

ESP 32 CODE

```
int count=0;int ave;
#define BLYNK_PRINT Serial
#include <WiFi.h>
#include <WiFiClient.h>
#include <BlynkSimpleEsp32.h>

#define BLYNK_TEMPLATE_ID "TMPL3Cwdc9AHm"
#define BLYNK_TEMPLATE_NAME "EV CHARGING"
#define BLYNK_AUTH_TOKEN "EG0N5i7fvTlzZBAhL_j_GwnYs-FEWQk7"

char auth[] = BLYNK_AUTH_TOKEN;

// Your WiFi credentials.
// Set password to "" for open networks.
char ssid[] = "IOT";
char pass[] = "123456789";

#define cv1 35
#define bv1 32
float cv, bv,act=0;
void setup() {
  // put your setup code here, to run once:
  Serial.begin(9600);
  pinMode(cv1, INPUT);
  pinMode(bv1, INPUT);
  Blynk.begin(auth, ssid, pass, "blynk.cloud", 80);
}

void loop() {
  // put your main code here, to run repeatedly:

  cv = analogRead(cv1);
  Serial.print("cv : ");
  Serial.println(cv);

  //bv=map(bv,1050,1750,0,100);

  for(int i=0;i<10;i++)
  {
    bv += analogRead(bv1);
  }
}
```

```

ave=(int)bv/10;
  Serial.print("ave : ");
ave=ave/2;
  delay(500);
  if(cv>=1501)
  {
    Blynk.virtualWrite(V4,"CHARGING ");
    Serial.println("=====CHARGING ");
    delay(500);

    Blynk.virtualWrite(V3,ave);
    count=0;
  }
  else if(cv<=1500)
  {
    count++;
  }
  if(count>=10){
    Serial.println("-----NOT charging");
    Blynk.virtualWrite(V4,"");}

  Serial.println("count : ");
  Serial.print(count);
  Blynk.virtualWrite(V3,ave);
}

```

Node MCU code

```

//e3049iot@gotgel.org
//Info@2024
#include <SoftwareSerial.h>
SoftwareSerial mySerial(D7, D4);/* (Rx, Tx) */

#define BLYNK_PRINT Serial
#include <ESP8266WiFi.h>
#include <BlynkSimpleEsp8266.h>

#define BLYNK_TEMPLATE_ID "TMPL3Cwdc9AHm"
#define BLYNK_TEMPLATE_NAME "EV CHARGING"
#define BLYNK_AUTH_TOKEN "EG0N5i7fvTlzZBAhL_j_GwnYs-FEWQk7"

char auth[] = BLYNK_AUTH_TOKEN;

```

```

// Your WiFi credentials.
// Set password to "" for open networks.
char ssid[] = "IOT";
char pass[] = "123456789";

#include <LCD_I2C.h>
LCD_I2C lcd(0x27);

#include <EveryTimer.h>
#define PERIOD_MS 1000
EveryTimer timer;
bool active = true;

float f;
unsigned char a[50];
unsigned int val1, val2, val3, val4, val5, val6, val7;
unsigned int m = 0;
unsigned char a1 = 0, a2 = 0, a3 = 0, a4 = 0, a5 = 0;
char inChar;

#define solareb D6
#define onoff D5
int count1 = 0, act = 0;
int count = 0; // count = 0
char input[12];
char readera[] = "4D0098A10D79";
char readerb[] = "540024BCE824";
char readerc[] = "54002669F5EE";
char readerd[] = "540024019CED";
boolean flag = 0;
int sec = 0, amount = 0;
#define sv1 A0
float sv, bv;
void setup() {
  // put your setup code here, to run once:
  Serial.begin(9600);
  mySerial.begin(9600);
  lcd.begin();
  lcd.backlight();
  pinMode(sv1, INPUT);
  pinMode(solareb, OUTPUT);
  pinMode(onoff, OUTPUT);
  digitalWrite(onoff, HIGH);
  digitalWrite(solareb, LOW);
  timer.Every(PERIOD_MS, action);

```

```

    lcd.setCursor(0, 0);
    lcd.print("EV CHARGING");
    lcd.setCursor(0, 1);
    lcd.print("STATIONS VEHICLE");
    Blynk.begin(auth, ssid, pass, "blynk.cloud", 80);
    lcd.clear();
}

void loop() {
    // put your main code here, to run repeatedly:
    //Blynk.virtualWrite(V4,"S: "+String(val1)+" CO: "+String(val2)+"M: "+String(val3)+"T:
    "+String(val4)+"W:"+String(kg));

    Blynk.virtualWrite(V1,"                ");
    //digitalWrite(onoff, LOW);
    Serial.println("val1 ; ");
    Serial.print(val1 );
    bv = (float)val1 / 100;
    Serial.println("bv : ");
    Serial.print(bv );
    if (mySerial.available())
    {
        count = 0;
        while (mySerial.available() && count < 12)    // Read 12 characters and store them in
input array
        {
            input[count] = mySerial.read();
            count++;
            delay(5);
        }
        Serial.print(input);                // Print RFID tag number

    }
    if (strcmp(input, readera, 12) == 0)
    {
        Serial.println(" Card 1 Detected");

        count1++;
        delay(500);
        input[0] = '5';
    }

    //RFID 2 .....
    if (strcmp(input, readerb, 12) == 0)
    {
        Serial.println("Card 2 Detected");
    }
}

```

```

// Blynk.virtualWrite(V1,"NOT MATCH ID CARD");
// Blynk.logEvent("msg","NOT MATCH ID CARD");
  delay(900);
  input[0] = '5';

}
if (count1 == 1 && act == 0)
{
//    lcd.setCursor(13, 0);
//    lcd.print("M:S");
  Serial.print("NAME : ");
  Serial.println("Sivakumar ");
  Serial.print("ID : ");
  Serial.println("713321EC046 ");
  digitalWrite(onoff, LOW);
  delay(200);
  act = 1;
}
if (act == 1) {
  timer.Update();
  lcd.setCursor(14, 0);
  lcd.print("M:");
  lcd.setCursor(8, 0);
  lcd.print("A:");
  lcd.setCursor(10, 0);
  lcd.print(amount);
  lcd.setCursor(13, 0);
  lcd.print("M:");
  lcd.setCursor(15, 0);
  lcd.print("S");
  Blynk.logEvent("msg","N: Sivakumar: ID : 713321EC046");
  Blynk.virtualWrite(V1,"N: Sivakumar: ID : 713321EC046");
  //Blynk.virtualWrite(V2,"A: "+String(amount));
}
if (count1 == 2)
{
  Blynk.virtualWrite(V1,"");
  digitalWrite(onoff, HIGH);
  Serial.println("colse: ");
  Blynk.virtualWrite(V1,"");
  delay(500);
  count1 = 0;

  amount = 0;
  act = 0;
}

```

```

        lcd.setCursor(8, 0);
        lcd.print("A:");
        lcd.setCursor(10, 0);
        lcd.print(amount);
        // Blynk.virtualWrite(V2,"A: "+String(amount));

    }
    lcd.setCursor(13, 0);
    lcd.print("M:");
    lcd.setCursor(8, 0);
    lcd.print("A:");

        lcd.setCursor(10, 0);
        lcd.print(amount);

    sv = analogRead(sv1);
    sv = ((sv * 15) / 1000);
    Serial.print("amount : ");

    lcd.setCursor(0,0);
    lcd.print("SV:");
    if(sv<=9){lcd.print("0"); lcd.print(sv);}
    else if( sv <=9){lcd.print(""); lcd.print( sv);}

    lcd.setCursor(0,1);
    lcd.print("BV: ");
    if(bv<=9){lcd.print("00"); lcd.print(bv);}
    else if( bv <=99){lcd.print("0"); lcd.print( bv);}
    else if( bv <=999){lcd.print(""); lcd.print( bv);}
    Blynk.virtualWrite(V2,"  AM:"+ String(amount)+"  SV:"+String(sv)+"  BV:"+String(bv));
    Blynk.run();
    delay(500);
    receive_();
}
void receive_()
{

    while (Serial.available()) {
        // get the new byte:
        inChar = (char)Serial.read();

        a[m] = inChar;
        if (a[0] == '*')
        {
            if (m <= 4) {

```

```

        m++;
    }
}
}
m = 5;

if (m > 1)
{
    val1 = (a[1]-0x30)*1000 + (a[2]-0x30)*100 + (a[3]-0x30)*10 +(a[4]-0x30);delay(100);
    //val2 = (a[4]-0x30)*100 + (a[5]-0x30)*10 + (a[6] - 0x30);

    m = 0;

}
}
void action()
{
    amount = amount + 2;
}
BLYNK_WRITE(V0)
{
    int button = param.asInt(); // read button
    if (button == 1)
    {
        digitalWrite(solareb,HIGH);
        ///Blynk.virtualWrite(V2,"A: "+String(amount));

        lcd.setCursor(15, 0);
        lcd.print("E");
    }
    else
    {
        lcd.setCursor(15, 0);
        lcd.print("S");
        digitalWrite(solareb, LOW);
    }
}
}

```

Pico code

```

//e2799iot@fthcapital.com
//Info@2024

```

```

#define sv1 27
#define bv1 26

float sv,bv,wind;
int pt2,send1,send2,send3;

void setup()
{
    Serial.begin(9600);

    //pinMode(sv1,INPUT);
    pinMode(bv1,INPUT);

    Serial1.setTX(16);
    Serial1.setRX(17);
    Serial1.begin(9600);

}

void loop()
{

    //sv =analogRead(sv1);
    //Serial.print("analog sV : ");
    //Serial.println(sv);
    //sv=((sv*30)/1000);

    //Serial.print(" convert sv: ");
    //Serial.println(sv);

    bv =analogRead(bv1);
    Serial.print("analog bv : ");
    Serial.println(bv);

    bv=((bv*16)/1000);

```



```

Serial.print("convern bv : ");
Serial.println(bv);

//send1=sv*100;
send1=bv*100;
  Serial.print("send1 bv : ");
  Serial.println(send1);

  senddata();
  delay(900);

}

void senddata()
{
  Serial1.print("*");

  if( send1<=9){Serial1.print("000"); Serial1.print( send1);}
  else if( send1 <=99){Serial1.print("00"); Serial1.print(send1);}
  else if( send1 <=999){Serial1.print("0");Serial1.print( send1);}
  else if( send1 <=9999){Serial1.print("");Serial1.print( send1);}

}

```