

Time-independent Schrödinger equation in 1D

For the time-dependent Schrödinger equation

$$i\hbar\frac{\partial}{\partial t}|\psi(t,x)\rangle=\hat{H}|\psi(t,x)\rangle$$

can be decomposed by the method of separation of variables when the potential is time-independent $V=V(x)$, that is

$$\hat{H}|\psi(x)\rangle=E|\psi(x)\rangle,$$

where the hamiltonian is given by

$$\hat{H}=-\frac{\hbar^2}{2m}\nabla^2+V(x).$$

Problem

The goal of this project is to solve time-independent Schrödinger equation in 1-dimension called "Eigen Problem", that is

$$-\frac{\hbar^2}{2m}\frac{d^2}{dx^2}\psi(x)+V(x)\psi(x)=E\psi(x),$$

Discrete Schrödinger equation

The time-independent Schrödinger equation is

$$-\frac{\hbar^2}{2m}\frac{d^2}{dx^2}|\psi\rangle+V|\psi\rangle=E|\psi\rangle,$$

where is the column vector

$$|\psi\rangle=\psi_i,\quad i=0,1,\dots,n-1,$$

potential V is a diagonal matrix

$$V=V_i\delta_{i,j},\quad i,j=0,1,\dots,n-1,$$

and the 1-dimension laplacian operator ∇^2 approximate to a $n\times n$ matrix, since

$$\frac{d^2f(x)}{dx^2}\approx\frac{f(x-\delta_x)-2f(x)+f(x+\delta_x)}{\delta_x^2},$$

we define

$$\frac{d^2}{dx^2}f_i=\frac{1}{\delta_x}(f_{i-1}-2f_i+f_{i+1}),\quad i=0,1,\dots,n-1,$$

where $f_{-1}=f_n=0$, plugging we have

$$-\frac{\hbar^2}{2m}\frac{d^2}{dx^2}\psi_i+V_i\delta_{i,j}\psi_i=E\psi_i,$$

or

$$-\frac{\hbar^2}{2m}\frac{1}{\delta x^2}\begin{pmatrix}-2&1&0&0&\cdots&0&0&0\\1&-2&1&0&\cdots&0&0&0\\0&1&-2&1&\cdots&0&0&0\\\vdots&\vdots&\vdots&\vdots&\ddots&\vdots&\vdots&\vdots\\0&0&0&0&\cdots&-2&1&0\\0&0&0&0&\cdots&1&-2&1\\0&0&0&0&\cdots&0&1&-2\end{pmatrix}+\begin{pmatrix}\psi_0\\\psi_1\\\psi_2\\\psi_3\\\vdots\\\psi_{n-3}\\\psi_{n-2}\\\psi_{n-1}\end{pmatrix}\begin{pmatrix}V_0&0&0&0&\cdots&0&0&0\\0&V_1&0&0&\cdots&0&0&0\\0&0&V_2&0&\cdots&0&0&0\\0&0&0&V_3&\cdots&0&0&0\\\vdots&\vdots&\vdots&\vdots&\ddots&\vdots&\vdots&\vdots\\0&0&0&0&\cdots&V_{n-3}&0&0\\0&0&0&0&\cdots&0&V_{n-2}&0\\0&0&0&0&\cdots&0&0&V_{n-1}\end{pmatrix}\begin{pmatrix}\psi_0\\\psi_1\\\psi_2\\\psi_3\\\vdots\\\psi_{n-3}\\\psi_{n-2}\\\psi_{n-1}\end{pmatrix}=E\begin{pmatrix}\psi_0\\\psi_1\\\psi_2\\\psi_3\\\vdots\\\psi_{n-3}\\\psi_{n-2}\\\psi_{n-1}\end{pmatrix},$$

So, now it becomes solving this eigen problem for a large system

$$\begin{pmatrix}\frac{\hbar^2}{\delta_x^2m}+V_0&-\frac{\hbar^2}{2\delta_x^2m}&0&0&\cdots&0&0&0\\-\frac{\hbar^2}{2\delta_x^2m}&\frac{\hbar^2}{\delta_x^2m}+V_1&-\frac{\hbar^2}{2\delta_x^2m}&0&\cdots&0&0&0\\0&-\frac{\hbar^2}{2\delta_x^2m}&\frac{\hbar^2}{\delta_x^2m}+V_2&-\frac{\hbar^2}{2\delta_x^2m}&\cdots&0&0&0\\0&0&-\frac{\hbar^2}{2\delta_x^2m}&\frac{\hbar^2}{\delta_x^2m}+V_3&\cdots&0&0&0\\\vdots&\vdots&\vdots&\vdots&\ddots&\vdots&\vdots&\vdots\\0&0&0&0&\cdots&\frac{\hbar^2}{\delta_x^2m}+V_{n-3}&-\frac{\hbar^2}{2\delta_x^2m}&0\\0&0&0&0&\cdots&-\frac{\hbar^2}{2\delta_x^2m}&\frac{\hbar^2}{\delta_x^2m}+V_{n-2}&-\frac{\hbar^2}{2\delta_x^2m}\\0&0&0&0&\cdots&0&-\frac{\hbar^2}{2\delta_x^2m}&\frac{\hbar^2}{\delta_x^2m}+V_{n-1}\end{pmatrix}\begin{pmatrix}\psi_0\\\psi_1\\\psi_2\\\psi_3\\\vdots\\\psi_{n-3}\\\psi_{n-2}\\\psi_{n-1}\end{pmatrix}=\begin{pmatrix}\psi_0\\\psi_1\\\psi_2\\\psi_3\\\vdots\\\psi_{n-3}\\\psi_{n-2}\\\psi_{n-1}\end{pmatrix}E$$

Algorithm

import package

```
In [ ]: import numpy as np
import matplotlib as mpl
import matplotlib.pyplot as plt
from scipy.linalg import eigh_tridiagonal
```

setting plotting default

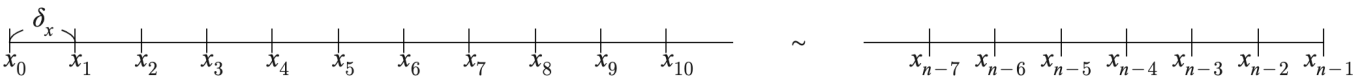
Matplotlib: how to change default style

How to change the font size on a matplotlib plot

```
In [ ]: mpl.rcParams['figure.dpi'] = 400
mpl.rcParams['figure.figsize'] = [12,3]
mpl.rcParams['lines.linewidth'] = 0.5
mpl.rcParams['lines.color'] = 'red'
mpl.rcParams['text.usetex'] = True
mpl.rcParams['font.family'] = 'Times New Roman'
mpl.rcParams['font.size'] = 8
mpl.rcParams['axes.prop_cycle'] = mpl.cycler('color', 'bgrcmyk')
mpl.rcParams['axes.linewidth'] = 0.2
plt.rcParams["mathtext.fontset"] = "cm"
plt.rc('axes', labelsiz=8)
plt.rc('font', size = 12)
plt.rc('xtick', labelsiz=5)
plt.rc('ytick', labelsiz=5)
```

setting the position space

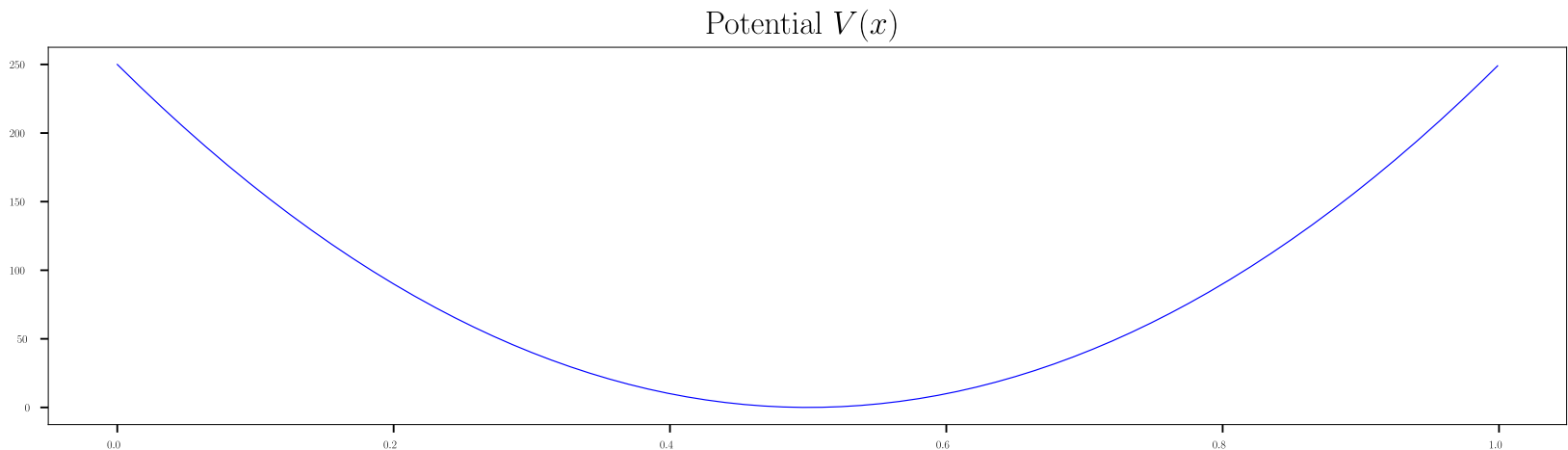
$$x=[x_i,x_i+dx,\dots,x_f]$$



```
In [ ]: xi = 0 # initial point
xf = 1 # final point
dx = 0.001 # step (delta_x)
x = np.arange(xi,xf,dx)
```

define the potential function

```
In [ ]: f=plt.figure()
def V(x):
    v = 1000 *(x-0.5)**2
    #V[x<0.5]=0
    return v
plt.plot(x,V(x))
plt.title("Potential $V(x)$")
plt.show()
f.savefig('assets/Potential.pdf')
```



Solving the eigen problem

Since the discrete Hamiltonian is an tridiagonal matrix in the form

$$\hat{H}=\begin{pmatrix}b_1&c_1&&&0\\a_2&b_2&c_2&&\\&a_3&b_3&\ddots&\\&&\ddots&\ddots&c_{n-1}\\0&&&a_n&b_n\end{pmatrix},$$

we can use [tridiagonal matrix algorithm](#) to solve it, which only need $\mathcal{O}(n)$ operations rather than $\mathcal{O}(n^3)$ operations by [Gaussian elimination](#).

Here using `eigh_tridiagonal(d,e)` function, built up by [scipy](#).

```
In [ ]: d = 1/dx**2 + V(x)
e = -1/(2*dx**2) * np.ones(len(x)-1)
w,v = eigh_tridiagonal(d,e)
```

Define the Eigenfunction ψ_i and Eigenvalue E_i

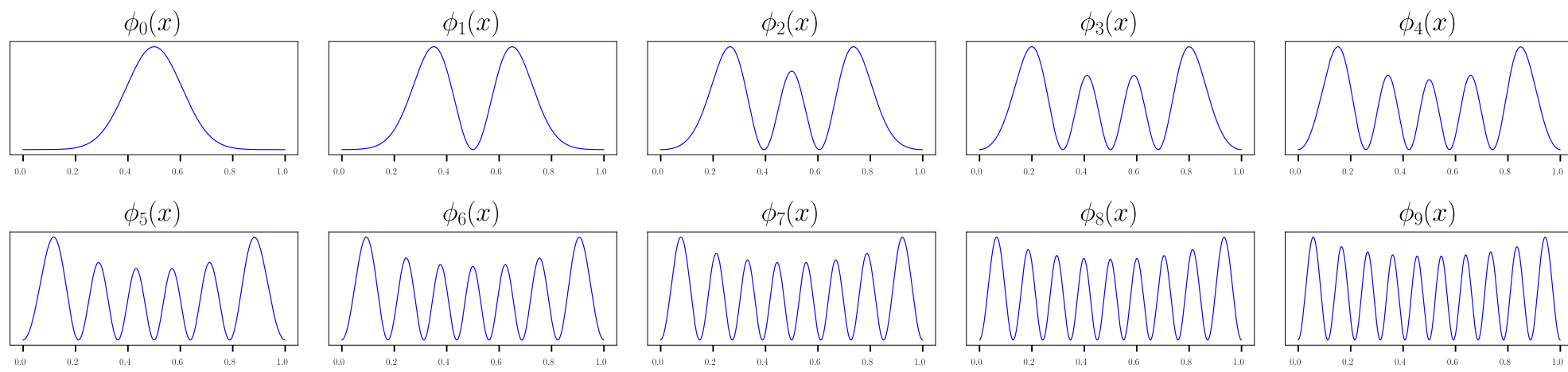
- Eigenfunction $\psi_i, i=0,1,\dots,\text{length}(x)$
- Eigenvalue $E_i, i=0,1,\dots,\text{length}(x)$

```
In [ ]: phi = v.T
E = w
```

Plot the Eigenfunction

$$|\phi_i(x)|^2,\quad i=0,1,\dots,9$$

```
In [ ]: row = 2
col = 5
f=plt.figure()
for i in range(row*col):
    plt.subplot(row,col,i+1)
    plt.plot(x,phi[i]**2)
    plt.title("$\phi_{%d}$"%(i+1))
    plt.xticks([])
    plt.yticks([])
f.tight_layout()
f.savefig('assets/Eigenfunction.pdf')
```



```
In [ ]: E_N = 100
f,(a0,a1) = plt.subplots(1,2,gridspec_kw={'width_ratios':[1,10]})
for i in range(E_N):
    a0.axhline(y = E[i])
    a1.plot(E[0:E_N],'.',markersize=2)
    a0.set_yticks([])
    a0.set_xticks([])
    a1.set_yticks([])
    a1.set_xlabel('$E_n$')
    a1.set_ylabel('Energy')
    f.suptitle('Eigenvalue $E_n$')
    f.savefig('assets/Eigenvalue.pdf')
```

