## Actividad 4.1 - Grafo: sus representaciones y recorridos

## **loadGraph**

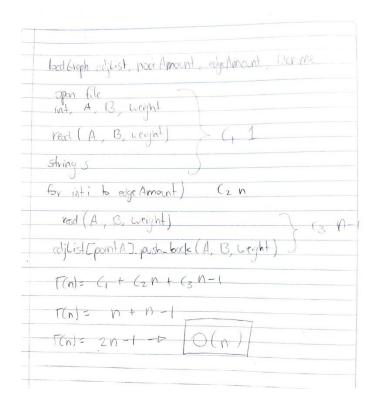
```
void loadGraph(vector<vector<Node<int>>> &adjList, int nodeAmount, int edgeAmount, string filename){
    fstream in(filename);
    int pointA, pointB, edgeWeight;

    // we read input to ignore first line.
    in >> pointA >> pointB >> edgeWeight;

    string s;
    // here we start from one bc we want to ignore the 0 index that is empty, but this will not
    // always be the case.
    for (int i = 0; i < edgeAmount; i++){
        in >> pointA >> pointB >> edgeWeight;

        adjList[pointA].push_back(Node<int>(pointA, pointB, edgeWeight));

        // PREGUNTALE AL PROFE SI ESTO ESTÁ BIEN.
        /* EN TEORÍA ES UN GRAFO NO DIRIGIDO, POR LO QUE LOS NODOS PUEDEN INTERCONECTARSE POR ESO
        LA LÍNEA DEBAJO ES VÁLIDA*/
        //adjList[pointB].push_back(Node<int>(pointB, pointA, edgeWeight));
    }
}
```



```
void BFS(vector<vector<Node<int>>> &adjList, int rootNode){
    queue<int> gray; // processed nodes
   vector<bool> visited;
    int currentNode;
    for (unsigned int i = 0; i < adjList.size(); i++){</pre>
       visited.push_back(false);
    gray.push(adjList[rootNode][0].getOrigin());
    visited[rootNode] = true;
    while(!gray.empty()){
       currentNode = gray.front();
       gray.pop();
       cout << currentNode;</pre>
        for (unsigned int adjNode = 0; adjNode < adjList[currentNode].size(); adjNode++){</pre>
            if (visited[adjList[currentNode][adjNode].getDestination()] == true){
                 visited[adjList[currentNode][adjNode].getDestination()] = true;
             gray.push(adjList[currentNode][adjNode].getDestination());
             cout << " ";
    cout << endl;</pre>
```

Void BFS (cdjList voot Node) for o to adjust sine usited push bock (folse) gray. pish(adjlist[not]bde][0].gelOng.n. Visited[rustulade] = the (3) \* o trave somes coda Cy & Ti while (gray not empty) nodo y vérfice. exoctamente una vez. ccwontrubde = gray, front() 0(n) (5 2+1-1) gloy.pop() print (current usde) for adjutal = 0 to adjuid [auventuble.size()] 6 241-1 if aliped in visited confince visited[odj Node] = true 6, 1 gray. push (a)List Couvert Nade I [a] Nove ] (9) T(n)= (,n+(2+(3+Cy \(\frac{1}{2}+\))+(\(\frac{1}{2}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}{2}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1}+\)]-1+(\(\frac{1} T(n)= O(n) - O(V+E)

```
void DFS(vector<vector<Node<int>>> &adjList, int rootNode){
    timeCounter = 0;
    if (dfsVisited[adjList[rootNode][0].getOrigin()] == true){
    cout << adjList[rootNode][0].getOrigin() << " ";</pre>
    for (unsigned int currentNode = rootNode; currentNode < adjList.size()-1; currentNode++){</pre>
        if (dfsVisited[adjList[currentNode][0].getOrigin()] == false){
            dfsVisited[adjList[rootNode][0].getOrigin()] = true;
            DFSVisit(adjList, adjList[currentNode]);
        dfsVisited[adjList[rootNode][0].getOrigin()] = true;
     for (unsigned int i = 0; i < dfsVisited.size(); i++){</pre>
         if (dfsVisited[i] == false && adjList[i].size() != 0){
             DFS(adjList, i);
```

Void OFS (alifist, rootNode) timeCounter = 0 Visited Codjlist (rastwode ] Cos. get Origins - Cos (11 print Gdj List Crost Node ] [0] gd Origin () for int current Node = root Node to adjust sect j-1 Gn if visited Edjlist Couvert Node Cod get Origin () == 6+5e Visibil Codjlist [rathot ) [o] got appro] = true DFS Visit (odjtist, odjtist Covertuct) visited [ocjlist[notuse][o] getongn() = the for inti= 0 b visited. size if visited[i] = = fotse and adjList[i].size()!= 0 DFS (dijlist, i) \* too code nodo y onsto una vez. T(n) = n-1 1 James