


Random Experiment, Sample Space, Event, & Probability

Random Experiment: Activity, process, or experiment whose outcome is uncertain

Sample Space: Set of all possible outcomes of experiment:

$S_{\Omega} = \{w_1, w_2, \dots\}$ Properties: (finite/infinite, continuous/not continuous, ...)

It can be either finite or infinite kind of outcome, and outcomes can be continuous or not as well.

Event: Collection (subset) of outcomes contained in the sample space S_{Ω}

Simple: contains only one outcome

Compound: is consisted of more than one outcome

$$A = \{ \dots \} \text{ and } A \subseteq S_{\Omega}$$

Head of event, denoted as capital letters

Probability: the proportion of event A occurring, written as $P(A)$

Can be seen as a function

$$P: A \rightarrow [0, 1]$$

↑
sample
space of S_{Ω}

Relative Frequency interpretation of probability

Let A be an event associated with some random experiment.

The proportion of A occurrence (under infinite tracking of experiment) is probability of A, written as

$$P(A)$$

Remark: This is the relative frequency interpretation of probability, which says that the probability of event is equal to its relative frequency in a large number of trials.

Limitations on the relative frequency interpretation of probability:

- ① One cannot actually repeat an experiment infinity many times
- ② To define probability carefully, we need to take a formal, axiomatic, mathematical approach

Lec 2 Preview

Discrete sample space:

We say a sample space is discrete if it is either finite or countably infinite

Countably infinite

A set is countably infinite if the elements of the set can be arranged as a sequence

Remark: and all countably infinite sets can be put in one-to-one correspondence with natural number (as they are sequence)

Assuming sample sets discussed are discrete, which means it can be written in

$$S_L = \{w_1, w_2, \dots, w_n\} \text{ or}$$

$$S_L = \{w_1, w_2, \dots\}$$

Properties of probabilities and event operations

Event operators: or, and, not

Set operators: union, intersection, complement

Set terminologies and notations:

Capital letters: Set

A set consists of $a_1, a_2, a_3: A = \{a_1, a_2, a_3\}$

S : denotes the universal set which is the set of all possible objects

\emptyset : denotes as null or empty set ($\emptyset = \{\}$), a set without any object

Subset:

For two set A, B ,

If every object in A is in B ,

Then A is a subset of B , denoted $A \subseteq B$

Hint: \emptyset is subset of every set

Union:

The union of A and B is the set that all objects are in A or B .

Denoted: $A \cup B$

Intersection:

The intersection of A and B is the set that all objects are in both A and B
Denoted: $A \cap B$

Complement:

If A is a subset of S , then complement of A is the set of all object in S that is not in A .

Denoted: A^c

Hint: $A^c \cup A = S$

$A^c \cap A = \emptyset$

Disjoint:

Two sets A and B are said to be disjoint or mutually exclusive if they have no element in common:

If $A \cap B = \emptyset$

Then A and B are disjoint

Independent:

Two events are independent if occurrence of one event does not alter the probability of occurrence of the other in any way.

Logic as set operators (symbolization from sentence to set)

Important laws for set operators:

Common:

$$A \cap B = B \cap A$$

$$A \cup B = B \cup A$$

Associate:

$$(A \cup B) \cup C = A \cup (B \cup C)$$

$$(A \cap B) \cap C = A \cap (B \cap C)$$

Distribution:

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

DeMorgan's laws

$$(A \cup B)^c = A^c \cap B^c$$

$$(A \cap B)^c = A^c \cup B^c$$

DeMorgan's laws general:

$$(\bigcup_{i=1}^n A_i)^c = \bigcap_{i=1}^n A_i^c$$

$$(\bigcap_{i=1}^n A_i)^c = \bigcup_{i=1}^n A_i^c$$

Probability functions

In random experiment with sample space S_L , the probability of an event A , denoted as $P(A)$ is a function assigned to event A a numerical value that chance that event A will occurs.

Three axioms:

$$\textcircled{1} P(A) \geq 0$$

$$\textcircled{2} P(S_L) = 1$$

\textcircled{3} For a set of disjoint event A_1, A_2, \dots, A_n in S_L

Probability Function:

Given a random experiment with discrete sample space Ω , a probability function P is a function on Ω with following properties:

- $P(w) \geq 0$, for all $w \in \Omega$ always non-negative
- $\sum_{w \in \Omega} P(w) = 1$ sum of all event is 1
- For all events $A \in \mathcal{F}_\Omega$, $P(A) = \sum_{w \in A} P(w)$ (the probability of A is sum of all its event probability)

Probability on discrete sample space:

For finite sample space $\Omega = \{w_1, \dots, w_k\}$

$$\text{Then } \sum_{w \in \Omega} P(w) = P(w_1) + \dots + P(w_k) = 1$$

For countable infinite sample space $\Omega = \{w_1, \dots\}$

$$\sum_{w \in \Omega} P(w) = \sum_{i=1}^{\infty} P(w_i) = 1$$

Properties of probability function: additive law

Thm: The additive law of probability. (Inclusive-Exclusive Principle)

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

Thm: The additive law of probability: general case

$$\begin{aligned} P(\bigcup_{i=1}^n A_i) &= \sum_{i=1}^n P(A_i) - \sum_{i,j} P(A_i \cap A_j) + \dots \\ &\quad + (-1)^{n+1} \sum_{i_1 < i_2 < \dots < i_n} P(A_{i_1} \cap A_{i_2} \cap \dots \cap A_{i_n}) + \\ &\quad (-1)^{n+1} P(A_{i_1} \cap A_{i_2} \cap \dots \cap A_{i_n}) \end{aligned}$$

Thm: Addition rule for mutually exclusive events

If A and B are mutually exclusive, then

$$P(A \text{ or } B) = P(A \cup B) = P(A) + P(B)$$

$$\text{since } P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

for mutually exclusive set A, B , $P(A \cup B) = P(A) + P(B)$

$$\text{then } P(A \cap B) = \emptyset$$

Thm: The Complement rule:

for an event A
 $P(A) = 1 - P(A^c)$

Thm: The Hierarchical rule

If A implies B ($A \subseteq B$), then

$$P(A) \leq P(B)$$

Otherwise

$$P(B) < P(A), \text{ then } A \subseteq B \text{ is false}$$

Lec 3 Preview

Thm: Probability as Relative Frequency

$$P(A) = \frac{\# \text{ of outcomes in } A}{\text{total # of outcomes in random experiment}} = \frac{n(A)}{n(\Omega)}$$

Thm: Weak Law of Large Numbers (WLLN)

When you take more and more trials, the sample average gets closer and closer to that long-run probability.

(repeat experiments will reduce randomness)

Thm WLLN, basic form:

Let X_1, X_2, \dots be random variables with finite mean $\mu = E[X_i]$ and finite variance

$\sigma^2 = \text{Var}(X_i) < \infty$, Define the sample mean

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

Then $\bar{X}_n \xrightarrow{P} \mu$

i.e. For $\forall \delta > 0$, $\lim_{n \rightarrow \infty} \Pr(|\bar{X}_n - \mu| > \delta) = 0$

Thm The multiplication principle (Fundamental principle of counting (FPC))

A n -element sequence (a_1, \dots, a_n) have $k_1 \cdot k_2 \cdots k_n$ number of choices.

The total number of possible sequences is

$$\prod_{i=1}^n k_i = k_1 \cdot k_2 \cdots k_n$$