

Problem 1

(a)

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Element 0 has label a, parent b, and representative d.  
Element 1 has label b, parent d, and representative d.  
Element 2 has label c, parent d, and representative d.  
Element 3 has label d, it is root, and also representative d  
Element 4 has label e, parent f, and representative d.  
Element 5 has label f, parent d, and representative d.  
Element 6 has label g, parent d, and representative d.  
Element 7 has label h, it is root, and also representative h  
[Finished in 0.1s]
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(b)

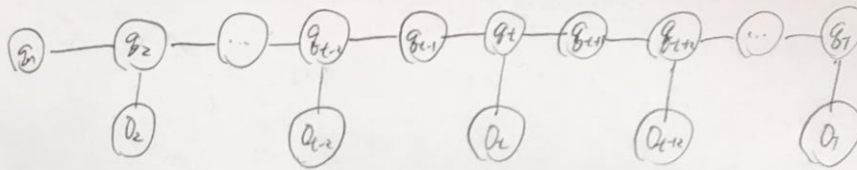
I use an array to implement the data structure. First for the initialization, I can use the Node class to create objects and I append it into nodes array. For initialize the node, I create repr for representative and parent each. This can my code to find out representative and parent separately. And my find_parent function can just return the node.parent since they are linked together. After this, I read the value from edge_list to check link the nodes. This is where I feel like my implementation is not the best runtime solution, since I have to check every element in the nodes which will take $O(n)$ time. It could be a problem and I think the dictionary implementation is a better way since it only take $O(1)$ compare the label from edge_list with nodes. And the rest is follow the pseudo code from the textbook.

Though it's not the best runtime solution, it still gave me a correct answer. Definitely can be improved if I have more time, and I will try to improve it if HW5 data is too many.

Problem 2.

(a)

problem 2 HMM



1. known $\alpha_t(i) = P[D_{1:t}, q_t = i]$ for even t .

Find $\alpha_2(i)$, $\alpha_t(i)$

$\Rightarrow \alpha_2(i) = P[D_{1:2}, q_2 = i]$ since we can't find o_1 .

$$\Rightarrow \alpha_2(i) = P[o_2, q_2 = i]$$

$$\alpha_t(i) = \sum_{j=1}^N \alpha_{t-1}(j) a_{ji} b_i(o_t)$$

since we can not find odd o_t , we find previous two steps and transform to $q_{t-1}(i)$, transform again and multiply by the likelihood, we will get $\alpha_t(i)$

$$\Rightarrow \alpha_t(i) = \sum_{j=1}^N \sum_{k=1}^N (\alpha_{t-2}(k) a_{kj}) a_{ji} b_i(o_t)$$

(b)

b. $\beta_t(i) = P[O_{t+1:T} | q_t = i]$ for even t .

Find $\beta_T(i)$, $\beta_t(i)$ as func($\beta_{t+2}(j)$)

the backward pass $\beta_T(i)$ is always 1, $\therefore \underline{\beta_T(i) = 1}$

$$\beta_t(i) = \sum_{j=1}^N a_{ij} b_j(O_{t+1}) \beta_{t+1}(j)$$

the same reason as the part (a), we can not find odd O . Therefore, we find even O and transform to odd O and transform to the desired state.

$$\beta_t(i) = \sum_{j=1}^N \sum_{k=1}^N (a_{kj} b_j(O_{t+2})) a_{ik} \beta_{t+2}(j)$$

(c)

(c) prove or disprove: $P[0_{1:2:T}] = \sum_{i=1}^N \alpha_t(i) \beta_t(i)$ for even t .

$$\begin{aligned}\alpha_t(i) \cdot \beta_t(i) &= \sum_{i=1}^N P[0_{1:2:t}, q_t = i] P[0_{t+1:2:T} | q_t = i] \\&= \sum_{i=1}^N P[0_{1:2:t} | q_t = i] P[q_t = i] P[0_{t+1:2:T} | q_t = i] \\&= \sum_{i=1}^N P[0_{1:2:T} | q_t = i] P[q_t = i] \\&= \sum_{i=1}^N P[0_{1:2:T}] \quad \# \text{ proved.}\end{aligned}$$

(d)

$$d. \quad r_t(i) = p(g_t = s_i | D, \lambda)$$

$$= \frac{\alpha_t(i) \beta_t(i)}{p(0 | \lambda)} = \frac{\alpha_t(i) \beta_t(i)}{\sum_{j=1}^N \alpha_t(j) \beta_t(j)}$$

(e)

$$e. \xi_t(i, j) = P[q_t = i, q_{t+1} = j | D_{1:T}] \text{ for any } t = 1 : T-1$$

$$\xi_t(i, j) = P[q_t = i, q_{t+1} = j | D, \lambda]$$

$$\xi_t(i, j) = \frac{\alpha_t(i) a_{ij} b_j(o_{t+1}) \beta_{t+1}(j)}{\sum_{k=1}^N \sum_{l=1}^N \alpha_t(k) a_{kl} b_l(o_{t+1}) \beta_{t+1}(l)}$$

$$\xi_t(i, j) = \frac{\alpha_t(i) a_{ij} b_j(o_{t+1}) \beta_{t+1}(j)}{\sum_{k=1}^N \sum_{l=1}^N \alpha_t(k) a_{kl} b_l(o_{t+1}) \beta_{t+1}(l)}$$

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