CPE301 - SPRING 2018

Design Assignment MIDTERM

DO NOT REMOVE THIS PAGE DURING SUBMISSION:

The student understands that all required components should be submitted in complete for grading of this assignment.

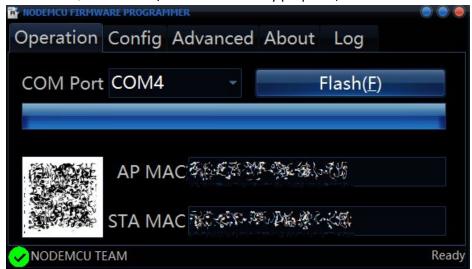
NO	SUBMISSION ITEM	COMPLETED (Y/N)	MARKS (/MAX)
1	COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS		
2.	INITIAL CODE OF TASK 1/A		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 2/B		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 3/C		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 4/D		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 5/E		
4.	SCHEMATICS		
5.	SCREENSHOTS OF EACH TASK OUTPUT		
5.	SCREENSHOT OF EACH DEMO		
6.	VIDEO LINKS OF EACH DEMO		
7.	GOOGLECODE LINK OF THE DA		

Task 1/A. Program the ADC of ATmega328/p to read the LM34/35 temperature sensor. FINISHED IN DA03, REFER TO DA03 DOC OR REFER TO FULL CODE LATER IN DOCUMENT

Task 2/B. Display the value to UART. FINISHED IN DA03, REFER TO DA03 DOC

Task 3/C. Make sure the AT Firmware is downloaded into the ESP8266-01 module.

- a) Proof of successful firmware download (green check bottom-left)
- distorted QR box and AP/STA MAC for safety purposes, FTDI was in COM4



Task 4/D. Register for a free Thingspeak account with MATHWORK. Setup and get the channel Key. a) Proof of ThingSpeak account creation

My Profile

MathWorks Account settings



Task 5/E. Transmit temperature sensor value to ESP8266-01 through UART port using AT Commands. REFER TO FULL CODE LATER IN DOCUMENT

Utilized this site for AT commands:

https://room-15.github.io/blog/2015/03/26/esp8266-at-command-reference/

Task 6/F. Display the temperature sensor value as a graph in Thingspeak a) Graph on ThingSpeak

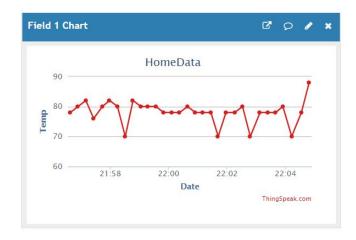
Notes:

- Normal temperature was around 78°-80° F.
- Temperature rises when pinching LM34.
- Temperature drops when placed cold object on top of LM34.

□ ThingSpeak™

Created: <u>about 4 hours ago</u>
Updated: <u>less than a minute ago</u>
Last entry: <u>less than a minute ago</u>

Entries: 31



Full Code:

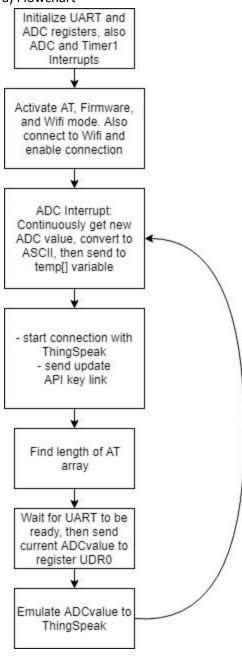
```
#define F CPU 16000000UL
#include <stdlib.h>
#include <avr/io.h>
#include <stdint.h> // needed for uint8_t
#include <util/delay.h> // delays
#include <avr/interrupt.h>
//calc baud rate
#define FOSC 16000000
                                     // Clock speed
#define BAUD 115200
#define MYUBRR FOSC/8/BAUD-1
//AT commands for ESP
volatile unsigned char AT[] = "AT\r\n";
volatile unsigned char CIPMUX[] = "AT+CIPMUX=0\r\n";
volatile unsigned char CIPSTART[] = "AT+CIPSTART=\"TCP\",\"184.106.153.149\",80\r\n"; //ip of thingspeak
volatile unsigned char SEND_DATA[] = "GET /update?key=4YEZ22JG6Q4EMQEC&field1="; //update thingspeak
volatile unsigned char CIPSIZE[] = "AT+CIPSEND=45\r\n"; //send data
volatile unsigned char CWMODE[] = "AT+CWMODE=3\r\n"; //wifi mode
volatile unsigned char CONNECTWIFI[] = "AT+CWJAP=\"WIFI MAME\",\"WIFI PASSWORD\"\r\n"; //connect to ap
volatile unsigned char FIRMWARE[] = "AT+GMR\r\n"; //view version info
volatile unsigned char BREAK[] = "\r\n\r\n"; //assures end of reading temp
//global variables
volatile uint8_t ADCvalue;
volatile unsigned char temp[5];
//prototypes
void initUart();
void send AT(volatile unsigned char AT[1);
∃int main(void)
     ADMUX = 0; // use ADC0
     ADMUX |= (1 << REFS0); // use AVcc as the reference
     ADMUX |= (1 << ADLAR); // Right adjust for 8 bit resolution
     ADCSRA |= (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0); // 128 prescale for 16Mhz
     ADCSRA |= (1 << ADATE); // Set ADC Auto Trigger Enable
     ADCSRB = 0; // 0 for free running mode
     ADCSRA |= (1 << ADEN); // Enable the ADC
     ADCSRA |= (1 << ADIE); // Enable Interrupts
     ADCSRA |= (1 << ADSC); // Start the ADC conversion
     initUart();
     _delay_ms(1500);
     send_AT(AT); //at
     _delay_ms(1500);
     send_AT(FIRMWARE); //firmware
     _delay_ms(1500);
     send_AT(CWMODE); //wifi mode
     _delay_ms(1500);
     send_AT(CONNECTWIFI); //connect with WiFi
     _delay_ms(5000);
     send_AT(CIPMUX); //enable
     sei();
     while (1)
         _delay_ms(500);
         send_AT(CIPSTART); // start connection
         _delay_ms(500);
         send_AT(CIPSIZE); // size
         _delay_ms(500);
         send_AT(SEND_DATA);
         send_AT(temp); //temperature
         send_AT(BREAK);
     return 0;
```

```
∃void initUart() {
     /*Set baud rate */
     UBRROH = ((MYUBRR) >> 8);
     UBRRØL = MYUBRR;
     UCSR0A = (1<< U2X0);
     UCSROB = (1 << TXENO); // Enable transmitter
     UCSROC |= (1 << UCSZO1) | (1 << UCSZO0); // Set frame: 8data, 1 stp
 }
 // Interrupt subroutine for ADC value
∃ISR(ADC_vect) {
     unsigned char i = 0;
     char tmptemp[5];
     ADCvalue = (ADCH << 1);
    itoa(ADCvalue, tmptemp, 10); //convert char to ascii
     for(i = 0; i < 5; i++)
         temp[i] = tmptemp[i]; //move converted ascii
 }

∃void send_AT(volatile unsigned char AT[]) {
     volatile unsigned char a;
     volatile unsigned char ATlength = 0;
     while(AT[ATlength] != 0)
         ATlength++; // find length
     for(a = 0; a < ATlength; a++)
         while(!(UCSR0A & (1<<UDRE0))); // wait for UART
         UDR0 = AT[a];
                                         // transmit char array
     }
 }
```

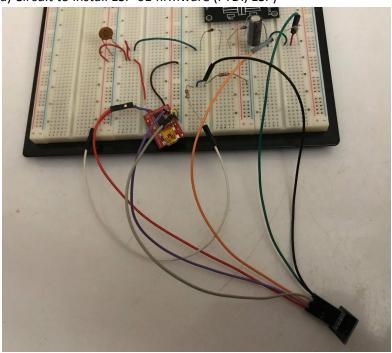
Flowchart:

a) Flowchart

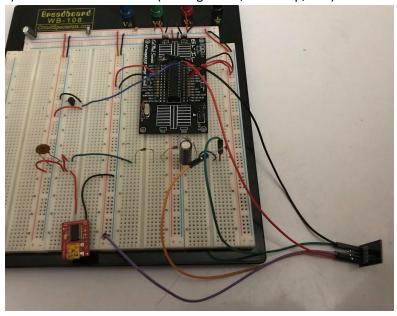


Physical Set-up:

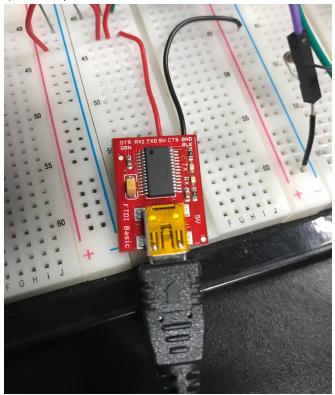
a) Circuit to install ESP-01 firmware (FTDI, ESP)



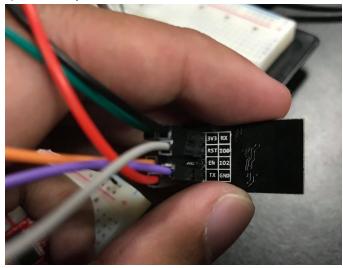
b) Full Breadboard circuit (ATMega328P, FTDI chip, ESP)



c) FTDI chip



d) ESP01 chip



GITHUB LINK: https://github.com/JeffinVegas/EmbSys.git **YOUTUBE LINK:** In the videos_DA_MIDTERM.txt file

Student Academic Misconduct Policy

http://studentconduct.unlv.edu/misconduct/policy.html