## Al Experimental Course

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#### Overview

- Search
  - Uninformed Search
  - Informed (Heuristic) Search
  - Adversarial Search
  - Constraint Satisfaction Problems (CSPs)
  - Typical Problems
- 2 Prolog
  - Typical Problems
- FF Planning System
  - Typical Problems
- Machine Learning
  - Typical Algorithms





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### Uninformed Search

- DFS
- BFS
- Uniform-cost search
- Depth-limited search
- Iterative-Deepening search

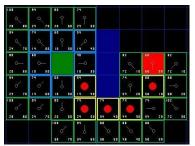
```
function ITERATIVE-DEEPENING-SEARCH(problem) returns a solution, or failure for depth = 0 to \infty do result \leftarrow DEPTH-LIMITED-SEARCH(problem, depth) if result \neq cutoff then return result
```

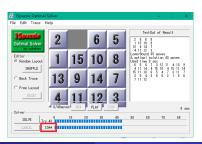
Bidirectional search



## Informed (Heuristic) Search

- Greedy best-first search
- A\* (https://www.redblobgames.com/pathfinding/ a-star/introduction.html)
  - $\Box$  f(n) = g(n) + h(n)
  - $\Box$  f(n) is the estimated cost of the cheapest solution through n
  - $\square$  g(n) is the path cost from the start node to node n
  - h(n) is the estimated cost of the cheapest path from n to the goal
- Iterative-deepening A\* (IDA\*)









### Adversarial Search

- The minimax algorithm
- $\alpha \beta$  pruning

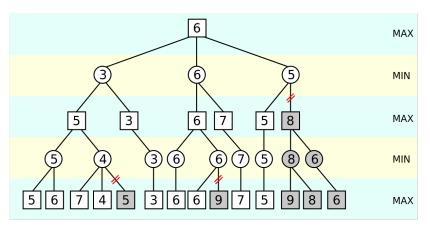


Figure 1:  $\alpha - \beta$  pruning



## Constraint Satisfaction Problems (CSPs)

- Backtracking Search for CSPs
- Forward Checking (FC)
- Generalized Arc Consistency (GAC)



# Typical Problems

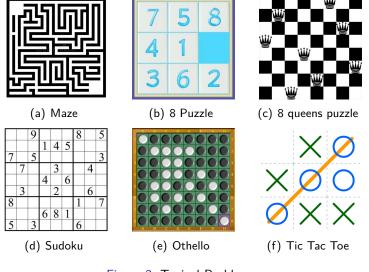


Figure 2: Typical Problems

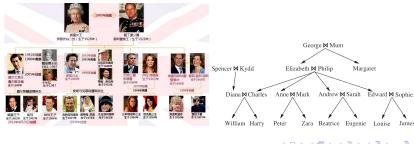


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## Typical Problems

- Search Problems
- KR (e.g. Family Problem)
- Queries on KB (Similar to SQL)
- CSPs
  - Sudoku Problem
  - Eight Queens Problem
  - Other Games





## **Examples**

## Example 1 (Family Problem)

```
\begin{split} & grandChild(A,B):\text{-child}(A,C),\text{child}(C,B).\\ & aunt(A,B):\text{-child}(B,C),\text{sister}(A,C).\\ & \dots\\ & male('George').\\ & child('Elizabeth','George').\\ & \dots\\ & \dots \end{split}
```

## Example 2 (Tower of Hanoi)

```
\begin{split} &\mathsf{hanoi}(\mathsf{N})\mathsf{:-move}(\mathsf{N},\mathsf{a},\mathsf{b},\mathsf{c}).\\ &\mathsf{move}(\mathsf{1},\mathsf{A},_{-},\mathsf{C})\mathsf{:-inform}(\mathsf{A},\mathsf{C}).\\ &\mathsf{move}(\mathsf{N},\mathsf{A},\mathsf{B},\mathsf{C})\mathsf{:-N1} \ \mathsf{is}\\ &\mathsf{N-1},\mathsf{move}(\mathsf{N1},\mathsf{A},\mathsf{C},\mathsf{B}),\mathsf{inform}(\mathsf{A},\mathsf{C}),\mathsf{move}(\mathsf{N1},\mathsf{B},\mathsf{A},\mathsf{C}).\\ &\mathsf{inform}(\mathsf{Loc1},\mathsf{Loc2})\mathsf{:-nl},\mathsf{write}(\mathsf{'from '}),\mathsf{write}(\mathsf{Loc1}),\mathsf{write}(\mathsf{' to '}),\mathsf{write}(\mathsf{Loc2}). \end{split}
```



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# Typical Problems

- Blocks Problem
- Logistic Problem
- 8-puzzle Problem
- Freecell Game
- Boxman Game





Figure 3: Freecell Game and Boxman Game



## **Examples**

## Spare Tire (domain)

```
(:action Remove
:parameters (?x - physob ?y - location)
:precondition (At ?x ?y)
:effect (and (not (At ?x ?y)) (At ?x Ground)))
(:action PutOn
:parameters (?x - physob)
:precondition (and (Tire ?x) (At ?x Ground)
(not (At Flat Axle)))
:effect (and (not (At ?x Ground)) (At ?x Axle)))
```

## Spare Tire (data)

```
(define (problem prob)
(:init (Tire Flat)(Tire Spare)(At Flat Axle)(At Spare Trunk))
(:goal (At Spare Axle))
```

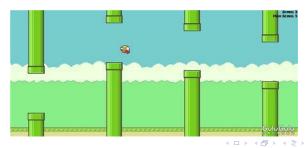


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## Typical Algorithms

- Probabilistic Reasoning (Bayesian Network)
- Decision Tree (ID3 and C4.5)
- Naive Bayes
- EM Clustering
- BP-Neural Network
- Deep Learning
- Reinforcement Learning (Q learning and Sarsa)
- Deep Q-Learing (DQN)





# The End

