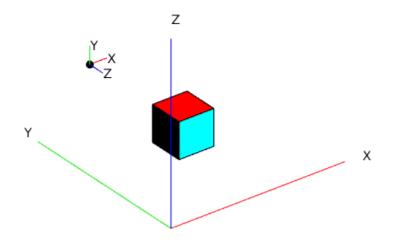
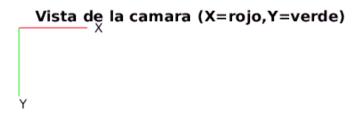
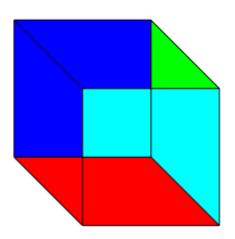
```
fprintf("Ejercicio 1");
Ejercicio 1
ej1
R1 =
    0.0000
           -1.0000
                       0.0000
   0.0000
            0.0000
                       1.0000
   -1.0000
                 0
                       0.0000
R2 =
           -0.0000
    0.0000
                       1.0000
           0.0000
                     -0.0000
    1.0000
           1.0000
                       0.0000
R3 =
    0.0000 0.2588
                       0.9659
    0.0000 0.9659
                    -0.2588
           0.0000
   -1.0000
                      0.0000
fprintf('\n\n');
fprintf("Ejercicio 2");
Ejercicio 2
ej2
X cam =
   -8.0000
    1.0000
    2.0000
fprintf("\n\n");
fprintf("Ejercicio 3");
Ejercicio 3
generar camara(1,0,0.5,0.5,90,0,0, [3 10 3])
Camara:
 Distancia Focal: 1.00
 Skewness: 0.00
 Centro de la imagen:
 x = 0.50, y=0.50
 Rotacion de la camara:
```

x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3







Camara:

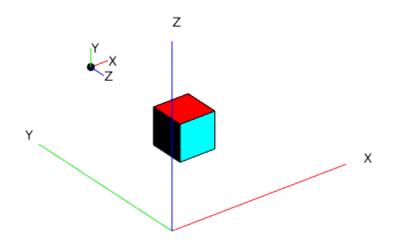
Distancia Focal: 0.10

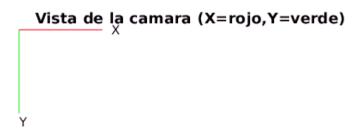
Skewness: 0.00

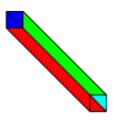
Centro de la imagen: x = 0.50, y=0.50

Rotacion de la camara:

x = 90.00, y=0.00, z=0.00Posicion de la camara: 3 Posicion de la camara: 10 Posicion de la camara: 3





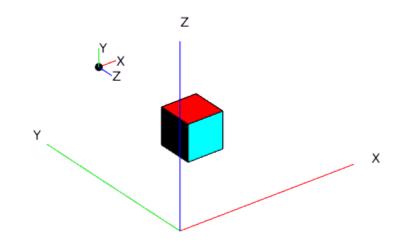


generar camara(1,0.5,0.5,0.5,90,0,0, [3 10 3])

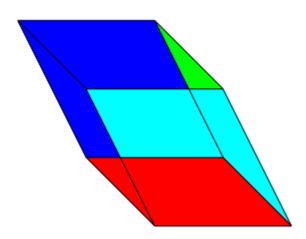
Camara:

Distancia Focal: 1.00
Skewness: 0.50
Centro de la imagen:
 x = 0.50, y=0.50
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3

Mundo (X=rojo,Y=verde,Z=azul)



Vista de la camara (X=rojo,Y=verde)



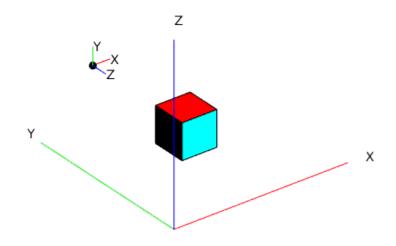
generar_camara(1,1,0.5,0.5,90,0,0, [3 10 3])

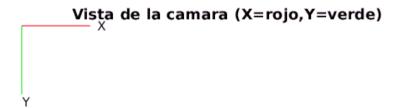
Camara:

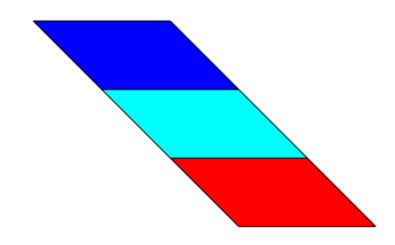
Distancia Focal: 1.00

Skewness: 1.00

Centro de la imagen:
 x = 0.50, y=0.50
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3







generar_camara(1,0,0,0,90,0,0, [3 10 3])

Camara:

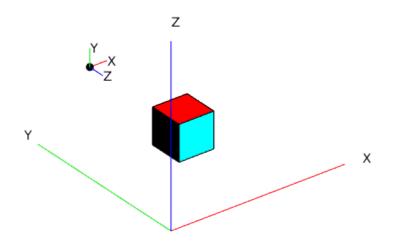
Distancia Focal: 1.00

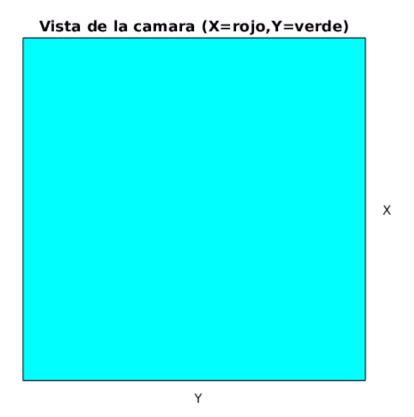
Skewness: 0.00

Centro de la imagen: x = 0.00, y=0.00

Rotacion de la camara: x = 90.00, y=0.00, z=0.00Posicion de la camara: 3 Posicion de la camara: 10

Posicion de la camara:



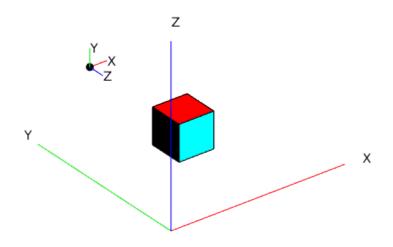


generar_camara(1,0,1,1,90,0,0, [3 10 3])

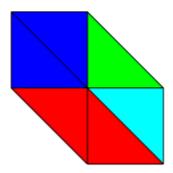
Camara:

Distancia Focal: 1.00
Skewness: 0.00
Centro de la imagen:
 x = 1.00, y=1.00
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3

Mundo (X=rojo,Y=verde,Z=azul)



Vista de la camara (X=rojo,Y=verde)



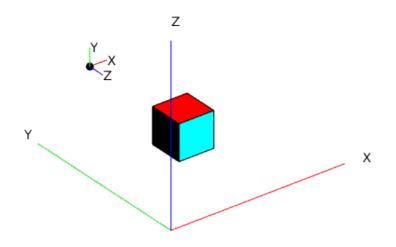
generar_camara(1,0,-0.5,0.5,90,0,0, [3 10 3])

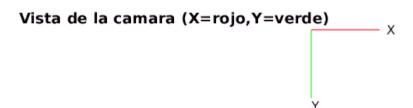
Camara:

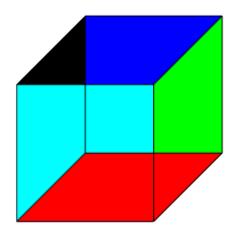
Distancia Focal: 1.00

Skewness: 0.00

Centro de la imagen: x = -0.50, y=0.50 Rotacion de la camara: x = 90.00, y=0.00, z=0.00 Posicion de la camara: 3 Posicion de la camara: 10 Posicion de la camara: 3







generar_camara(1,0,0,0,45,15,30, [3 10 3])

Camara:

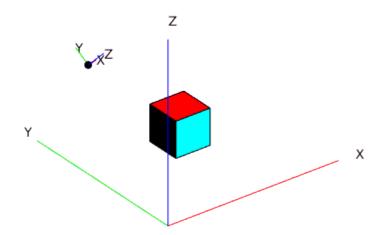
Distancia Focal: 1.00

Skewness: 0.00

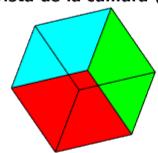
Centro de la imagen: x = 0.00, y=0.00

Rotacion de la camara:

x = 45.00, y=15.00, z=30.00
Posicion de la camara: 3
Posicion de la camara: 10
Posicion de la camara: 3



Vista de la camara (X=rojo,Y=verde)





generar_camara(1,0,0.5,0.5,90,0,0, [5 10 5])

Camara:

Distancia Focal: 1.00
Skewness: 0.00
Centro de la imagen:
 x = 0.50, y=0.50
Rotacion de la camara:
 x = 90.00, y=0.00, z=0.00
Posicion de la camara: 5
Posicion de la camara: 10
Posicion de la camara: 5

