Algorithmique

Pierre Aboulker, Paul Jeanmaire, Tatiana Starikovskaya 28 septembre 2023

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Première partie

Cours 1 - 28/09

1 Organisation

Mail Tatiana : starikovskaya@di.ens.fr Homeworks are 30% of the final grade, final (theory from lecture) Textbooks :

- Introduction to Algorithms Cormen, Leiserson, Riverst, Stein
- Algorithms on strings, trees, and sequences Gusfield
- Approximation Algorithms Vazirani
- Parametrized Algorithms Cygan, Fomin, Kowalik, Lokshtanov, Marx, Pilipczuk, Pilipczuk, Saurabh

2 Introduction

Algorithm take Inputs and give an output.

Open Problem 1 (Mersenne Prime). Find a new prime of form $2^n - 1$

Algorithms do not depend on the language. Algorithms should be simple, fast to write and efficient. Word RAM model: Two Parts: one with a constant number of registers of w bits with direct access, and one with any number of registers, only with indirect access (pointers). Allows for elementary operations: basic arithmetic and bitwise operations on registers, conditionals, goto, copying registers, halt and malloc. To index the memory storing input of size n with n words, we need register length to verify $w \ge \log n$ Algorithms can always be rewritten using only elementary operations. Complexity:

- Space(n) is the maximum number of memory words used for input of size n
- Time(n) is the maximum number of elementary operations used for input of size n

Complexity Notations:

- $-f \in \mathcal{O}(g) \text{ if } \exists n_0 \in \mathbb{N}, c \in \mathbb{R}_+, \ f(n) \le c \cdot g(n), \ \forall n \ge n_0$
- $-f \in \Omega(g) \text{ if } \exists n_0 \in \mathbb{N}, c \in \mathbb{R}_+, f(n) \geq c \cdot g(n), \forall n \geq n_0$
- $-f \in \Theta(g) \text{ if } \exists n_0 \in \mathbb{N}, c_1, c_2 \in \mathbb{R}_+, c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n), \forall n \geq n_0$

3 Data Structures

3.1 Introduction

Way to store elements of a data base that is created to answer frequently asked queries using pre-processing. We care about space used, construction, query and update time. Can be viewed as an algorithm, which analysed on basics. Containers are basic Data Structures, maintaining the following operations:

- 1. Random Access: given i, access e_i
- 2. Access first/last element
- 3. Insert an element anywher
- 4. Delete any element

3.2 Array

An array is a pre-allocated contiguous memory area of a *fixed* size. It has random access in $\mathcal{O}(1)$, but doesn't allow insertion nor deletion.

Linear Search: given an integer x return 1 if $e_i = x$ else 0.

```
Algorithme 1 Linear Search in an Array. Complexity: Time = \mathcal{O}(n) | Space = \mathcal{O}(n)
```

Input x

3.3 Doubly Linked List

Memory area that does not have to be contiguous and consists of registers containing a value and two pointers to the previous and next elements. It has random access in $\mathcal{O}(n)$, access/insertion/deletion at head/tail in $\mathcal{O}(1)$.

3.4 Stack and Queue

Stack : Last-In-First-Out data structure, abstract data structure. Access/insertion/deletion to top in $\mathcal{O}(1)$.

Open Problem 2 (Optimum Stack Generation). Given a finite alphabet Σ and $X \in \Sigma^n$. Find a shortest sequence of stack operations push, pop, emit that prints out X. You must start and finish with an empty stack. Current best solution is in $\tilde{\mathcal{O}}(n^{2.8603})$.

Queue : First-In-First-Out abstract data structure. Access to front, back in $\mathcal{O}(1)$, deletion and insertion at front and back in $\mathcal{O}(1)$.

Algorithme 2 Insertion in a Doubly Linked List

```
\frac{\text{Complexity}: \mathcal{O}(1)}{7}
```

```
\begin{aligned} \mathbf{Input}L, x \\ x.next \leftarrow L.head \\ \mathbf{if} \ L.head \neq NIL \ \mathbf{then} \\ L.head.prev \leftarrow x \\ \mathbf{end} \ \mathbf{if} \\ L.head \leftarrow x \\ x.prev = Nil \end{aligned}
```

4 Approaches to algorithm design

Solve smalle sub-problems to solve a large one.

4.1 Dynamic Programming

Break the problem into many closely related sub-problems, memorize the result of the sub-problems to avoid repeated computation

Examples:

Algorithme 3 Recursive Fibonacci Numbers

Complexity: Exponential

```
egin{aligned} &\operatorname{RFibo}(n): \\ &\operatorname{Input} n \\ &\operatorname{if}\ n \leq 1 \ \operatorname{then} \\ &\operatorname{return}\ n \\ &\operatorname{end}\ \operatorname{if} \\ &\operatorname{return}\ \operatorname{RFibo}(n-1) + \operatorname{RFibo}(n-2) \end{aligned}
```

Algorithme 4 Dynamic Programming Fibonacci Numbers

```
Time = \mathcal{O}(n) | Space = \mathcal{O}(n)
```

```
 \begin{array}{l} \textbf{Input} n \\ Tab \leftarrow zeros(n) \\ Tab[0] \leftarrow 0 \\ Tab[1] \leftarrow 1 \\ \textbf{for } i \leftarrow 2 \text{ to } n \textbf{ do} \\ Tab[i] = Tab[i-1] + Tab[i-2] \\ \textbf{end for} \\ \textbf{return Tab}[n] \\ \end{array}
```

Levenshtein Distance between two strings can be computed in $\mathcal{O}(mn)$ instead of exponential time. Based on https://arxiv.org/pdf/1412.0348.pdf, this is the best one can do. RNA folding: retrieving the 3D shape of RNA based on their representation as strings. Currently, we know it is possible to find $\mathcal{O}(n^3)$, in $\tilde{\mathcal{O}}(n^{2.8606})$ and if SETH is true, there is no $\mathcal{O}(n^{\omega-\varepsilon})$. We know $\omega \in [2, 2.3703)$

Open Problem 3. Is there a better Complexity for RNA folding? What is the true value of ω ?

Knapsack problem: An optimization problem with bruteforce complexity $\mathcal{O}(2^n)$.

4.2 Greedy Techniques

Problems solvable with the greedy technique form a subset of those solvable with DP. Problems must have the optimal substructure property. Principle: choosing the best at the moment.

```
Algorithme 5 Knapsack: Dynamic Programming
Time = \mathcal{O}(nW) | Space = \mathcal{O}(nW)
  Input W, w, v
                                                                       ▷ Capacity, weight and values vectors.
  KP = zeros(n, W)
  for i \leftarrow 0 to n do
      KP[i,0] = 0
  end for
  for w \leftarrow 0 to W do
      KP[0, w] = 0
  end for
  for i \leftarrow 0 to n do
      for w \leftarrow 0 to W do
           if w < w_i then
               KP[i, w] \leftarrow KP[i-1, w]
              KP[i, w] = \max \left\{ \begin{array}{c} KP[i-1, w] \\ KP[i-1, w-w_i] + v_i \end{array} \right.
      end for
  end for
  return KP[n, W]
```

Example: The Fractional Knapsack Problem

Algorithm: Iteratively select the greatest value-per-weight ratio.

Théorème 4.2.1. This algorithm returns the best solution, in time $\mathcal{O}(n \log n)$

By contradiction. Suppose we have $\frac{v_1}{w_1} \ge \ldots \ge \frac{v_n}{w_n}$. Let $ALG = p = (p_1, \ldots, p_n)$ be the output by the algorithm and $OPT = q = (q_1, \ldots, q_n)$ be optimal.

Assume that $OPT \neq ALG$, let i be the smallesst index such $p_i \neq q_i$. There is $p_i > q_i$ by construct. Thus, there exists j > i such that $p_j < q_j$. We set $q' = (q_1, \ldots, q_n') = (q_1, \ldots, q_{i-1}, q_i + \varepsilon, q_{i+1}, \ldots, q_j - \varepsilon \frac{w_i}{w_j}, \ldots, q_n)$

$$q'$$
 is a feasible solution : $\sum_{i=1}^{n} q'_i \cdot w_i = \sum_{i=1}^{n} q_i w_i \leq W$

Yet,
$$\sum_{i=1}^{n} q_i^{'} \cdot v_i > \sum_{i=1}^{n} q_i \cdot v_i$$
, ce qui contredit la

Deuxième partie

Devoir 1