



# Aircraft Image Classification Project



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# Problem

- ◊ Inspection takes resources.
- ◊ Inspections are tedious and defects can be missed.





# Contents

- ◊ Proposed solution
  - ◊ Convolutional Neural Network
  - ◊ Data Experimentation
  - ◊ Applications
  - ◊ Demonstration
  - ◊ Conclusions
- 



1

# Proposed solution



# Proposed solution

- ◊ Spexi Geospatial provided drone images
  - ◊ We propose image classification using a convolutional neural network (CNN).
  - ◊ Images need preprocessing
  - ◊ Label output for defect vs non-defect?
- 

# Convolutional Neural Network

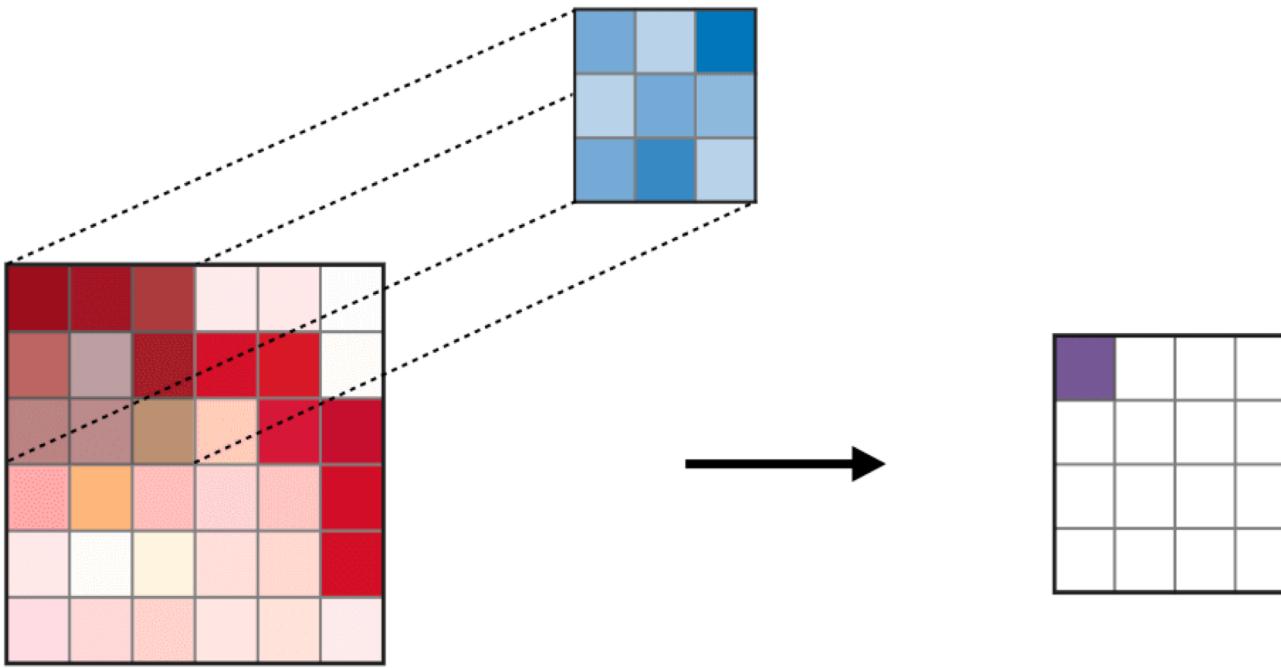
2

# Convolutional Neural Network

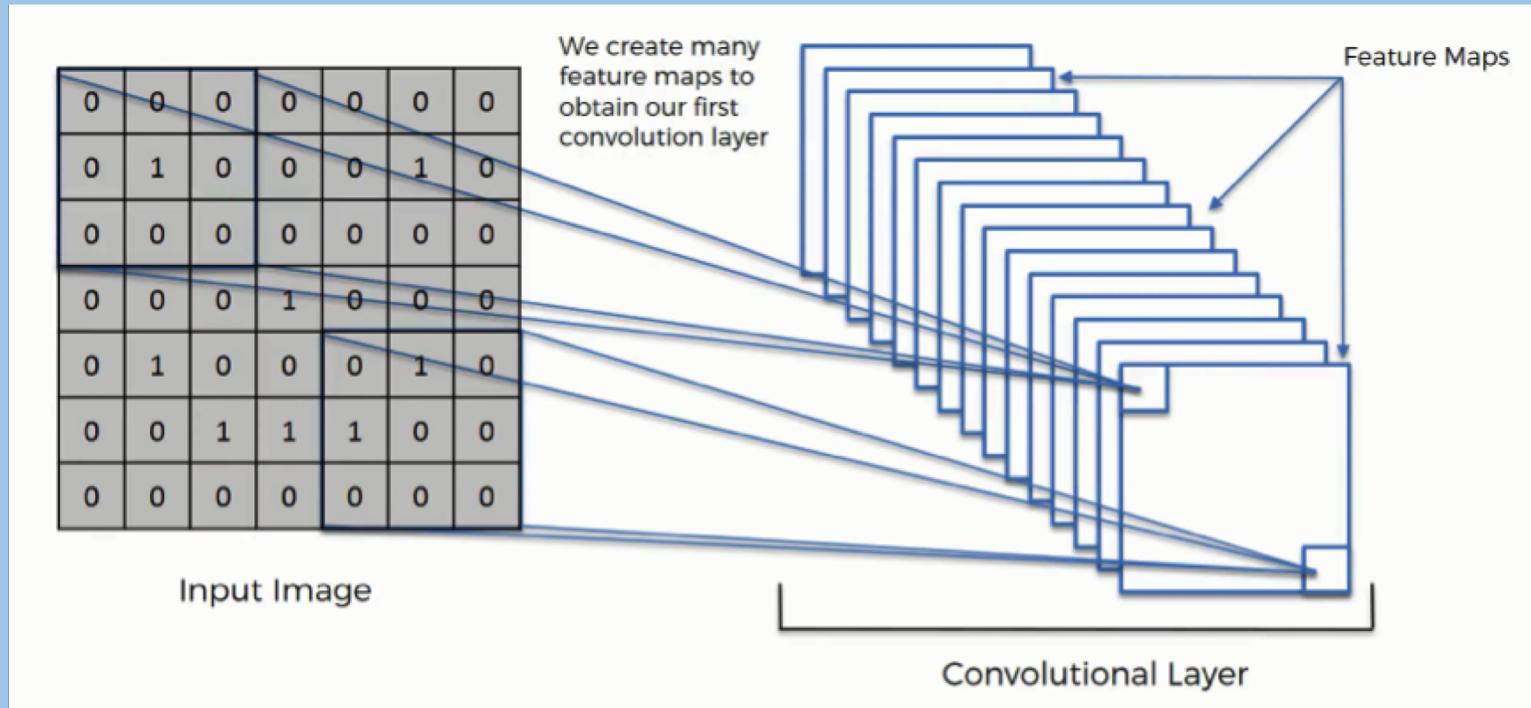
- ◊ A CNN involves multilayer processing to identify images.
- ◊ Input: image, output: prediction
- ◊ Key features:
  - Convolutional layer - detection of features.
  - Softmax layer - mapping of previous input to probabilities



# Convolutional Layer



# Convolutional Layer



# Softmax Layer

Input pixels,  $x$



Feedforward output,  $y_i$

	cat	dog	horse
5	4	2	
4	2	8	
4	4	1	

Forward  
propagation

Shape: (3, 32, 32)

Softmax output,  $S(y_i)$

	cat	dog	horse
0.71	0.26	0.04	
0.02	0.00	0.98	
0.49	0.49	0.02	

Softmax  
function

Shape: (3, )

Shape: (3, )





3

# Data Experimentation



# Initial Data

- ◊ Drone images and spreadsheet labelling defects
  - ◊ Binary classification for cracks
- 

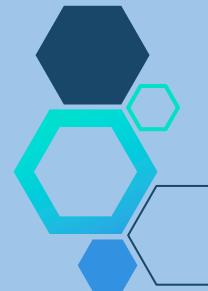
108	DJI_0107	Wing - Right Tip	cracks
109	DJI_0108	Wing - Right Tip	cracks
110	DJI_0109	Wing - Right Tip	cracks
111	DJI_0110	Wing - Right Tip	cracks
112	DJI_0111	Wing - Right Tip	cracks
113	DJI_0112	Wing - Right Tip	cracks
114	DJI_0113	Wing - Right Tip	cracks
115	DJI_0114	Wing - Right Tip	cracks
116	DJI_0115	Wing - Right Tip	cracks
117	DJI_0116	Wing - Right Tip	cracks
118	DJI_0117	Wing - Right Tip	cracks
119	DJI_0118	Wing - Right Tip	cracks
120	DJI_0119	Wing - Right Tip	cracks
121	DJI_0120	Wing - Right Tip	cracks





# Early Identifiable Problem

- ◊ Does not show where the crack is
- ◊ Too many features in the background that could introduce noise into the model.
- ◊ **Solution:** Crop out only the airplane









# Experiment 1

- ◊ Image with background removed.
  - ◊ 800 x 800 pixels, downscaled resolution.
  - ◊ Grayscale to remove color bias.
  - ◊ Images labeled as containing cracks or no cracks.
  - ◊ Training to test ratio: 1:1
- 

# Experiment 1 Input



# Experiment 1 Results

- ◊ Avg. prediction for ‘cracked’ images:  
0.5 (should be 1)
- ◊ Avg. prediction for ‘non-cracked’ images:  
0.19 (should be 0)





# Is it really detecting cracks?

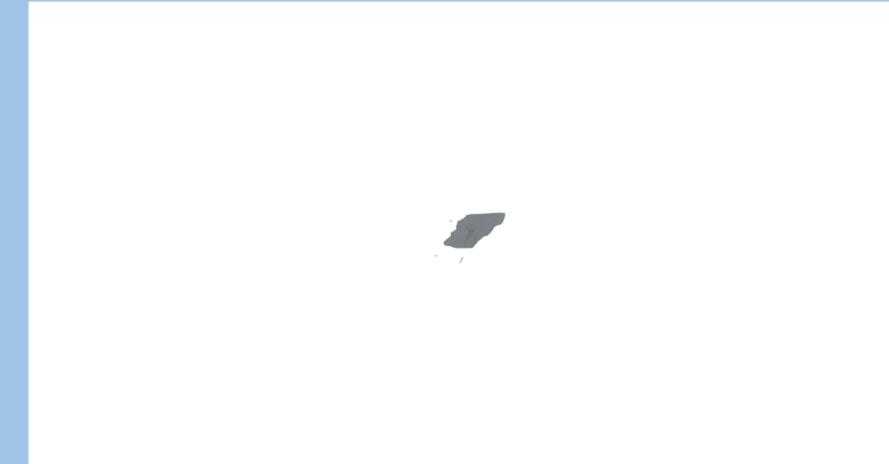
- ◊ Attempted a separate trial with the same model using:
    - Wing with crack as training
    - Same wing with crack removed as test
    - Crack from the wing as test
- 



# Is it really detecting cracks?



Image without crack



Crack by itself



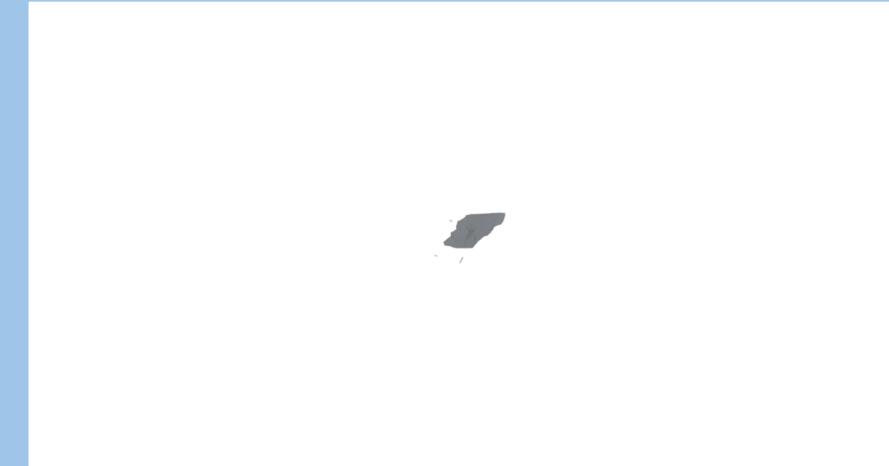


# Is it really detecting cracks?



Image without crack

Result: Crack



Crack by itself  
Crack





# Experiment 1 Conclusion

- ◊ We hypothesized compression of image led to loss of detail.
- ◊ Model looks at plane shape as opposed to features of a crack.
- ◊ Combat this by taking image subdivisions at  $180 \times 180$  pixel.

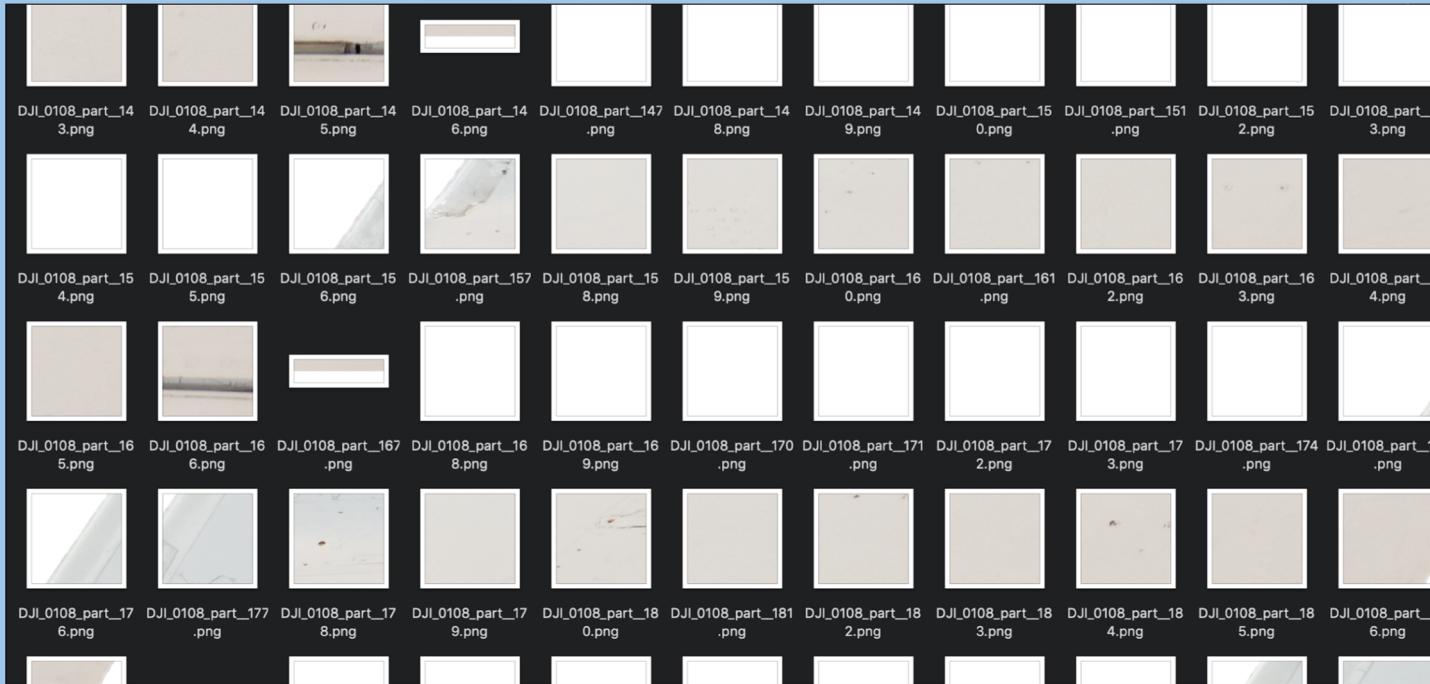




# Experiment 2

- ◊ 120 subimages constructed from original images
  - ◊ 180 × 180 pixels, no compression
  - ◊ Gray scale
  - ◊ Labeled crack, non-crack
  - ◊ Training to test ratio: 3:1
- 

# Experiment 2 Input



# Experiment 2 Results

- ◊ Avg. prediction for ‘cracked’ images:  
0.68 (1)
- ◊ Avg. prediction for ‘non-cracked’ images:  
0.65 (0)
- ◊ All images were being identified as cracked.
- ◊ Difference in prediction: 0.03





# Experiment 2 Conclusion

- ◊ Was the number of images a problem?
- ◊ Proposed increasing sample size for training, test, measuring new results.





# Experiment 3

- ◊ **1900** subimages constructed from original images
  - ◊  $180 \times 180$  pixels, original resolution
  - ◊ Gray scale
  - ◊ Labeled crack, non-crack
  - ◊ Training to test ratio: 3:1
- 

# Experiment 3 Results

- ◊ Avg. prediction for ‘crack’ images:  
0.09 (1)
- ◊ Avg. prediction for ‘non-crack’ images:  
0.02 (0)
- ◊ All images are identified as ‘non-crack’
- ◊ Difference in prediction: 0.07





# Experiment 3 Conclusion

- ◊ Because “non-cracked” was too vague, all images were being identified as non-cracked.
- ◊ For binary classification, the two categories should be concrete and distinct.





# Experiment



- ◊ 180 × 180 pixels, original resolution
  - ◊ Gray scale
  - ◊ Labeled crack, **cat**
  - ◊ Training to test ratio: 3:1
- 

# Experiment Results

- ◊ Avg. prediction for ‘cracked’ images:  
0.49 (1)
- ◊ Avg. prediction for ‘cat’ images:  
0.05 (0)
- ◊ All images were being identified as cat.
- ◊ Difference in prediction: 0.44



# Experiment 🐱 Conclusion

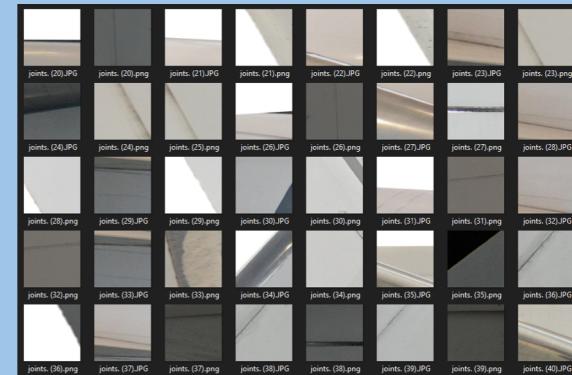
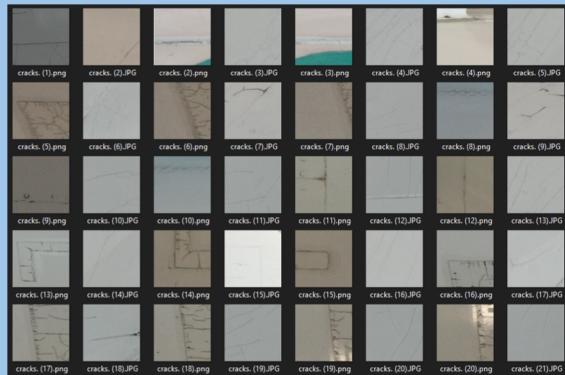
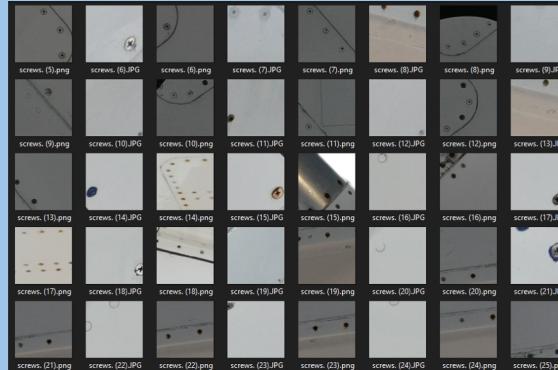
- ◊ The difference in complexity between crack and cat is too dramatic.

# Experiment 5

- ◊ **900** subimages cropped from original images (300 per feature).
- ◊ 180 × 180 pixels, original resolution, gray scale
- ◊ Labeled as:
  - Crack - jagged line.
  - Joint - straight line.
  - Screw - round object.
- ◊ Training to test ratio: 9:1



# Experiment 5 Input





# Experiment 5

- ◊ Categorical instead of binary
    - Example output: [0.12, 0.80, 0.08]
- 



# Experiment 5 Results

- ◊ Manual testing with 19 (180x180) images
  - ◊ Accuracy 42.1%
  - ◊ Most likely to be mistaken as ‘joint’
- 



# Experiment 5 Conclusion

- ◊ The feature ‘joint’ (Straight lines) is too simple
- ◊ It’s time to end this
- ◊ Model refinement





# Model Adjustment

- ◊ To improve model performance, we also increased number of epochs from 10 to 100.
  - ◊ This gives the model more ‘generations’ to learn over, producing a more accurate model.
  - ◊ Tradeoff is computation time.
  - ◊ Used different prediction thresholds for different features.
- 



4

# Applications



# Applications

- ◊ The completed model allows us to identify if a subimage contains a crack, joint, or screw.
  - ◊ Simple:
    - Feed in subimage, get prediction
  - ◊ More complex:
    - Feed in full image, get image “heatmap”
    - Each 180x180 subregion has been identified as crack, joint, screw.
- 



5

# Demonstration



6

# Conclusion



# Results

- ◊ Model was influenced by background, level of detail, quality of features.
  - ◊ Our best model - Experiment 5 gave results:
    - Able to extract accuracy = 42.1%
- 



# Insights Gained

- ◊ Data is very important!
    - Need enough data
    - Data should be correctly labeled
  - ◊ Labels should be intelligently selected
    - Labels should be distinct
    - Labels should be well defined
    - There should be enough images for each label
- 



# Is there a solution?

- ◊ Based on the data presented, and the nature of defects on aircraft, we do NOT believe there is a CNN solution to detecting aircraft defects.





# Thanks!

## Any questions?





# References

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