

Vikash Kumar

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Education/ Positions

| | |
|---|----------------------|
| Research Scientist, Google Brain | Feb 2018 - present |
| University of Berkeley, Berkeley Artificial Intelligence Research Lab (BAIR), Post Doc. | Oct 2017 - Jan 2018 |
| Member of technical staff, OpenAI | Apr 2017 - Oct 2017 |
| University of Washington, Ph.D. in Computer Science and Engineering | Feb 2013 - Feb 2017 |
| University of Washington, M.S. in Computer Science and Engineering | Sep 2010 - Feb 2013 |
| Indian Institute of Technology (IIT) Kharagpur, M.S. in Mathematics and Computing | July 2009 - Apr 2010 |
| Indian Institute of Technology (IIT) Kharagpur, B.S. in Mathematics and Computing | July 2005 - Apr 2009 |

Interests

Embodied Artificial Intelligence, Reinforcement Learning, Robotics, Optimal Control

Manuscripts

Under Review:-

- Deep Dynamics Models for Learning Dexterous Manipulations. *Anusha N., Kurt Konolige, Sergey Levine, Vikash Kumar*
- ROBEL: Robotics Benchmarks for Learning. *Michael A., Henry Z., Kristian H., Hugo P., Abhishek G., Sergey L., Vikash Kumar*
- Multi-Agent Manipulation via Locomotion using Hierarchical Sim2Real. *Ofir N., Michael A., Hugo P., Shane G., Vikash Kumar*
- Relay Policy Learning: Solving Long-Horizon Tasks via Imitation and Reinforcement Learning. *Abhishek G., Vikash K., Corey L., Sergey L., Karol Hausman*
- Learning Latent Plans from Play. *Corey Lynch, Mohi K., Ted X., Vikash K., Jonathan T., Sergey L., Pierre Sermanet*
- Time Reversal as Self-Supervision. *Suraj Nair, Mohammad B., Chelsea Finn, Sergey Levine, Vikash Kumar*
- Learning Dexterous Manipulation Policies from Experience and Imitation. *Kumar Vikash, Gupta A, Todorov E, Levine Sergey*
International Journal of Robotics Research (Special issue – Limits and Potentials of Deep Learning in Robotics)

Conference:-

- Dynamics-Aware Unsupervised Discovery of Skills. *Archit Sharma, Shixiang Gu, Sergey Levine, Vikash Kumar, Karol Hausman*
- Dexterous Manipulation with Deep Reinforcement Learning: *Efficient, General, and Low-Cost*. *Henry Zhu*, Abhishek Gupta*, Aravind Rajeswaran, Sergey Levine, Vikash Kuma*. *International Conference on Robotics and Automation (ICRA) 2019*
- Learning Deep Visuo-motor Policies for Dexterous Hand Manipulation. *Divye Jain, Andrew Li, Shivam Singhal, Aravind Rajeswaran, Vikash Kumar, Emanuel Todorov*. *International Conference on Robotics and Automation (ICRA) 2019*
- Learning Complex Dexterous Manipulation with Deep Reinforcement Learning and Demonstrations. *Rajeswaran A, Kumar V, Gupta A, Schulman J, Todorov E and Levine S*. *Robotics Science and Systems (RSS) 2019*
- Divide-and-Conquer Reinforcement Learning. *Ghosh D, Singh A, Rajeswaran A, Kumar V, Levine S*. *International Conference on Learning Representations (ICLR) 2018*
- Variance Reduction for Policy Gradient with Action-Dependent Factorized Baselines. *Wu C., Rajeswaran A., Duan Y., Kumar V, Bayen A, Kakade S, Mordatch I, Abbeel*. *International Conference on Learning Representations (ICLR) 2018*
- Optimal Control with Learned Local Models: Application to Dexterous Manipulation. *Kumar V, Todorov E, Levine S*. **BEST MANIPULATION PAPER AWARD**, *IEEE International Conference on Robotics and Automation (ICRA) 2016*
- MuJoCo Haptix: A virtual reality system for hand manipulation. *Kumar V, Todorov E*. *IEEE-RAS International Conference on Humanoid Robots (Humanoids) 2015*
- Real-time behavior synthesis for dynamic hand-manipulation. *Kumar V, Tassa Y, Erez T, Todorov E*. *IEEE International Conference on Robotics and Automation (ICRA) 2014*
- STAC: Simultaneous Tracking And Calibration. *Wu T, Tassa Y, Kumar V, Movellan J, Todorov E*. *Humanoids 2013*
- An integrated system for real time Model Predictive Control for humanoid robots. *Erez T, Lowrey K, Kumar V, Kolev S, Todorov E*. *Humanoids 2013*
- A low cost and modular, 20 dof anthropomorphic robotic hand: Design, Actuation and Modelling. *Zhe X, Kumar V, Todorov E*. *IEEE-RAS International Conference on Humanoid Robots (Humanoids) 2013*
- Synthesis of Complex Behaviors with Optimal Control. *Todorov E, Tassa Y, Erez T, Mordatch I, Kulchenko P, Kumar V*. *Computational and Systems Neuroscience (COSYNE) 2013*
- Fast, strong and compliant pneumatic actuation for dexterous tendon-driven hands. *Kumar V, Todorov E*. *IEEE International Conference on Robotics and Automation (ICRA) 2013*
- Design of an anthropomorphic robotic finger system with biomimetic artificial joints. *Zhe X, Kumar V, Matsuoka Y, Todorov E*. *IEEE International Conference on Biomedical Robotics and Bio mechatronics (BioRob) 2012*
- Self and Mutual learning in Robotic Arm, based on Cognitive systems. *Kumar V, Patil C, Sachan S*. *(best paper award finalist) International Multi-Conference of Engineers and Computer Scientists 2010*

Workshop :-

- Hand Manipulation Suite: A benchmark for dexterous manipulation. Kumar V, Rajeswaran R, Gupta A, Todorov E, Levine S, Robotics Science and Systems (RSS) 2017
- Physically-Consistent Hand Manipulation Dataset. Kumar V, Todorov E. Workshop on Grasping and Manipulation Datasets. IEEE International Conference on Robotics and Automation (ICRA) 2016

Selected Press Coverage

- [The New York Times](#): Inside Google's Rebooted Robotics Program. Mar 26th 2019
- [Columns](#): Inventing the future: A 'new landmark' for computer science and engineering. Feb 28th 2019
- [The New York Times](#): How robot hands are evolving to do what ours. July 30th 2018
- [New Atlas](#): Bridging the gap between science and fiction. Dec 28, 2016
- [Communications of the ACM](#): Hand Jive: A Robot Hand Learns to Spin. Aug 23, 2016
- [Reuters](#): Robot hand gets a human touch. May 13th 2016
- [Wired](#): This dexterous robot can teach itself to spin a tube of coffee beans. May 10, 2016
- [Business Insider](#): Researchers created a robotic hand that is eerily human-like and can learn on its own. May 29, 2016
- [MIT Tech Review](#): ADROIT featured in TR35. 2016
- [UW360](#): A robotic hand that can move like a human hand, Aug 31 2016
- [ScienceDaily](#): This 5-fingered robot hand learns to get a grip on its own. May 9th 2016
- [Engadget](#): Robot hand learns to twirl objects on its own. May 11th 2016
- [GeekWire](#): UW team creates robotic hand that learns to become more dexterous than yours. May 9th 2016
- [Gizmodo](#): This Robot's Teaching Itself to Twirl a Stick. May 11th 2016
- [UWToday](#): This five-fingered robot hand learns to get a grip on its own. May 9th 2016
- [UW CSE News](#): UW CSE robot hand teaches itself to manipulate objects. May 9th 2016
- [CNN](#): The superhuman robot hand that learns from its mistakes. May 19th 2016
- [Tech Insider](#): Researchers created a robotic hand that is eerily human-like and can learn on its own. May 25th 2016
- [Indian Express](#): Five-fingered robot hand learns to get a grip on its own. May 10th 2016
- [UK's Daily Mirror](#): Incredible five-fingered robotic hand has ability to learn from its own experiences. May 11th 2016
- [Economic Times](#): Five-fingered robot hand learns to get a grip on its own. May 10th 2016
- [ZDNet](#): Five-fingered robot hand has a mind of its own. May 11th 2016
- [Kurzweil](#): This five-fingered robot hand is close to human in functionality. May 10th 2016
- [Most significant bit](#): Adroit: The robot hand for which practice makes perfect. UW-CSE, Summer'16
- [Futurism](#): This five-fingered robot hand is nimbler than your own. May 13th 2016
- [Hackaday](#): Robot cheerleader just needs a hand to learn basic tricks. May 13th 2016
- [Futurism](#): This five-fingered robot hand is nimbler than your own. May 13th 2016
- [Interesting engineering](#): Robotic Hands that Teach Themselves to Move. May 12th 2016
- [Foxnews](#): Cool robot hand learns as it goes. May 10th 2016
- [IEEE Spectrum](#): Next-Gen Prosthetic Limbs in Simulation and Reality. Feb 12th 2015
- [UW CSE News](#): People's choice award. Oct 24th 2013
- [The New York Times](#): A robot with a delicate touch. Sep 18th 2012
- [The Daily](#): UW programmers create software for disaster response robot. Nov 12th 2012

Research Experiences/ Internships

Deep Dynamics models for Dexterous Manipulation

Oct'17-present



Advisor: [Dr. Vincent Vanhoucke, Google Brain](#)

Scale model-based deep reinforcement learning to high-dimensional continuous spaces on physical hardware. Our approach learns to simultaneously rotate two baoding ball in the palm of an five finger anthropomorphic hand within ~2 hours of on-hardware experience.

Extreme Sample Efficiency in Model-Free Deep-RL

Oct'17-present



Advisor: [Dr. Sergey Levine, UC Berkeley](#)

Scale model-free deep reinforcement learning to high-dimensional continuous spaces on physical hardware. Our approach leverages few demonstrations and takes few robot hours to solve complex, contact rich, in-hand manipulation tasks from scratch.

MuJoCo: Advanced Physics Simulation

Jan'12-present



Advisor: [Dr. Emanuel Todorov](#), Roboti, llc.

Significantly contributed towards the development of MuJoCo physics simulation engine and MuJoCo Haptix framework.

OpenAI: Embodied Artificial Intelligence

Apr'17-Sept'17



Advisor: [Elon Musk](#), OpenAI

Directly reported to Mr. Elon Musk. Conceptualized and developed the vision for the robotics team at OpenAI. Designed and developed reinforcement learning amenable infrastructure for the robotics lab. Led efforts for accelerating deep reinforcement learning for high dimensional continuous control problems.

Virtual Embodiment for bootstrapping learning based techniques

Aug'16-Nov'16

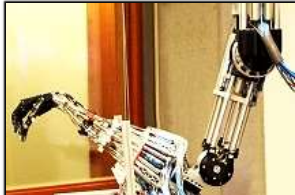


Advisor: [Wojciech Zaremba](#), co-founder, [OpenAI](#)

Developed first person virtual embodiment for FETCH robot. The low latency system is capable of hosting dexterous manipulation, both in simulation and on the physical robot. Further involvements include advisory and strategic mentorship for robotics infrastructure, robust physics simulation and motion planning.

Design, Control, & Behavior Synthesis for ADROIT- A reconfigurable manipulation platform

Mar'12-Dec'16

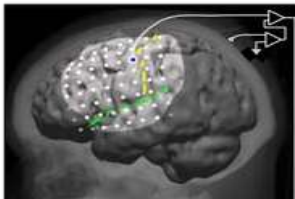


Advisor: [Dr. Emanuel Todorov](#), Applied math & CSE, Univ. of Washington, USA

Design, control, and dexterous manipulation behavior synthesis for a pneumatically-actuated, compliant, anthropomorphic, 28 degree-of-freedom robotic hand capable of performing dexterous object manipulation tasks. Adroit features: joint, touch, tendon length and muscle force sensing capabilities.

Closed-loop optimal control of prosthetic hands

Jan'14-June'15



Advisors: [Dr. Raj Rao](#), Director - CSNE & CSE, Univ. of Washington, USA

[Dr. Emanuel Todorov](#), Applied math & CSE, Univ. of Washington, USA

Closing the loop between the 28-dof-ADROIT-hand and the brain, using ECoG signals, for feedback during hand manipulation. ECoG signals provide high-level feedback in terms of goal selection & corrective maneuvers while an automated controller tries to control the hand.

Gesture based control strategies

Feb'11-May'14

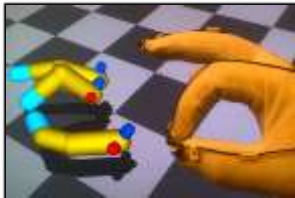


Advisor: [Dr. Emanuel Todorov](#), Applied math & CSE, Univ. of Washington, USA

Exploiting natural gestures such as eye movements, speech etc. for specifying high-level goals for robots (running low-level controller that realizes the specified high-level goals) thus seamlessly bridging the communication gap between a human and a machine.

Modeling & statistical analysis of virtual environment for understanding human finger interactions

April-July'09



Visiting Researcher, CSE, Univ. of Washington, USA

Advisor: [Dr. Emanuel Todorov](#), Applied math & CSE, Univ. of Washington, USA

Studied human finger performing dexterous manipulation experiments analyzing contacts, object interactions and grasping behaviors, addressing issues like contact forces, tactile feedback, 3D depth feedback, obstacle avoidance, optimal trajectories etc.

Optically perfect machining of acrylic surface- Discovery & Automation

April-July'08



Summer intern— [Intelligent Automation Inc. \(IAI\)](#), USA

Advisor: Founder & President Emeritus Leonard S. Haynes, IAI, Washington DC, USA

Identification/discovery of a process to polish glued edges of acrylic boxes to optical clarity and realization of an industrial assembly to automate the identified process.

| Dissertation | |
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| Ph.D. : Manipulators and Manipulation in High Dimensional Spaces | <p>Advisor: Dr. Emanuel Todorov, Applied math & CSE, Univ. of Washington, USA</p> <p>Dr. Sergey Levine, EECS, Univ. of California, Berkeley, USA</p> |
| M.S. : Fuzzy genetic Algorithms(FGA) | <p>Advisor: Prof. Debjani Chakraborty, Dept. of Mathematics, IIT Kharagpur</p> |
| B.S. : New Genetic Algorithm based multi-objective optimization algorithm(NMGA) | <p>Advisor: Prof. Nirupam Chakraborty, Head of Dept. of Metallurgical & Materials Engineering, IIT-Kharagpur</p> |
| Achievements | |
| Honors | <ul style="list-style-type: none"> • Best All Rounder, Indian Institute of Technology IIT-Kharagpur '10 (Ankik Dhar Memorial) • 'Spirit Of Nehru Award', Nehru Hall, IIT Kharagpur '10 • Best All Rounder'09 & Budding Spirit'07, Nehru Hall, IIT Kharagpur |
| Awards | <ul style="list-style-type: none"> • Best Manipulation Paper Award, ICRA'16 • 'Viewer's choice award', Affiliates'13, UW, CSE • Gold, Open hardware, KSHITIJ'09- Asia's largest techno-management Fest • 'Most Industrially feasible', Techkriti'09, IIT Kanpur • Silver, Open hardware, KSHITIJ'08, IIT Kharagpur • Gold, Geobotics, Great Step'08, IIT Kharagpur • Gold in Inter-hall Hardware modeling'07, IIT Kharagpur • Silver in Inter-hall Hardware modeling'08, IIT Kharagpur • Bronze, Robotic Water-polo, KSHITIJ'06, IIT Kharagpur • Gold, Inter-hall Product design'06, IIT Kharagpur • Bronze, Inter-hall ad-design'09, IIT Kharagpur |
| Position of Responsibilities | <ul style="list-style-type: none"> • Vice President, Dept. of Mathematics'08-09, IIT Kharagpur • Chief Editor, AWAAZ – campus monthly newsletter'06-09 • Member of Kharagpur Robotics & Artificial Intelligence Group (KRAIG) |
| Others | <ul style="list-style-type: none"> • Several state/district level awards in Hockey, Volleyball, Fine Arts |
| Scholarships and Grants | |
| <ul style="list-style-type: none"> • NSF Student travel grant, 2014 • Center for Neuroscience Travel Award, Univ. of Washington, 2012, 2014, 2015 • MERIT-CUM-MEANS Scholarship, IIT Kharagpur, 2005, 2006, 2007, 2008, 2009, 2010 • Inter-IIT Sports Scholarship, IIT Kharagpur, 2006-07 | |
| Students Advised | |
| <ul style="list-style-type: none"> • Abhishek Gupta, Ph.D. in EECS under Prof. Sergey Levine and Prof. Pieter Abbeel at UC Berkeley. (Apr'19-Aug'19) • Anusha Nagabandi, Ph.D. in EECS under Prof. Sergey Levine and Prof. Ron Fearing at UC Berkeley. (Sept'18-Aug'19) • Suraj Nair, Ph.D. in CS under Prof. Chelsea Finn and Prof. Silvio Savarese at Stanford University. (June'18-Sept'19) • Visak CV, Master's in Mechanical Engineering, University of Washington (Mar'15-Aug'16) (Pursuing Ph.D. in Georgia Tech under Dr. C. Karen Liu) • Dylan Holmes, Bachelors in Computer Science, University of Washington (Jul'14-Mar'16) • Anselm Nicklas, Visiting student from Department of Electrical and Computer Engineering, Technische Universitat Munich, Germany (Apr'15-Sept'15) • Kaiyu Zheng, , Bachelors in Computer Science, University of Washington (Mar'14-Apr'14) | |