

Robot 1

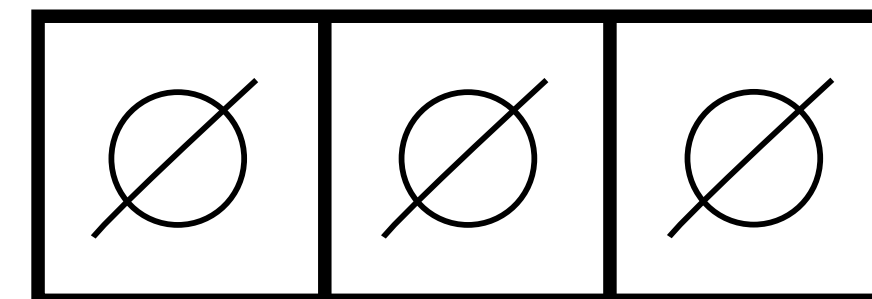
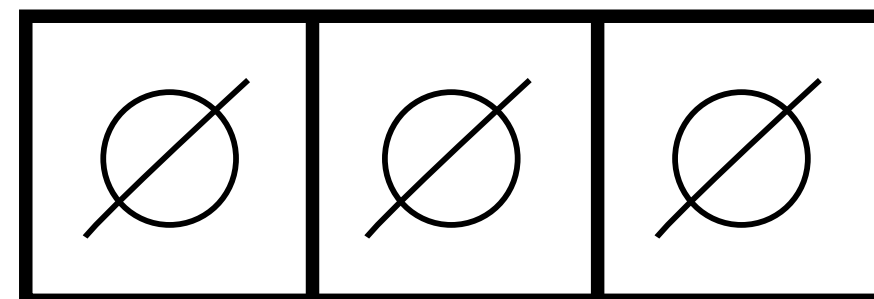
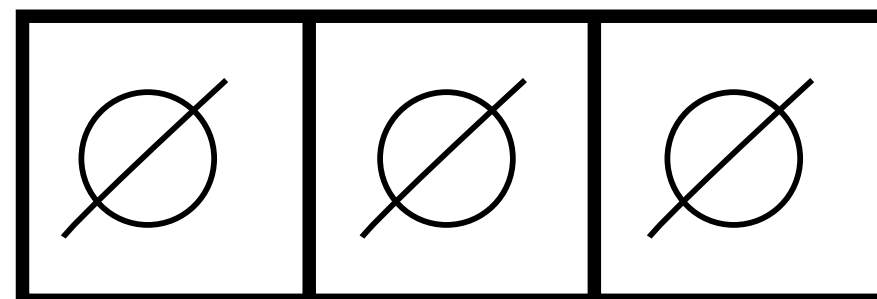
Robot 2

Robot 3

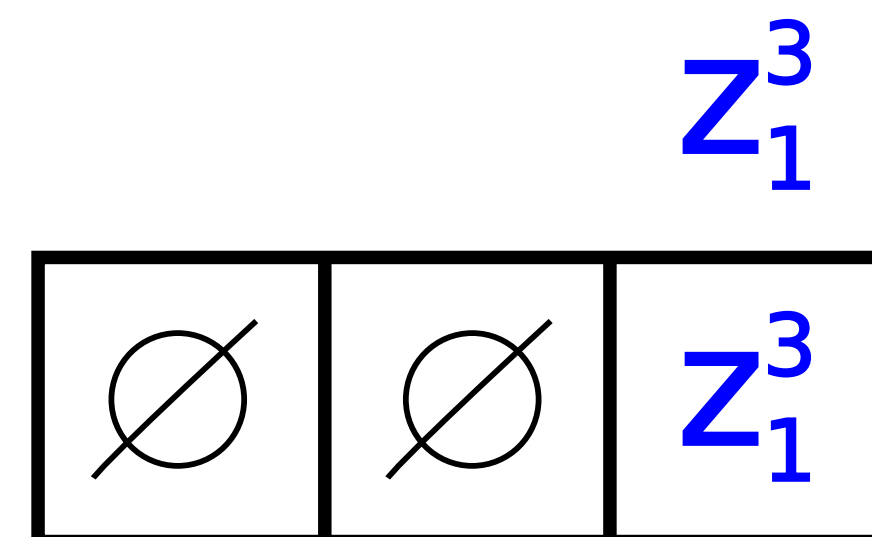
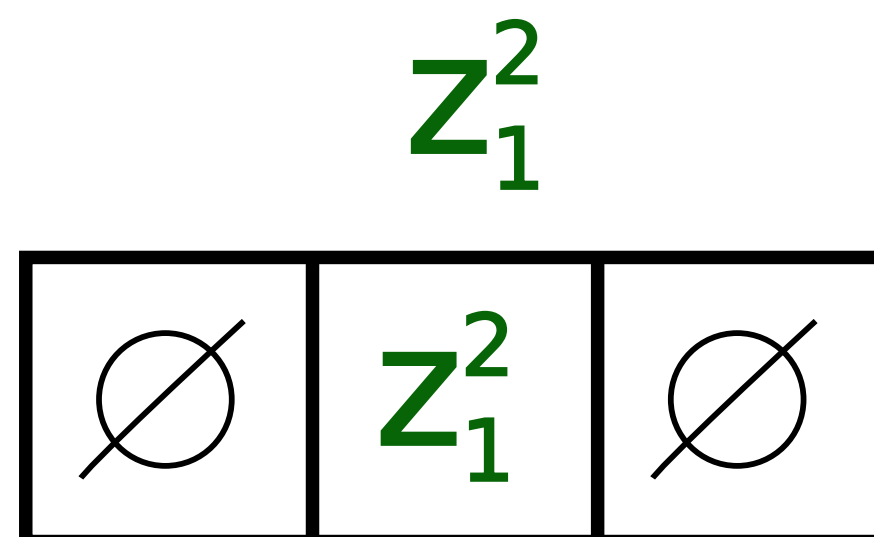
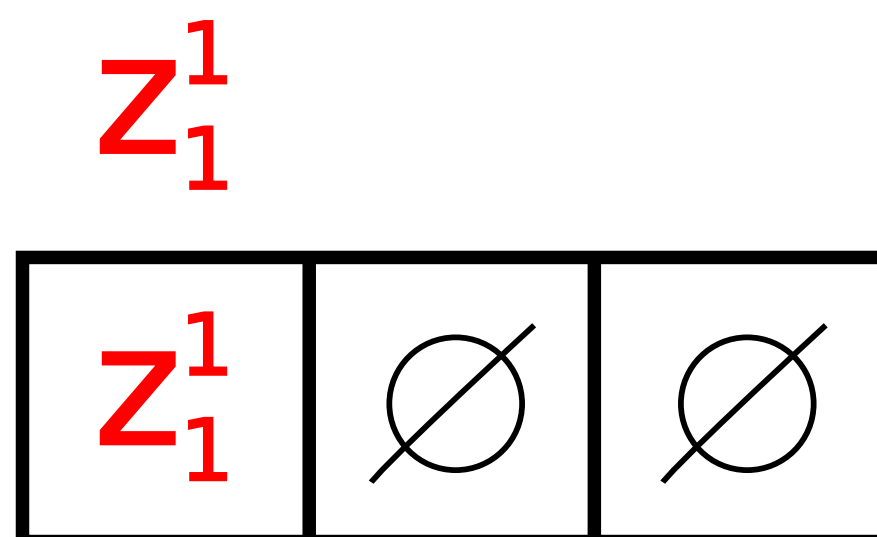
Buffer

Observation

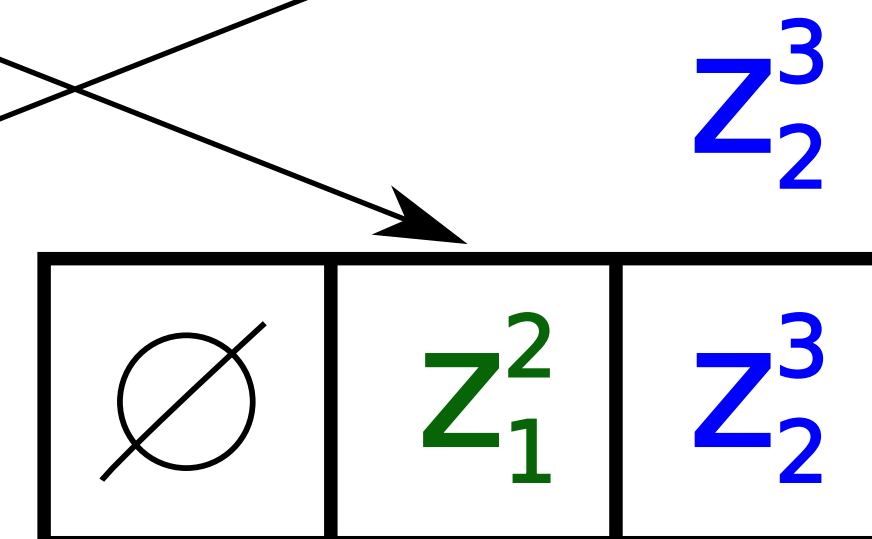
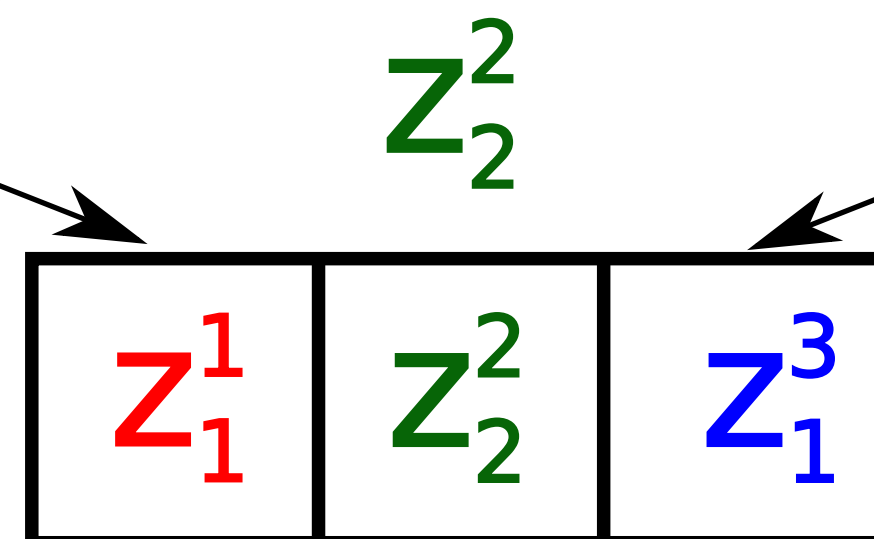
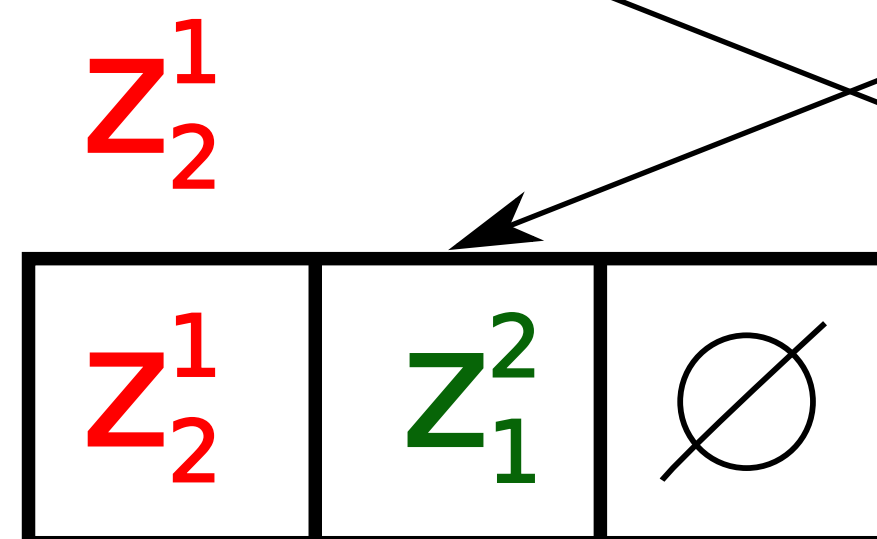
$k=0$



$k=1$



$k=2$



$k=3$

