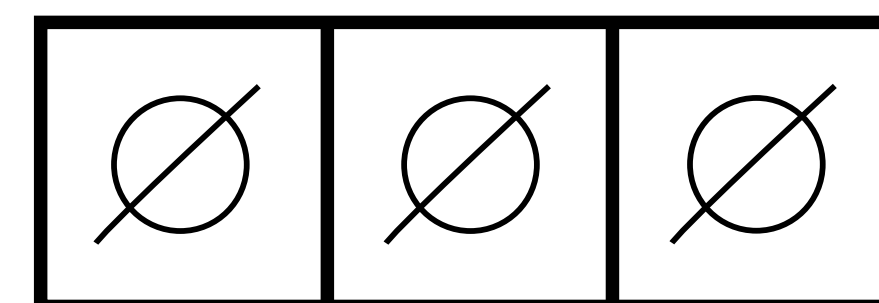
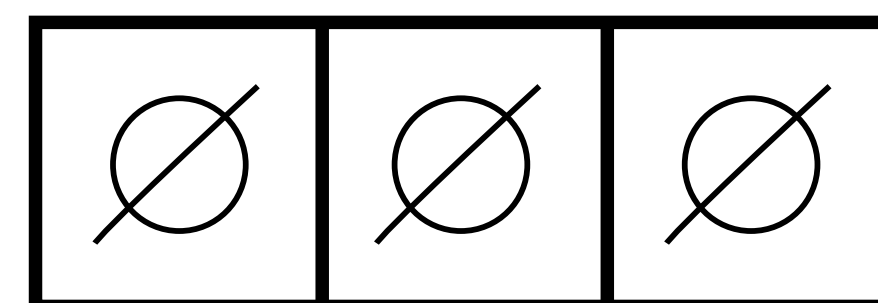
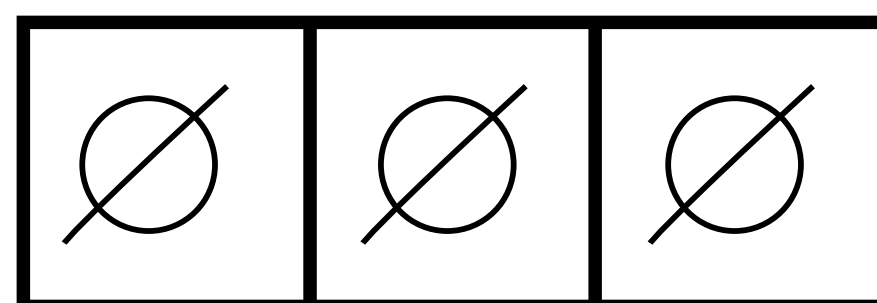


Robot 1 \longleftrightarrow Robot 2 \longleftrightarrow Robot 3

k=0



----- Buffer

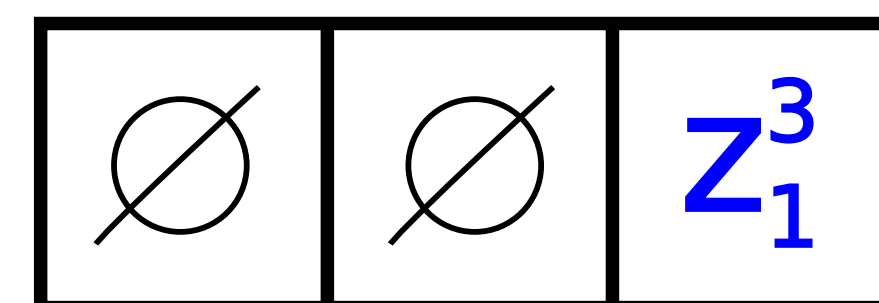
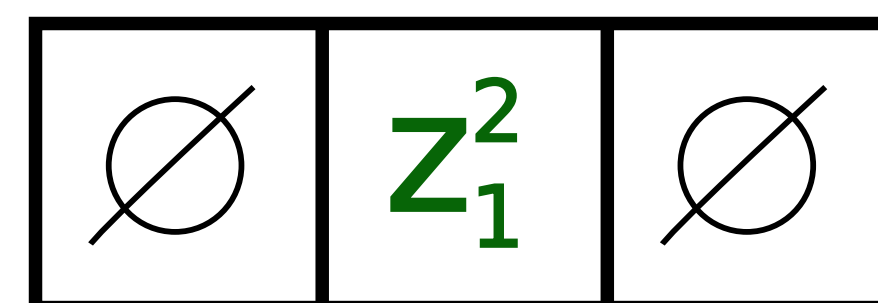
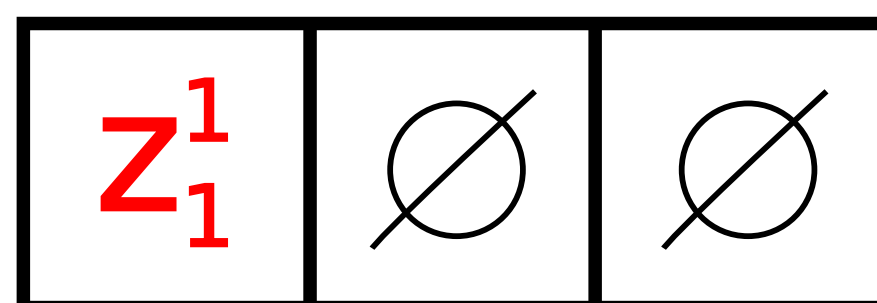
k=1

z_1^1

z_1^2

z_1^3

----- Observation



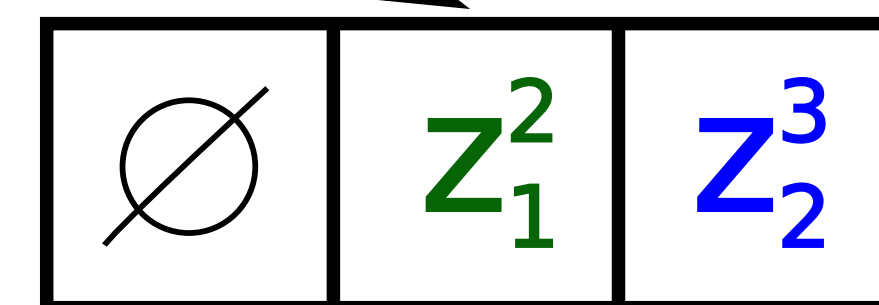
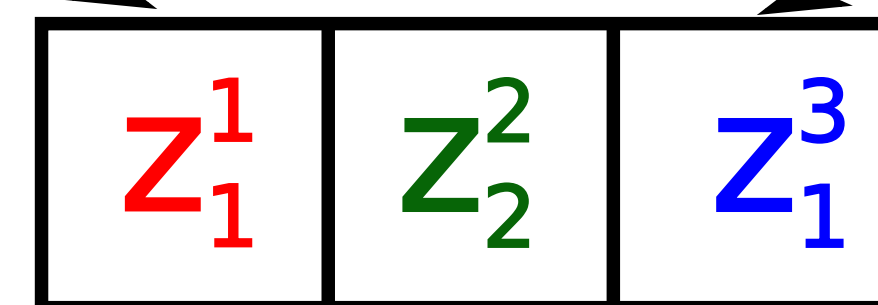
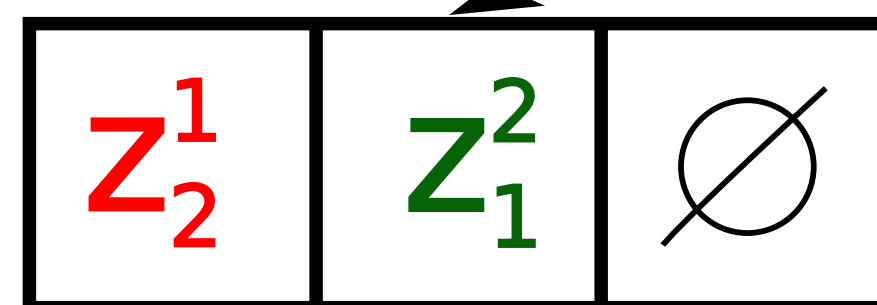
k=2

z_2^1

z_2^2

z_2^3

----- Communication

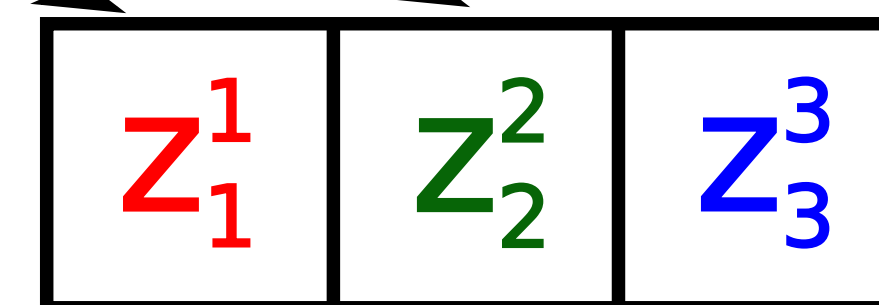
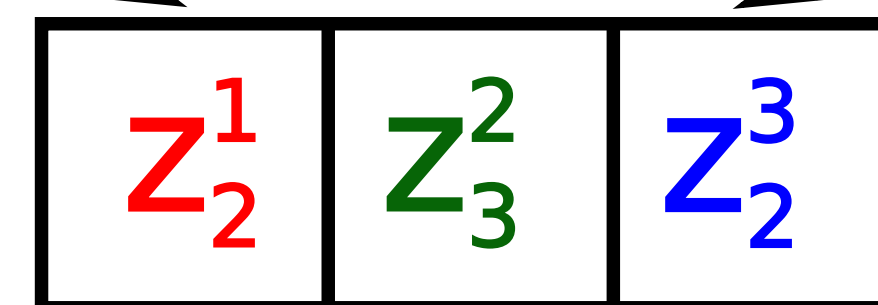
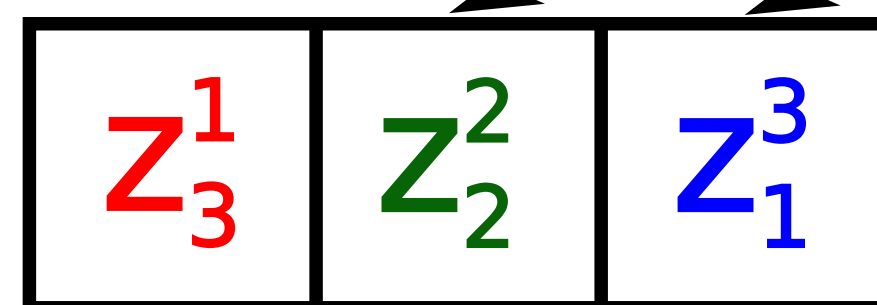


k=3

z_3^1

z_3^2

z_3^3



k=4

z_4^1

z_4^2

z_4^3

