

Literature Introduction

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THE INTELLIGENT HAND

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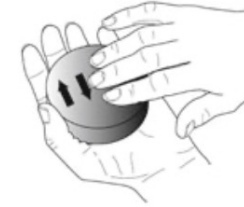
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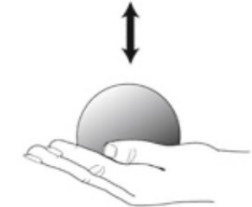
THE PSYCHOLOGY OF LEARNING
AND MOTIVATION, VOL. 21 1987

- Introduces the concept of *Exploratory Procedures (EPs)*.
- Each EP is related to a particular object property.

**Lateral Motion
(Texture)**



**Unsupported Holding
(Weight)**



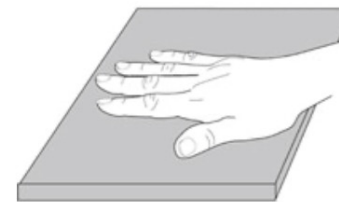
**Pressure
(Hardness)**



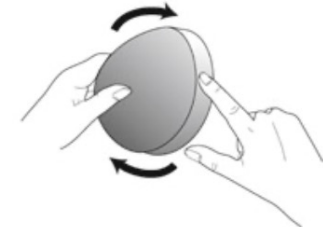
**Enclosure
(Global Shape)
(Volume)**



**Static Contact
(Temperature)**



**Contour Following
(Global Shape)
(Exact Shape)**





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Review

Hand synergies: Integration of robotics and neuroscience for understanding the control of biological and artificial hands

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Gionata Salvietti ^f, Domenico Prattichizzo ^{f,c}, Marc Ernst ^g, Alessandro Moscatelli ^{g,h},
Henrik Jörntell ⁱ, Astrid M.L. Kappers ^j, Kostas Kyriakopoulos ^k, Alin Albu-Schäffer ^l,
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Hand synergies: motor control

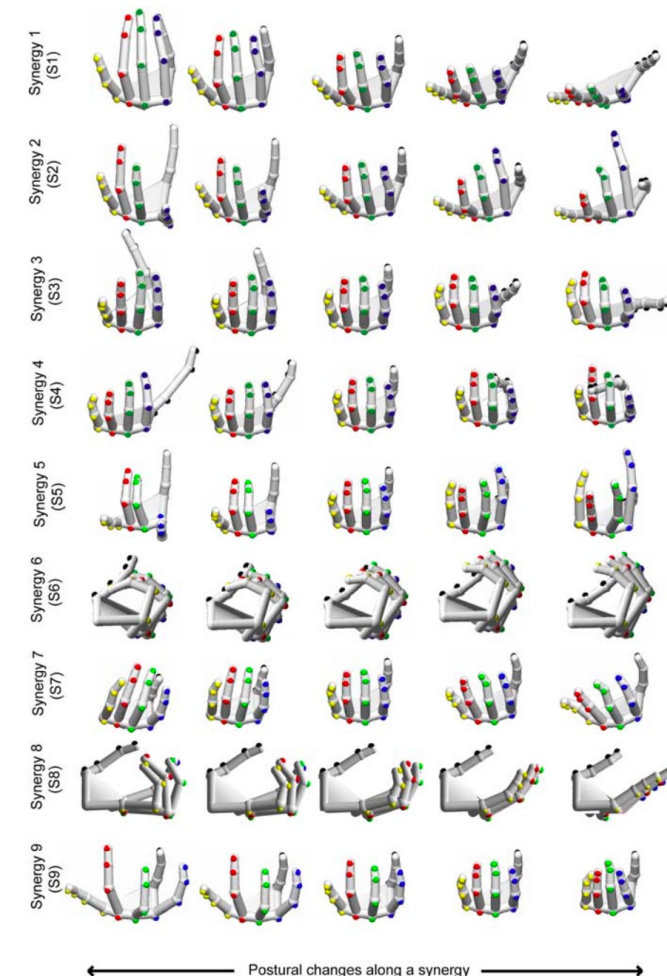
- “Hand postures used to **grasp** a wide variety of **imagined** objects could be described by a very small number of linear combinations of joint angles, i.e. principal components or postural synergies (or *eigenpostures*)”.
- “Lower-order principal components [...] are mainly responsible for coarse hand opening and closing – and higher-order principal components corresponding to finer hand shape adjustments”.
- “The apparent complexity associated with having to control multiple digit joints might be addressed by constraining them to move in a synergistic fashion. [...] The problem of controlling many joints is not as complex as it seems”.

Multidigit Movement Synergies of the Human Hand in an Unconstrained Haptic Exploration Task

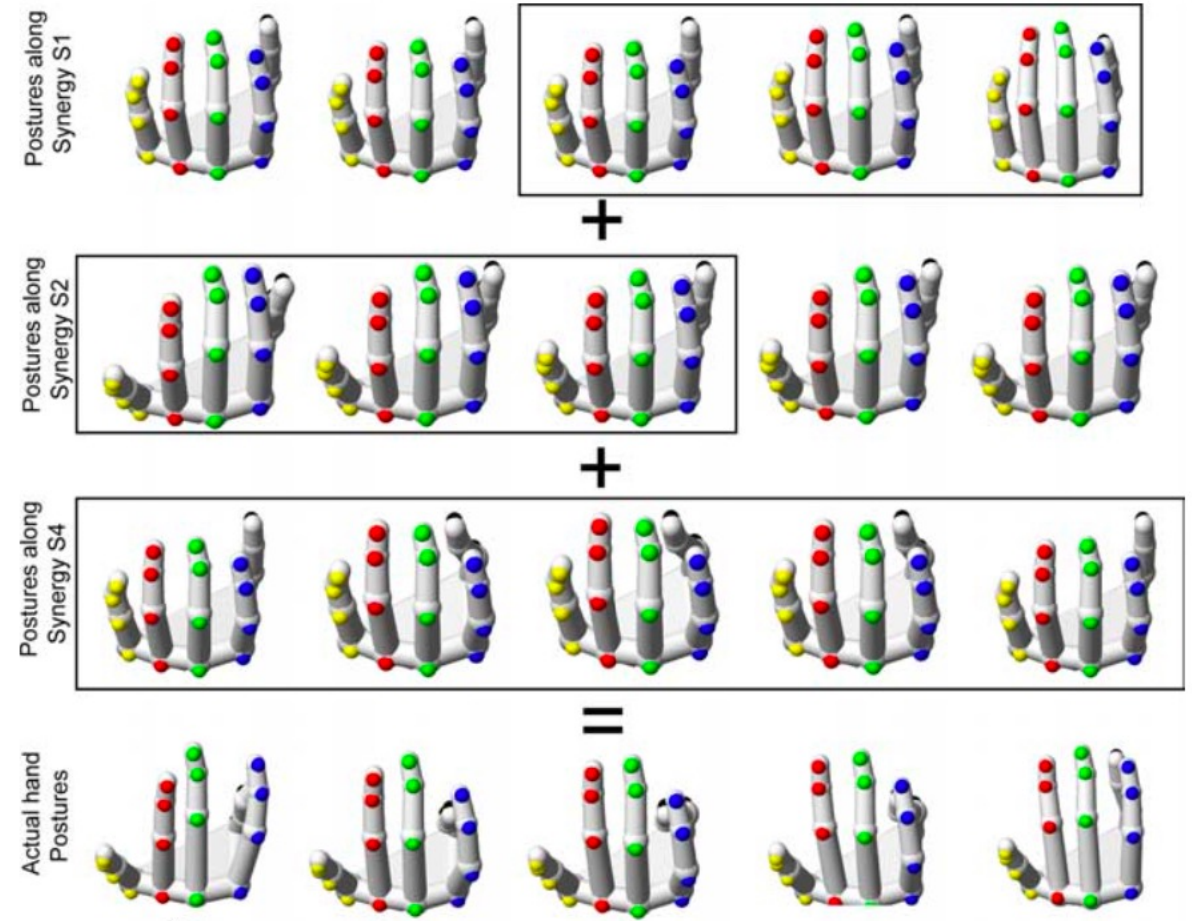
Pramodsingh H. Thakur, Amy J. Bastian, and Steven S. Hsiao

Departments of Neuroscience, Neurology, and Biomedical Engineering, Zanvyl Krieger Mind/Brain Institute and Kennedy Krieger Institute, Johns Hopkins University, Baltimore, Maryland 21218


- 8 blinfolded subjects perform a haptic exploration task to identify fifty common objects using only one hand.
- For each subject they perform *Principal Component Analysis* and select the 10 eigenvectors corresponding to the 10 higher eigenvalues.
- “The 10 sets of hand postures corresponding to the 10 eigenvectors for each subject were visually compared across different subjects to identify similar trends. Those with similarities across multiple subjects were considered to belong to a common synergy”.
- “Any posture can be considered as a unique point in this 9D space. Similarly, any exploratory movement can be considered as a trace or curve meandering inside this 9D space”.



- “Any hand movement can be thought of as a combination of postural changes along contributing synergies. [...] The synergies can be thought of as building blocks that contribute in varying proportions to construct any arbitrary hand movement patterns”.
- “Because synergies combine in various ways to construct any continuous segment of hand motion, they can be thought of as building blocks of *Exploratory Procedures*”.
- **Flaws:** Synergies are calculated for each subject and paired manually.



Kinematic synergies of hand grasps: a comprehensive study on a large publicly available dataset

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- Here synergies are also computed for each subject using *PCA*.
- Those synergies are grouped using a hierarchical cluster analysis.

- In this paper they compute hand synergies under two different conditions: with and without cutaneous (tactile) impairment.
- For the cutaneous impairment, participants were requested to wear rigid shells at their fingertips.
- They conclude that “the presence of tactile impairment, while modifying the strategies themselves, does not substantially modify the most basic kinematic ingredients commonly used to generate hand postures. [...] Cutaneous impairment affects posture refinement, which can be likely ascribed to higher order synergies”.

Postural Hand Synergies during Environmental Constraint Exploitation

Cosimo Della Santina^{1*}, Matteo Bianchi¹, Giuseppe Averta^{1,2}, Simone Ciotti^{1,2}, Visar Arapi¹, Simone Fani^{1,2}, Edoardo Battaglia¹, Manuel Giuseppe Catalano^{1,2}, Marco Santello³ and Antonio Bicchi^{1,2}

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Muscle Synergy Analysis of a Hand-Grasp Dataset: A Limited Subset of Motor Modules May Underlie a Large Variety of Grasps

**Alessandro Scano^{1*}, Andrea Chiavenna¹, Lorenzo Molinari Tosatti¹, Henning Müller² and
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- Authors extract muscle synergies from sEMG data using *non-negative matrix factorization (NMF)*.
- *They group the synergies using k-means clustering algorithm.*