

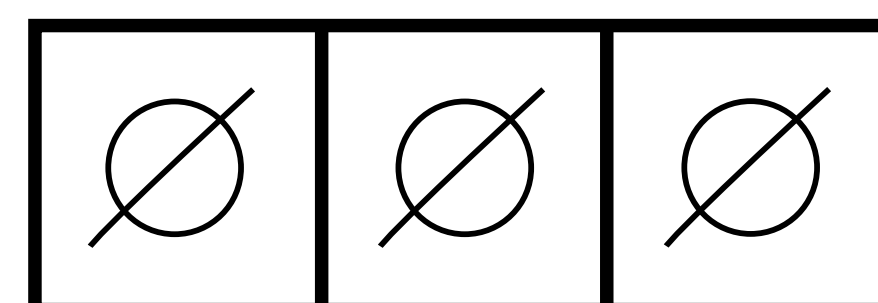
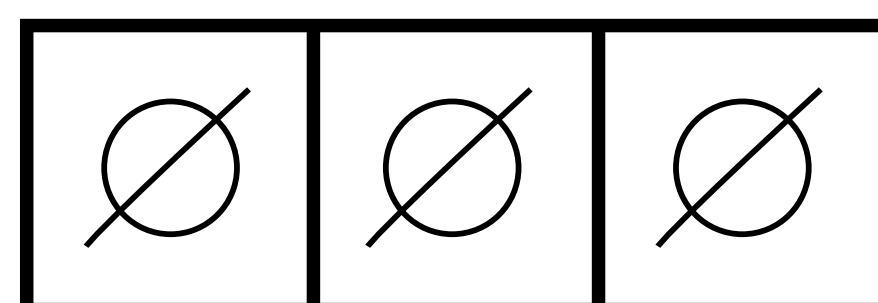
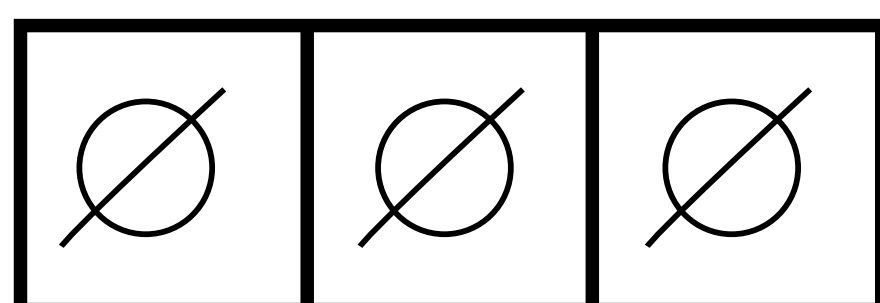


Robot 1

Robot 2

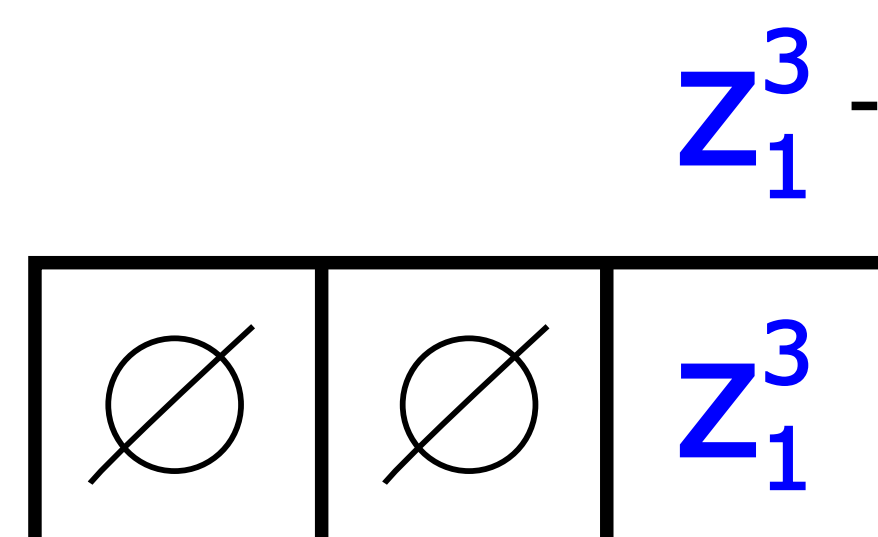
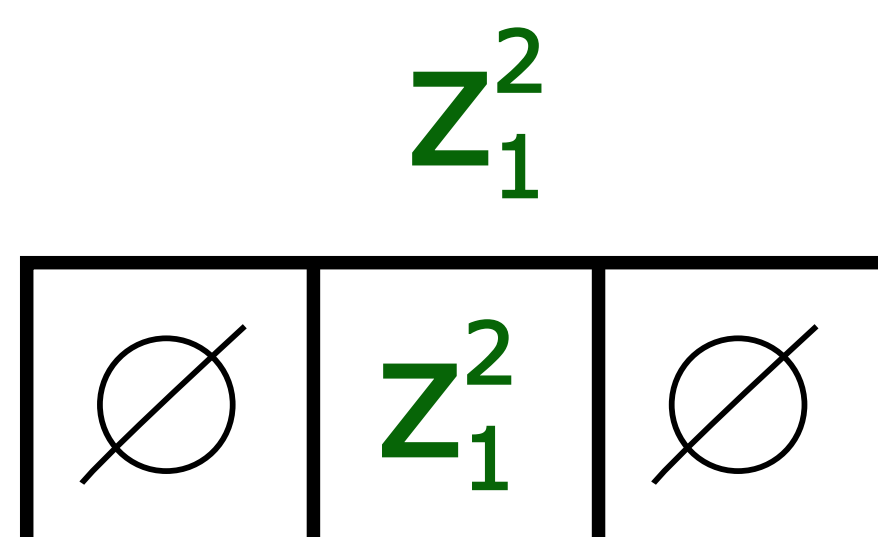
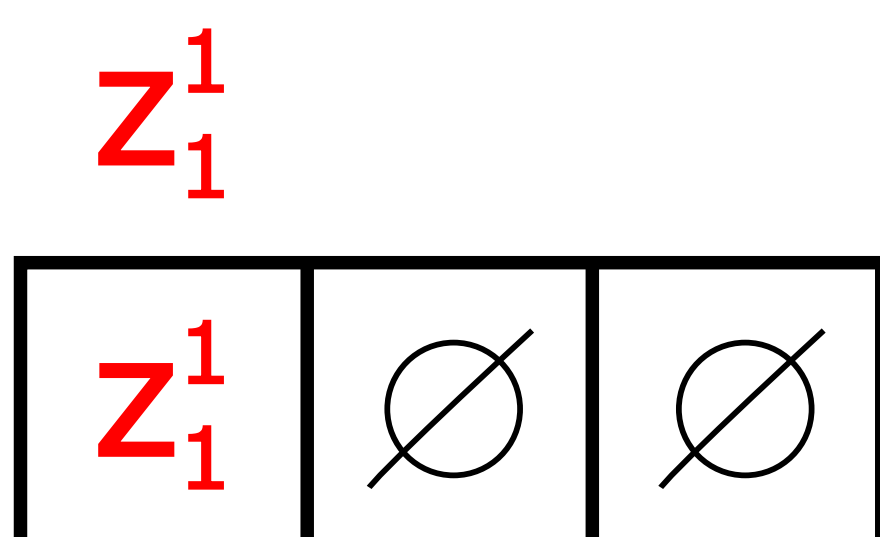
Robot 3

$k=0$



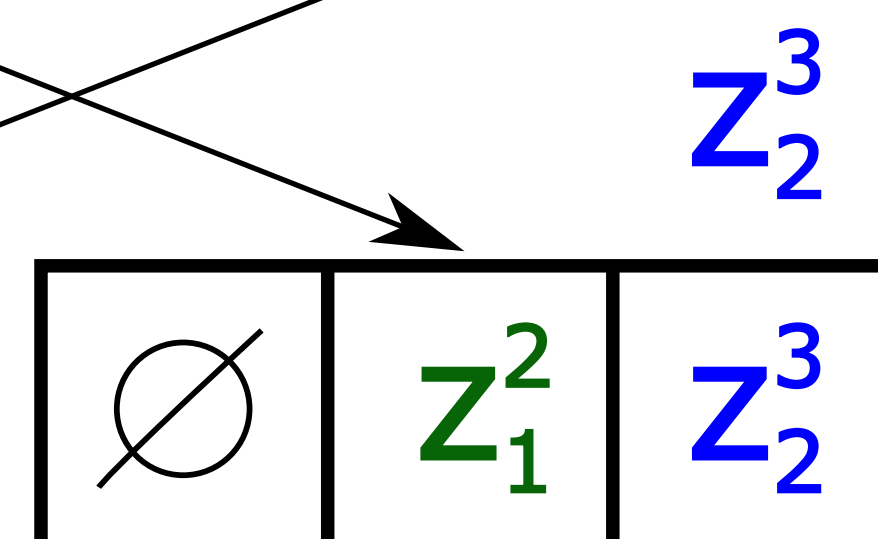
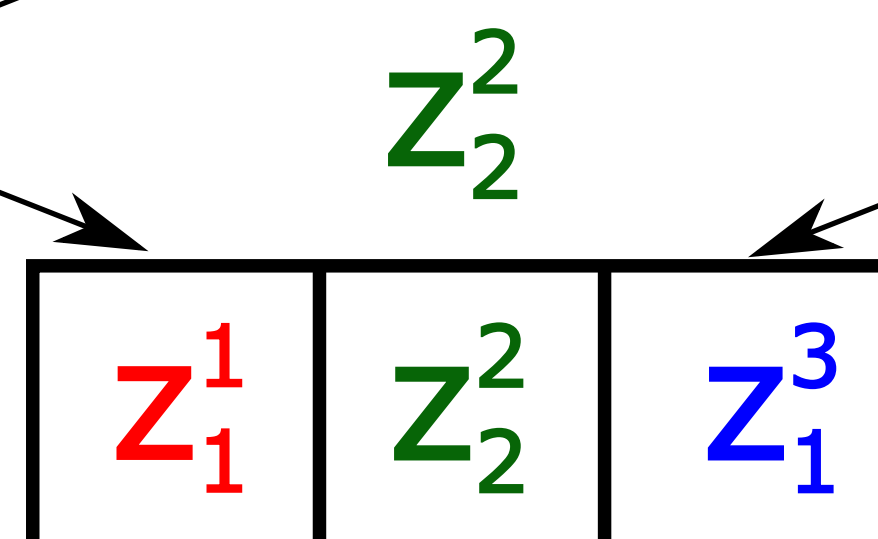
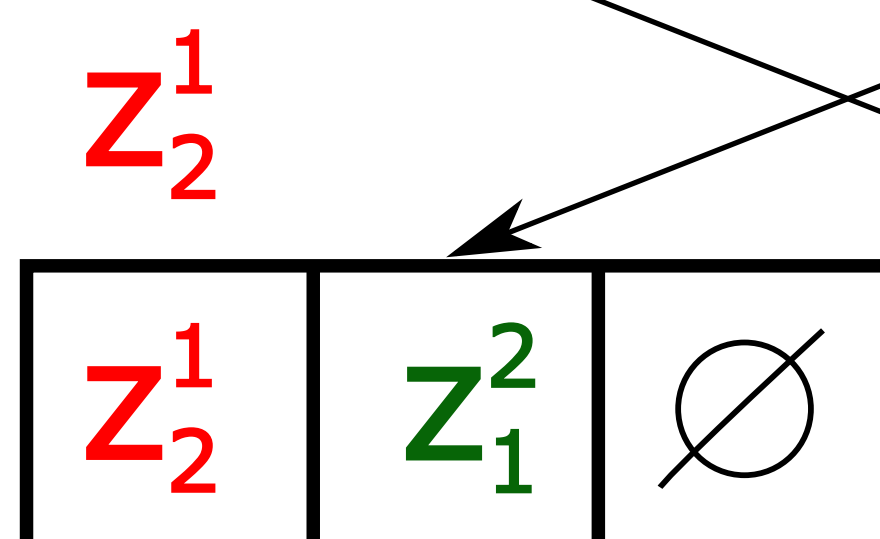
----- Buffer

$k=1$



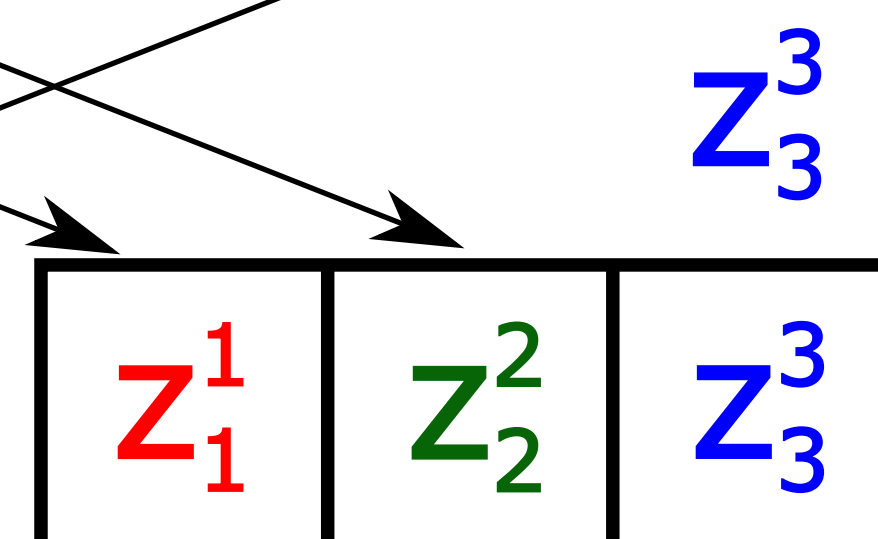
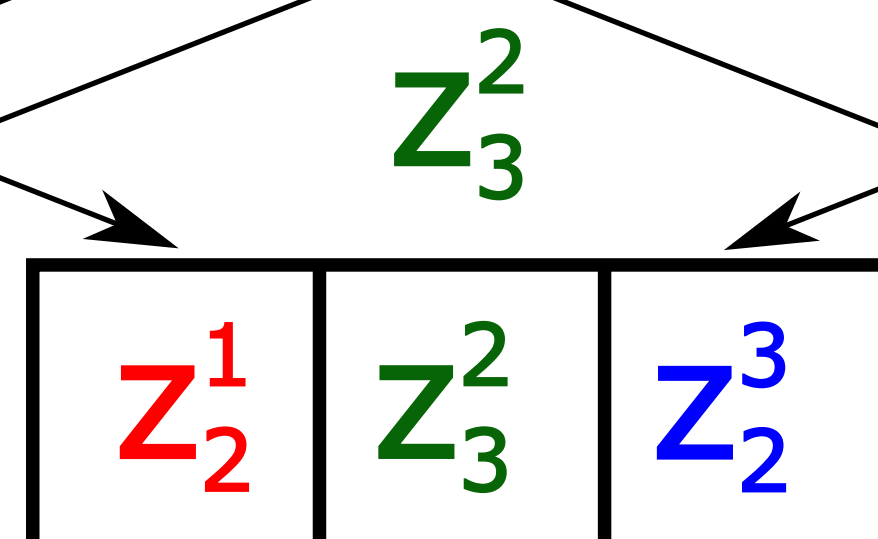
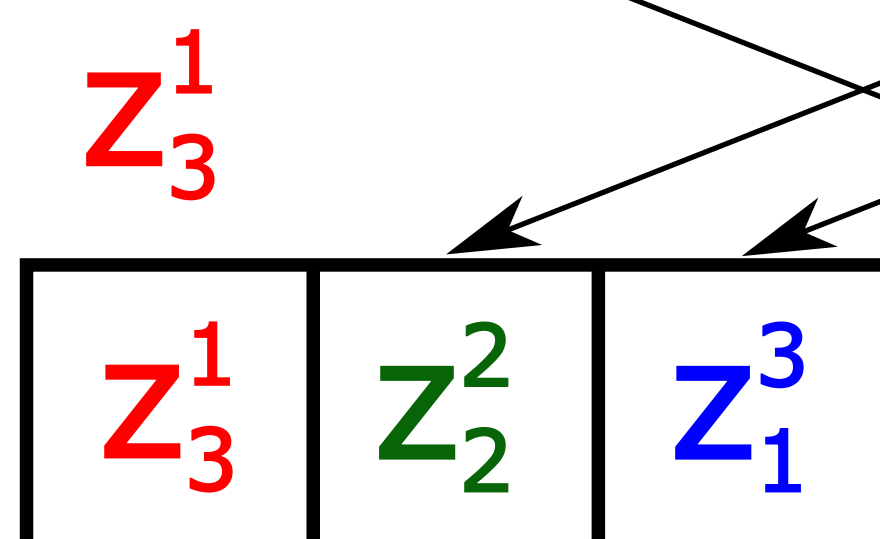
----- Observation

$k=2$



----- Communication

$k=3$



$k=4$

