JUSTIN WASSERMAN

Homepage: jbwasse2.github.io ♦ Email: jbwasse2@illinois.edu Interests: Robotics, Embodied Agents, Computer Vision

EDUCATION University of Illinois at Urbana-Champaign August 2019 - Present Ph.D. in Electrical and Computer Engineering · Advisor: Girish Chowdhary University of Illinois at Urbana-Champaign August 2014 - May 2019 Bachelor of Sciences (B.S) in Computer Engineering · Advisor: Steven LaValle RESEARCH EXPERIENCE Skild AI November 2023 - Present Research Scientist Pittsburgh, PA · Mentors: Abhinav Gupta, Deepak Pathak Carnegie Mellon University March 2023 - November 2023 Research Assistant Pittsburgh, PA · Mentors: Unnat Jain, Abhinav Gupta CONFERENCE PUBLICATIONS Legolas: Deep Leg-Inertial Odometry J. Wasserman, A. Agarwal, R. Jangir, G. Chowdhary, D. Pathak, A. Gupta Conference on Robot Learning (CoRL), 2024 [project] Exploitation-Guided Exploration for Semantic Embodied Navigation J. Wasserman, G. Chowdhary, A. Gupta, U. Jain IEEE International Conference on Robotics and Automation (ICRA), 2024 [project] [pdf] Best Paper at NeurIPS 2023 Robot Learning Workshop (oral) Under-Canopy Dataset for Advancing Simultaneous Localization and Mapping in Agricultural Robotics J. Cuaran, A. Velasquez, M. Gasparino, N. Uppalapati, A. Sivakumar, J. Wasserman, M. Huzaifa, S. Adve, G. Chowdhary Internation Journal of Robotics Research (IJRR), 2023 [project] Last-Mile Embodied Visual Navigation J. Wasserman, K. Yadav, G. Chowdhary, A. Gupta, U. Jain. Conference on Robot Learning (CoRL), 2022 [project] [pdf] A Hardware and Software Testbed for Underactuated Self-Assembling Robots A. Nilles, J. Wasserman, A. Born, C. Horn, J. Born, S. LaValle. IEEE International Symposium on Multi-Robot and Multi-Agent Systems (MRS). 2019 [pdf] TALKS AND AWARDS CMU Robot Learning Retreat 2023 Exploitation-Guided Exploration for Semantic Embodied Navigation 2022 EAI Seminar, Facebook AI Research Labs (FAIR) Last-Mile Embodied Visual Navigation [slides]

2019

2019

Undergraduate Research Symposium, UIUC

Leung Student Venture Fund Award

Controlling, Modeling, and Scaling Underactuated, Non-deterministic Robot Structures

· Awarded \$1000 to support research in robotics for undergraduate thesis.

SERVICE

Reviewer

- · IROS, ICRA, RA-L, CoRL, NeurIPS, ICLR, ICML, CVPR
- · RoboAdapt Worksop CoRL 2022 [webpage], Robot Learning Workshop NeurIPS 2023 [webpage]

Academic Services

- · CSL Student Conference 2021 Robotics Chair [webpage]
- · CSL Student Conference 2020 Reception Chair [webpage]

Mentoring

- · Shivani Kamtikar (PhD at UIUC : Publication in submission.)
- · Ruben Dorian Serrano (BS at UIUC \rightarrow Amazon)
- · FIRST Robotics : Mentored many undegraduates, high schoolers, and middle schoolers in competitive robotics.
- · Various work supporting the women of Afghanistan.

INDUSTRY EXPERIENCE

EarthSense May 2019 - August 2019

Deep Learning Intern

Champaign, IL

· Applied deep learning techniques to agriculture data to assist the TerraSentia robot in localization and analysis of data.

Arity January 2018 - May 2018

Software Engineering Intern

Chicago, IL

· Translated high-level motion data from a car to movement on a testbed robot to create a platform to demonstrate the captured motion data.

Yaskawa America Inc.

May 2016 - January 2017

Applications Engineering Co-Op

Waukegan, IL

· Built software library for motion applications for gantries, Cartesian robots, robotic arms, and other robotics applications.

TECHNICAL STRENGTHS

Computer Languages Python, Shell Scripting, C++, C, IEC 61131-3 Computing Pytorch, ROS, Linux, Git, Vim, LATEX

TEACHING

ECE 110 Spring 2022

Teaching Assistant

Urbana-Champaign, IL

· Led and supervised four 20-student lab sections.

ENG 298 LRM Fall 2015, Fall 2017

Teaching Assistant

Urbana-Champaign, IL

- · Taught collegiate students how to mentor middle school-aged students in Lego robotics and First Tech Competition.
- · Communicated with local teams, coaches, and students to organize mentorships.