

# THE LAPLACE-DE RHAM OPERATOR ON A RIEMANNIAN MANIFOLD

JEFFREY JIANG

In  $\mathbb{R}^2$ , we know about the standard Laplace operator on  $C^\infty(\mathbb{R}^2)$

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

In a more general setting, let  $(M, g)$  be a Riemannian manifold. We can define an analogous operator

$$\Delta = \operatorname{div}(\operatorname{grad} f)$$

In local coordinates  $(x^i)$ , we have that for  $f \in C^\infty(M)$  and  $X \in \mathfrak{X}(M)$

$$\begin{aligned} \operatorname{grad} f &= g^{ij} \frac{\partial f}{\partial x^i} \frac{\partial}{\partial x^j} \\ \operatorname{div} X &= \frac{1}{\sqrt{\det g_{ij}}} \frac{\partial}{\partial x^i} \left( (X^i \sqrt{\det g_{ij}}) \right) \end{aligned}$$

Where  $g_{ij}$  is the symmetric matrix given by  $g_{ij} = \langle \partial_i, \partial_j \rangle$  and  $g^{ij}$  is the inverse of  $g_{ij}$ . This gives the coordinate formula for

$$\Delta f = \frac{1}{\sqrt{\det g_{ij}}} \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g_{ij}} \frac{\partial f}{\partial x^j} \right)$$

Which using the standard metric  $g_{ij} = \delta_{ij}$  on  $\mathbb{R}^2$  recovers the standard Laplacian. However, we want to generalize  $\Delta$  to arbitrary differential forms, which requires us to construct a bit of machinery.

To do this, we first note that the metric  $g$  determines an inner product on each tangent space  $T_p M$  where  $\langle v, w \rangle = g_p(v, w)$ . From this, we can construct an inner product on the alternating tensors  $\Lambda^k(T_p M)$ , which will give us a smoothly varying inner product on  $\Omega^k(M)$ . To do this, we will use the fact that  $g$  determines a bundle isomorphism  $TM \rightarrow T^*M$  via the mapping  $(x, v) \mapsto (x, \langle v, \cdot \rangle)$ .

**Proposition 1.1.** *For a Riemannian manifold  $(M, g)$ , there is a unique inner product on each  $\Lambda^k(T_p M)$  characterized by the formula*

$$\langle \omega^1 \wedge \dots \wedge \omega^k, \eta^1 \wedge \dots \wedge \eta^k \rangle = \det \left( \langle (\omega^i)^\sharp, (\eta^j)^\sharp \rangle \right)$$

Where  $\sharp$  is the index raising operator  $\omega_i dx^i \mapsto g^{ij} \omega_j \frac{\partial}{\partial x^i}$ .

*Proof.* We define the inner product locally in terms of an orthonormal frame  $E_i$ , and show that it is independent of the choice of frame. Let  $\varepsilon^i$  denote the coframe to  $E_i$ . We first claim that the set of  $\varepsilon^I$  where  $I$  is a strictly increasing multi-index of length  $k$  form an orthonormal basis. To see this, we compute

$$\langle \varepsilon^I, \varepsilon^J \rangle = \det(E_{i_k}, E_{j_\ell})$$

We note that this is 1 if and only if  $I = J$ , since then the matrix we are taking the determinant of is  $\operatorname{id}_{\mathbb{R}^k}$ , otherwise,  $I$  contains some  $i_k$  not in  $J$ , which implies the  $k^{\text{th}}$  row of the matrix is 0, so the determinant is 0. This then defines an inner product by extending linearly to arbitrary  $k$ -forms.

To show that this is independent of our choice of frame, let  $B_i$  be another orthonormal frame with coframe  $\beta^i$ . Then we know that  $B_i = A_i^j E_j$  with smooth functions  $A_i^j$  forming an orthogonal matrix every point. We

then compute

$$\begin{aligned}\langle \beta^I, \beta^J \rangle &= \det \langle B_{i_k}, B_{j_\ell} \rangle \\ &= \det \langle A_{i_k}^j E_j, A_{j_\ell}^p E_p \rangle\end{aligned}$$

Noting that  $A_{i_k}^j E_j$  is just the  $i_k^{\text{th}}$  column of the matrix  $A$ , we have that this is equal to  $\det \langle A_{i_k}, A_{j_\ell} \rangle$ . Again, if  $I = J$ , this is just the identity matrix, but if  $I \neq J$ , there will be a row of zeroes in the matrix  $\langle A_{i_k}, A_{j_\ell} \rangle$ , so the determinant will be 0. This shows that  $\langle \cdot, \cdot \rangle$  is uniquely characterized. ■

*Remark.* One observation is that the Riemannian volume form  $dV_g$  is the unique  $n$ -form on  $M$  with norm 1.

We can then use this inner product to produce an important operator. Recall that given a function  $f \in C^\infty(M)$ , we can define the integral of  $f$  over  $M$  by integrating the  $n$ -form  $f dV_g$ , which is a bundle homomorphism  $\Omega^0(M) \rightarrow \Omega^n(M)$ . We can generalize this to arbitrary  $k$  forms.

**Proposition 1.2.** *For every  $k \in \{0, \dots, n\}$ , there exists a unique bundle homomorphism*

$$\star : \Omega^k(M) \rightarrow \Omega^{n-k}(M)$$

*called the **Hodge star operator** such that for any  $\omega, \eta \in \Omega^k(M)$ , we have that  $\omega \wedge \star \eta = \langle \omega, \eta \rangle dV_g$  where  $dV_g$  is the Riemannian volume form. The  $n - k$ -form  $\star \omega$  is often referred to as the **Hodge dual** to  $\omega$*

*Proof.* We first prove uniqueness. Let  $\varepsilon^I$  be the coframe to an orthonormal basis  $E_i$ . Then for an increasing index set  $I$  of length  $k$ , we have that  $\star$  must satisfy

$$\varepsilon \wedge \star \varepsilon^I = dV_g$$

Therefore, we must have that  $\star \varepsilon^I = \pm \varepsilon^J$ , where  $I \cup J = \{1, \dots, n\}$  and  $J$  is an increasing index and the sign are chosen such that when we permute  $I$  and  $J$  to be in increasing order, the sign chosen for  $\star \varepsilon^I$  cancel the ones that come from the permutation, since otherwise,  $\varepsilon \wedge \star \varepsilon^I = 0$ . This uniquely characterizes  $\star$  on a basis, so it uniquely extends linearly to  $\Omega^k(M)$ . ■

One observation we make is that  $\star \star \varepsilon^I = (-1)^{k(n-k)} \varepsilon^I$ , which can be verified by shuffling the wedge products and carefully tracking signs. This extends to all  $k$ -forms, so  $\star \star \omega = (-1)^{k(n-k)} \omega$ . Another observation is that this determines a bundle isomorphism  $\Omega^k(M) \rightarrow \Omega^{n-k}(M)$ , since it maps an orthonormal basis to an orthonormal basis.

**Example 1.3.** In  $\mathbb{R}^n$  with the standard coordinates  $x^i$  and the standard metric tensor  $g_{ij} = \delta_{ij}$ , we have that the  $dx^i$  form an global orthonormal frame for  $\mathbb{R}^n$ . Given any  $dx^i$ , we have that

$$\star dx^i = (-1)^{i-1} dx^1 \wedge \dots \wedge \hat{dx}^i \wedge \dots \wedge dx^n$$

Where  $\hat{dx}^i$  indicates that  $dx^i$  is missing from the wedge product. The sign comes from the fact that

$$dx^i \wedge dx^1 \wedge \dots \wedge \hat{dx}^i \wedge \dots \wedge dx^n = (-1)^{i-1} dx^1 \wedge \dots \wedge dx^n$$

**Example 1.4.** For  $\mathbb{R}^5$ , consider  $\star \star dx^1 \wedge dx^3$ . We first compute

$$\begin{aligned}\star dx^1 \wedge dx^3 &= -dx^2 \wedge dx^4 \wedge dx^5 \\ \star \star dx^1 \wedge dx^3 &= \star -dx^2 \wedge dx^4 \wedge dx^5 = dx^1 \wedge d^3\end{aligned}$$

Finally, we can use the Hodge star to define yet another operator

**Definition 1.5.** Let  $(M, g)$  be a compact oriented Riemannian manifold. Then the *codifferential*  $\delta$  (also denoted in the literature by  $d^*$ ) is a map

$$\begin{aligned}\delta : \Omega^k(M) &\rightarrow \Omega^{k-1}(M) \\ \delta \omega &= (-1)^{n(k+1)+1} \star d \star \omega\end{aligned}$$

Where  $\delta$  is defined on  $\Omega^0(M) = C^\infty(M)$  by  $\delta f = 0$  for all smooth functions  $f$ .

**Proposition 1.6.** *The codifferential  $\delta$  on a Riemannian manifold  $(M, g)$  without boundary satisfies the following properties:*

- (1)  $\delta^2 = 0$
- (2) For  $\omega, \eta \in \Omega^k(M)$ , let

$$(\omega, \eta) = \int_M \langle \omega, \eta \rangle dV_g$$

Then for  $\omega \in \Omega^k(M)$  and  $\eta \in \Omega^{k-1}(M)$ , we have that

$$(\delta\omega, \eta) = (\omega, d\eta)$$

where  $d$  is the exterior derivative. In this way, we see that  $\delta$  is the **adjoint** of  $d$  with respect to the inner product, justifying the name **codifferential**.

*Proof.* (1) We have that

$$\begin{aligned} \delta^2 &= (-1)^{n(k+1)+1} \delta \star d \star \\ &= (-1)^{n(k+1)+1} (-1)^{nk+1} \star d \star \star d \star \end{aligned}$$

We note that  $\star \star = (-1)^{k(n-k)} \text{id}_{\Omega^k(M)}$ , so this simplifies to

$$(-1)^p \star d d \star = 0$$

Since  $d^2 = 0$ .

- (2) We first verify that  $(\cdot, \cdot)$  determines an inner product. We note that it is symmetric since  $\langle \cdot, \cdot \rangle$  is symmetric, and it is also bilinear since integration is linear and  $\langle \cdot, \cdot \rangle$  is as well. All that remains is to show that it is positive definite. We note that it is positive since  $\langle \omega, \omega \rangle$  is positive for all  $\omega$ , so

$$\int_M \langle \omega, \omega \rangle dV_g > 0$$

. In addition, we have that  $\langle \omega, \omega \rangle = 0$  if and only if  $\omega = 0$ , and  $\int_M f dV_g = 0$  if and only if  $f = 0$ . Therefore,  $(\cdot, \cdot)$  is positive definite, so it defines an inner product on  $\Omega^k(M)$ .

We note that by how we've defined the  $\star$  operator, the inner product is given by the equivalent definition for  $\xi, \alpha \in \Omega^k(M)$

$$(\xi, \alpha) = \int_M \xi \wedge \star \alpha$$

Therefore, we wish to prove the equivalent statement that for  $\omega \in \Omega^k(M)$  and  $\eta \in \Omega^{k-1}(M)$

$$\int_M \delta\omega \wedge \star \eta = \int_M \omega \wedge \star d\eta$$

Then using symmetry of the inner product, this is equivalent to the statement

$$\int_M \eta \wedge \star \delta\omega = \int_M d\eta \wedge \star \omega$$

We then compute

$$\begin{aligned} d\eta \wedge \star \omega - \eta \wedge \star \delta\omega &= d\eta \wedge \star \omega - (-1)^{n(k+1)+1} \eta \wedge \star \star d \star \omega \\ &= d\eta \wedge \star \omega - (-1)^{n(k+1)+1} (-1)^{(n-k+1)(n-(n-k+1))} \eta \wedge d \star \omega \\ &= d\eta \wedge \star \omega + (-1)^{-k^2+1} \eta \wedge d \star \omega \\ &= d\eta \wedge \star \omega + (-1)^{k-1} \eta \wedge d \star \omega \\ &= d(\eta \wedge \star \omega) \end{aligned}$$

Where we use the fact that  $-k^2 + 1$  has the opposite parity of  $k$ , and that  $d$  is an antiderivation on  $\Omega(M)$ . Therefore, we have by Stokes' Theorem

$$\int_M d\eta \wedge \star \omega - \eta \wedge \star d\omega = \int_M d(\eta \wedge \star \omega) = \int_{\partial M} \eta \wedge \star \omega = 0$$

Which gives us that

$$(\delta\omega, \eta) = (\omega, d\eta)$$

Finally, we have the necessary tools to define the fabled **Laplace-de Rham Operator** (Also known as the **Laplace-Beltrami Operator**. ■

**Definition 1.7.** On a oriented compact Riemannian manifold  $(M, g)$ , define the **Laplace-de Rham Operator**, denoted  $\Delta$ , as the family of maps  $\Omega^k(M) \rightarrow \Omega^k(M)$  such that

$$\Delta = \delta d + d\delta$$

A  $k$ -form  $\omega$  satisfying  $\Delta\omega = 0$  is called **harmonic**.

**Proposition 1.8.** The Laplace-de Rham operator agrees with (up to sign) to the Laplacian on  $C^\infty(M)$

*Proof.* We have that for  $f \in C^\infty(M)$  (letting  $\Delta$  denote the Laplace-de Rham operator)

$$\Delta f = d\delta f + \delta df = \delta df$$

Since we defined  $\delta$  to be 0 on  $\Omega^0(M) = C^\infty(M)$ . We then have that  $\delta df = -\star d\star df$ . We first compute  $\star df$ , which is the  $n-1$ -form satisfying

$$df \wedge \star df = \langle df, df \rangle dV_g$$

. Noting that  $df^\sharp = \text{grad } f$ , we compute

$$\begin{aligned} \langle \text{grad } f, \text{grad } f \rangle dV_g &= \frac{\partial f}{\partial x^i} dx^i \left( g^{jk} \frac{\partial f}{\partial j} \frac{\partial}{\partial x^k} \right) dV_g \\ &= g^{ij} \frac{\partial f}{\partial x^i} \frac{\partial f}{\partial x^j} dV_g \\ &= \sqrt{\det g} \left( g^{ij} \frac{\partial f}{\partial x^i} \frac{\partial f}{\partial x^j} dx^1 \right) \wedge \dots \wedge dx^n \end{aligned}$$

Therefore, we conclude that

$$\star df = (-1)^{i-1} \sqrt{\det g} \left( g^{ij} \frac{\partial f}{\partial x^j} \right) dx^1 \wedge \dots \wedge \hat{dx}^i \wedge \dots \wedge dx^n$$
■

We then compute  $d\star df$  to be

$$\begin{aligned} d\star df &= (-1)^{i-1} \frac{\partial}{\partial x^k} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right) dx^k \wedge dx^1 \wedge \dots \wedge \hat{dx}^i \wedge \dots \wedge dx^n \\ &= \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right) dx^1 \wedge \dots \wedge dx^n \\ &= \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right) dV_g \end{aligned}$$

We then have that  $\star d\star df$  must satisfy  $d\star f \wedge \star d\star df = \langle d\star f, d\star f \rangle dV_g$ . We then compute

$$\begin{aligned} &\left\langle \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right) dV_g, \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^k} \left( g^{kl} \sqrt{\det g} \frac{\partial f}{\partial x^l} \right) dV_g \right\rangle dV_g \\ &= \frac{1}{\det g} \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right) \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^k} \left( g^{kl} \sqrt{\det g} \frac{\partial f}{\partial x^k} \right) dV_g \end{aligned}$$

Where we use the fact that  $\langle dV_g, dV_g \rangle = 1$ . Therefore, we conclude that

$$\delta df = -\star d\star f = -\frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^i} \left( g^{ij} \sqrt{\det g} \frac{\partial f}{\partial x^j} \right)$$

Due to our choice of sign convention, this is unfortunately the negative of the the original Laplacian we had. Some sign conventions define  $\Delta f = -\text{div}(\text{grad } f)$  for this reason.