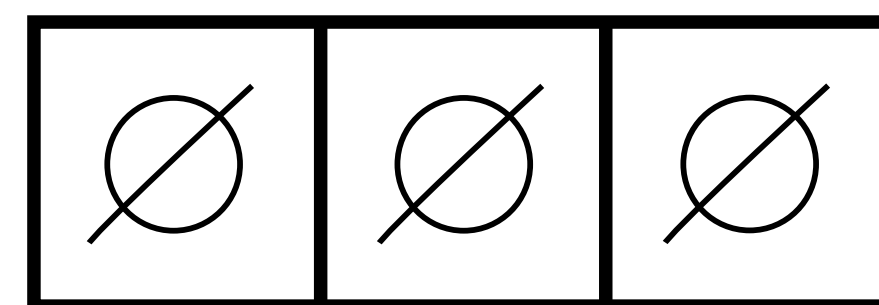
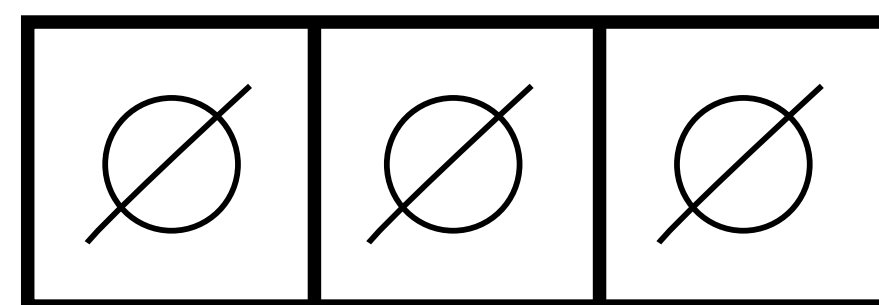
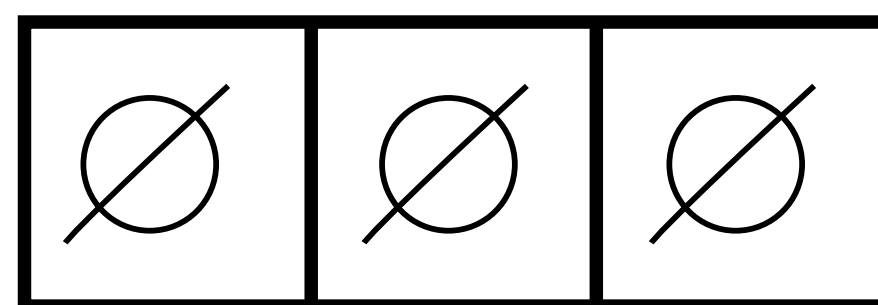


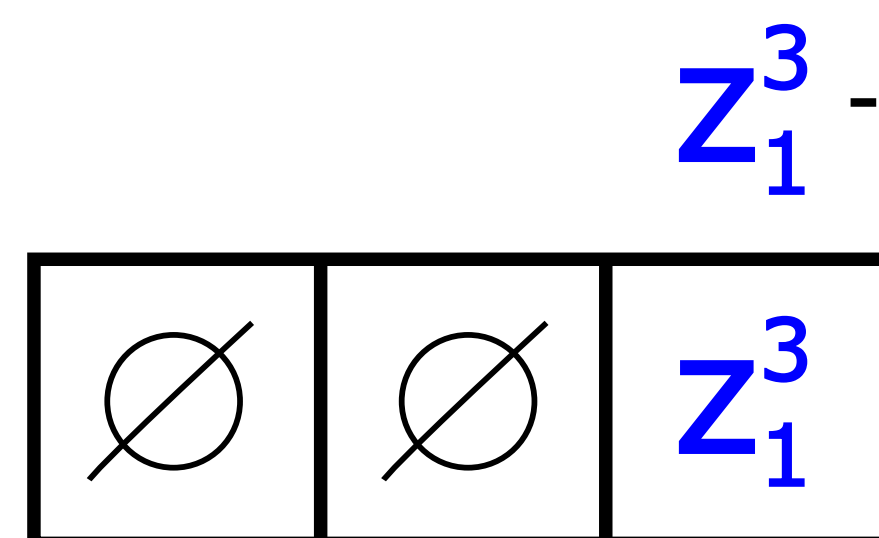
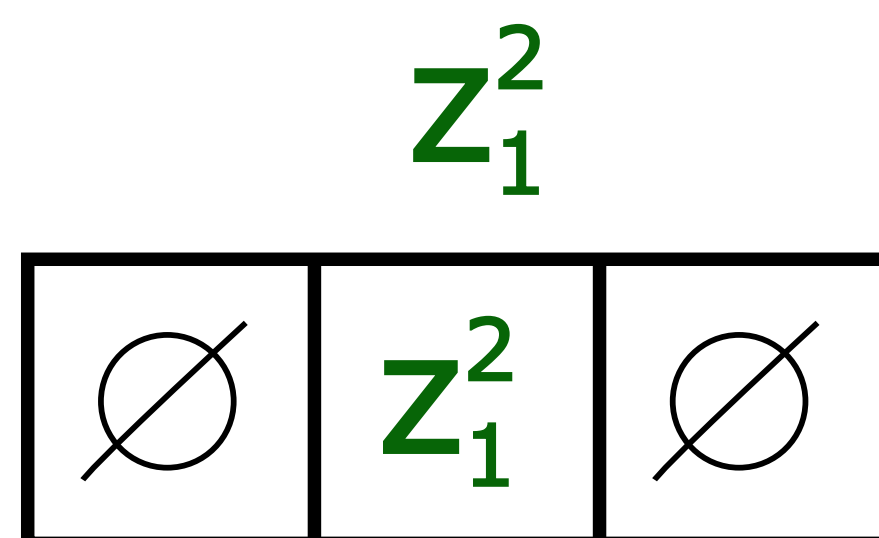
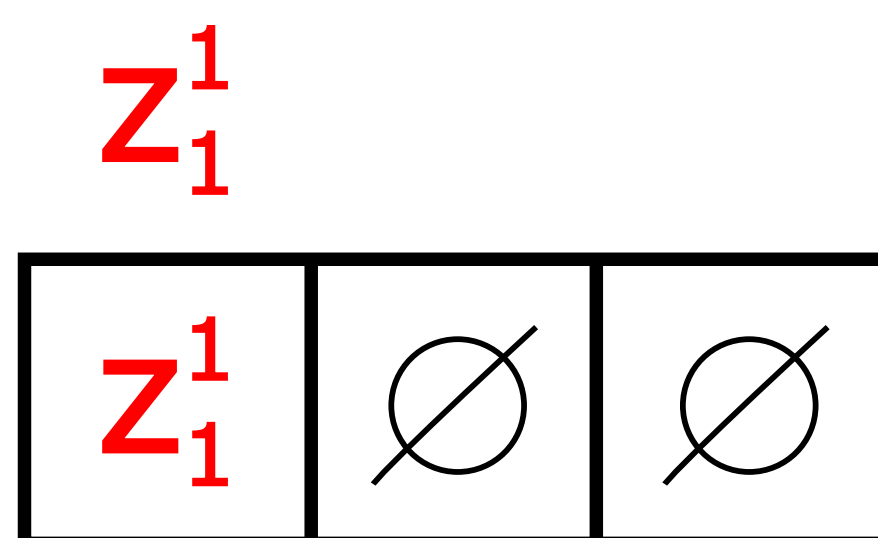
Robot 1 \longleftrightarrow Robot 2 \longleftrightarrow Robot 3

$k=0$



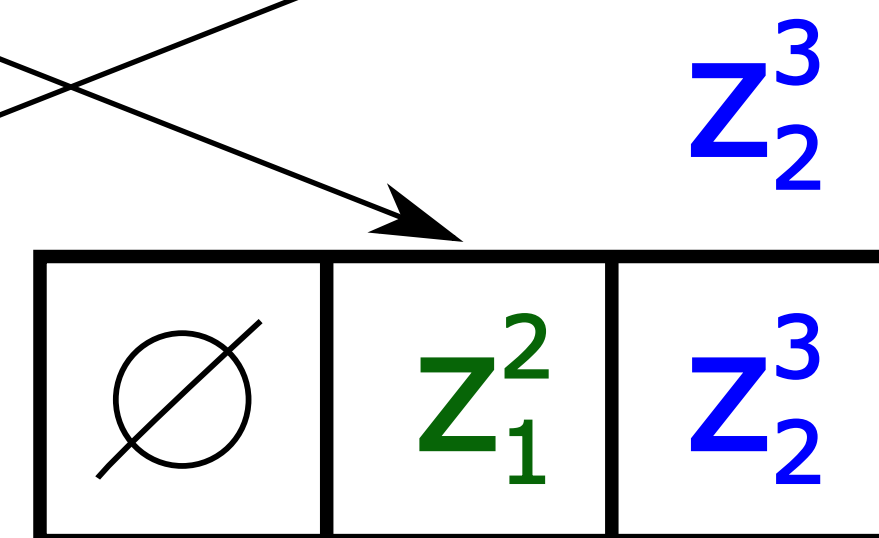
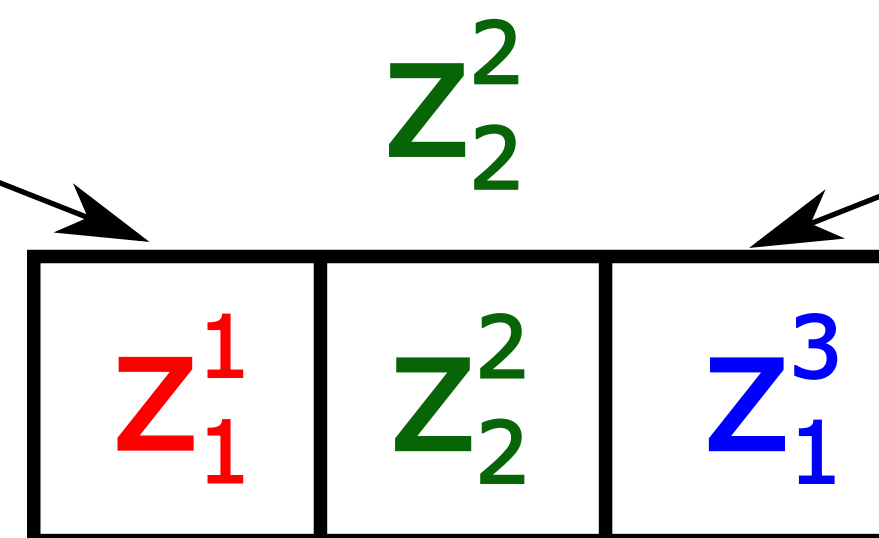
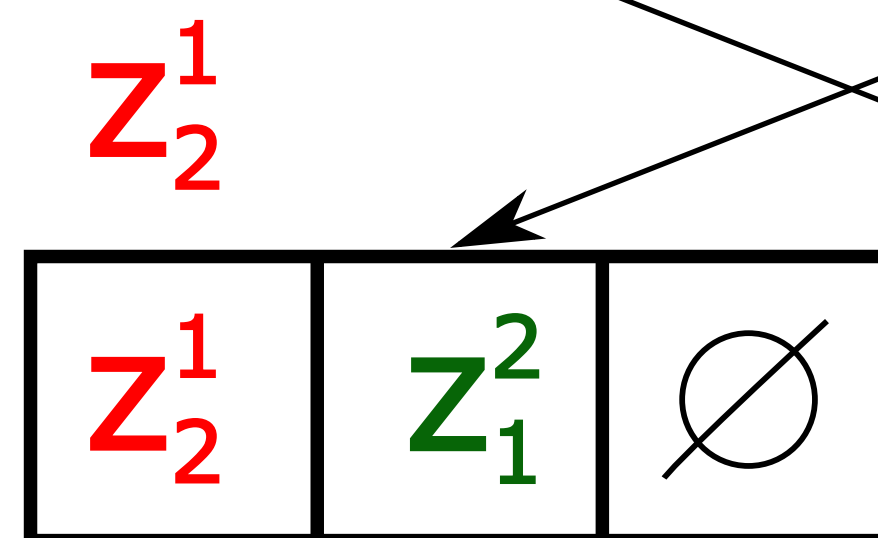
----- Buffer

$k=1$



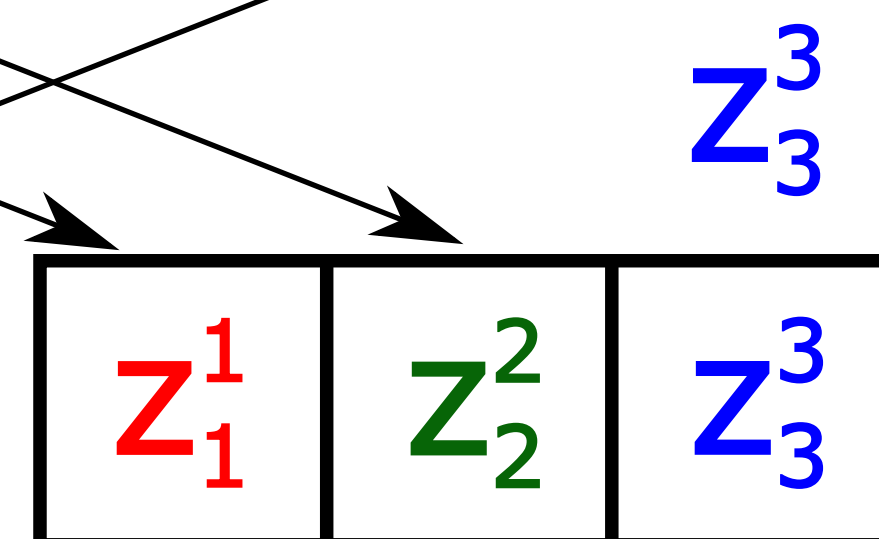
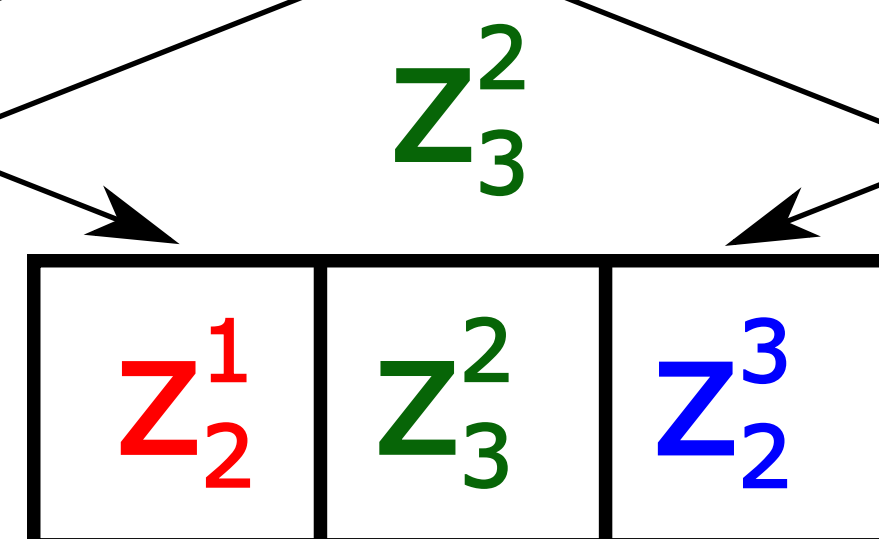
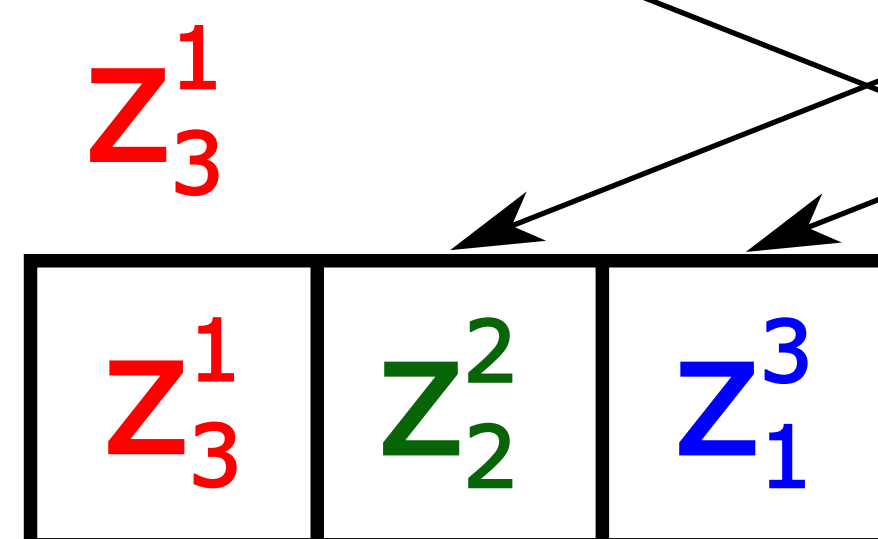
----- Observation

$k=2$



----- Communication

$k=3$



$k=4$

