Autoencoders

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What is a autoencoder?

- An autoencoder¹ is a artificial neural network that learns the efficient codings of unlabeled data.
- It works both as a discriminator and a generator.



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Definition

- Discriminator p(y|x) estimates the probability of a label y given an observation x.
- Generator p(x|y) is the probability of observing x for a optional label y.

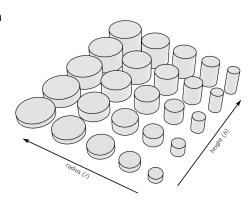
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Generator Framework

- We have a set of observation X.
- We assume that the observation was generated by some unknown distribution P_d .
- Our aim is to generate a model P_m that is as close to P_d as possible.
- We are happy with P_m if
 - The observations sampled from P_m appears to be drawn from P_d .
 - The observations sampled from P_m is considerably different from X.

An example

- Given a set of observations X in a very high dimensional sample space, they can be instead represented in a compact low dimensional space.
- Learning the low dimensional representation is called representation learning.
- The low dimensional representation is called latent space.



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Definition

- The sample space is the set of all observation x can take, i.e, X.
- The probability density function, p(x) is a function that maps a point in the sample space to a number between 0 and 1.
- An encoder Enc(x) takes a high-dimensional input vector and "compresses" the data to a low dimensional output.
- A decoder, *Dec* "decompresses" the data from low dimension to a high dimension.

$$Enc: \mathbb{R}^m \to \mathbb{R}^n, \ Dec: \mathbb{R}^n \to \mathbb{R}^m \qquad m >> n$$
 (1)



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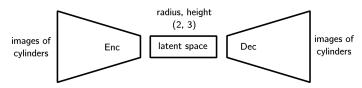
Definition

An autoencoder $AE : \mathbb{R}^n \to \mathbb{R}^n$ is defined as,

$$AE_{\theta}(x) = Dec_{\theta}(Enc_{\theta}(x)) \tag{2}$$

The *Enc* and *Dec* functions are both neural networks in our cases, but it is not necessary that they should be one.

 θ is the weights of the neural networks.



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The AE loss

The loss function is defined as, $\mathcal{L}(x, AE(x))$ is generally uses the RMSE loss, defined as,

$$RMSE(x, AE(x)) = \sqrt{\mathbb{E}[(x - AE(x))^2]}$$
 (3)

and the KL-divergence loss,

$$D_{kl}(P_d, P_m) = \sum_{x \in X} P_d(x) \log \left(\frac{P_d(x)}{P_m(x)} \right)$$
 (4)



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