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```
zuser@ubuntu2025:~$ rover_system_check.sh
```

```
all systems operational!
```

```
zuser@ubuntu2025:~$ g++ rover_navigation.cpp -o rover_navigation
```

```
zuser@ubuntu2025:~$ ./rover_navigation
```

```
New Position: (x_final, y_final, z_final)
```

```
zuser@ubuntu2025:~$ python morse_decipher.py
```

```
Decoded Message: MARS
```

```
zuser@ubuntu2025:~$ python martian_filter.py
```

```
Most Stable Value: 36.7
```

```
zuser@ubuntu2025:~$
```

```
root@2025:~/rover_mission$ mkdir rover_mission && cd rover_mission
root@2025:~/rover_mission$ touch log1.txt log2.txt
root@2025:~/rover_mission$ mv log1.txt mission_log.txt
log3.txt log3.txt mitbl
root@2025:~/rover_mission$ cat mission_log.txt
mission_log.txt
mission_log.txt
root@2025:~/rover_mission$ grep ERROR mission_log.txt
ERROR mission_log.txt
root@2025:~/rover_mission$ wc -l mission_log.txt

23 13:57:58 CDT 2025
0.0 us, 0.0 sy, 0.0 00u id, 0.0 wa, 0.0 hi, 0.0.0 si, 0.0 st
root@2025:~/rover_mission$
root@2025:~/rover_mission$ sudo shutdown -c 'Scheduled for Tue 2025-04-24-23 14:07:58 CDT, use 'shutdown -c' to cancel'
root@2025:~/rover_mission$ sudo shutdown +10
```