Homework Assignment 1

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13 octobre 2023

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1 Exercise 1 - [Edit Distance/Levenshtein Distance]

1.1 Question 1

Proposition 1.1.1 (Complexity and Correction). If we denote C_f the complexity of f, this algorithm has time complexity $\mathcal{O}\left(C_f\left(\frac{n}{t}\right)^2\right)$. This algorithm is correct.

Démonstration. — Moreover, it is clear this algorithm is correct as it only just applies the dynamic programming algorithm for the Levenshtein distance by steps.

This algorithm complexity comes from the fact it has two while loops for which the commands are executed at most n/t times. The commands in both while loops are executed in $\mathcal{O}\left(C_f\right)$. The for loops inside the left while loop are equivalent to loops for i between left and left t-1 and thus are disjoint. The sum of their complexity over the left while loop is then n. The number of operations inside the up while loop is then in $\mathcal{O}\left(C_f\frac{n}{t}\right)$ and thus the total complexity is, as announced, in $\mathcal{O}\left(C_f\left(\frac{n}{t}\right)^2\right)$

1.2 Question 2

that $\mathbf{D}[i][j]$ is at most 1 plus one of its left neighbour, upper neighbour or upper left corner neighbour.

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Algorithme 1 Question 1 - Levenshtein Distance with f
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Input S, T, f, t
                                                             \triangleright Two Strings, the function f computing the values and the step t
                                                                                                                                                           \triangleright len(S) = len(T) = n
\mathbf{D} = \operatorname{zeros}(n+1, n+1)
for i \leftarrow 0 to n+1 do
       \mathbf{D}[i][0] \leftarrow i
end for
for j \leftarrow 0 to n+1 do
       \mathbf{D}[0][j] \leftarrow j
end for
up, left \leftarrow 0, 0
while up < n \, do
       left \leftarrow 0
       while left < n \, do
               down \leftarrow \min(n - \operatorname{up}, t)
              right \leftarrow \min(n - \text{left}, t)
              b \leftarrow \mathbf{D}[\text{up}][\text{left}]
               a \leftarrow \mathbf{D}[\text{up} + 1 \rightarrow \text{up} + 1 + down][\text{left}]
               c \leftarrow \mathbf{D}[\text{up}][\text{left} + 1 \rightarrow \text{left} + 1 + right]
              f(a, b, c, d, e)
                                                       \triangleright We can suppose here that f modifies only the last line and column
                                                             of F in \mathbf D with side-effect.
              \mathsf{left} \leftarrow \mathsf{left} + right
              for i \leftarrow 1 to down - 1 do
                    \mathbf{D}[\text{up}+i][\text{left}] \leftarrow \min \left\{ \begin{array}{l} \mathbf{D}[\text{up}+i][\text{left}-1]+1 \\ \mathbf{D}[\text{up}+i-1][\text{left}]+1 \\ \mathbf{D}[\text{up}+i-1][\text{left}-1]+\mathbbm{1}_{\{S[\text{up}+i]=T[\text{left}]\}} \\ \geqslant \text{We update the first Column of the block we consider.} \end{array} \right.
               end for
       end while
       up \leftarrow up + d
              \begin{array}{l} \leftarrow \text{up} + u \\ : i \leftarrow 1 \text{ to } n \text{ do} \\ \\ \mathbf{D}[\text{up}][i] \leftarrow \min \left\{ \begin{array}{l} \mathbf{D}[\text{up}][i-1] + 1 \\ \\ \mathbf{D}[\text{up}-1][+i] + 1 \\ \\ \mathbf{D}[\text{up}-1][i-1] + \mathbbm{1}_{\{S[up+i] = T[left]\}} \\ \\ \triangleright \text{ We update the first line of the blocks we will consider.} \end{array} \right. 
       for i \leftarrow 1 to n do
       end for
end while
return \mathbf{D}[n][n]
```

1.3 Question 3

By recurrence formula, if we substract from all the values in A, B, C a certain integer k, then we get for the new matrix F, the one we would have gotten with A, B, C with k substracted to all values. Thus, if the values in A, A', B, B' and C, C' all differ from a common integer, the resulting values after applying f will differ from this same value. Thus, F' = F + (A' - A) and A' - A is a matrix with all values equal.

1.4 Question 4

We will show here that we can pre-compute all $t \times t$ matrices in $\mathcal{O}(3^{2t}\sigma^{2t}t^2)$.

First, as $\mathbf{D}[i][j]$ here is the minimal number of elementary operations to go from string S[0:i] to string T[0:j]. We can thus interpret the submatrix of \mathbf{D} between (i,j) and (i+t,j+t) as the dynamic programming matrix for minimum number of operations to go from string S[i:i+t+1] to string T[j:j+t+1] to which we added a first line and a first column.

We thus see that those matrices can be fully determined by their first line, first column and by two words.

As the values in **D** are bounded by 0 and 2n (we can always remove all letters in S and add all letters in T), and by question 2., as values along a line or a column differ by an integer in -1, 0, 1, the number of first lines and columns is $\mathcal{O}(n3^{2t})$. However, from question 3., if we allow negative values for f (which we have no reason not to do), we can always substract from the first line and column the value in the top left corner, and re-add it in $\mathcal{O}(t^2)$ after pre-processing.

Moreover, there are σ^t words of length t over the alphabet so the number of submatrices is $\mathcal{O}(3^{2t}\sigma^{2t})$.

We can then use the recurrence equation to derive the values on the submatrix in $\mathcal{O}(t^2)$. Finally, we can pre-compute all $t \times t$ submatrices in $\mathcal{O}(3^{2t}\sigma^{2t}t^2)$.

Then, to access the values of the submatrix from (up, left) to (up+t, left+t), we need to identify the preprocessed corresponding matrix and thus we need to go through S[up:up+t], T[left:left+t], the first column and row of this submatrix to which we substracted the upper left value, which all are done in $\mathcal{O}(t)$.

1.5 Question 5

From Question 4, we have got an algorithm that allows us to compute the result in $\mathcal{O}(3^{2t}\sigma^{2t}t^2 + \left(\frac{n^2}{t}\right))$. Indeed, after pre computing, we only need to check in $\mathcal{O}(1)$ the $\mathcal{O}\left(\left(\frac{n}{t}\right)^2\right)$ $t \times t$ submatrices in \mathbf{D} . Thus, if we take $t = \log_{(3\sigma)}(\sqrt{n})$, we have complexity in $\mathcal{O}\left((3\sigma)^{\log_{3\sigma}(n)}\log_{3\sigma}(\sqrt{n}) + \left(\frac{n^2}{\log_{3\sigma}(\sqrt{n})}\right)\right)$. As $\log_{3\sigma}(\sqrt{n}) = \Theta(\log(n))$ and $(3\sigma)^{\log_{3\sigma}(n)}\log_{3\sigma}(\sqrt{n}) = \mathcal{O}(n\log(n)^2) = o(\frac{n^2}{\log(n)})$, this algorithm has complexity in $\mathcal{O}\left(\frac{n^2}{\log n}\right)$

2 Exercice 2

In this exercise, we will denote by $\lg(n)$ the log in base 2 of n

2.1 Question 1

We will try to precompute arrays containing part of the answer by dividing the bitvector B into multiple blocks, of smaller and smaller size. We will use two intermediate arrays of size $\mathcal{O}\left(\frac{n}{\lg(n)}\right) = o(n)$ bits and a final array (meaning lowest level array) of size $\mathcal{O}(n)$.

We build a first array A_0 which will contain blocks of size $s_0 = \lg^2(n)$ (we will justify this value later). The blocks of this array contain the rank of the first position in B that is compacted in the block, i.e., $A[i] = \operatorname{rank}_1(i \times s_0)$ where rank designates the rank operation in B. As each entry in A takes at most $\lg(n)$ bits to store, A takes $\mathcal{O}\left(\frac{n}{\lg^2(n)}\lg(n)\right) = \mathcal{O}\left(\frac{n}{\lg(n)}\right) = o(n)$ bits to store, thus justifying the value chosen for s_0 .

Then we build a second array A_1 which will store the ranks of smaller blocks of size $s_1 = \lg(n)/2$ (as for s_0 , we will justify this value later). Here, the items in the array only need at most $\lg\left(\lg^2(n)\right)$ bits to be stored. This table thus takes $\mathcal{O}\left(\frac{n}{s_1}\lg\left(\lg^2(n)\right)\right) = \mathcal{O}\left(4n\frac{(\lg\lg(n))}{\lg(n)}\right) = o(n)$ bits to store, the equality coming from the properties of \lg , thus explaining the general form of s_1 as $\lg*c$ but not yet why c=1/2

To finally answer the query, we need to maintain a third array A_2 which will contain correspondances between every possible $\operatorname{rank}_1(i)$ query on a bitvector of length s_1 with $i < s_1$ and their answers. There are 2^{s_1} such bitvectors, and storing all answers on each can be done in $\mathcal{O}(s_1 \lg(s_1))$. A_2 thus needs $\mathcal{O}(2^{s_1} \lg(s_1)s_1) = \mathcal{O}(\sqrt{n} \lg(n) \lg(\lg(n))) \leq n$, as $\lg(n)/2 = \lg(\sqrt{n})$ and from the properties of \lg , thus explaining the coefficient of \lg in s_1 .

Using these arrays we can compute $\operatorname{\mathsf{rank}}_1(i)$ in $\mathcal{O}(1)$ time by searching in blocks i/s_0 , $(i \mod s_0)/s_1$ and $(i \mod s_0) \mod s_1$ in A_0, A_1 and A_2 , and as : $\operatorname{\mathsf{rank}}_0(i) = i - \operatorname{\mathsf{rank}}_1(i)$, we obtain the wanted time complexity. The total number of bits used by these arrays is at most n + o(n) so we have the wanted space complexity, and this solution is one.

2.2 Question 2

The solution proposed before can lead to a $\mathcal{O}(\lg(n))$ time complexity, so it is not sufficient to answer the select queries. We will thus refine the latter to get a new structure, by using three levels of intermediate arrays using o(n) bits and two final arrays using $\mathcal{O}(n)$ bits.

We define our first array C_0 which records the positions of the $\lg^2(n)$ -th (again, this value will be explained later) 1 bits. Storing a value in this array costs at most $\lg(n)$ bits and there are at most $\frac{n}{\lg^2(n)}$ values stored in the array. So it only uses: $\frac{n}{\lg(n)}$ bits.

Then, we will repeat the operation. Let s_1 be the size of a block in our first array. We want to use at most $\frac{s_1}{\lg(n)} \leq \lg(n)$ bits on this block in our second array C_1 . We can calculate s_1 on the fly in $\mathcal{O}(1)$ during calculation, and using this, we can deduce the location in B of this block. However, there are $\lg^2(n)$ answers in that range, and it so requires $\lg(n)^3$ bits to store. Then, if we have $s_1 \geq \lg(n)^4$, we would have sufficient space to store the values in o(n) bits, but, in the other case, we need to redivide the block in the same way.

We denote by s_2 the size of the considered block in C_1 . We would need $\lg(s_2)\lg(s_1)\lg(n)$ bits to store all the answers. We obtain a similar inequality on s_2 as on s_1 before, by the same methods. If we have $s_2 \ge \lg(s_2)\lg(s_1)\lg(n)$ then we have sufficient space not to need to go further in the

construction and keep o(n) space. Else, we have :

$$s_2 < \lg(s_2)\lg(s_1)\lg(n)$$

$$s_1 < (\lg(n))^4$$

So we have : $\lg(s_1) < 4(\lg(\lg(n)))$. Then, by growing of \lg and as $s_2 < s_1$ we get : $\lg(s_1) < 4\lg(\lg(n))$ and thus :

$$s_2 < 16\lg(n)\lg^2(\lg(n))$$

.

Using the same idea as in question 1., we answer select queries using final arrays, storing the values we need. Indeed, for each of the 2^{s_3} bit pattern of length $s_3 = \frac{\lg(n)}{2}$, we can record the position of the *i*-th 1 bit in the pattern in an array C_3 , and store the number of 1 in the pattern in an array C_4 . Then to compute the value of select₁(*i*) we can scan the range using C_4 to know which subrange contains the answer and use C_3 to get the answer, all in time $\mathcal{O}(1)$.

Finally, $\mathsf{select}_1(i)$ can be computed by finding the block in C_0 in which i is. From here, we compute s_1 and then, based on the case disjunction detailed earlier, we either get the correct answer from C_1 or compute s_2 and start over, using the final arrays. Thus, this data structure supports select queries in $\mathcal{O}(1)$ time. For storing the auxiliary directories C_0 , C_1 and C_2 , we need at most $\frac{3n}{\lg(n)}$ bits (the simplicity of this expression justifies the values chosen for s_1 and s_2), and for the final arrays we use $\sqrt{n} \left(\lg(n) + \frac{1}{2} \lg(n) \lg(n) \right)$, by the same calculation as in question 1, thus justifying the choice for the size of the patterns in C_4 . The extra storage is in $\mathcal{O}(n)$, and this data structure is compatible with our requirements.

2.3 Question 3

Here, we model our set S of items as a bitvector B of length $n = \max S$ with coefficients:

$$B[i] = 1$$
 if $i \in S$ else 0

Then, solving, the predecessor problem can be done using the data structures introduced in questions 1 and 2. Indeed, finding the predecessor of j in S can be done by calling $\operatorname{rank}_1(j)$, getting the number of elements smaller than j in S, then calling select_1 on the resulting value, giving us the greatest element in S that is smaller than j.

2.4 Question 4

We first proceed by induction to prove that the depth of the tree is in $\mathcal{O}(\log_2(n))$

- Initialization: For all c > 0, the depth of the tree is $0 \le c \log_2(1) = 0$.
- Heredity: Let P be a set of points of size n. We let P_0 and P_1 as in the definition. We have $|P_0| + |P_1| = |P| = n$. Let $a = |P_0|$. If a = n or a = 0, there is nothing to inspect, since we can directly reduce the size of the rectangle we are studying. Else, by induction hypothesis, since both P_0 , P_1 have size at most n 1, the left subtree has depth at most $c \log_2(a)$ and the right subtree has depth at most $c \log_2(n a)$. Thus, we get the depth of the full tree to be: $c \max(\log_2(a), \log_2(n a)) + 1 \le c \log_2(n)$ if $c \ge 1$ by concavity of logarithm.

Thus, by induction, the depth of a wavelet tree is in $\mathcal{O}(\log_2(n))$.

Then, since we store in each depth bitvectors whose sum of lengths in n, along with the data structures from questions 1 and 2.

We so use
$$\mathcal{O}(\log_2(n) \times (n + o(n) + \mathcal{O}(n))) = \mathcal{O}(n \log_2(n))$$

2.5 Question 5

The points in $\{(x,y) \in P_0 : x_1 \le x \le x_2\}$ are the points which are in position $i \in [x_1, x_2]$ in B with B[i] = 1. Thus we get that this interval corresponds in B_0 to the interval

$$[rank_0(x_1-1)+1, rank_0(x_2)]$$

The same goes with P_1 by replacing the queries by their opposite value element. Note that this is done in $\mathcal{O}(1)$ from the first questions.

2.6 Question 6

We construct a wavelet tree over [1, n] using the method defined earlier. Then we use the following to answer the query.

Algorithme 2 Orthogonal Range Query

```
\begin{array}{l} \textbf{Input } B, x_1, x_2, y_1, y_2, m, M \\ \textbf{if } [m, M] \cap [x_1, x_2] = \varnothing \textbf{ then} \\ \textbf{return } 0 \\ \textbf{end if} \\ \textbf{if } [m, M] \subseteq [x_1, x_2] \textbf{ then} \\ \textbf{return } x_2 - x_1 + 1 \\ \textbf{end if} \\ \\ tmp \leftarrow \left\lfloor \frac{m+M}{2} \right\rfloor \\ [x_1, 0, x_2, 0] \leftarrow [\mathsf{rank}_0(B, x_1 - 1) + 1, \mathsf{rank}_0(B, x_2)] \\ [x_1, 1, x_2, 1] \leftarrow [\mathsf{rank}_1(B, x_1 - 1) + 1, \mathsf{rank}_1(B, x_2)] \\ \textbf{return } \mathsf{ORQ}(B_0, [x_{1,0}, x_{2,0}], [y_1, y_2], [m, tmp]) + \mathsf{ORQ}(B_1, [x_{1,1}, x_{2,1}], [y_1, y_2], [tmp, M]) \\ \textbf{end function} \\ \mathsf{ORQ}(B, x_1, x_2, y_1, y_2, m, M) \end{array}
```

Théorème 2.6.1. This algorithm is correct and has complexity in $\mathcal{O}(\log_2(n))$

Démonstration. — The algorithm finds the maximum range of points that covers $[y_1, y_2]$. The answer is the points in it with first coordinate in $[x_1, x_2]$. From question 5., we are tracking accordingly those points as we go down the tree and thus the algorithm is correct.

— Everytime we go down in depth in the tree, we update the intervals to check in the children of the node considered. When arriving at a node sufficiently small, the answer is given, thus, this algorithm has complexity in $\mathcal{O}(\log_2(n))$

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