Element E: Application of STEM principles and practices

Due to the nature of the project, the application of physics, math and aspects of mechanical engineering play a key role in the development of both stability and visibility designs.

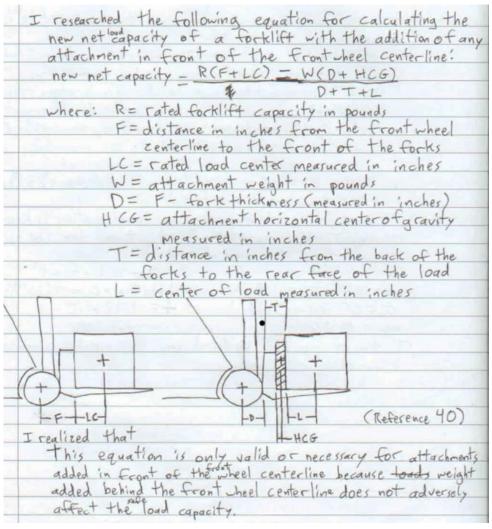
For the stability design, calculations regarding the center of gravity of an object, centripetal force calculations, and moment equations have been essential to the progress in the design of the device. Also calculations involving determining the size of a hydraulic cylinder and the size of a motor, which correlates to mechanical engineering, have been a part of the team's design determination.

As for the visibility design, calculations involving the stopping distance of a forklift and the physics behind the properties of reflected light affected the design specifications.

Forkift Attachment Calculations

As proven through the following calculations performed by the team, even relatively low weight attachments can have a significant negative impact on the safe load capacity if the attachment is located forward of the forklift's front wheel

centerline. The researched equation is derived from a moment equation.



(Pictures of calculations are excerpts from the 10/31/12 entry of [redacted student name] Engineering Notebook.)

SUMMARY: These calculations prove that the addition of a hypothetical 25 pound attachment results in a lost capacity of 366 pounds and indicates that attachments placed forward of the front wheel centerline would have a significant negative impact on the performance and productivity of a forklift. Therefore, it was decided that a product specification would be that the solution would not have any components forward of the front wheel centerline.

Forklift Stopping Distance Calculations

The following calculations determine an approximation for the distance that it takes for a forklift to stop.

(Pictures of above calculations were copied from the 11/12/12 entry of [redacted student name] Engineering Notebook.)

(The picture of calculations above was copied from the 11/21/12 entry of [redacted student names] Engineering Notebook.)

SUMMARY: The calculated results for an approximation of the stopping distance of a forklift allowed the team to determine a value for the minimum safe distance between a forklift and an object, or person, in front of the forklift that the industrial vehicle can stop in without hitting the object or person. This became product specification 19: The minimum distance between the forklift and a hazard must be five meters at the instant that

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I researched the following values for the Toyota Model 8F6CU20
   forklift which the team will primarily be testing with: (Reference 41)
   R = 4,000 16
    F= 16.7 in
   LC=ZYin
    D= #200 16.7in - 4in = 12.7in (Gyneth and I agreed on
     the estimate of 4in for the fork thickness)
   L= 24in
I decided on the following values for a forklift with a front
    mounted attach ment:
   W= 4848 2516
   HCG = Zin
    T = 8 in
I calculated the new net capacity of the previously mentioned
  Forklift with attachmentusing the equation researched on 10/30/12
  new net capacity - R(F+LC) - W(D+HCG)
new net capacity - (4,000 lb) (16.7in +24in) - (251b) (12.7in + Zin)
                       12.7 in + 8 in + 24 in
new net capacity - 162,8001bin - 367,51bin
                          44.7in
                 162432.51bin
new net capacity = 3,634 lb
  R-new net capacity = lost capacity
  lost capacity = 4,000 1b - 3,6341b = 3661b
I calculated the lost capacity above which I define as the
  difference between the previous maximum safe load weight,
  or rated forklift apacity, and the new maximum sateload
  weight, or new net capacity
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forklift operator is alerted to said hazard. (The 4.7690 meters was rounded up to 5 meters to be safe).

Physics and Newton's First Law

To analyze a possible failure in the design of the visibility solution, certain physical laws were utilized.

SUMMARY: The overwhelming majority of forklifts have lap belts, not seatbelts that extend over a shoulder. This means that when a forklift stops suddenly, the forward momentum of the operator causes the driver's head and upper body to keep moving forward, as per Newton's 1st Law: *objects in motion remain in motion unless acted upon by an unbalanced force.* In some situations, the driver's head can continue forward far enough to hit the device, especially when the device is in an angled position, as shown in Figure 4. As a result, such an occurrence is reasonably possible enough that it does represent a legitimate problem that must be addressed in order to produce a safe solution.

Physics and Properties of Reflected Light

Because of the fact that the angle of incidence is equal to the angle of reflection, as shown in the following sketch, the team was able to determine the angle of the mirrors in

the

visibility solution concept to be 45 degrees:

(The picture above shows the incident and reflected light at a reflective surface at a 45 degree angle, such as that of the mirror in the visibility design sketched by [redacted student name] on 1/20/13)

Mrs. Famoso, an Advanced Placement physics teacher and an alumni of Rensselaer Polytechnic Institute's School of Engineering confirmed the team's choice of angle of the mirrors in the device, 45 degrees.

SUMMARY: The team determined the angle of the mirrors in the visibility solution concept to be 45 degrees. See the explanation of how the 45 degree angle factors into the visibility solution at the bottom of <u>Element D: Design concept generation</u>, analysis, and <u>selection</u>.

Physics and Center of Mass Calculations

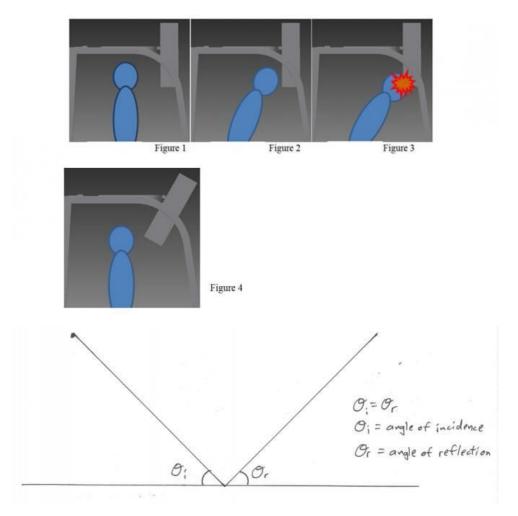
Regardless of whether the team decides to work with the "under mounted hydraulic cylinders" or the "under mounted counterweight with electric motor", the

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Based on the fact that a direct relationship exists between a
 for klift's weight and its stopping distance, the following proportion
 was set up using calculated and researched values:
   - stopping distance without load = 1.9812 m
      (The larger calculated stopping distance was used to besafe)
  - weight w/o load = 7,13016
   - weight w/ load = 11,1301b
  weight w/o load = stopping distance Wo load
weight w/ load stopping distance w/ load
    7,130 lb = 1,9812m
11,130 lb = stopping distance w/load
   Stopping distance with load = 3.0927m
operator reaction time = .75 seconds
     ( Same source as both stopping distance conversion factors)
The distance that a forklift travels at 5"/hr in 75 seconds
   was calculated:
5 m/hr ( 1hr ) ( 1609.34m) = 2.235 m/s
      d= V.+
      d = 2.235% · .75s = 1.6763m
The total stopping distance was calculated:
total stopping distance = stopping distance + reaction time distance
total stopping distance = 3.0927m + 1.6763m
total stopping distance = 4.7690m
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I calculated the maximum and minimum stopping,
I calculated the maximum and minimum stopping inmeters distances of a warehouse for klift moving at 5 m/hr based based on information from the meeting with Mr. Ascoli and Mr. Gorhan
based on information from the meeting with Mr. Ascoli and Mr. Gorham
on 1/17/17.
max stopping distance = 17ft (12in) (2.54cm) (102m) - 5.1816m
(1ft/(lin /(lcm)
min stopping distance= 10ft (12in) (2.54cm) (102m) - 3.0480m]
(1ft/(1 in / 1 cm /
These results confirm my calculated approximate
These results confirm my calculated approximate stopping distance of 4.7690m from 11/12/12 which is between 3.0480m and 5.1816m.
is between 3.0480m and 5.1816m.

weight of the moving counterweight needs to be determined.

The way that both solution devices stated above are designed to work is by activating when a certain type of sensor (which is yet to be determined) indicates



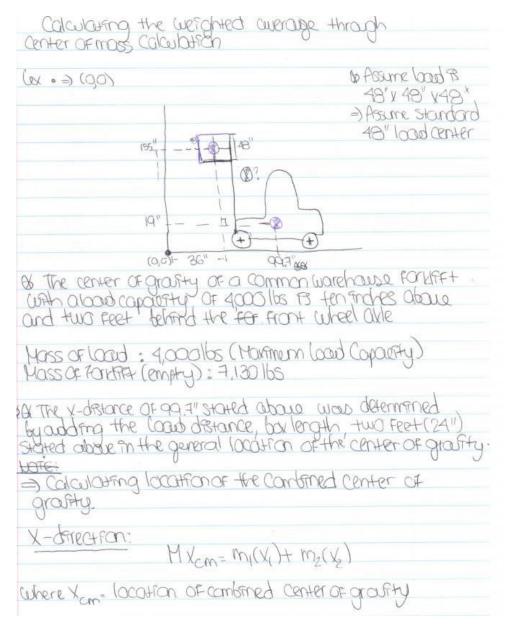
the system to do so. This causes the device to move the counterweight in the opposite direction of the tipping force, forcing the center of gravity back to its center.

The first step to these calculations is to determine the location of the combined center of mass of the empty forklift and a 4000 lb load at maximum fork height (this represents the "worst possible case scenario")

(Pictures of above calculation were copied from the 01/19/13 entry of [redacted student name] Engineering Notebook.)

SUMMARY: The above calculation was performed to determine what the combined center of gravity was when a forklift was at maximum fork height with a full capacity load of 4000 lbs. Now that the location has been determined it can be used to determine when the moment of the gravitational force equals the moment of the centripetal force of a forklift making a turn at seven miles an hour. A moment is defined as a force applied at a perpendicular distance. All of the measurements/dimensions were taken for the Specification Booklet of the Toyota Eight Series ("Toyota Industrial Equipment 8 Series specifications." Toyota Material Handling, USA, Inc.2008.pdf. 19 Jan. 2013)

NOTE: Most warehouses place the speed limit of the forklifts at this speed, therefore this is the speed that will be used throughtout the calculations. Although, it is enforced that forklift drivers drive at five miles an hour.

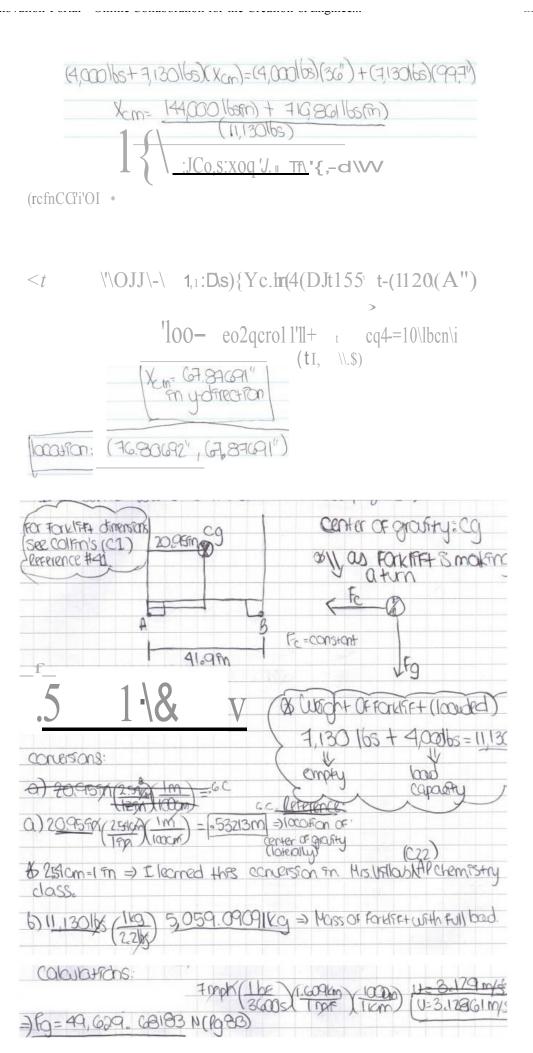


The statement regarding speed limits in warehouses is supported by Mr. Harford, Head Technician of Thompson & Johnson Equipment Co., Inc and Mr. Ascoli, Albany Branch Manager of Thompson and Johnson Equipment Co., Inc.

Determining Centripetal Force and Magnitude of the Center of Gravity

(Pictures of above calculations were copied from the 01/19/13 entry of [redacted student name] Engineering Notebook.)

SUMMARY: To be able to calculate the moment of the centripetal force and the moment of the gravitational force, the magnitudes of each force had to be determined. The team made these calculations using the Metric system, and then converted back to Customary. The value of the radius used was the turning radius of the Toyota 8FGCU20 which was obtained from the Specification Booklet of the Toyota Eight Series ("Toyota Industrial Equipment 8 Series specifications." Toyota Material Handling, USA, Inc.2008.pdf. 19 Jan. 2013).

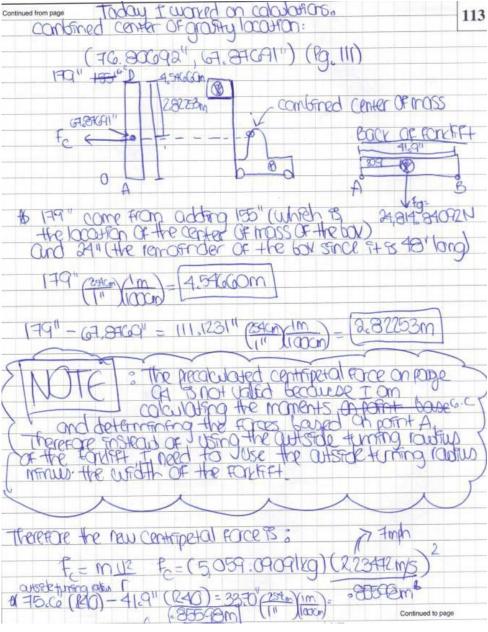


The point at which the moments are equal, is the point of equilibrium. If the moment of the centripetal force at a point exceeds the moment of the gravitational

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force acting on that same point, the forklift will tip over.

Centripetal Force and Gravitational Force Moments: Determining the Mass of the Moving Counterweight.



(Pictures of above calculations were copied from the 01/22/13 entry of [redacted student name] Engineering Notebook.)

SUMMARY: As stated in the summary above the moment of centripetal force and the moment of the gravitational force needed to be computed. The calculations above show the determination for the value of centripetal force at seven miles an hour. Due to the very high mass required as a result of such a high centripetal force, the values were then recalculated to determine at what speed a five hundred pound weight could be used. This is assuming all of other factors remain constant. The reason why the five hundred pounds were chosen was because this leaves two hundred pounds available for the other components

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that may be in the system. If hydraulic cylinders are used then the entire system may be heavier versus using a motor. Also, the mininum size piston required was found. Eventually, the smallest size motor must be found to be able to compare which system is the most viable.

Having a 2500 pound moving counterweight may not be feasible in the amount of room available. This is why the team has considered adding a throttle back to the system. Please see **Element F: Consideration of design viability** (http://innovationportal.org/portfolio/2312/element/28354) for more details.

NOTE: Certain values pertaining to the Toyota 8FGCU20 were obtained from the Specification Booklet of the Toyota Eight Series ("Toyota Industrial Equipment 8 Series specifications." Toyota Material Handling, USA, Inc.2008.pdf. 19 Jan. 2013).

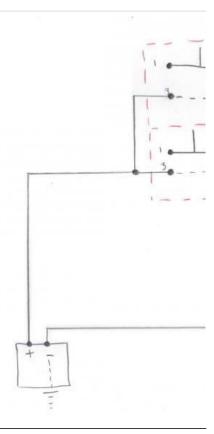
Schematics

From taking the Principles of Engineering class at school the team learned how to draw simple schematic diagrams. The use of these made it simple to show others the way in

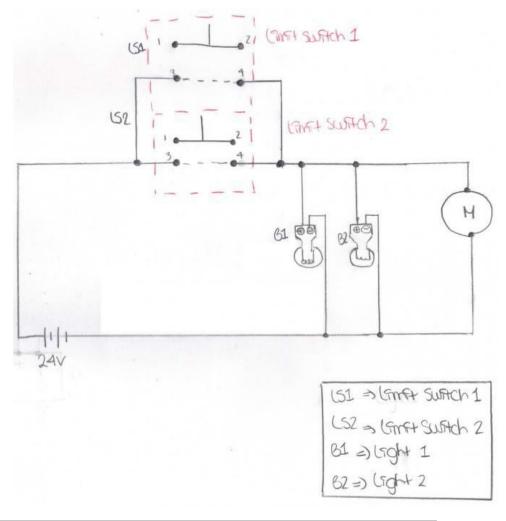
Continued from page (UFI) TO OUV.
EMED = 0 = (Fg=8m) + (Fg=2,8253m)+ (21,84,848)2N=4,590
FC and = 39, 997. 34953N
$F_C = M U^2$
39,972,34953N= 5,059,09091kg)(UZ)
U= 2.60000 mys (3000 ytem x ms) U= 5.81805 mph
So at the point where ma info assuming after all of sets constant the contribet would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the sorthist would be turning at 5 the constant the constant the sorthist would be turning at 5 the constant
=) If I am garing to place a soull limit on the weight itself to
500 bs (16g) = [227.24273 kg]
F=ma F= (260 (221, 212736) (9.81 M/S)
F=1,50 E= 2,229,54556N
The difference between to and for it there were to be a 400 60 500 165 Weight would be 2, 229. 545460 N
F FO = difference F (2,229,54546N) + (2,229,54546N) F 24,814, 319,2N+ 1,50.68182N
(fc= 21041-38031N)
F _C =MU ² 24,044,38(687 N = (5,058,0909/19) U ² (5,058,0909/19) U ² (5,058,0909/19) U ² (6,058,0909/19) U ² (7,058,0909/19) U ² (8,059,0909/19) U ²

which the stability system was designed to be wired using the limit switches. These schematics were reviewed by Bruce Campbell, an Electrical Contractor for the Chase Electric Company Inc.

Continued from page 116 U= 2,13911m/c U= 4,78609 mph Soft the throttle back was placed of would need to slow down the forefield of 425009 mph of mmediately along with the weight to counterbolance the centripetal force and balance the foreliff. = Now IF I were to use the indiculse cultimer as the solution I need to determine the uninformation the minimum SIZE regulated. where P= 2,275 15T (awk/10mg P= Force Function, Area Agsure letter 500 lbm = 500 lbx (19,98) P = Force 1=(20A5Om) V2=.52809 m) The smallest size piston for a hydrolle cylinder I know from learning hydroulicis in frinciples of Engineering is 1/2 %.
This & I fount larger by . Ozg.



(Picture of above schematic was copied from the 05/02/1



(Picture of above schematic was copied from the 05/02/13 entry of [reducted student name] Engineering Notebook.)