Introduction to Machine Learning

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1 Lecture 1

linear function

$$y = f_{\mathbf{W}}(\mathbf{X}) = f(\mathbf{X}, \mathbf{W}) = \mathbf{W}^{\mathrm{T}}\mathbf{X}$$

linear classifier (perception model)

$$\mathbf{x}_i \cdot \mathbf{w} + b \geq 0$$

$$\mathbf{x}_i \cdot \mathbf{w} + b < 0$$

linear regression in 1 dimension

$$y^i = \mathbf{W}^{\mathrm{T}}\mathbf{X}^i + \epsilon^i$$

where ϵ is the noise(loss).

Loss function: sum of squared errors

$$L(\mathbf{W}) = \sum_{i=1}^{N} (\epsilon^i)^2$$

$$L(w_0, w_1) = \sum_{i=1}^{N}$$

$$\frac{\partial L(w_0, w_1)}{\partial w_0} = \sum_{i=1}^{N} \frac{\partial [y^i - (w_0 x_0^i + w_1 x_1^i)]^2}{\partial w_0} = -2 \sum_{i=1}^{N} (y^i - (w_0 x_0^i + w_1 x_1^i)) x_0^i = 0$$

$$\sum_{i=1}^{N} y^i x_0^i = w_0 \sum_{i=1}^{N} x_0^i x_0^i + w_1 \sum_{i=1}^{N} x_1^i x_0^i$$

as follow, the partial gradient of w_1 would be

$$\sum_{i=1}^{N} y^i x_1^i = w_0 \sum_{i=1}^{N} x_0^i x_1^i + w_1 \sum_{i=1}^{N} x_1^i x_1^i$$

Therefore

$$\begin{bmatrix} \sum_{i=1}^{N} y^i x_0^i \\ \sum_{i=1}^{N} y^i x_1^i \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{N} x_0^i x_0^i & \sum_{i=1}^{N} x_0^i x_1^i \\ \sum_{i=1}^{N} x_0^i x_1^i & \sum_{i=1}^{N} x_1^i x_1^i \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} \tag{1}$$

Formally, it could conclude that

$$\mathbf{X}^{\mathrm{T}}\mathbf{y} = \mathbf{X}^{\mathrm{T}}\mathbf{X}\mathbf{w}$$

$$\mathbf{w} = (\mathbf{X}^{\mathrm{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathrm{T}}\mathbf{y}$$

Why the gradient could be equal to 0

Hessian matrix is a square matrix of second-order partial derivatives of scalar-valued function, or scalar field.

$$\mathbf{H}(f) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix} \tag{2}$$

$$\mathbf{H} = \begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial x^2} \end{vmatrix}$$

In the 2 dimension, when $\mathbf{H} > 0$: if $\frac{\partial^2 f}{\partial x^2} > 0$, then point$(x_0, y_0)$ is the local min point. If $\frac{\partial^2 f}{\partial x^2} < 0$, then point$(x_0, y_0)$ is the local max point.

when $\mathbf{H} < 0$, then point(x_0, y_0) is the stationary point.

when $\mathbf{H} = 0$, second order cannot decide the point property, then consider it in higher order Taylor's Expansion.

In the example,$\mathbf{H} = 4(x_0^i)^2(x_1^i)^2 - 4(x_1^i x_0^i)(x_0^i x_1^i) = 0$, and $\frac{\partial^2 f}{\partial x^2} = 4(x_0^i)^2(x_1^i)^2 > 0$. Therefore, it is a local min point for the loss function.

In higher dimension space (multi-variables), $\mathbf{H}(f)$ should be a positive definite matrix($(\nabla \mathbf{x})^{\mathrm{T}}\mathbf{H}(f)\nabla \mathbf{x} \geq 0$ for any $\nabla \mathbf{x}$).

Generalized linear regression

$$L(\mathbf{w}) = \sum_{i=1}^{N} (y^i - \mathbf{w}^{\mathrm{T}}\phi(\mathrm{x}^i))^{\mathrm{T}}$$

where $\phi(\mathbf{x}^i)$ is a polynomial function for $\mathbf{x}^i$