

Existing Tests

test_baseplanes

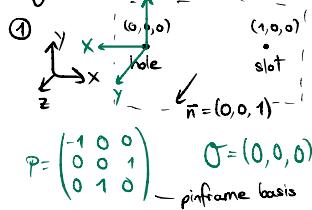
- all functions tested, notable functions: get_base_plane_origin, get_base_plane_normal

test_pins

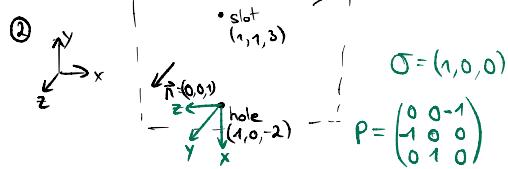
- all functions tested

test_pinframe ✓

- get_basis

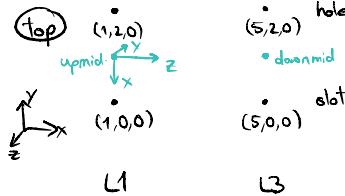


$$\vec{x}_{\text{glob}} = P \vec{x}_{\text{pin}}$$



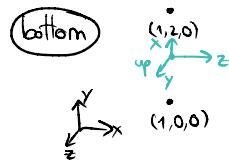
test_ballframe ✓

- get_ballframe



$$O = (1,1,0)$$

$$B = \begin{pmatrix} 0 & 0 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix}$$

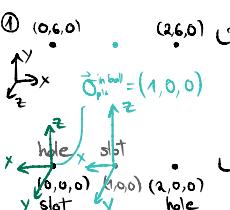


$$O = (1,1,0)$$

$$B = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

test_uchannel ✓

- pin_in_ballframe

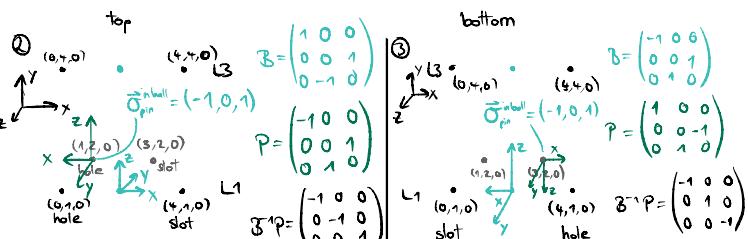


$$B \vec{x}_{\text{ball}} = P \vec{x}_{\text{pin}}$$

$$B = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$B^{-1}P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



test_fixture ✓

- get_ball_basis

$$\mathcal{B}^I = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \sigma = (1, 0, 0)$$

- get_pin_basis

$$\mathcal{P} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \sigma = (1, 1, 0)$$

- get_pin_in_ball

$$\mathcal{B}^I = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \mathcal{B}^{-1} \mathcal{P} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad \sigma = (4, 1, 0)$$

$$\mathcal{P} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

test_mathballframe ✓

- test_get_matt_basis / test_get_basis

top

$$\mathcal{L}^1 \quad \mathcal{B} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

bottom

$$\mathcal{L}^3 \quad \mathcal{B} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \mathcal{M}^{-1} \mathcal{B} = \begin{pmatrix} 0 & 0 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\mathcal{L}^3 \quad \mathcal{B} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \quad \mathcal{M}^{-1} \mathcal{B} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\mathcal{M} \vec{x}_{\text{matt}} = \mathcal{B} \vec{x}_{\text{ball}}$$

→ get basis in Matt coordinates

test_mattfixture ✓

- get_ball_basis

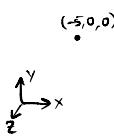
$$\mathcal{B}^I = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \sigma = (1, 0, 0)$$

- get_pin_basis

$$\sigma = (1, 1, 0)$$

$$P = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

- get_matt_basis

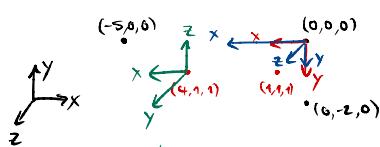


$$H' = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\sigma = (0, 0, 0)$$

Matt measurement

- get_pin_in_ball / get_ball_in_pin



$$B' = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad P = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad H' = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

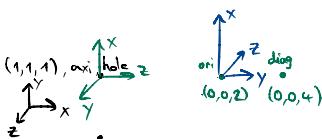
$$B'^{-1}P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad \sigma = (4, 1, 0) \text{ origin of pin in ball}$$

$$P^{-1}B' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \quad \sigma = (-4, 0, 1) \text{ origin of ball in pin}$$

test_shofixture ✓

- test_ball_in_pin / test_pin_in_ball

^{• ori}



$$B' = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$P^{-1}B' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad \text{ball in pin}$$

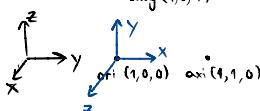
$$\sigma = (0, 0, 2)$$

^{• ori}

test_sensors ✓

- get_ball_basis

^{• diag}



$$\sigma = (1, 0, 0)$$

$$B' = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$P = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B'^{-1}P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \quad \text{pin in ball}$$

$$\sigma = (0, -2, 0)$$

- get_sensor_origin_ballframe

• ori_{ori}
 $(1, 2, 3)$
 $(2, 3, 0)$

$$\vec{\alpha}_s = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \left(\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right) = \mathcal{B}' (\vec{x}_o^{exp} - \vec{x}_{ori}^{exp})$$

- get_sensor_origin_pinframe

$$\mathcal{B}' \vec{x}_{ball} = \mathcal{P} \vec{x}_{pin}$$

$$\mathcal{B}'^{-1} (\vec{\alpha}_s - \vec{\alpha}_{ball}) = \vec{\alpha}_{ball}$$

$$\mathcal{P}'^{-1} \mathcal{B}' (\vec{\alpha}_s^{ball} - \vec{\alpha}_{pin}^{inball}) = \vec{\alpha}_s^{pin}$$

could be
diff. \mathcal{B}' from
above

- get_sensor_normal_ballframe

$$\vec{n}_{ball} = \mathcal{B}'^{-1} \vec{n}_{opp}$$

$$\mathcal{O} = (1, 0, 0) \quad \vec{n} = (0, 1, 0)$$

$$\mathcal{B}' = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \mathcal{B}'^{-1} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

- get_sensor_normal_pinframe

$$\vec{n}_s = (0, 0, 1) \quad \vec{n}_s = (0, 0, 1)$$

$$\mathcal{B}' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\vec{n}_s = (0, 0, 1)$$

$$\mathcal{B}'' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathcal{P} = \begin{pmatrix} +1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\vec{n}_s^{pin} = \underbrace{\mathcal{P}'^{-1} \mathcal{B}' \mathcal{B}''^{-1}}_{\substack{\text{ball in pin} \\ \text{sensor normal}}} \vec{n}_s$$

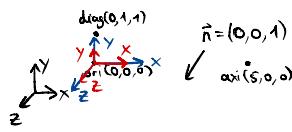
$$\vec{n}_s^{balz} = \mathcal{B}''^{-1} \vec{n}_s \quad \text{sensor normal ballframe}$$

$$\vec{n}_s^{bal1} = \vec{n}_s^{bal2}$$

$$\mathcal{P} \vec{n}_s^{pin} = \mathcal{B}' \vec{n}_s^{bal1} = \mathcal{B}' \mathcal{B}''^{-1} \vec{n}_s$$

test_mattsensor ✓

- get_matt_basis / matt_to_ball



$$M' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

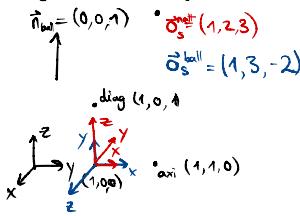
$$B' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \quad \vec{x}^{matt} = B' \vec{x}^{ball}$$

$$\hat{y} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \quad \hat{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \hat{z} = \hat{x} \times \hat{y} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$$

$$M \vec{x}^{matt} = B' \vec{x}^{ball} \Rightarrow \vec{x}^{ball} = B'^{-1} M \vec{x}^{matt}$$

$$B'^{-1} M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$

- get_sensor_origin_ballframe



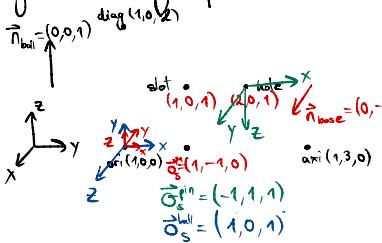
$$\text{matt in ball frame } B'^{-1} M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$M' = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$M \vec{o}_s^{matt} = B' \vec{o}_s^{ball}$$

$$\Rightarrow \vec{o}_s^{ball} = B'^{-1} M' \vec{o}_s^{matt} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix}$$

- get_sensor_origin_pinframe



$$M' = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B' = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$P'^{-1} B' = \begin{pmatrix} 0 & +1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} +1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

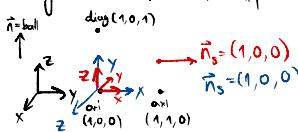
$$\vec{o}_s^{ball} = (2, 1, 0)$$

$$B' \vec{o}_s^{ball} = M' \vec{o}_s^{matt}$$

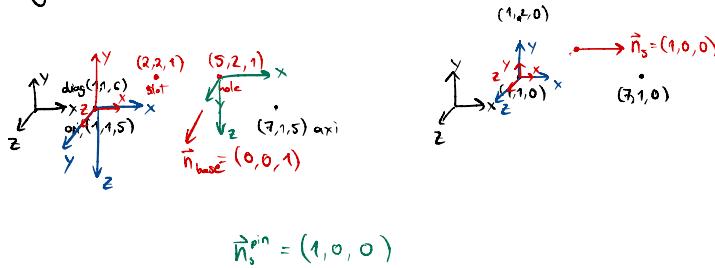
$$\vec{o}_s^{ball} = B'^{-1} M' \vec{o}_s^{matt} \quad \underbrace{\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}}_{\vec{o}_s^{matt}} = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\vec{o}_s^{pin} = (P'^{-1} B') \left(\underbrace{(B'^{-1} M') \vec{o}_s^{matt}}_{\vec{o}_s^{ball} \rightarrow \text{sensor_origin_ballframe}} - \vec{o}_s^{pin \text{ in ball}} \right) = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

- get_sensor_normal_ballframe



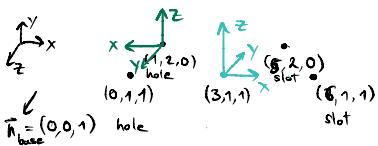
- get_sensor_normal_pinframe



$$\vec{n}_s^{pin} = (1, 0, 0)$$

test_survey

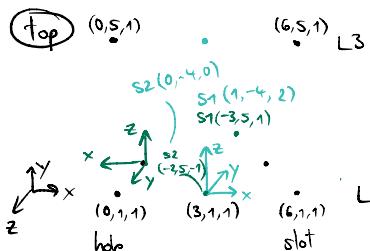
- get_pin_in_uchannel_ballframe



$$P = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B^{-1}P = \begin{pmatrix} -1 & -1 & 1 \end{pmatrix} \quad \text{basis} = (-2, 1, 1)$$

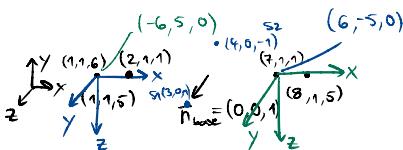
- transform_sensor_to_uchannel_ballframe



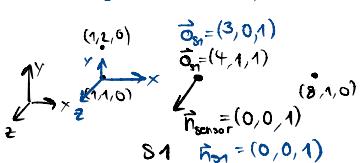
$$P = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B^{-1}P = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{origin } (-2, 1, 1)$$

$$\vec{n}_{s1} = (0, 0, 1) \quad \vec{n}_{s2} = (0, 0, -1)$$

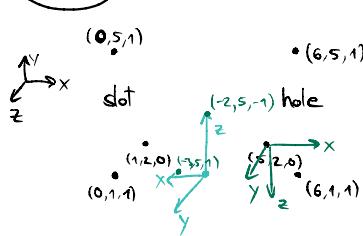


$$\vec{n}_{s1} = (0, 0, 1) \quad \vec{n}_{s2} = (0, 0, -1) \\ \vec{o}_{s1} = (-3, 5, 1) \quad \vec{o}_{s2} = (-2, 5, -1)$$



$$\vec{o}_{s1} = (4, 0, -1) \quad \vec{o}_{s2} = (4, 1, 1) \\ \vec{n}_{sensor} = (0, 0, 1) \quad \vec{n}_{s2} = (0, 0, -1)$$

bottom



$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$B = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\vec{n}_{s_1} = (0, 0, -1)$$

$$\vec{n}_{s_2} = (0, 0, 1)$$

$$\vec{o}_{s_1} = (1, 4, 0)$$

$$\vec{o}_{s_2} = (0, 4, 2)$$

