value of the sem
- Destroy a semaphore:

int sem_destory(sem_t *sem)

Unnamed Semaphores

Wait on a semaphore:
int sem_wait(sem_t *sem)

Signal a semaphore:
int sem_post(sem_t *sem)

Named Semaphores

Create and open a semaphore:

```
sem_t *sem_open(char *name, O_CREAT, mode_t mode, unsigned value)
```

- Iname: a permanent name (like a file name) for the sem
- mode: permission mode: combination of S_IRUSR (owner read), S_IWUSR (owner write), S_IXUSR (owner exec), S_IRGRP (owner's group read), S_IWGRP (group write), S_IXGRP (group exec), S_IROTH (other users read), S_IWOTH (other write), S_IXOTH (other exec)
- value: initial value of the sem
- Return the pointer to the sem_t structure of the sem
- Open an existing semaphore:

```
sem_t *sem_open(char *name, O_EXCL)
```

Named Semaphores

- Once a named semaphore has been open, it can be accessed using sem_wait() and sem_post() as an unnamed semaphore
- Close a semaphore:

```
sem_close(sem_t *sem);
```

Destroy (permanently delete) a semaphore:

```
sem_unlink(char *name);
```

Classical Problems of Synchronization

- Bounded-Buffer Problem
- Readers and Writers Problem

Bounded-Buffer Problem

- N buffers, each can hold one item
- Two types of processes: producer processes and consumer processes
- Requirements:
 - No two processes can access the buffers simultaneously (mutual exclusion)
 - A producer cannot put an item to the buffers if the buffers are all full
 - A consumer cannot remove an item from the buffer if the buffers are all empty

Shared Variables:

int numAvailBuffer=N;

semaphore mutex; //=1, to ensure mutual exclusion

Producer:

```
wait(mutex);
while(1) {
         if(numAvailBuffer>0){
                  numAvailBuffer --;
                   ... put data into a buffer ...
                  signal(mutex);
                   break;
         }else{
                  signal(mutex);
                  wait(mutex);
```

Consumer:

```
wait(mutex);
while(1) {
         if(numAvailBuffer<N){
                  numAvailBuffer ++;
                  ... fetch data from a buffer ...
                  signal(mutex);
                  break;
         }else{
                  signal(mutex);
                  wait(mutex);
```

Bounded-Buffer Problem

- To ensure mutual exclusion
 - Semaphore mutex initialized to the value 1 (number of admissible process)
 - Only when mutex == 1 can a process proceed to access the buffers (i.e., put in or remove an item)
- To synchronize consumer processes
 - Semaphore full initialized to the value 0 (number of full buffers)
 - \square Only when full >0 can a consumer process proceed
- To synchronize producer processes
 - Semaphore empty initialized to the value N (number of empty buffers)
 - \square Only when empty >0 can a producer process proceed

Bounded Buffer Problem

The structure of the producer process

```
... produce an item
wait (empty);
wait (mutex);
... add the item to the buffer
signal (mutex);
signal (full);
```

Bounded Buffer Problem

The structure of the consumer process

```
wait (full);
wait (mutex);
... remove an item from buffer
signal (mutex);
signal (empty);
... consume the item in nextc
```

Reader-Writer Problem

- A data set is shared among a number of concurrent processes
 - Readers: only read the data set; they do not perform any updates
 - Writers: can both read and write
- Problem allow multiple readers to read at the same time. Only one single writer can access the shared data at the same time.

Reader-Writer Problem: Analogies



It is fine for a group of people to watch (read) a TV simultaneously.



But changing (write) programs must be done sequentially (no concurrency)!

Reader-Writer Problem: Observations

- A writer is allowed to access the data set only when there is no other writer or reader accessing
- Readers can simultaneously access the data set
 - When a reader arrives, it is allowed to access the data set if (i) no one is accessing the data set, or (ii) some other reader is reading; otherwise (some writer is writing), it should wait.
 - For a waiting reader, it is allowed to read if the writing writer completes.

Reader-Writer Problem: Observations Solution

- A writer is allowed to access the data set only when there is no other writer or reader accessing
- Data Structure
 - Semaphore wrt initialized to 1 → to ensure at most one writer (no 2+ writers or one writer and reader(s)) allowed to access the data set (To guard access to data set)
- Code: The structure of a writer process

```
wait (wrt);.... writing is performed ...signal (wrt);
```

Reader-Writer Problem: Observations Solution

- Readers can simultaneously access the data set
 - When a reader arrives, it is allowed to access the data set if (i) no one is accessing the data set, or (ii) some other reader is reading; otherwise (some writer is writing), it should wait.
 - For a waiting reader, it is allowed to read if the writing writer completes.

Additional Data Structures:

- Integer readcount initialized to $0 \rightarrow$ to keep track of number of readers that are currently reading the data set
- Semaphore mutex initialized to 1 → to ensure mutual exclusive modification of readcount (To guard access to readcount)

Readers-Writers Problem: Solution

The structure of a reader process wait (mutex); if (readcount == 0) wait (wrt); //check if there is already reader being reading //if yes, go ahead to read; //otherwise, go on only if no writer writing //note: if this reader has to wait, follow-up readers should wait as well; so block them readcount ++; signal (mutex); ... reading is performed...

Readers-Writers Problem: Solution

The structure of a reader process

```
... reading is performed...
wait (mutex);
readcount --;
if (readcount == 0) signal (wrt); //if this is the last reader
signal (mutex);
```

- Must guarantee:
 - No two processes can actively execute wait() on the same semaphore at the same time (but when one is blocked by wait, another is allowed to execute it)
 - No two processes can modify the value of semaphore at the same time (i.e., signal() and "S--" of wait() must be atomic)
- Thus, implementation becomes the critical section problem where the wait and signal code are placed in the critical section.

All competing processes share a variable lock initialized to false

```
Signal(S) {
     while(testAndSet(&lock));
     S++;
     lock=False;
}
```

All competing processes share a variable lock initialized to false

- Ideally, will not have busy waiting in critical section
 - Otherwise, applications may spend lots of time in critical sections.

- With each semaphore, there are
 - value (of type integer)
 - list: an associated waiting queue. Each entry in a waiting queue has two items: (1) pointer to a process/thread; (2) pointer to next record in the list
- Two (atomic) operations:
 - block place the process invoking the operation on a waiting queue.
 - wakeup remove one of processes on a waiting queue and place it in the ready queue.

```
(Rewritten) Definition of wait:
    wait(semaphore *S) {
        S->value--;
        if (S->value < 0) {
            add this process to S->list;
            block();
        }
    }
}
```

```
Implementation of wait (example):
       wait(semaphore *S) {
               while(testAndSet(&lock));
               S->value--;
               if (S->value < 0) {
                       add this process to S->list;
                       lock=False;
                       block();
               else lock=False;
```

Definition of signal:

```
signal(semaphore *S) {
    S->value++;
    if (S->value <= 0) {
        remove a process P from S->list;
        wakeup(P);
    }
}
```

```
Implementation of signal (example):
       signal(semaphore *S) {
               while(testAndSet(&lock));
              S->value++;
              if (S->value \le 0) {
                      remove a process P from S->list;
                      wakeup(P);
               lock=False;
```