

Automating Scan-to-BIM for Telecom Site Planning

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Midterm Presentation

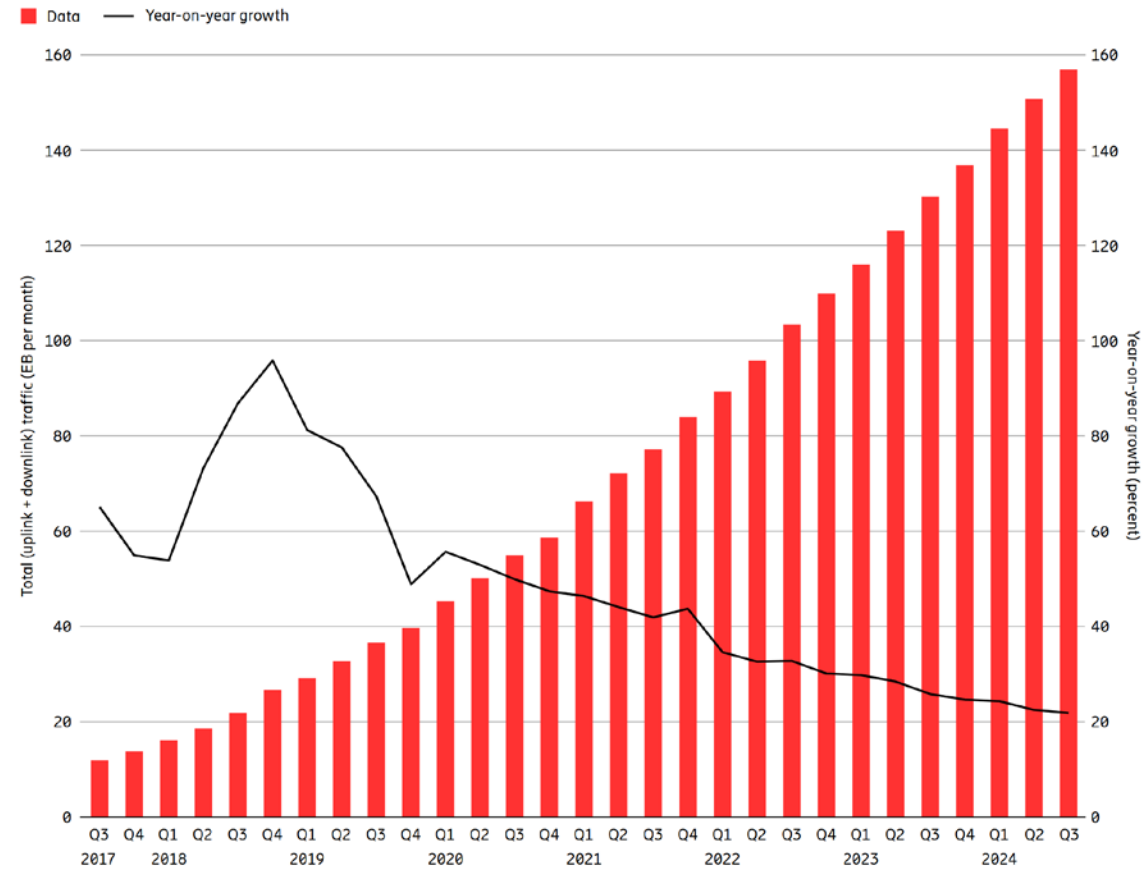
Bachelor's Thesis

03.04.2025



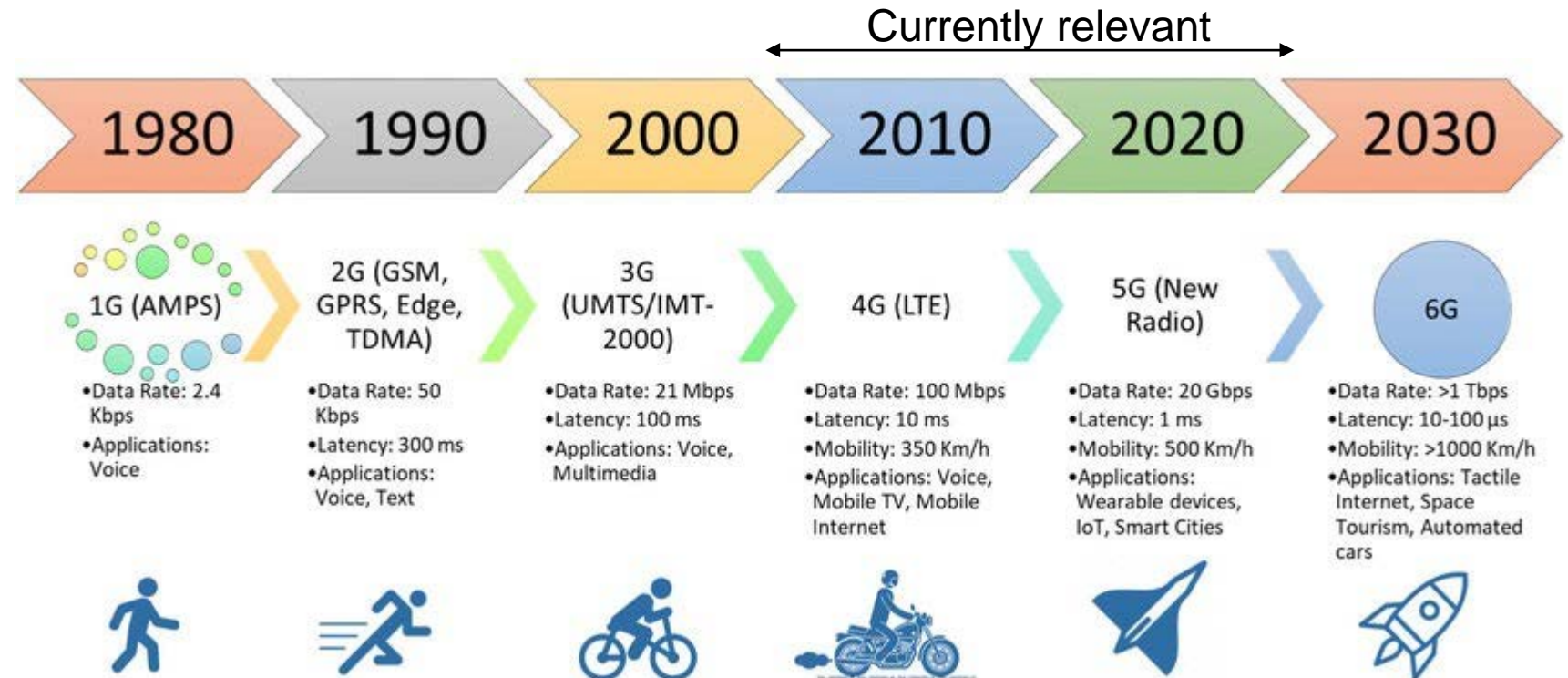
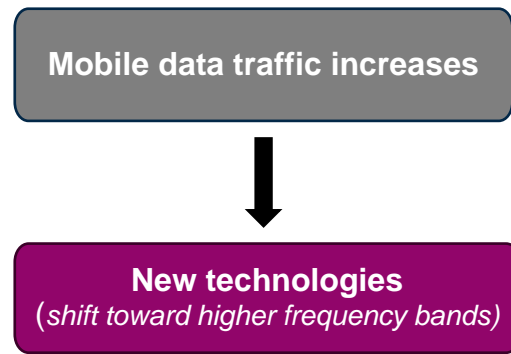
Motivation

Mobile data traffic increases



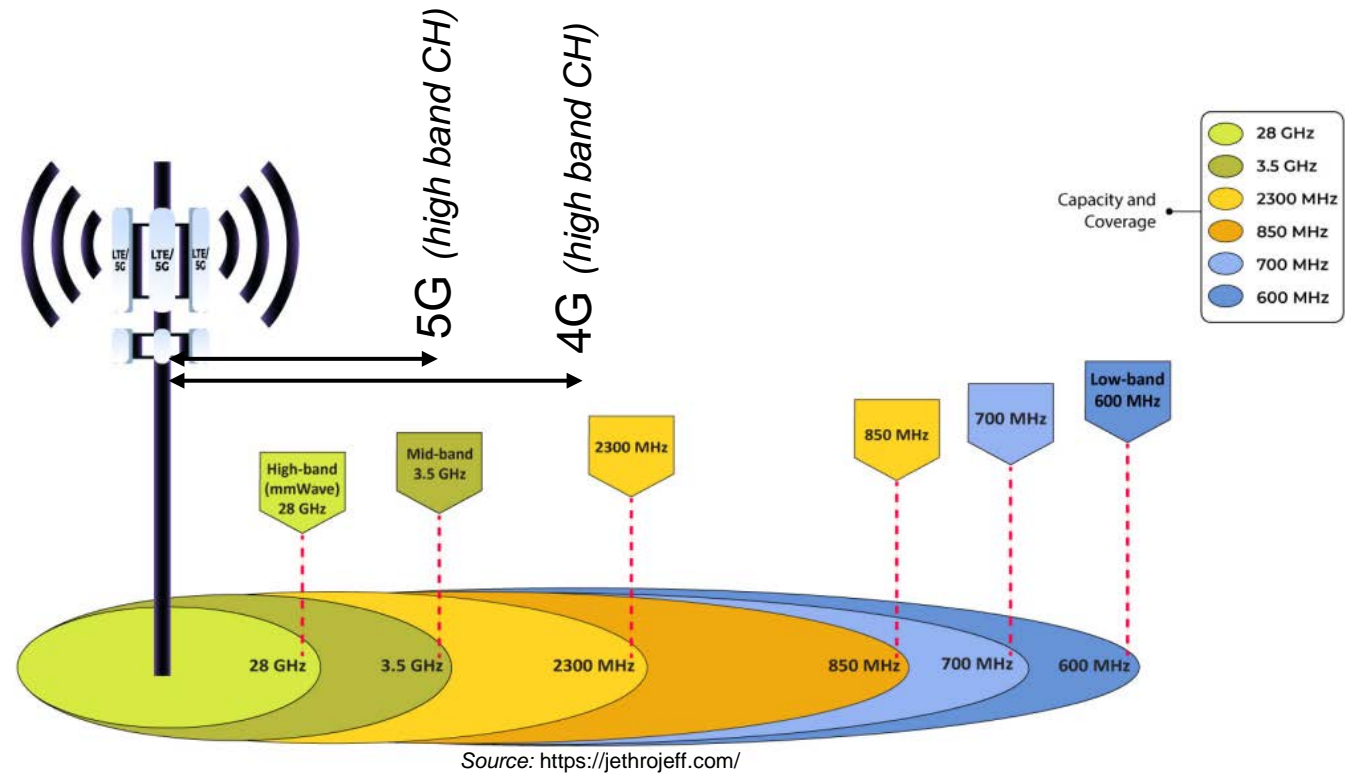
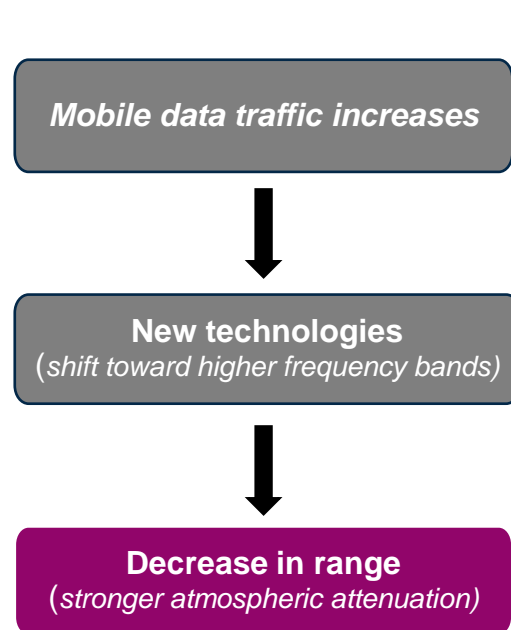
Source: Ericsson Mobility Report (November 2024)

Motivation

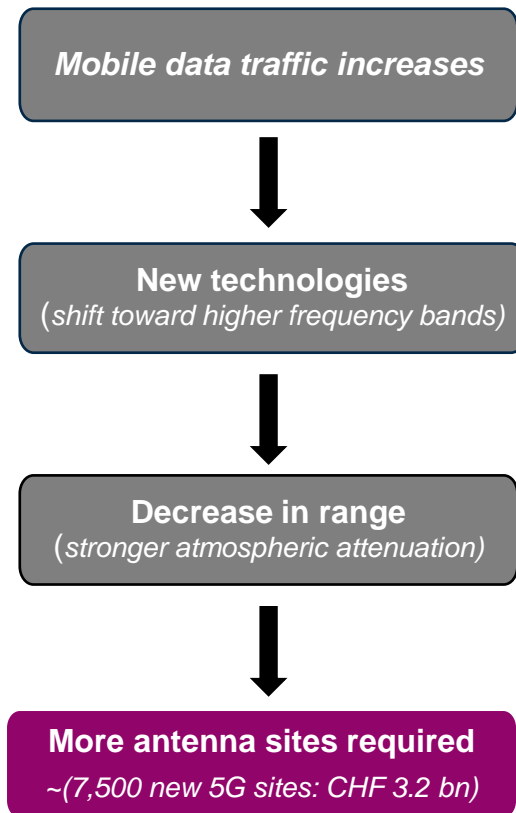


Source: <https://www.linkedin.com/pulse/understanding-5g-glimpse-6g-evolution-connectivity-dr-manpreet-puri>

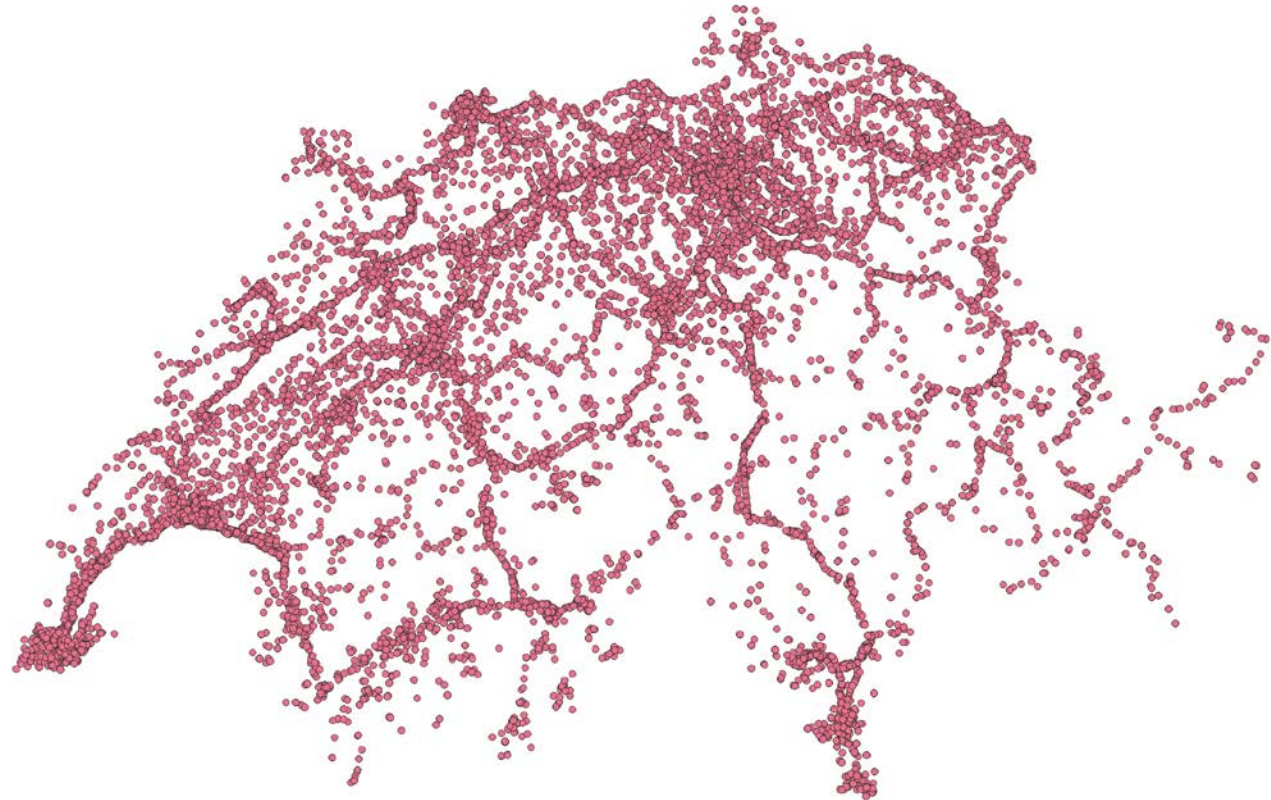
Motivation



Motivation



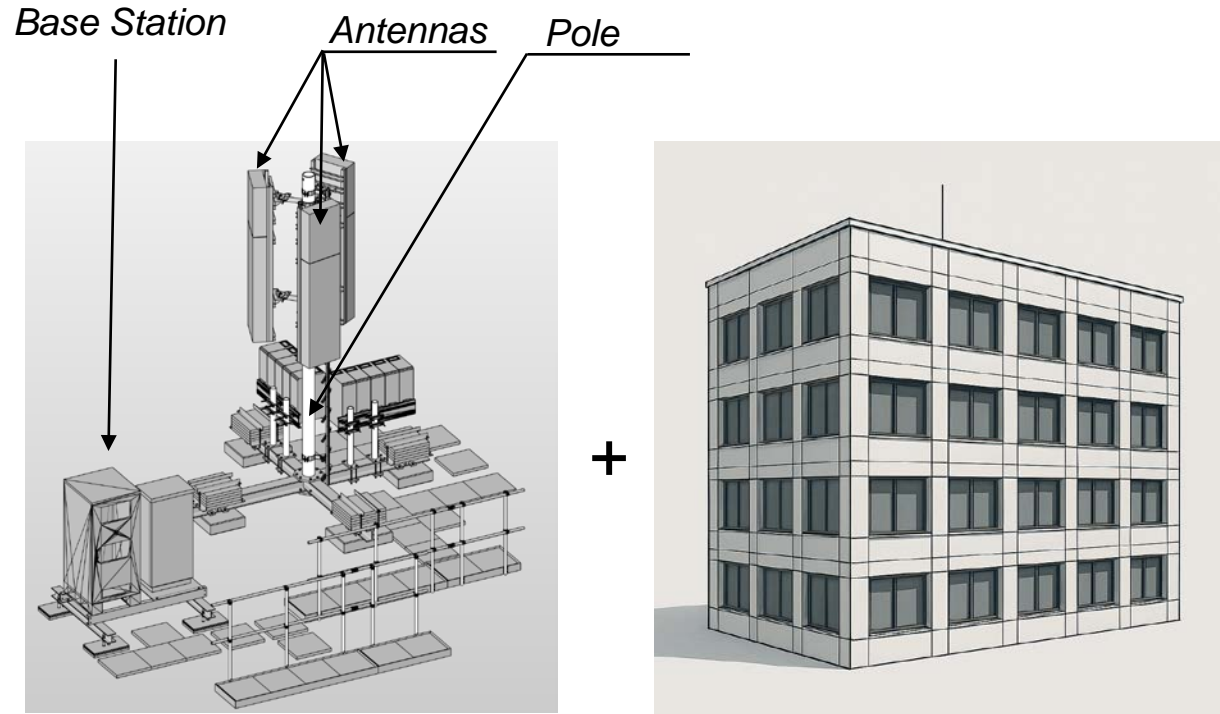
Conclusion: Large-scale deployment calls for efficient planning strategies.



Status quo: ~15,000 sites (> 5 W)

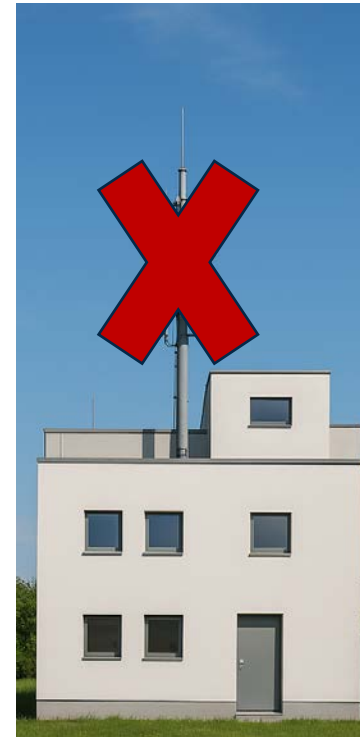
Source: Own GIS analysis based on data from <https://data.geo.admin.ch/browser/index.html#/collections/ch.bakom.standorte-mobilfunkanlagen?.language=en>

Cellular Sites

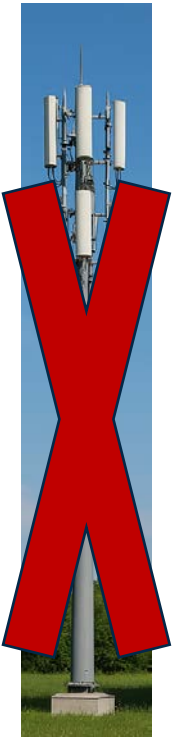


- Steel structures
- Radio Access Network (RAN) Equipment

=



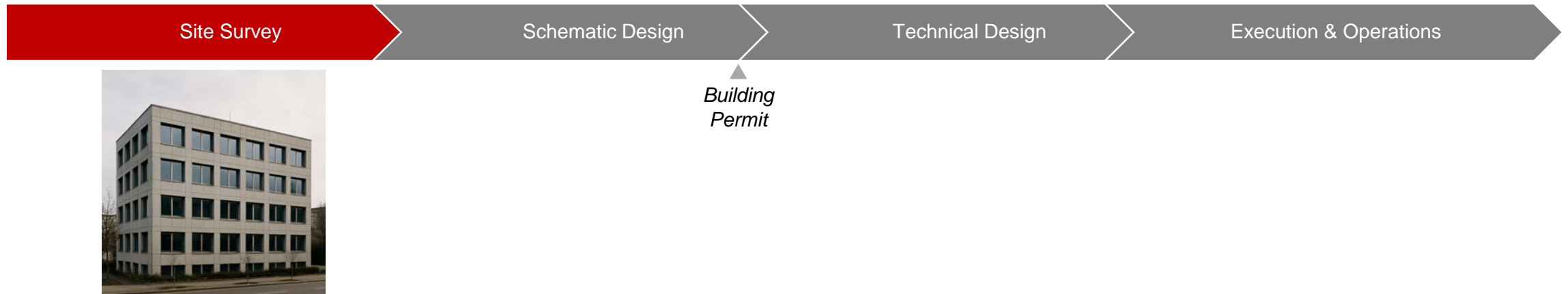
Rooftop Site
mainly urban areas



Greenfield Site
mainly rural areas

← Thesis focus

Problem Statement: Conventional Site Planning

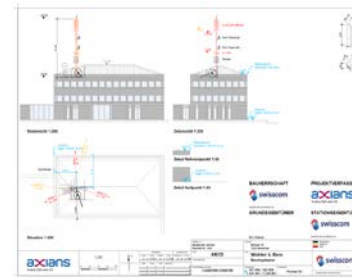


Site Survey: Site inspection with the provider, building owner, and a team of specialists

- Drone-based environmental capture for non-ionizing radiation (NIR) calculation
→ Building point cloud as a by-product
- Geodetic survey with GNSS and total station
- Attempt to organize existing building drawings



Problem Statement: Conventional Site Planning



Building
Permit

Schematic Design: Preparation for building permit application

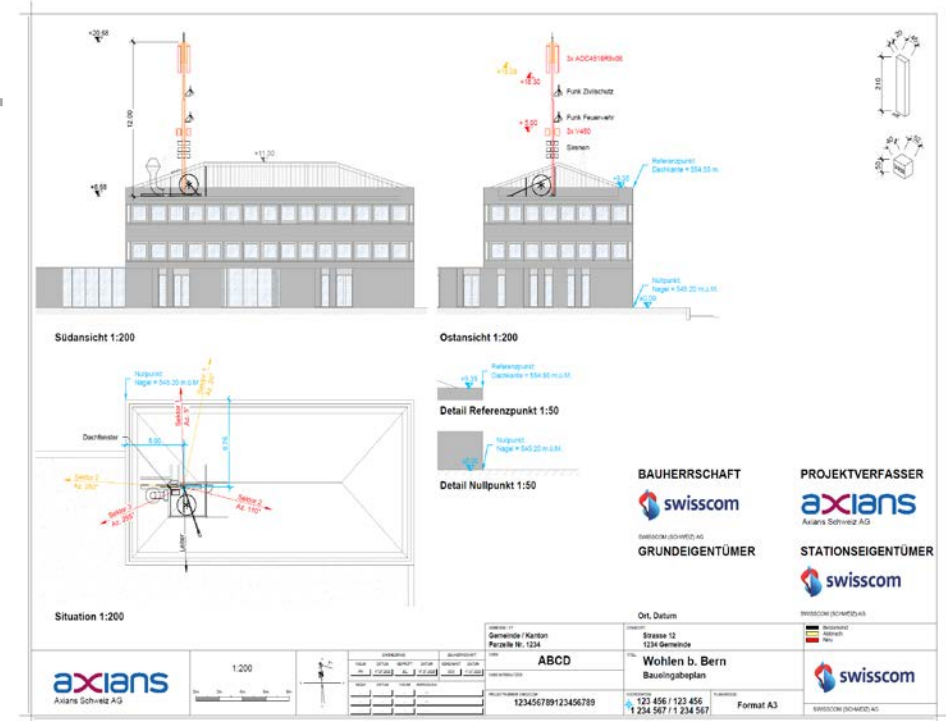
Computer-Aided Design (CAD): Software for 2D/3D drawings

Average Case:

1. Scanning of paper building drawings
2. CAD-vectorization of digitalized building drawing (tracing)

Worst Case

1. Draw building from scratch with geodetic survey data



2D CAD Drawing

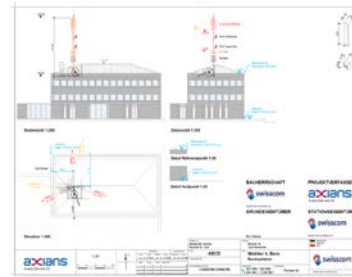
- Building Reconstruction
- Simplified Technical Representation

Problem Statement: Conventional Site Planning

Site Survey

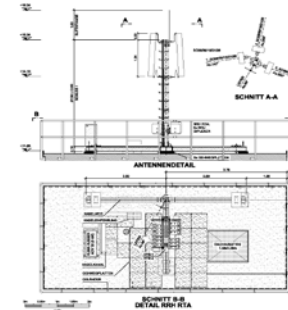


Schematic Design



Building Permit

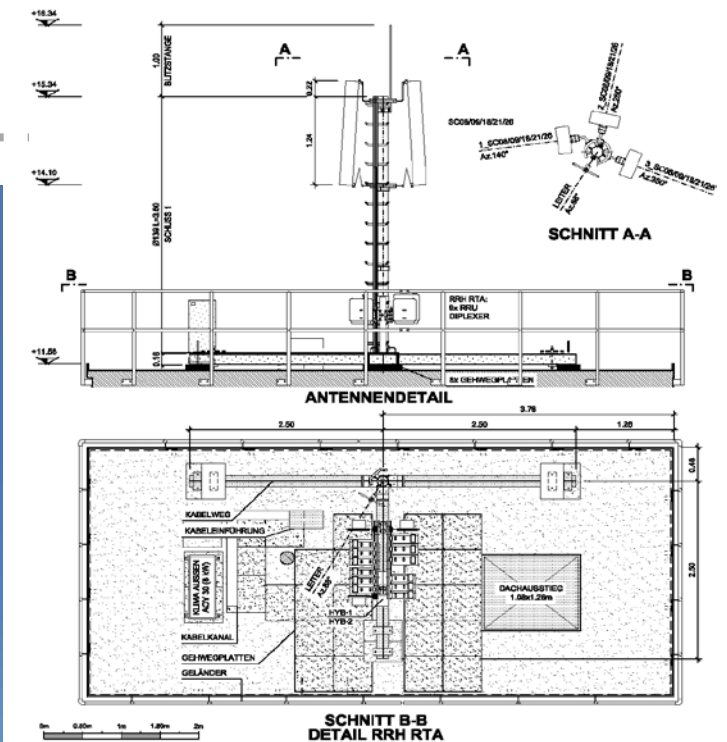
Technical Design



Execution & Operations

Technical Design: Preparation for execution

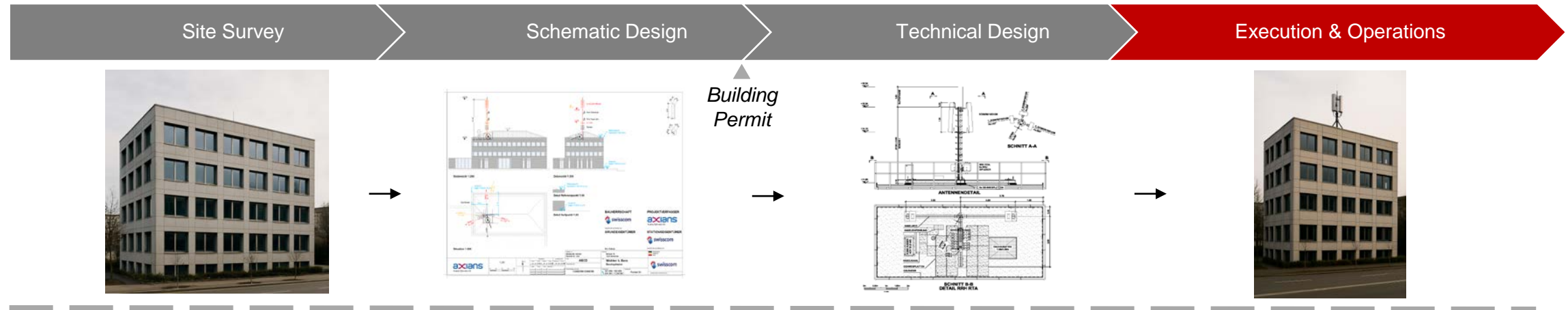
- Planning of steel structure and RAN equipment.
- Bills of materials must be manually derived from the drawings
- High component density
- Many standardized, modular components



2D CAD Drawing

- Detailed technical representation
- Bill of Materials

Problem Statement: Conventional Site Planning



Execution: Construction and maintenance of planning documents.

- Sites are operated over many years.
- Technical modifications must be manually updated in the drawings (often in multiple views)

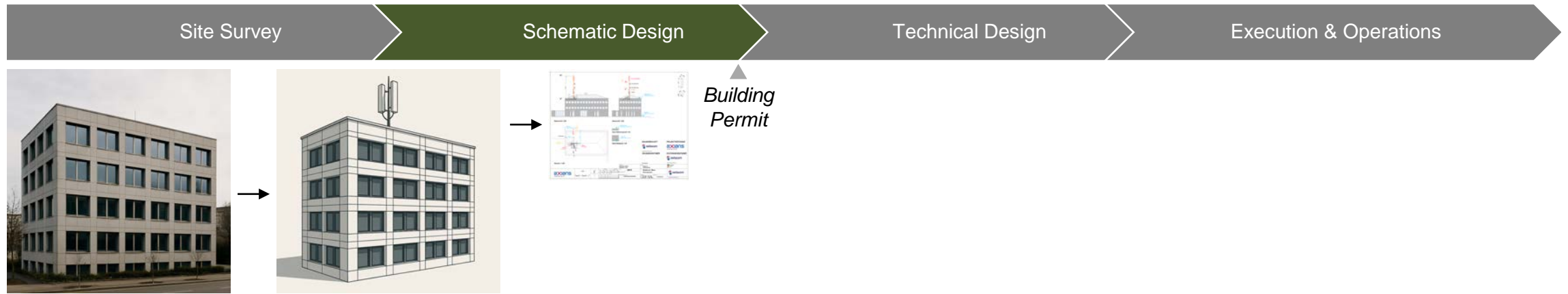
Conclusion

- High dependence on third parties (building drawings)
- Labor-intensive

Proposed Solution

- Model-based site planning

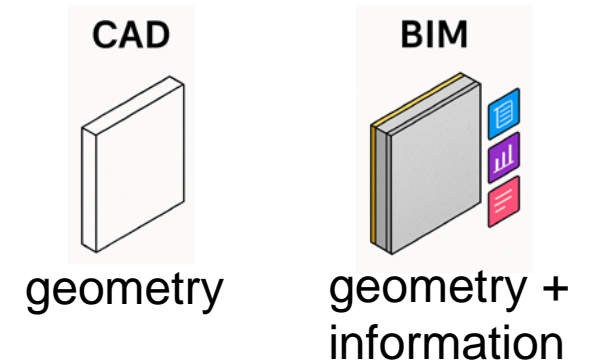
Proposed Solution: Model-Based Site Planning



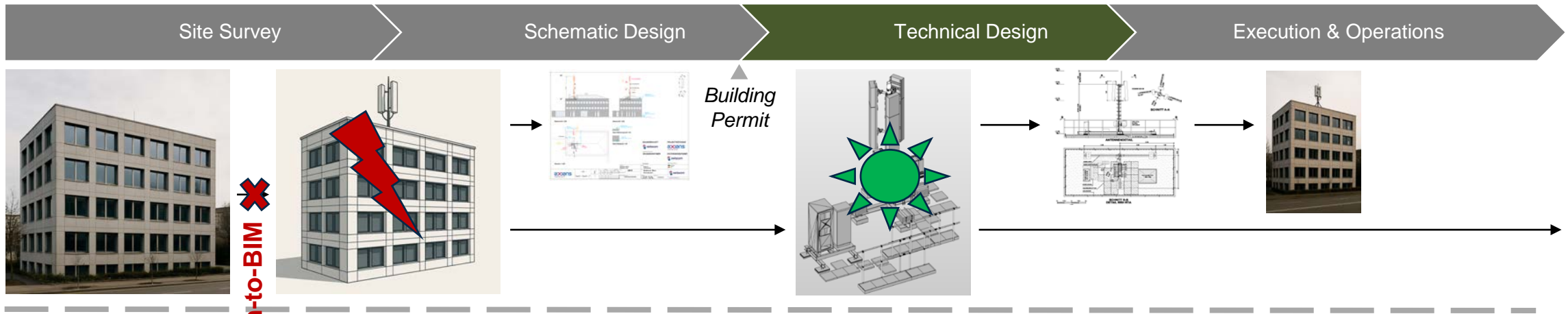
Building Information Modeling (BIM): Planning Method that works with a smart 3D model.

Process:

1. Generate a model from point cloud data
2. Automatically generate plans from the model



Proposed Solution: Model-Based Site Planning



Process:

- Technical design is already done using BIM
- The process would be simplified if a building model were available

Scan-to-BIM: Converts building point cloud into BIM model

Conclusion

- **BIM has proven effective in the execution phase**
- **No efficient solution for Scan-to-BIM has been found yet**
- **The logical next step is the development of a Scan-to-BIM method**

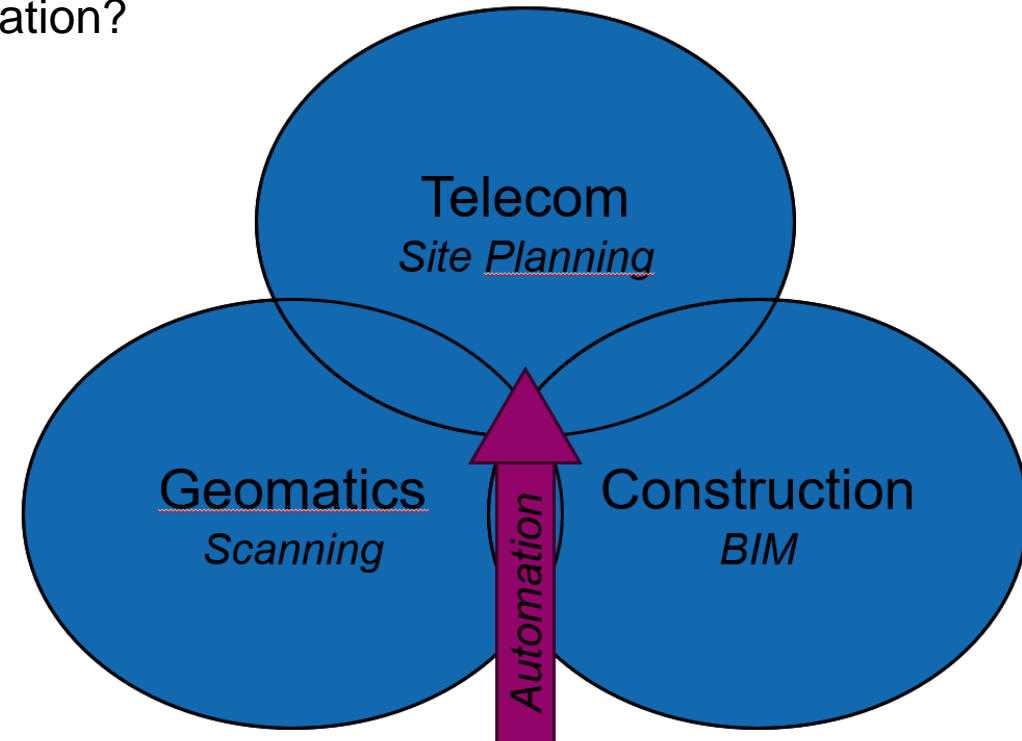
Research Questions

Main Research Question:

- How can Scan-to-BIM be automated for telecom rooftop site planning?

Sub-Questions:

- Which steps of Scan-to-BIM can be automated for rooftop site planning?
- Which tools enable rooftop Scan-to-BIM automation?



Design Science Research Methodology (DSRM) *by Peffers et al. (2007)*



Use of **Exchange Information Requirements (EIR)** to identify problems, objectives and artefacts

Problems

- Inefficiency of conventional site planning
- Lack of commercial solutions for automation

Objectives

- Tool that converts point clouds into a BIM model

Artefacts

1. Scan-to-BIM Framework
2. Python-Script

ETH

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Swiss Federal Institute of Technology Zurich

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Jeffrey Lei
Bachelor Thesis
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Assumptions

- Point clouds with sufficient accuracy, coverage, and density will be given. At least three known points (x, y, z) for georeferencing, with low extrapolation to improve the numerical stability of the Helmert transformation.

Limitations

The BIM workflow covers:

- rooftop locations only (no greenfield locations)
- building envelope model only (no interior, no poles, no telecom equipment)
- building permit phase only (no execution or operation phase)
- 3D BIM only (no construction sequencing (4D BIM), cost estimation (5D BIM) or facility management (6D))
- No suitability evaluation or comparison to conventional working methods
- No measurement techniques for quality assessment are planned

5. Requirements for Data and Information

This section defines the required deliverables, their specifications, and the Definition of Done (DoD). Furthermore, model guidelines are defined, consisting of the required building elements, the required level of detail (LoD), and the required non-geometric attributes².

| Deliverables | DoD |
|--------------|--|
| Mesh | ? |
| Model | Enables the creation of plans without manual adjustments while ensuring compliance with the modeling guidelines. |
| Plans | confirmation from the Building Department of Zurich that all regulatory requirements are met. Retention of the existing plan layout with design flexibility. |

Modeling guidelines

General Model

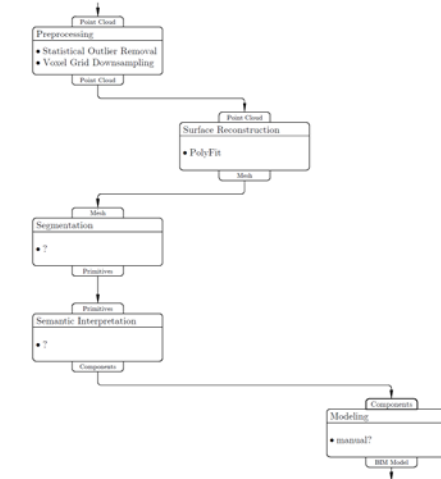
| | |
|-------------------------------------|--|
| Required Level of Development (LoD) | Generally lowest required according to the Building Authority of Zurich (100-200). |
| Required Level of Geometry (LoG) | Pole area: approximate geometry (20 mm) Remaining area: conceptual (50 mm) |
| Model referencing | Georeferenced |

Design Science Research Methodology (DSRM) *by Peffers et al. (2007)*



Artefact 1: Scan-to-BIM Framework

Development of a Scan-to-BIM framework based on the current state of research



Artefact 2: Python Script

Concrete implementation of the developed framework

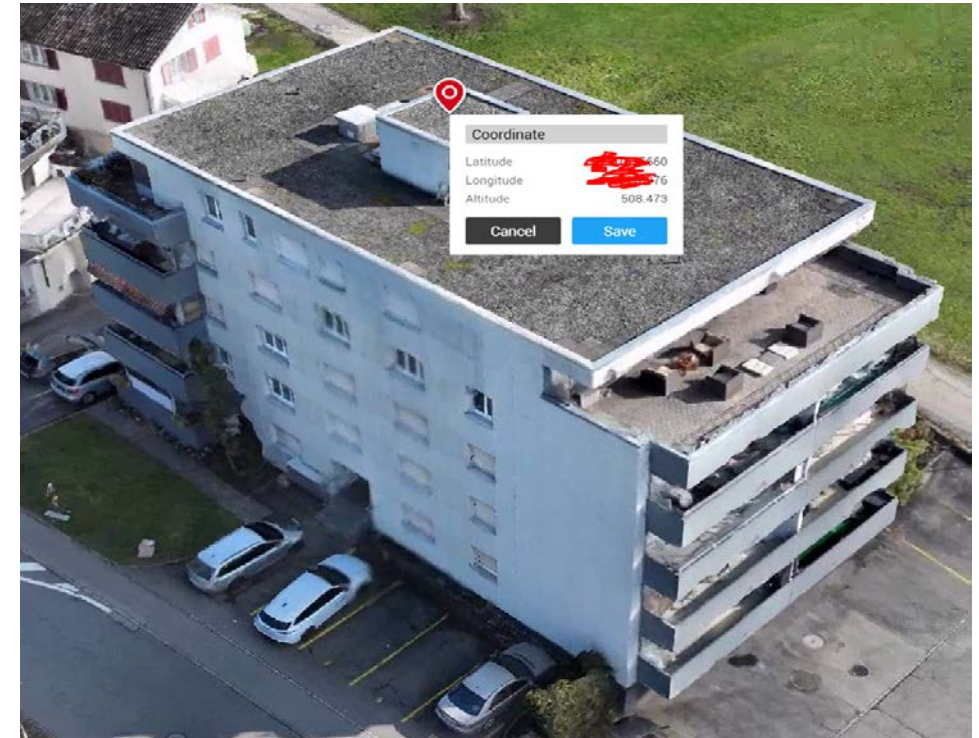
```
13 # Outlier detection
14 if print_outlier:
15     .. outliers = pcl.remove_statistical_outlier(nb_neighbors=20, std_ratio=2.0)
16     num_outliers = num_points - len(outliers)
17
18 # Print results
19 print("Number of points: %d" % num_points)
20 print("Average distance to neighbors: (avg_distance * 100.0) cm")
21
22 if print_outlier:
23     print("Estimated number of outliers: (%d)" % num_outliers)
24     print("Ratio of outliers: (%d)" % (num_outliers/num_points * 100.0))
25
26 print("Bounding Box Center: x: (%d), y: (%d), z: (%d)" % (bbox_center[0], bbox_center[1], bbox_center[2]))
27 print("Bounding Box Size: x: (%d), y: (%d), z: (%d)" % (bbox_size[0], bbox_size[1], bbox_size[2]))
28 print("Bounding Box Max: x: (%d), y: (%d), z: (%d)" % (bbox_max[0], bbox_max[1], bbox_max[2]))
29 print("..." * 50)
30
31 # Steps
32 # Load the point cloud
33 script_dir = os.path.dirname(os.path.abspath(__file__))
34 file_path = os.path.join(script_dir, "pointcloud.ply")
35 if not os.path.exists(file_path):
36     raise FileNotFoundError("File (%s) not found!" % file_path)
37 else:
38     print("Loading point cloud from (%s)" % file_path)
39     pc = pcl.load(file_path)
40     print("Point cloud loaded successfully")
41     viz.visualize_pointcloud(pc, window_name="Original Point Cloud")
42
43 # Preprocessing
44 center_point_cloud = pc
45
46 print("..." * 50)
47 print("Box Data:")
48 get_statistics(pc, print_outlier=True)
49 viz.visualize_boundingbox(pc)
50
51 # Outlier Filter: Statistical Outlier Removal (SOR)
52 pc_filtered, ind = pcl.remove_statistical_outlier(nb_neighbors=20, std_ratio=2.0)
53
54 print("After Outlier Filter:")
55 get_statistics(pc_filtered)
56
57 # Downsampling: Voxel Grid Downsampling
58 pc_down = pc_filtered.voxel_down_sample(sample_size=0.05)
```

Design Science Research Methodology (DSRM) *by Peffers et al. (2007)*



Applying the developed artifact in a real-world **case study**.

The point cloud is provided



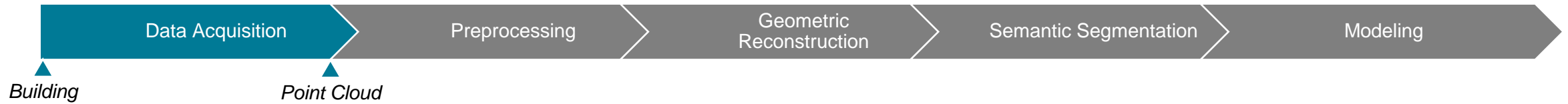
Design Science Research Methodology (DSRM) *by Peffers et al. (2007)*



Evaluation of the demonstration

Evaluation methodology yet to be defined

Scan-to-BIM Framework

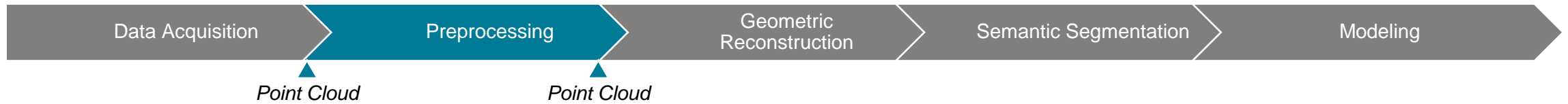


Reality Capture: Captures the real world and represents it as a point cloud

- **Photogrammetry:** Captures the real world using overlapping images
- **LiDAR:** Scans the environment using laser pulses

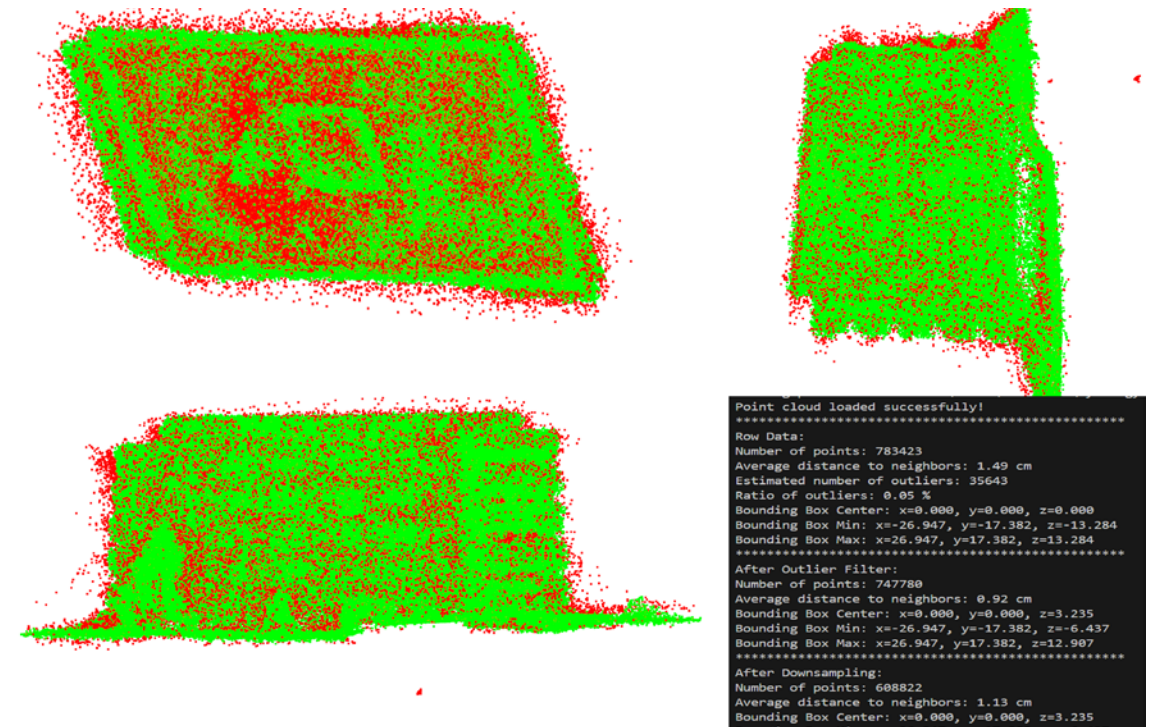


Scan-to-BIM Framework

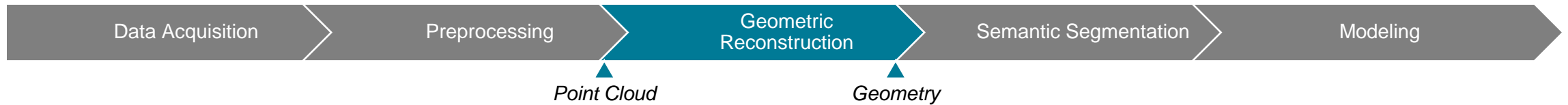


Preprocessing: Prepare data for further processing

1. **Outlier Removal:** Removing far data points
Statistical Outlier Removal (SOR)
2. **Downsampling:** Reducing the amount of data
Voxel Grid Downsampling



Scan-to-BIM Framework



Geometric Reconstruction: Determine geometry of building elements

Achieved with **PolyFit Software** by Nan & Wonka (2017)

1. **Candidate Face Generation:** Generates many planar faces

RANSAC, ...

2. **Face Selection:** Selects optimal faces

Optimization Problem (Integer Linear Programming)

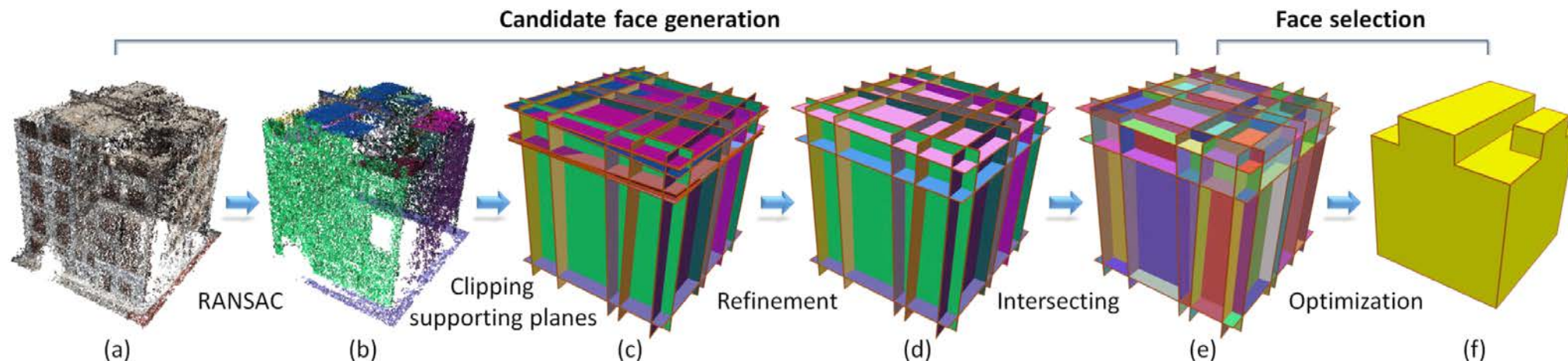
$$\min_{\mathbf{x}} \quad \lambda_f \cdot E_f + \lambda_m \cdot E_m + \lambda_c \cdot E_c$$

$$\text{s.t.} \quad \begin{cases} \sum_{j \in \mathcal{N}(e_i)} x_j = 2 \quad \text{or} \quad 0, & 1 \leq i \leq |E| \\ x_i \in \{0, 1\}, & 1 \leq i \leq N \end{cases}$$

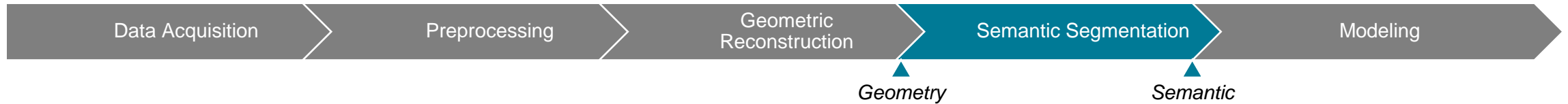
E_f : Point-to-face fitting error

E_m : Penalizes unnecessary complexity

E_c : Encourages clean topology and connectivity



Scan-to-BIM Framework



Semantic Segmentation: Determine semantics of building elements

1. **Feature Extraction:** Selecting useful information from data

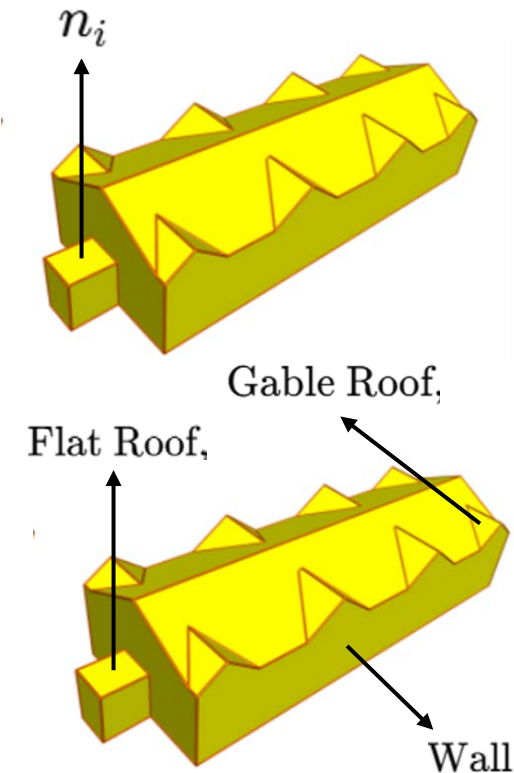
Normal Vector

$$n_i = \begin{bmatrix} x_i \\ y_i \\ z_i \end{bmatrix}, \quad \text{for } i \in \mathcal{I} \subset \mathbb{N}, \text{ the index set of all faces in the model}$$

2. **Classification:** Labeling data points

Rule Based Classification

$$\text{SurfaceType}(n_i) = \begin{cases} \text{Wall,} & \text{if } |z_i| \approx 0 \\ \text{Flat Roof,} & \text{if } \sqrt{x_i^2 + y_i^2} \approx 0 \\ \text{Gable Roof,} & \text{otherwise} \end{cases}$$



Scan-to-BIM Framework



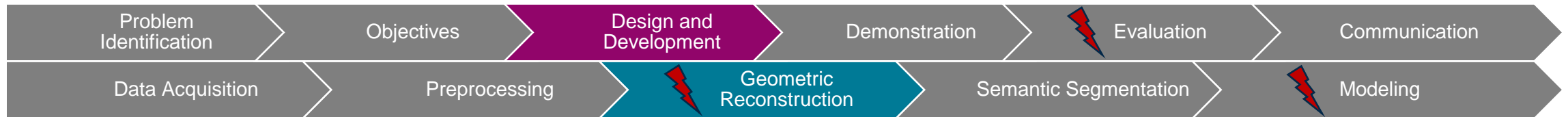
Modeling: Integration of geometry and semantic in BIM-Software

1. **Automated Model Generation:** Automatic generation of building elements
?

2. **Model Refinement:** Import and manual refinement in BIM software
LOD enhancement (windows, doors), ?

3. **Derivation of 2D drawings**

Where am I standing?



Challenges:

1. Implementation of PolyFit (C++) in Python is not yet working
2. Difficult to estimate the complexity of the modeling due to lack of BIM experience
3. Evaluation methodology is still undecided
4. Writing report (and other courses) takes more time than expected - leaving little time for coding 😞

Thank you

Happy to hear your suggestion! 😊