

# CS 153: Concepts of Compiler Design

## November 28 Class Meeting

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San Jose State University



Fall 2017  
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# Extra-Credit Oral Presentations

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- ❑ Let me know if your team would like to do an oral presentation for extra credit.
- ❑ Tell about your language.
  - Show some example programs.
- ❑ Describe its grammar
  - Show syntax diagrams.
- ❑ What Jasmin code do you generate?
  - Show some code diagrams.
- ❑ Demo: Compile, execute, and run some sample programs.

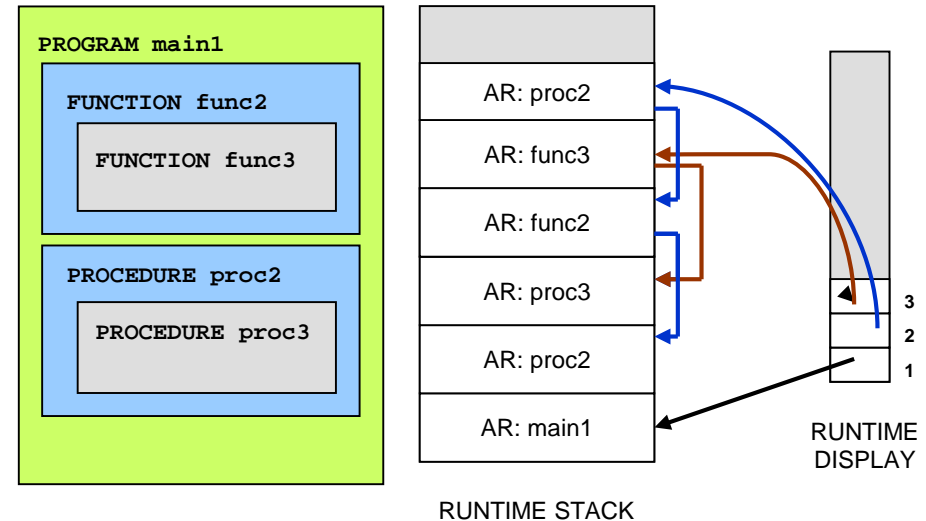
# Extra-Credit Oral Presentations, *cont'd*

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- Submit a note by Friday, Dec. 1 into Canvas: [Assignments | Miscellaneous | Presentation](#) if your team wants to present.
  - Choose either Dec. 5 or 7 to present.
- 15-20 minutes.
- Can add up to 50 points to each team member's total assignment score.

# Static Scoping

- ❑ Pascal uses **static (lexical) scoping**.
- ❑ Scopes are determined at compile time by how the routines are nested in the source program.



main1 → proc2 → proc3 → func2 → func3 → proc2

- ❑ At runtime, variables are “**bound**” to their values as determined by the lexical scopes.
- ❑ The runtime display helps do the bindings.

# Static Scoping in Java

- What value is returned by calling function `g()`?

```
int x = 0;  
int f() { return x; }  
int g() { int x = 1; return f(); }
```

What is the binding  
of this `x` with  
**static scoping**?

# Dynamic Scoping

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- ❑ With **dynamic scoping**, runtime binding of variables to their values is determined by the call chain.
- ❑ To determine a variable's binding, search the call chain backwards starting with the currently active routine.
- ❑ The variable is bound to the value of the first declared variable found with the same name.

# Hypothetical Dynamic Scoping in Java

- What value is returned by calling function `g()`?

```
int x = 0;  
int f() { return x; }  
int g() { int x = 1; return f(); }
```

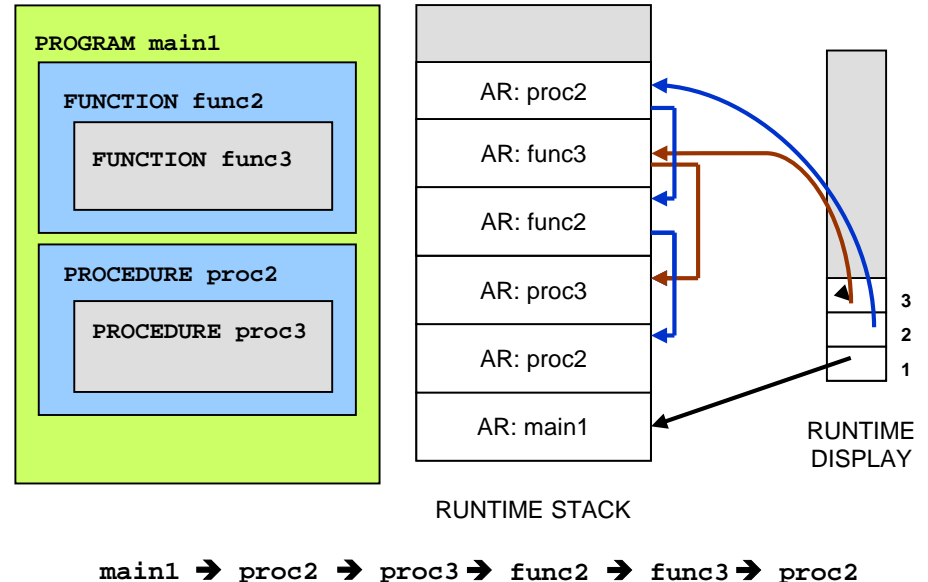
- Call chain: `main` → `g` → `f`

How would you implement runtime dynamic scoping?

# Runtime Memory Management

- In the “Pascal Virtual Machine”, all local data is kept on the runtime stack.

- All memory for the parameters and variables declared locally by a routine is allocated in the routine's activation record.



- The memory is later automatically deallocated when the activation record is popped off the stack



# Runtime Memory Management, *cont'd*

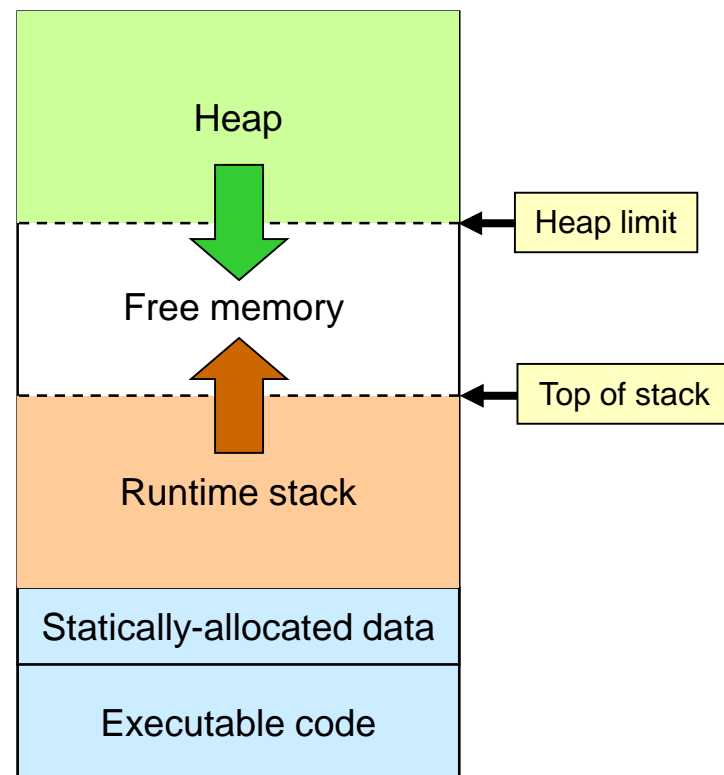
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- What about dynamically allocated data?
- Memory for dynamically allocated data is kept in the “heap”.

# Runtime Memory Management, *cont'd*

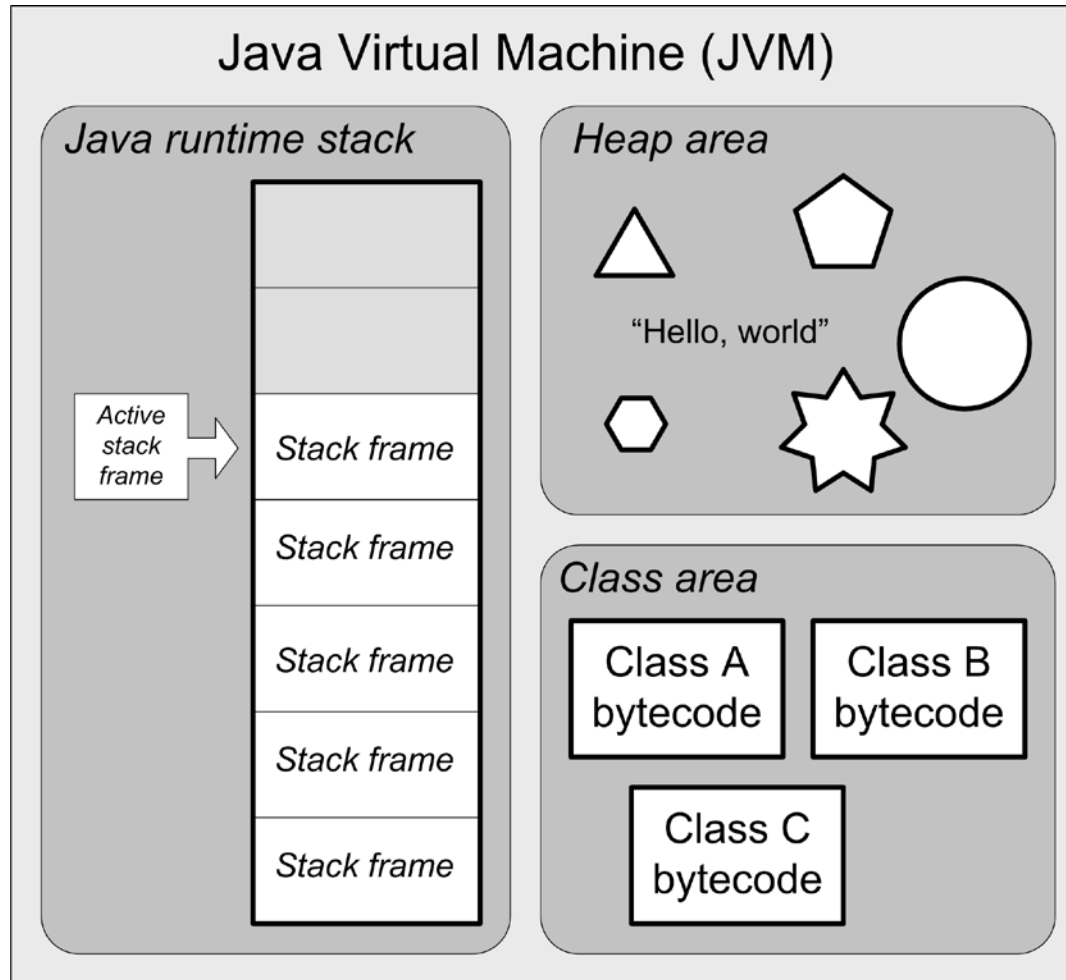
□ Runtime memory can be divided into four partitions:

1. Static memory
  - executable code
  - statically-allocated data
2. Runtime stack
  - activation records that contain locally-scoped data
3. Heap
  - dynamically-allocated data
  - such as Java objects
4. Free memory



Avoid: **Heap-stack collision**  
(Out of memory error)

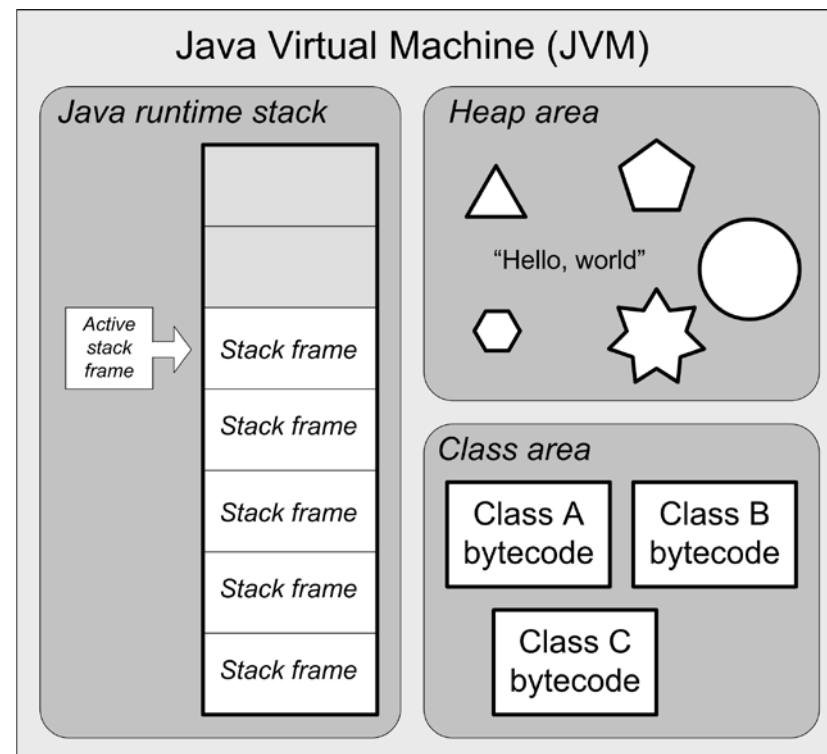
# Recall the JVM Architecture ...



# Java Command-Line Arguments

□ **java -Xms<size> -Xmx<size>**

- **ms**: initial heap size
- **mx**: maximum heap size
- **<size>**: size in megabytes (**m|M**) or gigabytes (**g|G**)



- Example: **java -Xms512M -Xmx2G HelloWorld**

# Runtime Heap Management

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- Handled by language-specific runtime routines.
- Pascal, C, and C++
  - Call **new/malloc** to allocate memory.
  - Call **dispose/free** to de-allocate.
- Java
  - Call **new** to allocate memory.
  - Set the initial and maximum heap size using the **-Xms** and **-Xmx** options.
  - **Automatic garbage collection.**

# Runtime Heap Management, *cont'd*

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- ❑ Keep track of all allocated blocks of memory and all free blocks.
- ❑ Free blocks are “holes” caused by freeing some of the dynamically allocated objects.

# Runtime Heap Management, *cont'd*

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- When a new block of memory needs to be allocated dynamically, where should you put it?
- You can allocate it at the end of the heap, and thereby expand the size of the heap.
- You can find a hole within the heap that's big enough for the block.

# Runtime Heap Management, *cont'd*

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- ❑ What's the optimal memory allocation strategy?
  - Find the smallest possible hole that the block will fit in.
  - Randomly pick any hole that's big enough.
- ❑ Should you periodically compact the heap to get rid of holes and thereby reduce the size of the heap?
- ❑ If allocated data moves due to compaction, how do you update references (pointers) to the data?



# Garbage Collection

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- Return a block of memory (“garbage”) to unallocated status ...
  - ... when there are no longer any references to it.
- Various algorithms to locate garbage.
  - reference counts
  - mark and sweep
  - stop and copy
  - generational

# Automatic Garbage Collection

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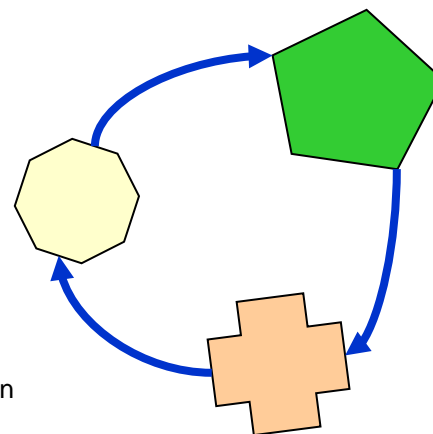
- Automatic garbage collection is great for programmers, because you don't have to think about it.
- But it can slow runtime performance unpredictably.
  - How?

# Garbage Collection: Reference Counts

- Include a counter with each block of allocated memory.
  - Increment the counter each time a pointer is set to point to the block.
  - Decrement the counter whenever a pointer to the block is set to null (or to point elsewhere).
  - Deallocate the block when the counter reaches 0.

- Problem: **Cyclic graphs**

- The reference counts never become 0.



# Garbage Collection: Mark and Sweep

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- Make a pass over the heap to **mark** all allocated blocks of memory that are reachable via pointers.
  - Various marking algorithms.
- Make a second pass to **sweep** (deallocate) blocks that are not marked.

# Garbage Collection: Stop and Copy

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- Partition the heap into two halves.
  - Allocate memory only in one half at a time.
- When an allocation fails to find a sufficiently large block of free memory ...
  - Stop
  - Copy all allocated blocks to the other half of the heap, thereby compacting it.
  - Update all references to the allocated blocks.
    - How do you update pointer values?

# Generational Garbage Collection: Theory

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- Most objects are short-lived.
- Long-lived object are likely to last until the end of the run of the program,

# Generational Garbage Collection: Practice

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- Partition the heap into a **new generation** area and an **old generation** area.
  - Allocate new objects in the new generation area.
  - Keep track of how long an object lives.
  - Once an object lives past a predetermined threshold of time, migrate it to the old generation area.
- The old generation area stays fairly compacted.
- The new generation area needs compacting infrequently.

# Aggressive Heap Management

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- Aggressive heap management means doing garbage collection frequently, even when it's not necessary.
  - There's still adequate free space remaining in the heap area.
- Keep the heap as small as possible.
  - Improve reference locality.
  - Optimize the use of physical memory when multiple programs are running.
  - Reduce virtual memory paging.



# Aggressive Heap Management: Tradeoff

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- ❑ GC operations slow program performance.
- ❑ But paging to disk can be orders of magnitude slower.

# Garbage Collection Research

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- ❑ Entire books have been written about garbage collection.
- ❑ It's still an area with opportunities for research.
- ❑ You can become famous by inventing a better GC algorithm!
- ❑ Maybe some form of **adaptive GC** using machine learning?