## %Ejercicio 1 ej1

```
R1 =
           -1.0000
   0.0000
                      0.0000
            0.0000
                      1.0000
   0.0000
   -1.0000
                 0
                      0.0000
R2 =
                      1.0000
           -0.0000
   0.0000
   1.0000
           0.0000
                     -0.0000
             1.0000
                      0.0000
R3 =
           0.2588
   0.0000
                      0.9659
   0.0000 0.9659
                     -0.2588
                      0.0000
   -1.0000 0.0000
```

## %Ejercicio 2

#### Ejercicio 2

#### ej2

```
X_cam =
-8.0000
1.0000
2.0000
```

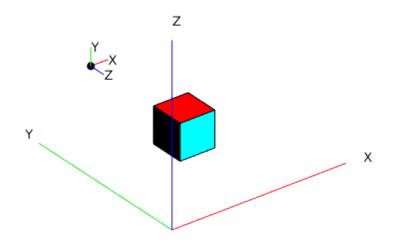
## % Ejercicio 3

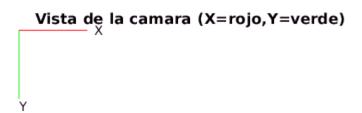
#### Ejercicio 3

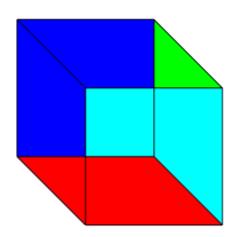
## generar\_camara(1,0,0.5,0.5,90,0,0, [3 10 3])

```
Camara:
Distancia Focal: 1.00
Skewness: 0.00
Centro de la imagen:
x = 0.50, y=0.50
Rotacion de la camara:
x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3
```

# Mundo (X=rojo,Y=verde,Z=azul)







generar\_camara(0.1,0,0.5,0.5,90,0,0, [3 10 3])

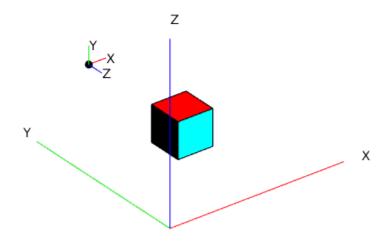
Camara:

Distancia Focal: 0.10

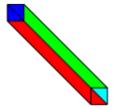
Skewness: 0.00

Centro de la imagen: x = 0.50, y=0.50 Rotacion de la camara: x = 90.00, y=0.00, z=0.00 Posicion de la camara: 3 Posicion de la camara: 10 Posicion de la camara: 3

# Mundo (X=rojo,Y=verde,Z=azul)



Vista de la camara (X=rojo,Y=verde)



## generar\_camara(1,0.5,0.5,0.5,90,0,0, [ 3 10 3])

Camara:

Distancia Focal: 1.00

Skewness: 0.50

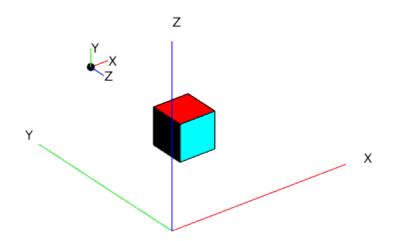
Centro de la imagen: x = 0.50, y=0.50

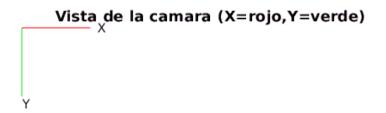
Rotacion de la camara:

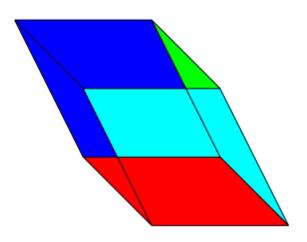
Posicion de la camara:

x = 90.00, y=0.00, z=0.00Posicion de la camara: 3 Posicion de la camara: 10

## Mundo (X=rojo,Y=verde,Z=azul)





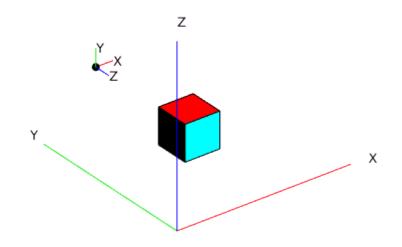


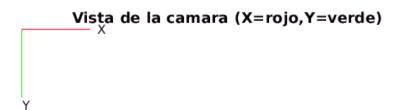
## generar camara(1,1,0.5,0.5,90,0,0, [ 3 10 3])

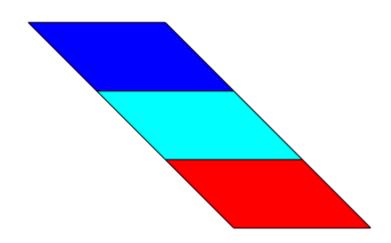
#### Camara:

Distancia Focal: 1.00
Skewness: 1.00
Centro de la imagen:
 x = 0.50, y=0.50
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3

# Mundo (X=rojo,Y=verde,Z=azul)







generar\_camara(1,0,0,0,90,0,0, [ 3 10 3])

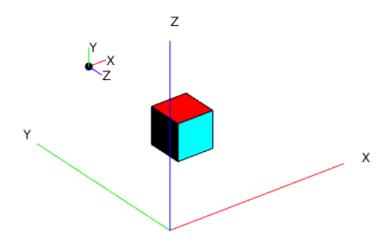
Camara:

Distancia Focal: 1.00

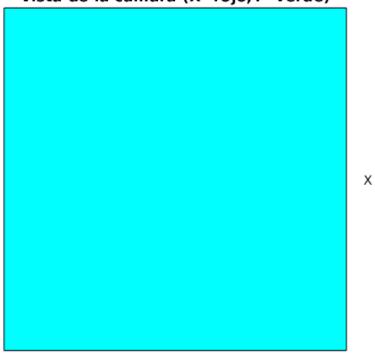
Skewness: 0.00

Centro de la imagen: x = 0.00, y=0.00 Rotacion de la camara: x = 90.00, y=0.00, z=0.00 Posicion de la camara: 3 Posicion de la camara: 10 Posicion de la camara: 3

# Mundo (X=rojo,Y=verde,Z=azul)



# Vista de la camara (X=rojo,Y=verde)



## generar\_camara(1,0,1,1,90,0,0, [ 3 10 3])

Camara:

Distancia Focal: 1.00

Skewness: 0.00

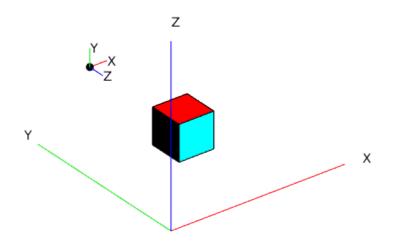
Centro de la imagen: x = 1.00, y=1.00

Rotacion de la camara:

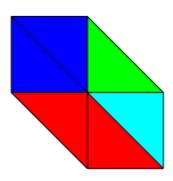
Posicion de la camara:

x = 90.00, y=0.00, z=0.00Posicion de la camara: 3 Posicion de la camara: 10

## Mundo (X=rojo,Y=verde,Z=azul)



# Vista de la camara (X=rojo,Y=verde)

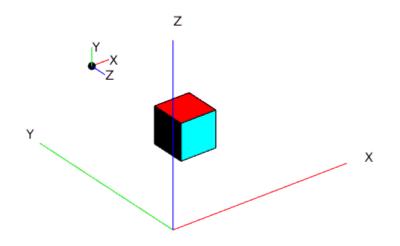


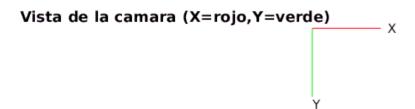
## generar camara(1,0,-0.5,0.5,90,0,0, [ 3 10 3])

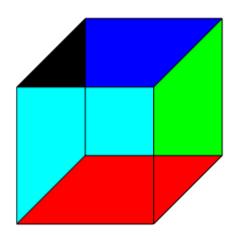
#### Camara:

Distancia Focal: 1.00
Skewness: 0.00
Centro de la imagen:
 x = -0.50, y=0.50
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3

# Mundo (X=rojo,Y=verde,Z=azul)







generar\_camara(1,0,0,0,45,15,30, [ 3 10 3])

Camara:

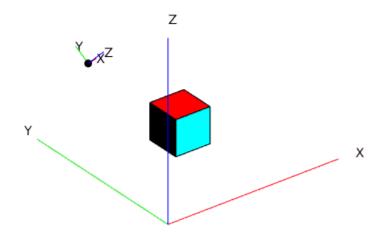
Distancia Focal: 1.00

Skewness: 0.00

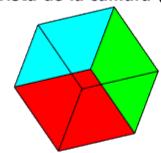
Centro de la imagen: x = 0.00, y=0.00 Rotacion de la camara: x = 45.00, y=15.00, z=30.00

Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3

# Mundo (X=rojo,Y=verde,Z=azul)



# Vista de la camara (X=rojo,Y=verde)





## generar\_camara(1,0,0.5,0.5,90,0,0, [ 5 10 5])

Camara:

Distancia Focal: 1.00

Skewness: 0.00

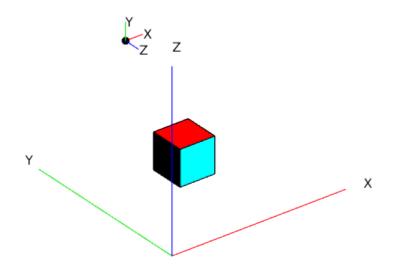
Centro de la imagen: x = 0.50, y=0.50

Rotacion de la camara:

x = 90.00, y=0.00, z=0.00Posicion de la camara: 5

Posicion de la camara: 10 Posicion de la camara: 5

## Mundo (X=rojo,Y=verde,Z=azul)



Vista de la camara (X=rojo,Y=verde)

