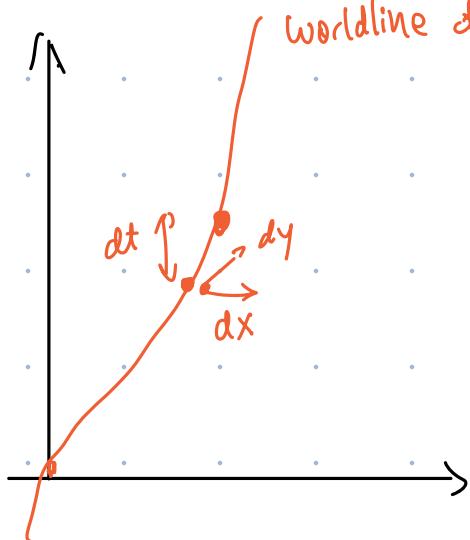


Relativistic Newton's Laws.

invariant: same in every coordinate system.
conserved: does not evolve in time -



worldline of particle.

proper time:

$$d\zeta = \sqrt{dt^2 - d\vec{r}^2}$$

$$\zeta = \int d\zeta$$

$$= \int \sqrt{dt^2 - d\vec{r}^2}$$

$$= \int dt \sqrt{1 - \left(\frac{d\vec{r}}{dt}\right)^2}$$

$$= \int dt \sqrt{1 - \vec{\omega}^2}$$

the particle's velocity as seen in its own frame.

proper velocity:

$$\vec{u} \equiv \frac{d\vec{r}}{d\zeta}, \quad \vec{\omega} \equiv \frac{d\vec{r}}{dt}.$$

In the object's frame:

$$\vec{\omega} = 0, \quad \zeta = t$$

$$\vec{u}^0 = \frac{dt}{d\zeta} = \cancel{\frac{1}{\sqrt{1-\vec{\omega}^2}}} \quad \vec{u} = \frac{d\vec{r}}{d\zeta} =$$

Zeroth component

$$\frac{d\vec{r}}{dt} = \frac{d\vec{r}}{d\zeta} = \frac{\vec{u}}{\sqrt{1-\vec{\omega}^2}}$$

$$= \gamma \vec{\omega}.$$

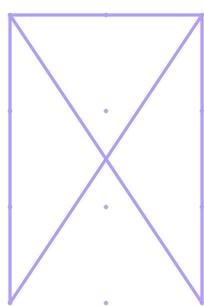
$$E = \frac{m}{\sqrt{1-\vec{\omega}^2}}$$



$$E = mu^0$$

$$\vec{P} = m\vec{u}$$

$$\vec{P} = \frac{m\vec{\omega}}{\sqrt{1-\vec{\omega}^2}}$$



Transformation:

$$\begin{cases} u^0 = \gamma(u^0 - vu_x) \\ u_x' = \gamma(u_x - vu^0) \\ u_y = u_y \\ u_z' = u_z \end{cases}$$

Since $d\tau$ invariant
 u^0 transforms like $d\tau$
 \vec{u} transforms like $d\vec{r}$

Similarly

$$\begin{cases} E' = \gamma(E - vp_x) \\ p_x' = \gamma(p_x - vE) \\ p_y' = p_y \\ p_z' = p_z \end{cases}$$

or

$$\begin{cases} E = \gamma(E' + vp_x') \\ p_x = \gamma(p_x' + vE') \\ p_y = p_y' \\ p_z = p_z' \end{cases}$$

Newton's Laws

$$P_{N.R} = m \vec{w}$$

$$F_{N.R} = \frac{dP_{N.R.}}{dt}; \quad \frac{dE}{dt} = \vec{F} \cdot \vec{w}$$

$$F = \frac{d\vec{P}}{dt}$$

(relativistic free) or $f = \frac{d\vec{p}}{dt}$
(4-force)

$$\begin{cases} t = \gamma(t' + vx') \\ x = \gamma(x' + vt') \end{cases} \quad x^2 - t^2 \text{ invar.}$$

$$E^2 - \vec{p}^2 = E'^2 - \vec{p}'^2 = m^2 \left(\frac{1}{1-\vec{\omega}^2} - \frac{\vec{\omega}^2}{1-\vec{\omega}^2} \right) = m^2$$

$$m(u^0)^2 - m(\vec{u})^2 = m^2$$

$$(u^0)^2 - (\vec{u})^2 = 1$$

Finding the relativistic force

$$F_x^1 = \frac{dP_x^1}{dt^1} = \frac{d(\gamma p_x - vE)}{dt^1} = \frac{d(\gamma p_x - vE)}{\frac{dt^1}{dt}}$$

$$\begin{aligned} dt^1 &= \gamma(dt - v\vec{r}) \\ \frac{dt^1}{dt} &= \gamma \left[\left(\frac{dp_x}{dt} \right) - v \frac{dE}{dt} \right] = \frac{F_x - v \frac{dE}{dt}}{1 - vw_x} \end{aligned}$$

$$\vec{E}^2 - \vec{p}^2 = m^2$$

$$2E \frac{d\vec{E}}{dt} - 2\vec{p} \frac{d\vec{p}}{dt} = 0$$

$$E \frac{d\vec{F}}{dt} - \vec{p} \frac{d\vec{p}}{dt} = 0$$

$$\vec{F} \frac{dE}{dt} = \vec{p} \frac{d\vec{p}}{dt}$$

$$\frac{dE}{dt} = \vec{p} \cdot \vec{F}_x$$

$$\frac{dF_x}{dt} = \gamma F_x$$

$$F_x' = \frac{F_x - v\omega}{1 - v\omega_x} \vec{F}$$

$$F_y' = \frac{dP_y'}{dt'} = \frac{\frac{d\vec{p}}{dt}}{\frac{dt'}{dt}} = \frac{F_y}{\gamma(1-v\omega_x)}$$

$$F_z' = \frac{F_z}{\gamma(1-v\omega_x)}$$

$$\begin{aligned} \vec{p}' &= \frac{\vec{p}}{\sqrt{1-\omega^2}} \\ &= \frac{m\vec{v}}{\sqrt{1-\omega^2}} \end{aligned}$$

$$\tau_{\text{in}} = \gamma \tau$$

Understanding what that is by setting

$\omega \rightarrow 0$,

$$\vec{F}_x^1 = \frac{\vec{F}_x - v \vec{r} \vec{\omega}}{r - v w_x} \xrightarrow{\downarrow} \boxed{\vec{\omega} = 0}$$

$$\left\{ \begin{array}{l} \vec{F}_x = F_{NR1x} \\ F_y = \frac{F_{NR1y}}{r} \\ F_z = \frac{F_{NR1z}}{r} \end{array} \right.$$

$$f = \gamma \vec{F}$$

$$f^\circ = M \frac{du^\circ}{dz}$$

$$f = M \frac{d\vec{u}}{dz}$$

$$(u^\circ)^2 - (\vec{u})^2 = 1$$

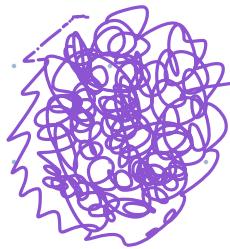
$$2u^\circ \frac{du^\circ}{dz} - 2\vec{u} \frac{d\vec{u}}{dz} = 0$$

$$u^\circ f^\circ - \vec{u} \vec{f} = 0$$

they are orthogonal.

$$w_x^I = \frac{w_x + v}{1 + v w_x}$$

$$u_x^I = \gamma (u_x - \cancel{v} u^0)$$



$$\vec{j} \equiv p \cdot \vec{w}$$

\xrightarrow{v} $\text{sen: } p \uparrow \therefore \# \text{ particles are const.}$

(with no interaction

\hookrightarrow space shrinks

$$p = \frac{p^0}{\sqrt{1 - \vec{w}^2}}$$

$$p \cdot \vec{w} : \vec{j} \equiv \frac{p^0 w}{\sqrt{1 - \vec{w}^2}}$$

$$\rho = \rho_0 h^{\alpha}$$

$$\vec{\rho} = \rho_0 \vec{h}$$