

Machine Learning

Introduction

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9, 16 décembre 2016 13 janvier, 9 mars 2017







Supervised

Unsupervised

Reinforcement



Course structure

Four days

- Friday 9 December (9h)
- Friday 16 December (9h)
- Friday 13 January (8h30)
- Thursday 9 March (8h30)

Course structure

Communication

- <https://ynov-ml.slack.com/>
- <https://github.com/ynov-ml/2016-2017>

Course structure

Tasks

- Email `jeff@purple.com` so I can invite you to slack.
- Create a github account if you don't have one. Anonymous if you must.
- Clone the course repository, add your github repository to repositories, send a PR.

Course structure

Good git practices

- One line summary, declarative, < 60 characters
- Good comments
- Work on branches

Curse of Dimensionality

Machine learning is not magic

Machine learning is mathematics

Mostly, it's these maths:

- Probability
- Statistics
- Linear algebra
- Optimisation theory
- Differential calculus

Probability

Probability

events

- independent
- dependent

Addition rule: independent events

$$\Pr(A \cup B) = \Pr(A) + \Pr(B)$$

Addition rule: dependent events

$$\Pr(A \cup B) = \Pr(A) + \Pr(B) - \Pr(A \cap B)$$

Multiplication rule: independent events

$$\Pr(A \cap B) = \Pr(A) \Pr(B)$$

Multiplication rule: dependent events

$$\Pr(A \cap B) = \Pr(A | B) \Pr(B)$$

Conditional probability

$$\Pr(A | B) = \frac{\Pr(A \cap B)}{\Pr(B)}$$

Conditional probability

$$\cup_i A_i = A \quad \wedge \quad A_i \cap A_j = \emptyset \implies$$

$$P(A_1 | B) = \frac{\Pr(B | A_1) \Pr(A_1)}{\sum_i \Pr(B | A_1) \Pr(A_1) + \dots + \Pr(B | A_k) \Pr(A_k)}$$

Statistics

What is Statistics

- ① Identify a question or problem.
- ② Collect relevant data on the topic.
- ③ Analyze the data.
- ④ Form a conclusion.

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Sadly, sometimes people forget 1.

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Statistics is about making 2–4 efficient, rigorous, and meaningful.

OpenIntro Statistics, 2nd edition, D. Diez, C. Barr, M. Çetinkaya-Rundel, 2013.

What is data science?

(Exercise: Is this the same question as the last slide?)

- ① Define the question of interest
- ② Get the data
- ③ Clean the data
- ④ Explore the data
- ⑤ Fit statistical models
- ⑥ Communicate the results
- ⑦ Make your analysis reproducible

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What the public thinks.

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Where we spend most of our time.

What is data science?

(Exercise: Is this the same question as the last slide?)

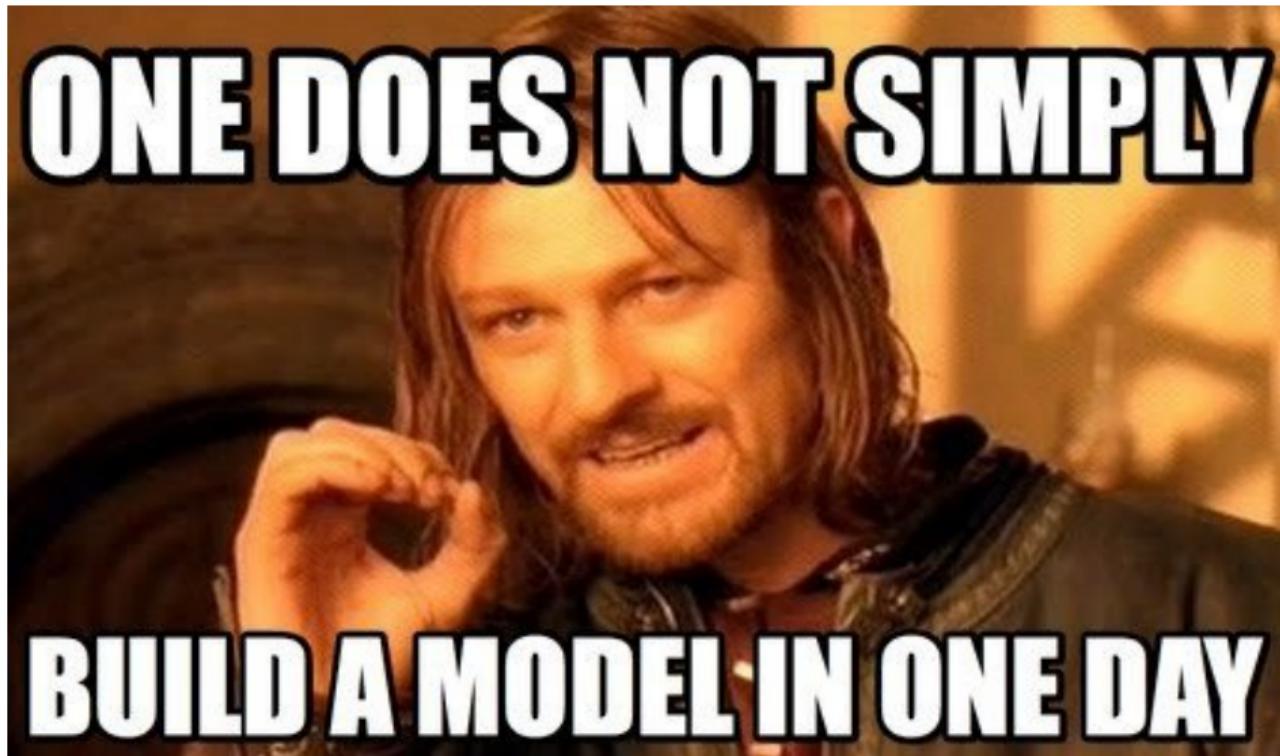
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- ⑥ Communicate the results
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The easiest part to forget.

What is data science?

*[http://simplystatistics.org/2015/03/17/
data-science-done-well-looks-easy-and-that-is-a-big-
problem-for-data-scientists/](http://simplystatistics.org/2015/03/17/data-science-done-well-looks-easy-and-that-is-a-big-problem-for-data-scientists/)*

What is data science?



Anecdote

Some properties of anecdote:

- is data
- haphazardly collected
- is generally not representative
- sometimes result of selective retention
- does not accumulate to be representative
- might be true (by chance)
- is ok to use as hypothesis, but be clear that hypothesis is anecdote

Study Types

- Observational
- Experimental

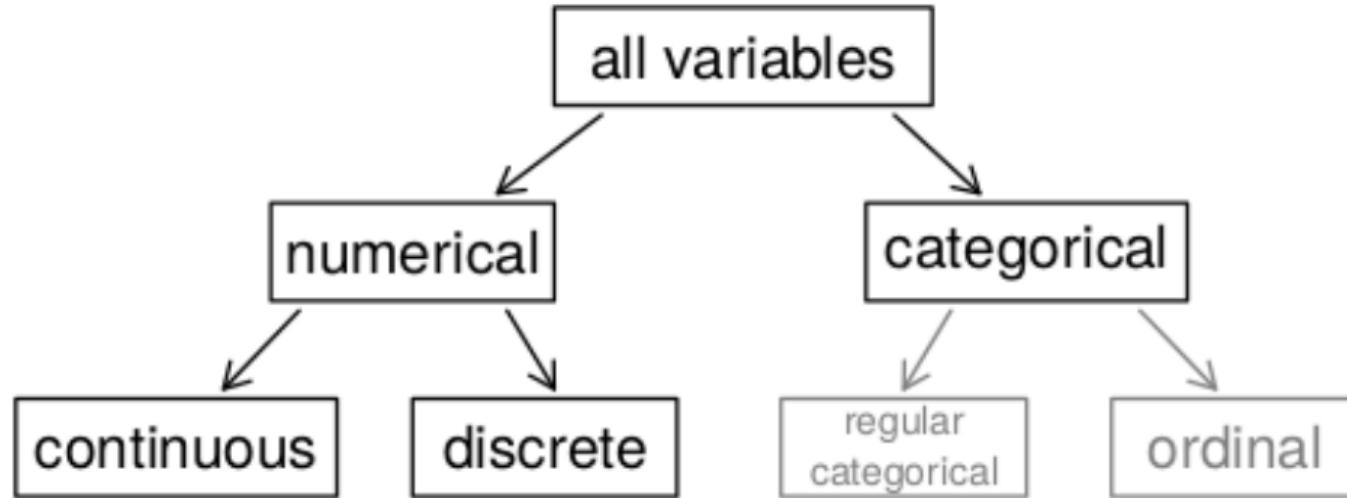
Study Types

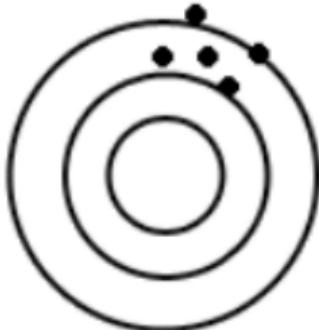
- Observational
- Experimental

What can go wrong?

- Forgetting that association \neq causation
- Not random
- Confounding variables

Variable types





High bias, low variance



Low bias, high variance



High bias, high variance



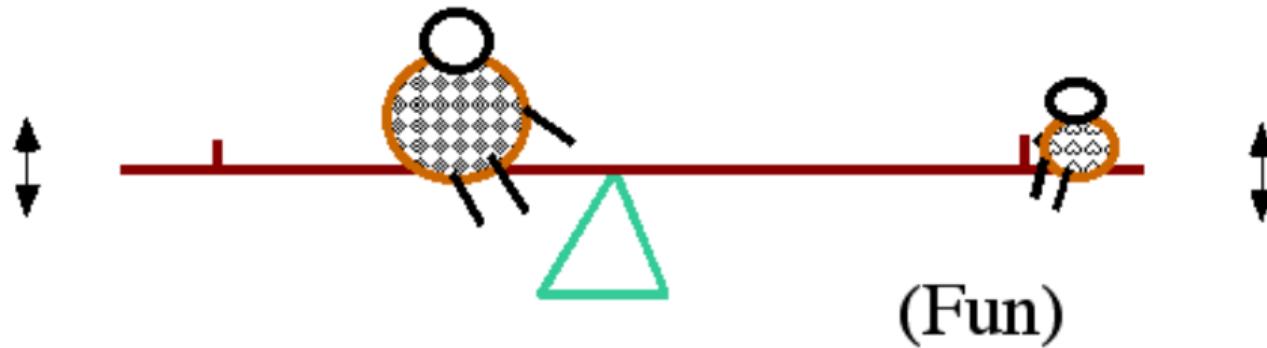
Low bias, low variance

Mean

- Weighted and unweighted
- Centroid to physicists

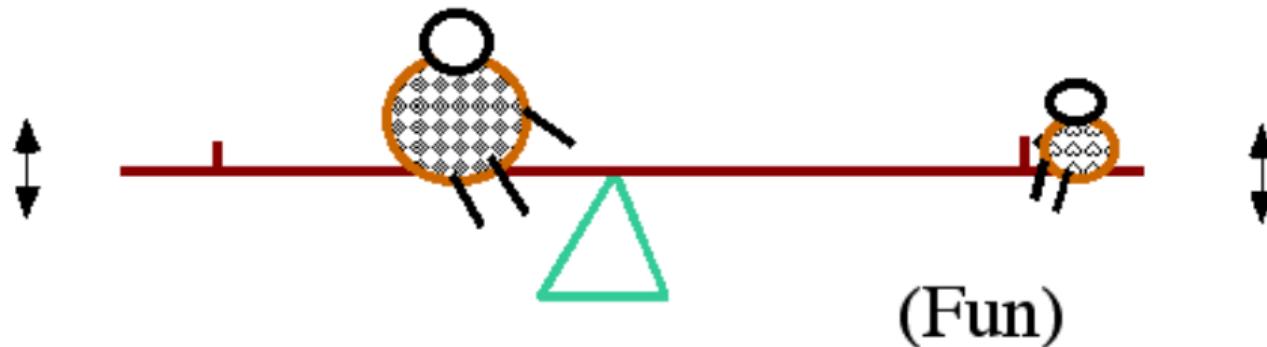
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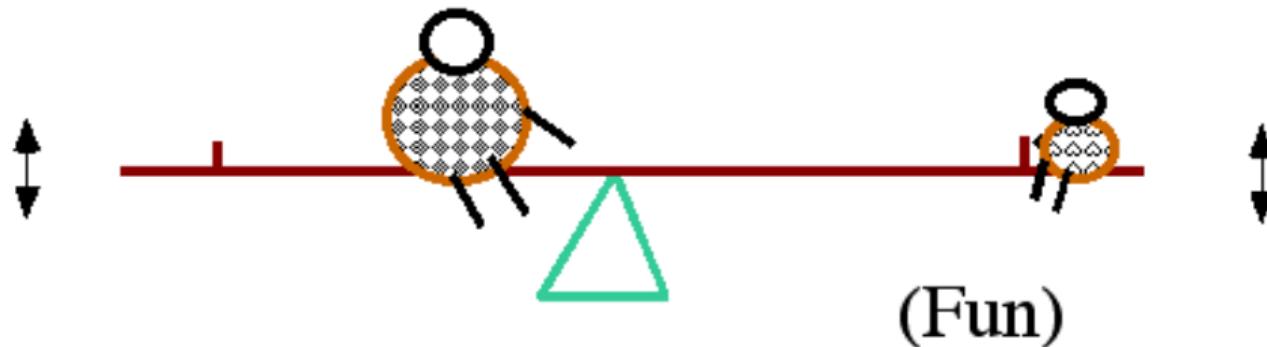
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$$\mu = E(X) = \sum w_i x_i = \mathbf{w} \cdot \mathbf{x}$$

Mean

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$$\mu = E(X) = \sum \Pr(X = x_i)x_i$$

Mean

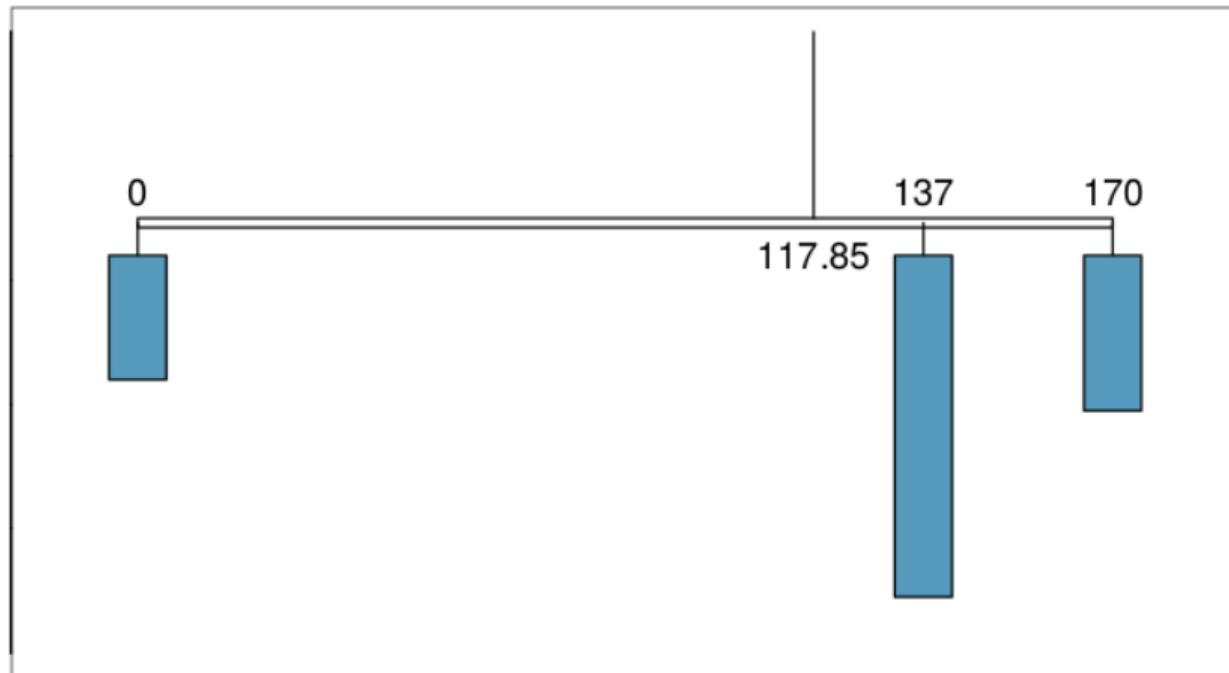
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$$\mu = E(X) = \int xf(x) dx$$

<http://telescopes.stardate.org/images/research/teeter-totter/TT4.gif>

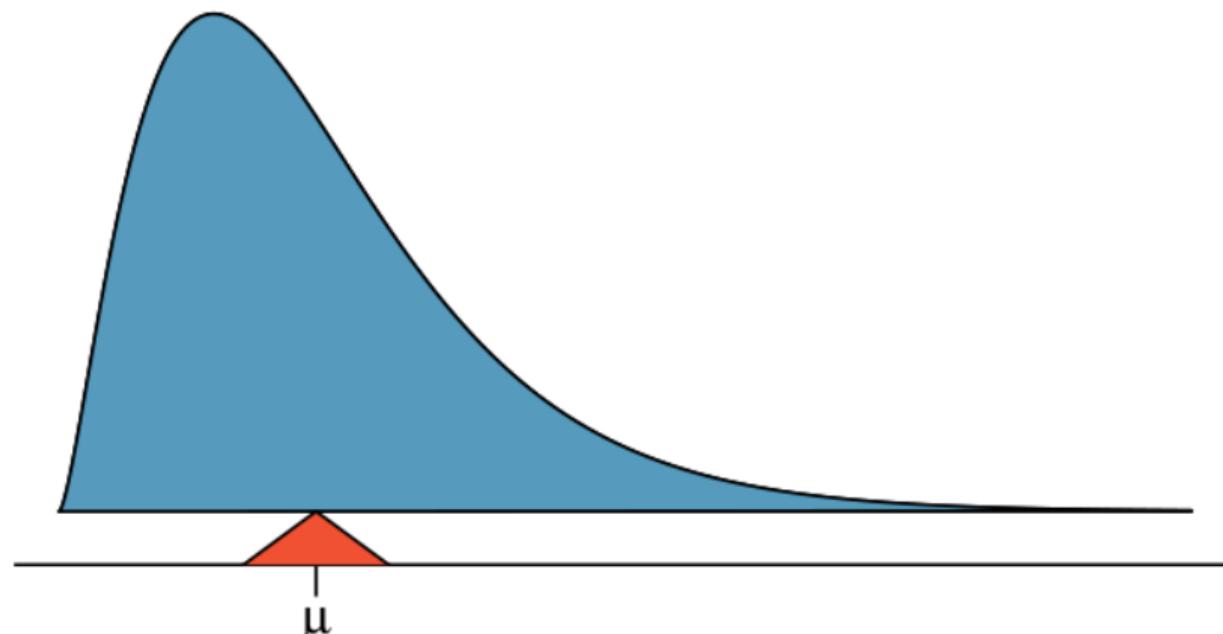
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Population statistics

Deviation is distance from mean.

Population statistics

Variance is mean square of deviations

Population statistics

Standard deviation is square root of variance

Population statistics

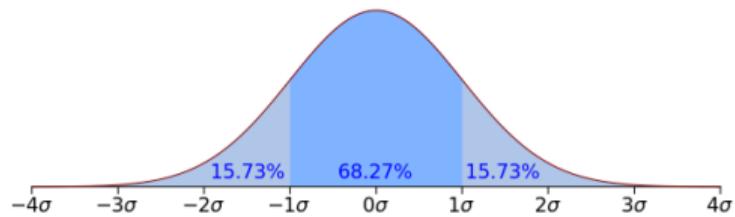
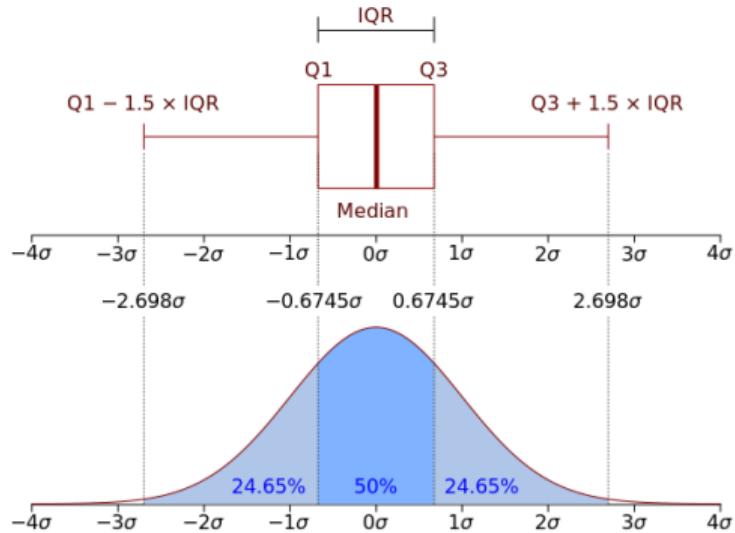
$$s^2 = \frac{(\bar{x} - x_1)^2 + \cdots + (\bar{x} - x_n)^2}{n - 1}$$

Population statistics

$$\sigma^2 = \frac{(\bar{x} - x_1)^2 + \cdots + (\bar{x} - x_n)^2}{n}$$

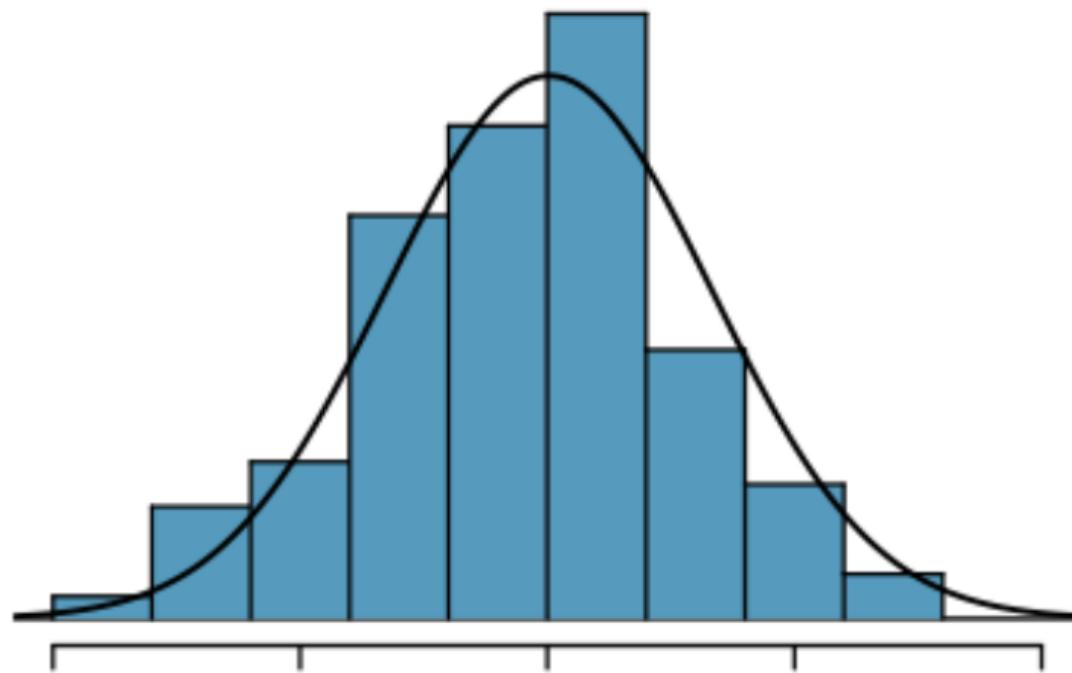
Population statistics

$$\text{Var}(X) = \sigma^2 = (\bar{x} - x_1)^2 \Pr(X = x_1) + \cdots + (\bar{x} - x_n)^2 \Pr(X = x_n)$$



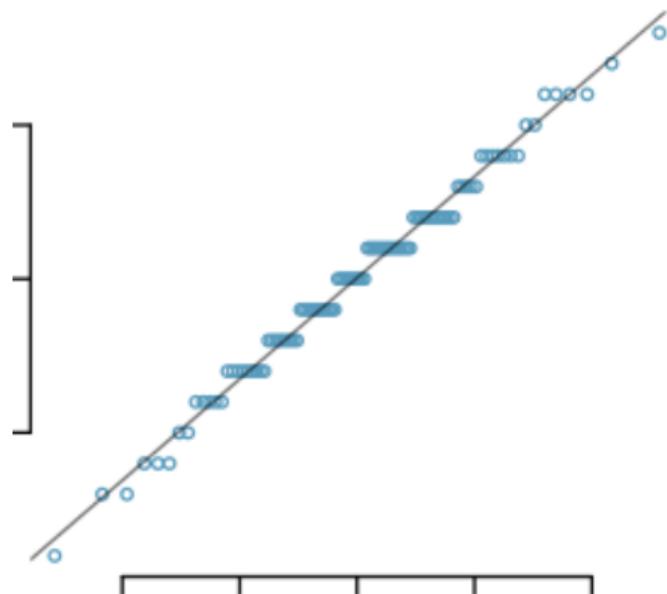
Evaluating Normal Approximations

Easy technique 1: visually compare to normal plot.



Evaluating Normal Approximations

Easy technique 2: normal probability plot.



Also known as a quantile-quantile plot.

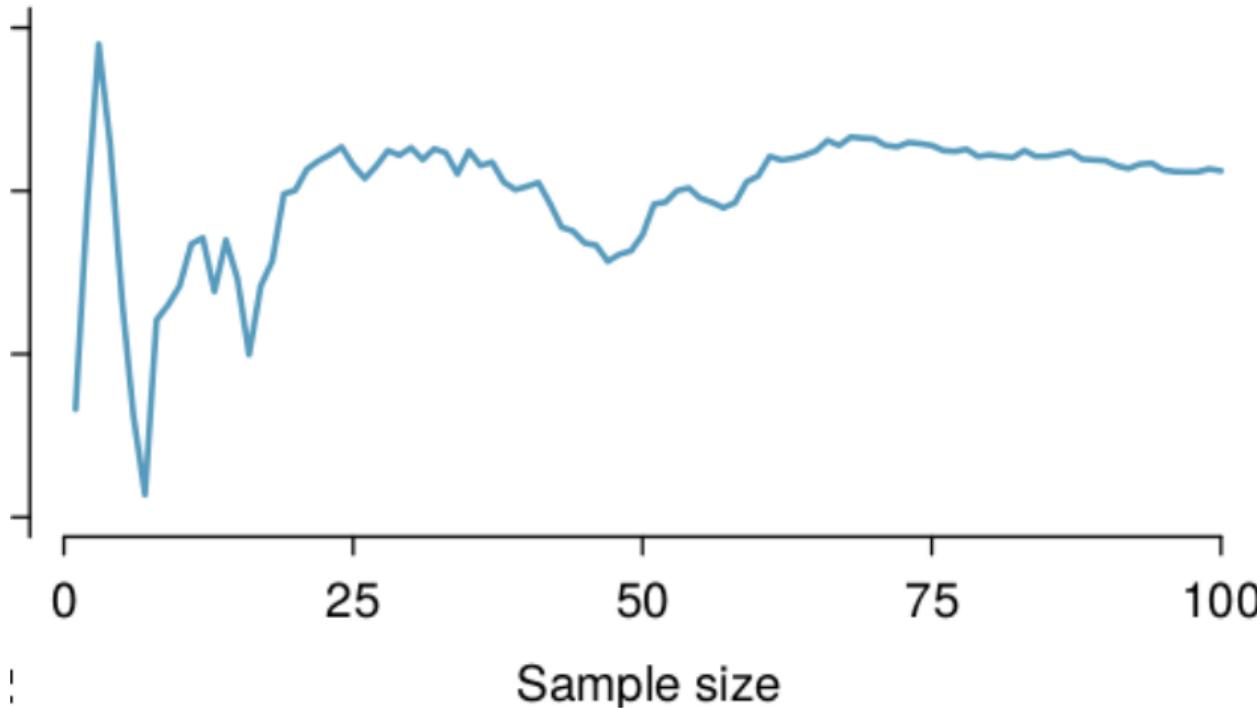
$$\overline{x} \neq \mu$$

Inference Concepts

Running mean. Sequence of partial sums (divided by number in sum).

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Sampling variation. Change of \bar{x} from one sample to the next.

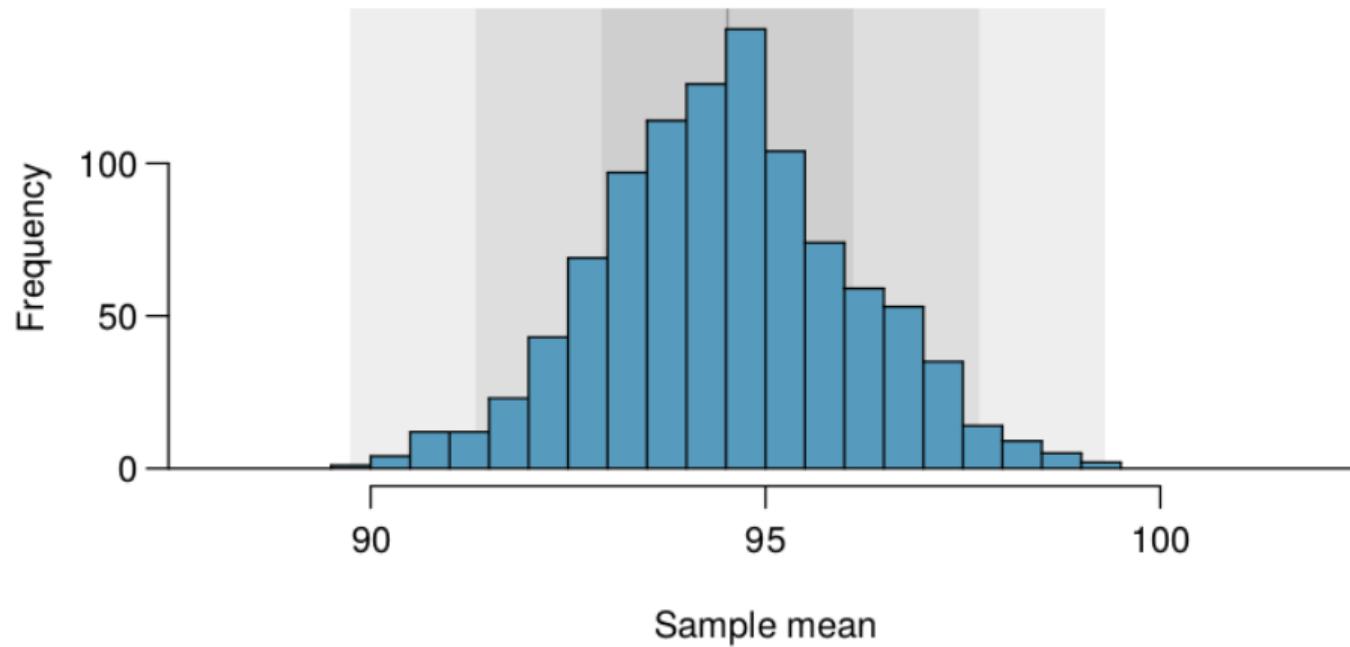
Inference Concepts

Running mean. Sequence of partial sums (divided by number in sum).

Sampling variation. Change of \bar{x} from one sample to the next.

Sampling distribution. The distribution of possible point samples of a fixed size from a given population.

Sampling distribution



Confidence intervals

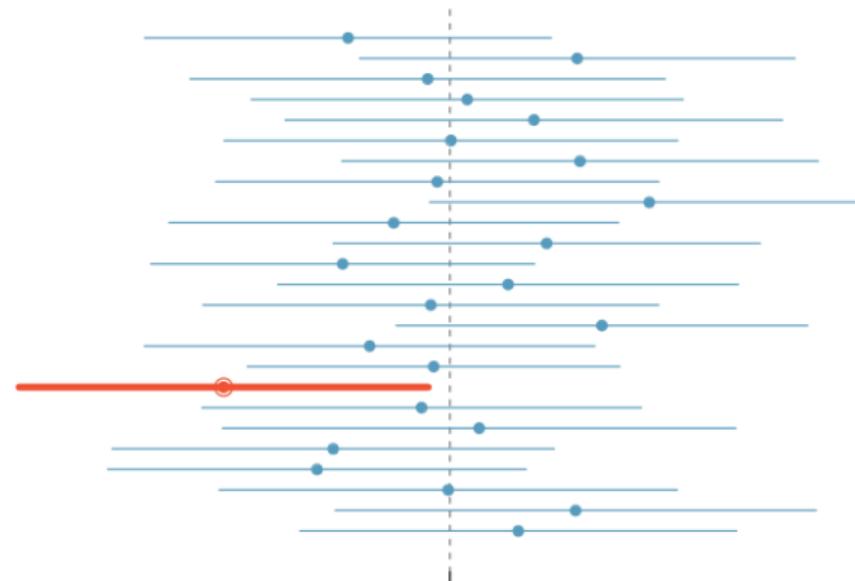
Sample n points, choose an interval around the sample mean.

A 95% confidence interval means if we sample repeatedly, about 95% of the samples will contain the population mean.

Confidence intervals

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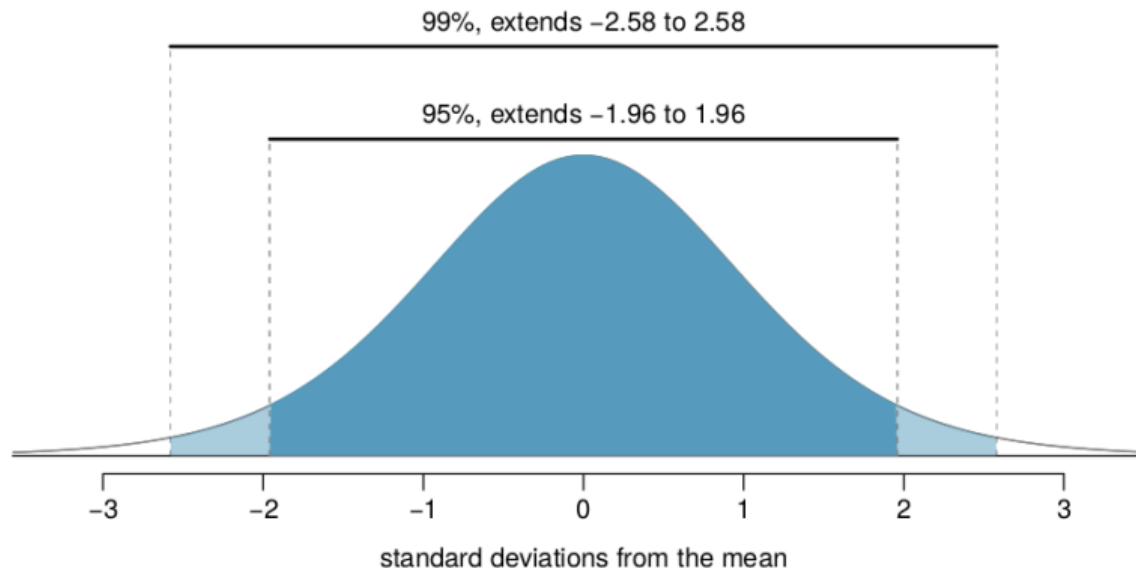
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Confidence intervals

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Linear Algebra

Linear algebra: basics

$$v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \in \mathbb{R}^n$$

Linear algebra: basics

$$A = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} = \begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{pmatrix}$$
$$= \left\{ \begin{array}{ccc} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{array} \right\} \in \mathbb{R}^{n \times n}$$

Linear algebra: basics

$$u + v = \begin{pmatrix} u_1 + v_1 \\ u_2 + v_2 \\ \vdots \\ u_n + v_n \end{pmatrix}$$

Linear algebra: basics

$$\alpha \mathbf{v} = \begin{pmatrix} \alpha v_1 \\ \alpha v_2 \\ \vdots \\ \alpha v_n \end{pmatrix} \quad (\alpha \in \mathbb{R})$$

Linear algebra: basics

$$\| v \| = \sqrt{v_1^2 + \cdots + v_n^2}$$

Linear algebra: basics

$$\begin{aligned} \mathbf{u} \cdot \mathbf{v} &= u_1 \cdot v_1 + \cdots + u_n \cdot v_n \\ &= \| \mathbf{u} \| \| \mathbf{v} \| \cos \theta \end{aligned}$$

Linear algebra: basics

$$C = A + B \iff c_{ij} = a_{ij} + b_{ij}$$

$$C = AB \iff c_{ij} = \sum_k a_{ik} b_{kj}$$

$$A = B^T \iff a_{ij} = b_{ji}$$

$$AA^{-1} = A^{-1}A = \text{diag}(1)$$

Linear algebra: transformations

$$Ax = y \quad f = T_A : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$x = A^{-1}Ax = A^{-1}y \quad f^{-1} = T_{A^{-1}} : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

Linear algebra: transformations

B is a basis for V iff any of these conditions are met:

- B is a minimal generating set of V
- B is a maximal set of linearly independent vectors
- Every vector $v \in V$ can be expressed in a unique way as a sum of $b_i \in B$

(The conditions are equivalent.)

Linear algebra: transformations

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Bases are not unique.

Linear algebra: transformations

Eigenvectors, eigenvalues:

$$Av = \lambda v$$

Linear algebra: transformations

Eigenvectors, eigenvalues:

$$Av = \lambda v$$

$$Av = \lambda 1 v \iff (A - \lambda 1)v = 0$$

Linear algebra: transformations

Eigenvectors, eigenvalues:

$$Av = \lambda v$$

Some matrices are diagonalisable. Then

$$A = Q\Lambda Q^{-1} \quad \text{with } \Lambda = \begin{bmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & 0 \\ 0 & 0 & \lambda_n \end{bmatrix}$$

$$\text{and } Q = \begin{bmatrix} | & & | \\ v_1 & \cdots & v_n \\ | & & | \end{bmatrix}$$

Linear algebra: transformations

video time

Questions?