

## § 1.6 复数

### § 1.6.1 复数的四则运算

$$z = x + iy$$

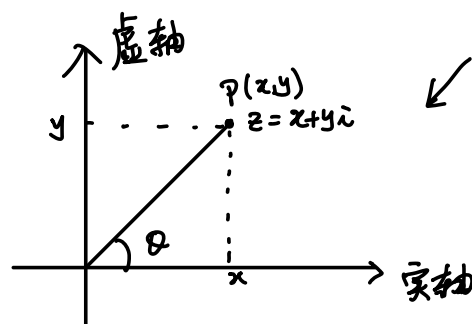
↙ ↘  
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实部 虚部  
 $\operatorname{Re} z$      $\operatorname{Im} z$

$$"+": (x_1 + iy_1) \pm (x_2 + iy_2) = (x_1 \pm x_2) + i(y_1 \pm y_2)$$

$$": (x_1 + iy_1) \cdot (x_2 + iy_2) \stackrel{i^2 = -1}{=} (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)$$

$$": \frac{x_2 + iy_2}{(0 \neq) x_1 + iy_1} = \frac{(x_2 + iy_2)(x_1 - iy_1)}{(x_1 + iy_1)(x_1 - iy_1)} = \frac{(x_1 x_2 + y_1 y_2) + i(x_1 y_2 - x_2 y_1)}{x_1^2 + y_1^2}$$

### § 1.6.2. 复数的几何表示



复平面.

$z$  用  $\vec{OP}$  表示 ( $z = \vec{OP}$ )

$z$  的模长:  $|z| := |\vec{OP}| = \sqrt{x^2 + y^2}$

$z$  的辐角:  $\arg z := x$  轴(逆时针)旋转到  $\vec{OP}$  的角度  $= \theta + 2k\pi$ .  
(一般规定  $0 \leq \arg z < 2\pi$  主值)

性质:  $z_1 + z_2 = \vec{OP}_1 + \vec{OP}_2$   
 $|z_1 + z_2| \leq |z_1| + |z_2|$

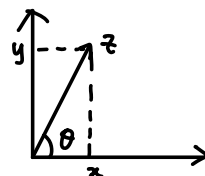
$z = x + iy$  的共轭复数定义为:

$$\bar{z} = x - iy$$

性质:  $|\bar{z}| = |z|$ ,  $\arg \bar{z} + \arg z = 2\pi$

$$|z|^2 = z\bar{z}, \quad \overline{z_1 + z_2} = \bar{z}_1 + \bar{z}_2, \quad \overline{z_1 z_2} = \bar{z}_1 \cdot \bar{z}_2$$

三角表示:  $z = r(\cos \theta + i \sin \theta)$



性质:  $z_1 = r_1(\cos \theta_1 + i \sin \theta_1)$ ,  $z_2 = r_2(\cos \theta_2 + i \sin \theta_2)$  则

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$$|z_1 z_2| = r_1 r_2 \quad \text{且} \quad \arg(z_1 z_2) = \arg z_1 + \arg z_2$$

$$\text{pf: } \cos(\theta_1 + \theta_2) = \cos\theta_1 \cos\theta_2 - \sin\theta_1 \sin\theta_2$$

$$\sin(\theta_1 + \theta_2) = \sin\theta_1 \cos\theta_2 + \cos\theta_1 \sin\theta_2$$

□

复数乘法的几何解释.  $w = r(\cos\theta + i\sin\theta)$

$$z \xrightarrow{\text{伸缩}} rz \xrightarrow{\text{旋转}} wz$$

Euler 公式  $e^{i\theta} = \cos\theta + i\sin\theta$ .

↑ 暂时看成 + 记号

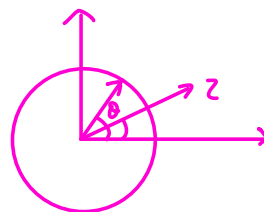
$$\text{性质: } 1) r_1 e^{i\theta_1} \cdot r_2 e^{i\theta_2} = (r_1 r_2) e^{i(\theta_1 + \theta_2)}$$

$$2) (\text{de Moivre}) (r e^{i\theta})^n = r^n \cdot e^{in\theta}, \quad \forall n \in \mathbb{Z}$$

例: 求  $z = 1 + i\cos\theta + i\sin\theta$  ( $-\pi \leq \theta < \pi$ ) 的三角形式.

$$\text{解: } |z| = 2\cos\frac{\theta}{2}$$

$$\arg z = \arccos \frac{1 + \cos\theta}{2\cos\frac{\theta}{2}} = \frac{\theta}{2}$$



$$\Rightarrow z = 2\cos\frac{\theta}{2} \cdot (\cos\frac{\theta}{2} + i\sin\frac{\theta}{2})$$

例: 逆时针旋转  $z = x + iy$  角度  $\frac{\pi}{2}$ .

$$\text{解: } z e^{\frac{\pi}{2}i} = (x + iy)i = -y + ix.$$

例：解方程：  $z^n = a$ .

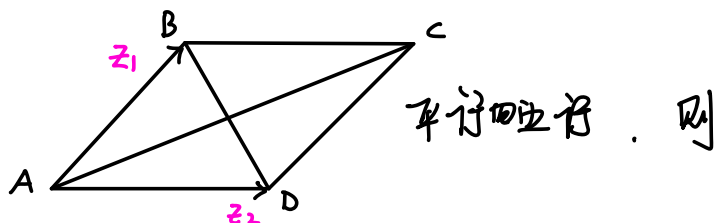
解：设  $a = re^{i\theta}$ ,  $r \geq 0, 0 \leq \theta < 2\pi$ .

设  $z = se^{i\phi}$ , 则

$$\left. \begin{aligned} s^n &= r \\ n\phi &= \theta + 2k\pi \end{aligned} \right\} \Rightarrow \begin{cases} s = \sqrt[n]{r} \\ \phi = \frac{\theta + 2k\pi}{n} \end{cases} \Rightarrow z = \sqrt[n]{r} e^{i \frac{\theta + 2k\pi}{n}}$$

□

例：

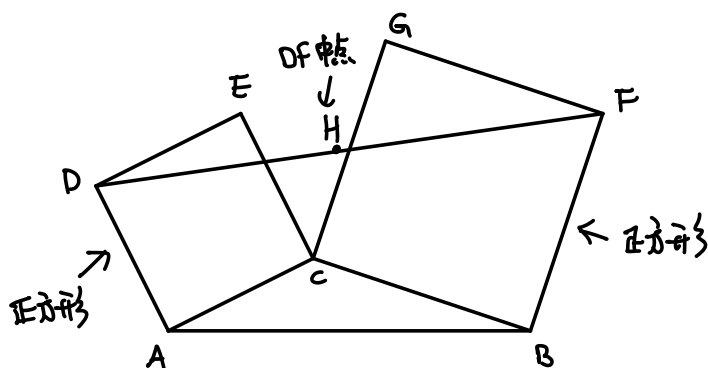


$$|AC|^2 + |BD|^2 = |AB|^2 + |BC|^2 + |CD|^2 + |AD|^2$$

$$\begin{aligned} \text{Pf: LHS} &= |z_1 + z_2|^2 + |z_1 - z_2|^2 = (z_1 + z_2)(\bar{z}_1 + \bar{z}_2) + (z_1 - z_2)(\bar{z}_1 - \bar{z}_2) \\ &= 2z_1\bar{z}_1 + 2z_2\bar{z}_2 = 2|z_1|^2 + 2|z_2|^2 = \text{RHS} \end{aligned}$$

□

例：



则 H 与 C 无关.

$$\begin{aligned} \text{证: } \vec{AH} &= \frac{1}{2} \vec{AD} + \frac{1}{2} (\vec{AB} + \vec{BF}) \\ &= \frac{1}{2} \vec{AB} + \frac{1}{2} \vec{AC} e^{\frac{\pi i}{2}} + \frac{1}{2} \vec{CB} e^{\frac{\pi i}{2}} = \frac{1+i}{2} \cdot \vec{AB} \end{aligned}$$

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