

# Integrated Sensing and Communications

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# Sensing

- To detect the location, motion of mobile devices, vehicles or human
- Sensing may improve the communication efficiency
- Sensing may also provide services other than communications

# IEEE 802.11bf

- “802.11bf is a new Task Group about **WLAN sensing** within the IEEE 802.11 working group.”
- “WLAN sensing is the use, by a WLAN sensing capable STA(s), of received WLAN signals **to detect feature(s) of an intended target(s)** in a given environment.”

# IEEE 802.11bf

## WLAN sensing

### Use case example 1

- **Multiple devices diversity:** Makes use of 802.11 devices found in **various locations** inside the house
  - Different rooms/floors could be “sensed”
  - High level of device diversity, wide coverage
- **Applications**
  - Home security and safety
  - Energy management and control
    - HVAC, light, device power save
  - Home elderly care and assisted living

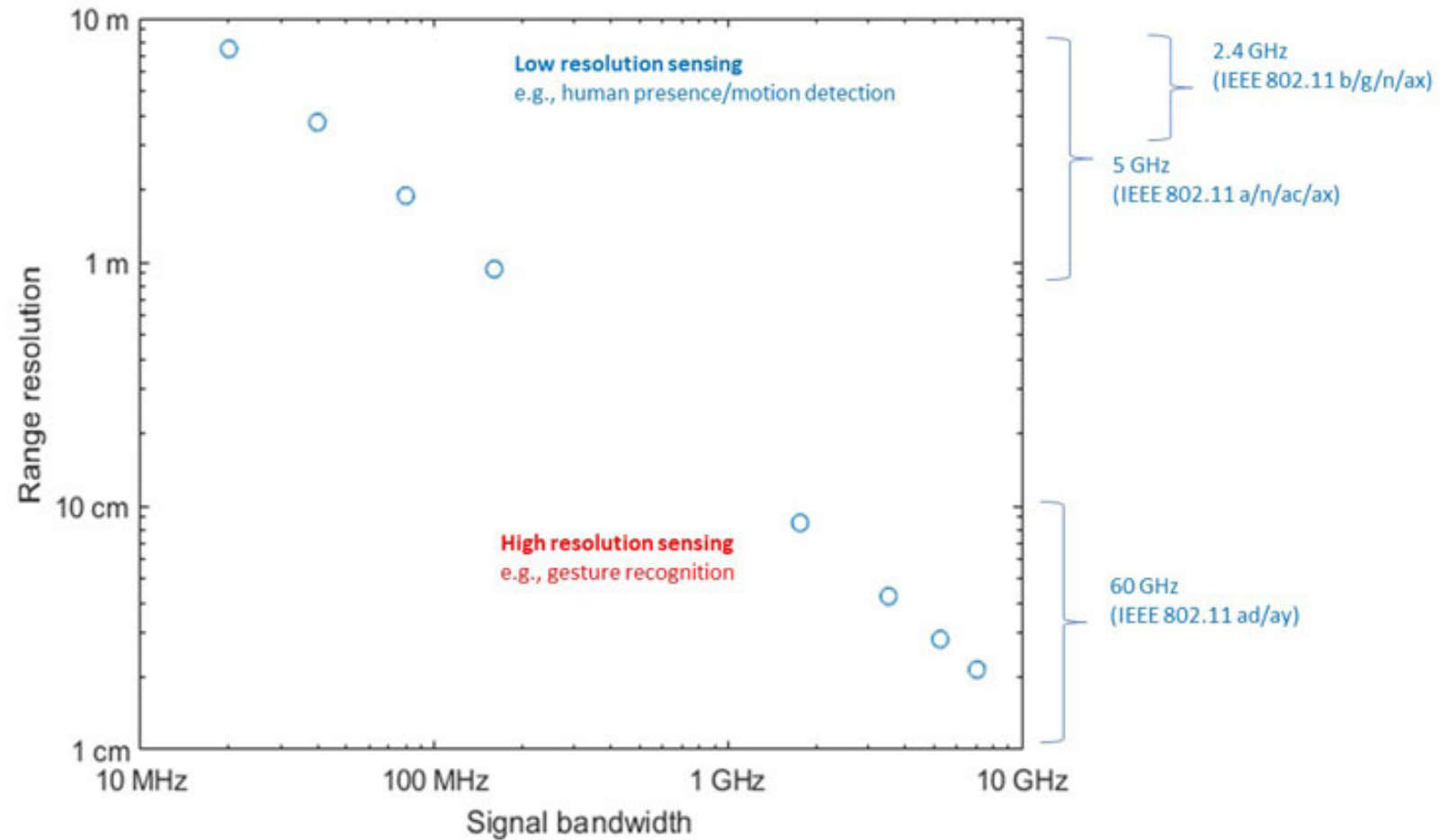


### Use case example 2

- **mmWave:** 60 GHz 802.11 technology offers better performance to detect/track movement
  - Higher resolution
  - Higher accuracy
- **Applications**
  - More than just a teleconferencing tool to speak with your physician, upon consent, your laptop could also be able to provide your physician with **vital data**, both historical and in real time

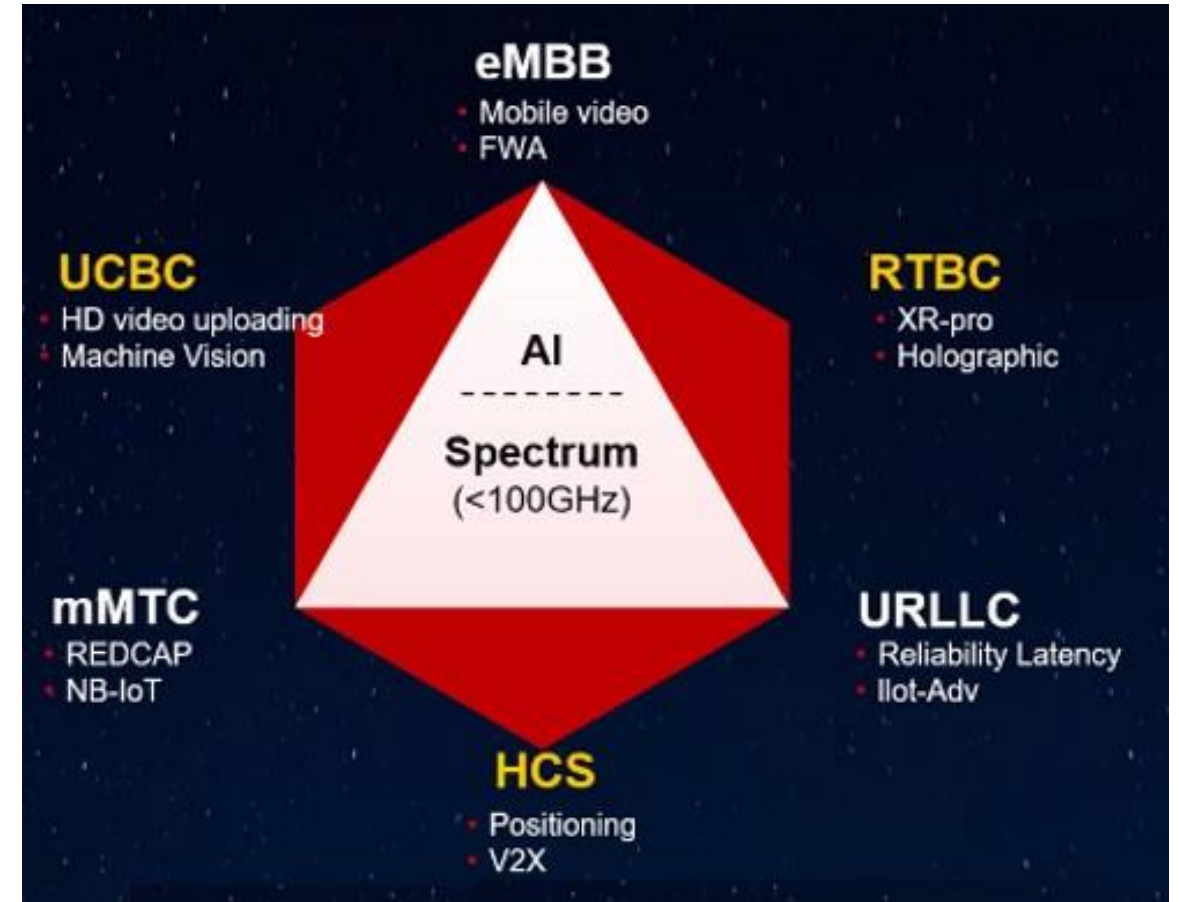


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# Sensing in 3GPP

- Currently, 5G is not so successful in applications
- Industry tries to define new application scenarios for cellular systems
- Huawei: 5.5G



# Sensing Modes and Parameters

- Distance to the BS or mobile devices
  - Angles
  - Velocity
  - Motion
- 
- Proactive and passive

# Proactive Sensing

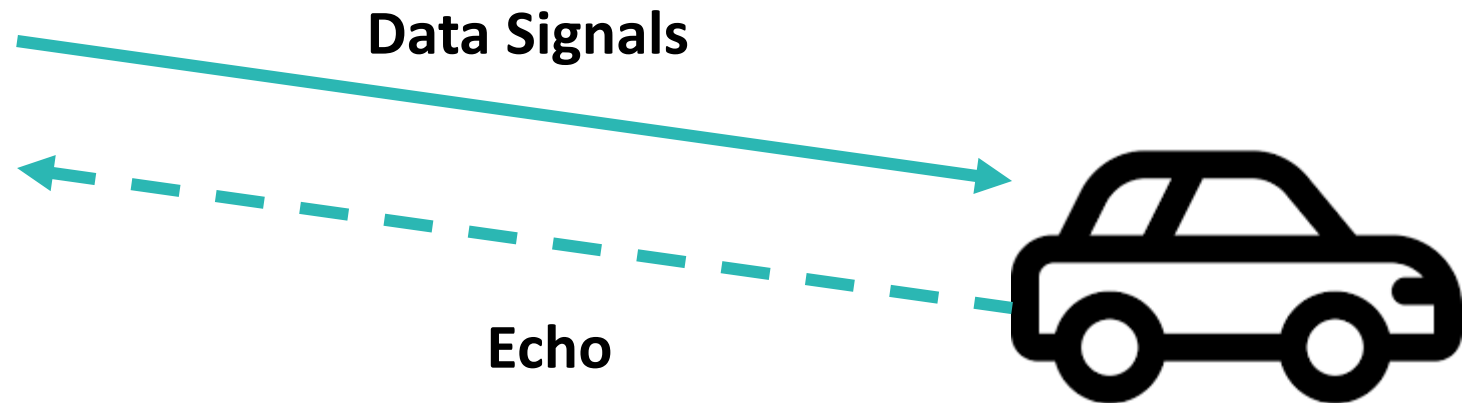


**Data Signals**

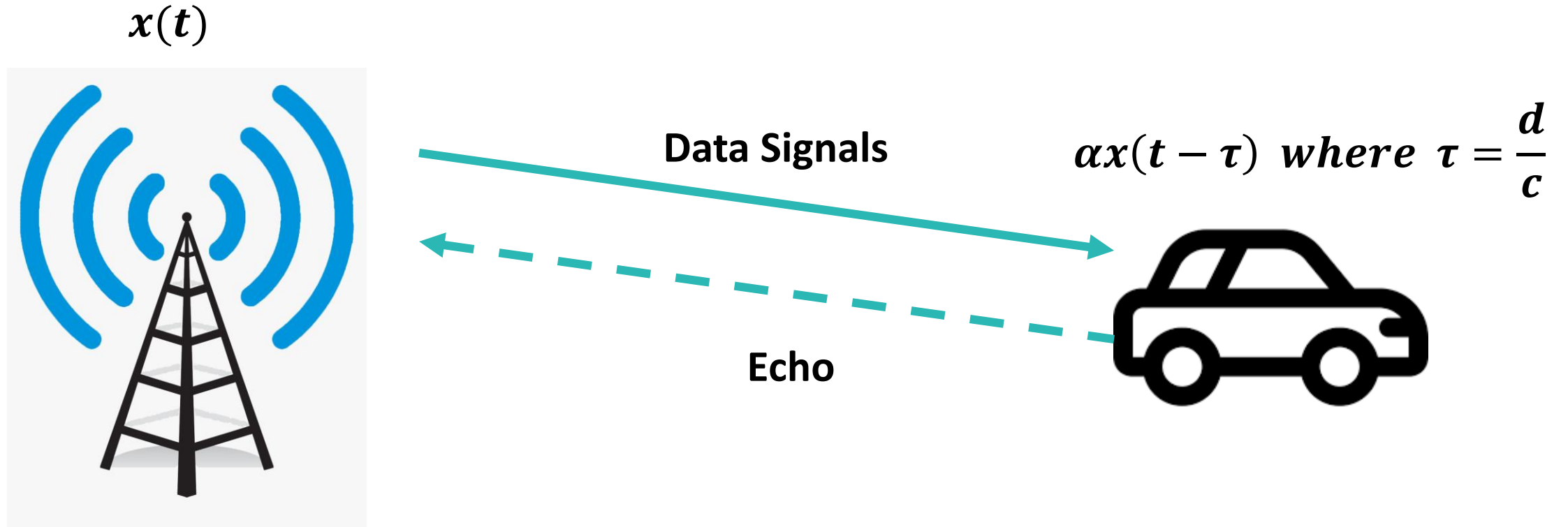




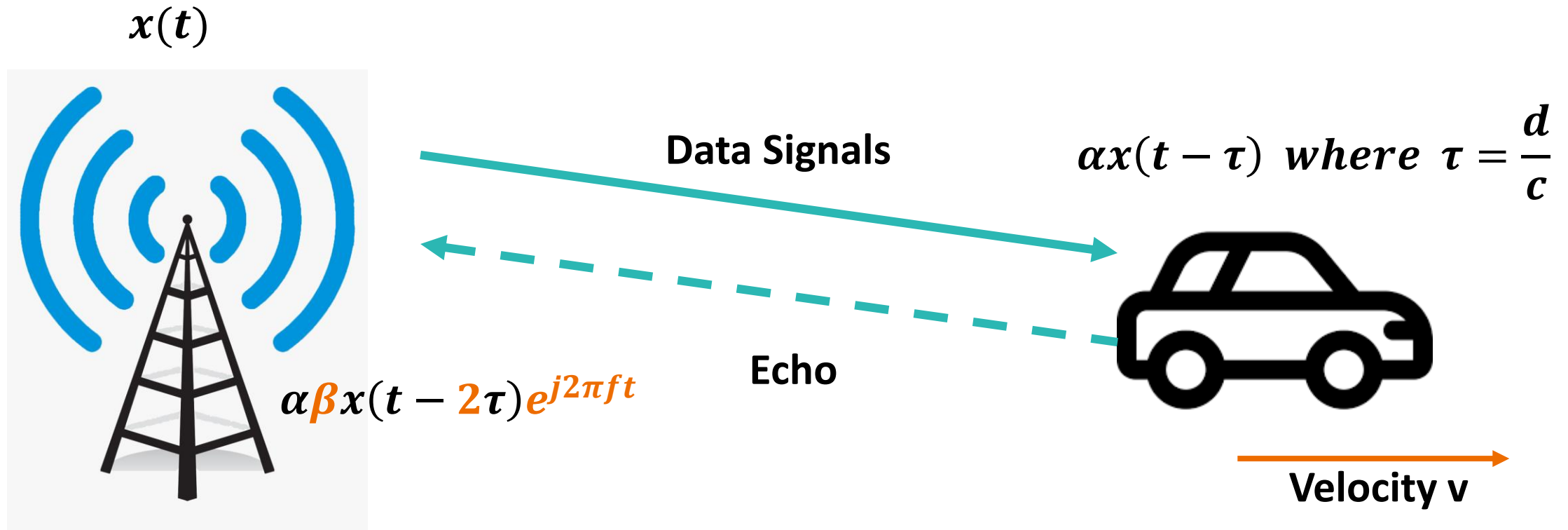
# Proactive Sensing



# Proactive Sensing



# Proactive Sensing



- $\beta$  is due to the pathloss of echo path + radar cross-section (RCS)
- $f$  is the Doppler frequency  $= \frac{2vf_c}{c}$

# Proactive Sensing

$x(t)$



- If the BS knows  $y(t)$
- Define  $Cor(c, d) = \int x(t - 2c) e^{j2\pi dt} y^*(t) dt$
- The estimation of  $(\tau, f)$ :

$$(\hat{\tau}, \hat{f}) = \arg \max_{c, d} Cor(c, d)$$

$$y(t) = \alpha \beta x(t - 2\tau) e^{j2\pi ft}$$

# Proactive Sensing: Analysis

$x(t)$



- If  $\tau$  is known,  $Cor(\tau, d) = \int x(t - 2\tau)e^{j2\pi dt}y^*(t) dt$
- The estimation of  $f$ :

$$\begin{aligned}\hat{f} &= \arg \max_d Cor(\tau, d) \\ &= \arg \max_d \int x(t - 2\tau)e^{j2\pi dt} \alpha^* \beta^* x(t - 2\tau)^* e^{-j2\pi ft} dt \\ &= \arg \max_d \alpha^* \beta^* \int |x(t - 2\tau)|^2 e^{j2\pi(d-f)t} dt\end{aligned}$$

$$y(t) = \alpha\beta x(t - 2\tau)e^{j2\pi ft}$$

# Proactive Sensing: Analysis

$x(t)$



- If  $f$  is known,  $Cor(c, f) = \int x(t - 2c) e^{j2\pi f t} y^*(t) dt$
- The estimation of  $\tau$ :

$$\begin{aligned}\hat{\tau} &= \arg \max_c Cor(c, f) \\ &= \arg \max_c \int x(t - 2c) e^{j2\pi f t} \alpha^* \beta^* x(t - 2\tau)^* e^{-j2\pi f t} dt \\ &= \arg \max_c \alpha^* \beta^* \int x(t - 2c) x(t - 2\tau)^* dt\end{aligned}$$

$$y(t) = \alpha \beta x(t - 2\tau) e^{j2\pi f t}$$

# Proactive Sensing: Full Duplexing

$x(t)$



- The BS **should** know  $y(t)$
- BS is sending  $x(t)$  => It must be full duplex
- Full duplex is currently **a huge challenge** for data transceiver design

$$y(t) = \alpha\beta x(t - \mathbf{2\tau})e^{j2\pi ft}$$

# Proactive Sensing: TDMA

$x(t)$



$$y(t) = \alpha\beta x(t - 2\tau) e^{j2\pi ft}$$

- The BS sends the radar and data waves in different time
- Radar wave: Frequency Modulated Continuous Wave (FMCW)
- Only require full duplexing in FMCW transmission – Easy-peasy

