

Class Notes

Introduction to fluid mechanics

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1 The Equation of Motion

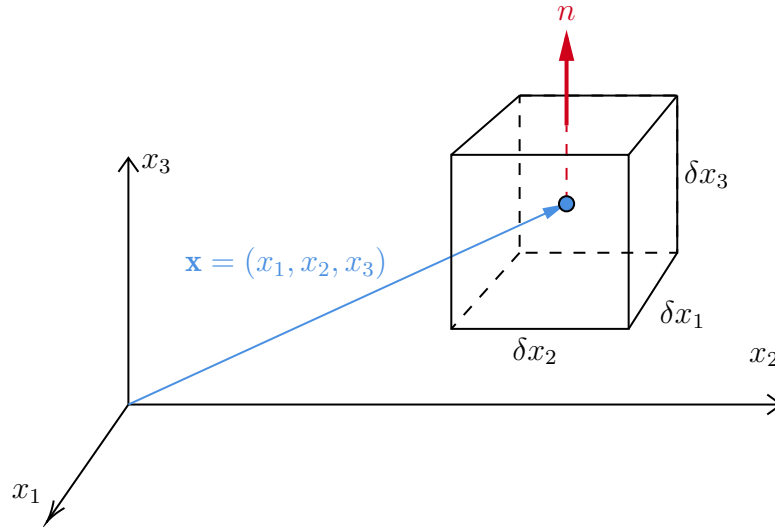
1.1 Introduction

1.1.1 Euler's equation:

Consider a fluid in a domain D in \mathbb{R}^n ($n = 2, n = 3$).

Let $x \in D$, and $\rho(\mathbf{x}, t)$, $\mathbf{u}(\mathbf{x}, t)$, $p(\mathbf{x}, t)$ be the fluid density, velocity vector field and the pressure at the point x and time t . Consider an infinitesimal element of the fluid of volume ∂V located at point x at time t with mass $\delta m = \rho(\mathbf{x}, t)$, which is moving $\mathbf{u}(\mathbf{x}, t)$ and momentum $\delta m \cdot \mathbf{u}(\mathbf{x}, t)$

The normal force directed into the infinitesimal volume across a face of area δa is $\mathbf{n} \cdot p(\mathbf{x}, t) \cdot \delta a$



Note that the pressure is the magnitude of the force per unit area or normal stress, imposed on the fluid from neighboring fluid elements.

1.1.2 Convective derivative

convective derivative 對流導數 / material derivative 物質導數 / advective derivative 隨流導數 / convective derivative 對流導數 / derivative following the motion 隨體導數 / hydrodynamic derivative 水動力導數 / Lagrange derivative 拉格朗日導數 / substantial derivative 隨質導數 Couder a fluid particle moving in fluid, whose position \mathbf{x} at time t is $\mathbf{x}(t)$. Then

$$\frac{d\mathbf{x}(t)}{dt} = \dot{\mathbf{x}} = \mathbf{u}(\mathbf{x}(t), t) \quad (1)$$

Hence, if $f(\mathbf{x}, t)$ is a function on $D \times (0, T)$, then $f(\mathbf{x}(t), t)$ is the value of f at the moving fluid particle at $\mathbf{x}(t)$ at time t . We define the convective derivative of f :

$$\begin{aligned}\frac{Df(\mathbf{x}, t)}{Dt} &= \frac{\partial f(\mathbf{x}, t)}{\partial t} + \dot{\mathbf{x}} \cdot \nabla f(\mathbf{x}, t) \\ &= f_t + \mathbf{u} \cdot \nabla f\end{aligned}\quad (2)$$

where $\nabla f = (f_x, f_y, f_z)$ and $\mathbf{u} = (u_1, u_2, u_3)$.

Hence, if $f(\mathbf{x}, t)$ is a function on $D \times (0, T)$, then $f(\mathbf{x}(t), t)$ is the value of f at the moving fluid particle at $\mathbf{x}(t)$ at time t .

We define the convective derivative of f as:

$$\begin{aligned}\frac{Df(x, t)}{Dt} &= \frac{\partial f}{\partial t} + \dot{\mathbf{x}}(t) \cdot \nabla f, \\ &= f_t + \mathbf{u} \cdot \nabla f\end{aligned}\quad (3)$$

where $\nabla f = (f_x, f_y, f_z)$ and $\mathbf{u} = (u_1, u_2, u_3)$.

1.1.2.1 Def.

For any vector field $\mathbf{F} = (F_1, F_2, \dots, F_n)$ on D , we let

$$\int_D \mathbf{F} dV = \left(\int_D F_1 dV, \int_D F_2 dV, \dots, \int_D F_n dV \right). \quad (4)$$

1.1.2.2 Def.

We will assume that D is a smooth domain, i.e. for any $x_0 \in \partial D$, $\mathbb{R}^n = (x', x_n)$, $n = 2, 3$ $\exists \delta_0 > 0$ and a smooth function $\varphi : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$, s.t.

$$\partial D \cap B(x_0, \delta_0) = \{(x', \varphi(x')) : \|x'\| < \delta_0, x' \in \mathbb{R}^{n-1}\} \cap B(x_0, \delta_0) \quad (5)$$

and

$$D \cap B(x_0, \delta_0) = \{(x', x_n) : x_n > \varphi(x'), x' \in \mathbb{R}^{n-1}, \|x'\| < \delta_0\} \cap B(x_0, \delta_0) \quad (6)$$

1.1.2.3 Claim

Consider the volume δV of an element of mass δm , which moves in the fluid by the fluid motion

$$\frac{d(\delta V)}{dt} = (\nabla \cdot \mathbf{u})(\mathbf{x}, t) \cdot \delta V \quad \text{as } \delta x_1, \delta x_2, \delta x_3 \rightarrow 0, \quad (7)$$

where $\nabla \cdot \mathbf{u} = \text{div } \mathbf{u} = \sum_{i=1}^3 \frac{\partial u_i}{\partial x_i}$, $\mathbf{u} = (u_1, u_2, u_3)$.

1.1.2.4 proof

$$\begin{aligned}\frac{d(\delta V)}{dt} &= \frac{d}{dt}(\delta x_1, \delta x_2, \delta x_3) \\ &= \frac{d(\delta x_1)}{dt} \delta x_2 \delta x_3 + \frac{d(\delta x_2)}{dt} \delta x_1 \delta x_3 + \frac{d(\delta x_3)}{dt} \delta x_1 \delta x_2\end{aligned}\quad (8)$$

For the first term

$$\begin{aligned} \frac{d(\delta x_1)}{dt} &\approx u_1 \left(x_1 + \frac{\delta x_1}{2}, x_2, x_3 \right) - u_1 \left(x_1 - \frac{\delta x_1}{2}, x_2, x_3 \right) \\ &= \frac{\partial u_1}{\partial x_1}(\xi_1, x_2, x_3) \delta x_1, \quad \text{for some } \xi_1 \in \left(x_1 - \frac{\delta x_1}{2}, x_1 + \frac{\delta x_1}{2} \right) \end{aligned} \quad (9)$$

then

$$\frac{d(\delta x_1)}{dt} \delta x_2 \delta x_3 \rightarrow \frac{\partial u_1}{\partial x_1}(x_1, x_2, x_3) \delta x_1 \delta x_2 \delta x_3, \quad \text{as } \delta x_1, \delta x_2, \delta x_3 \rightarrow 0 \quad (10)$$

Similarly

$$\frac{d(\delta x_2)}{dt} \delta x_1 \delta x_3 \rightarrow \frac{\partial u_2}{\partial x_2}(x_1, x_2, x_3) \delta x_1 \delta x_2 \delta x_3, \quad \text{as } \delta x_1, \delta x_2, \delta x_3 \rightarrow 0 \quad (11)$$

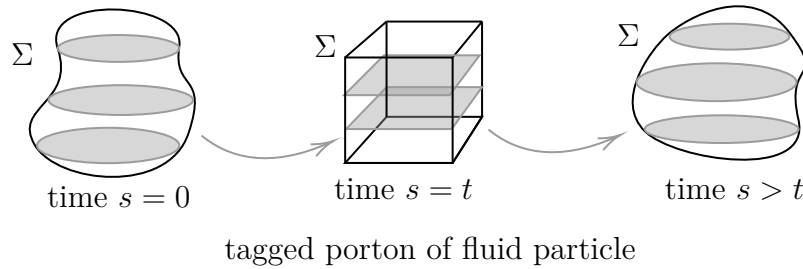
and

$$\frac{d(\delta x_3)}{dt} \delta x_1 \delta x_2 \rightarrow \frac{\partial u_3}{\partial x_3}(x_1, x_2, x_3) \delta x_1 \delta x_2 \delta x_3, \quad \text{as } \delta x_1, \delta x_2, \delta x_3 \rightarrow 0 \quad (12)$$

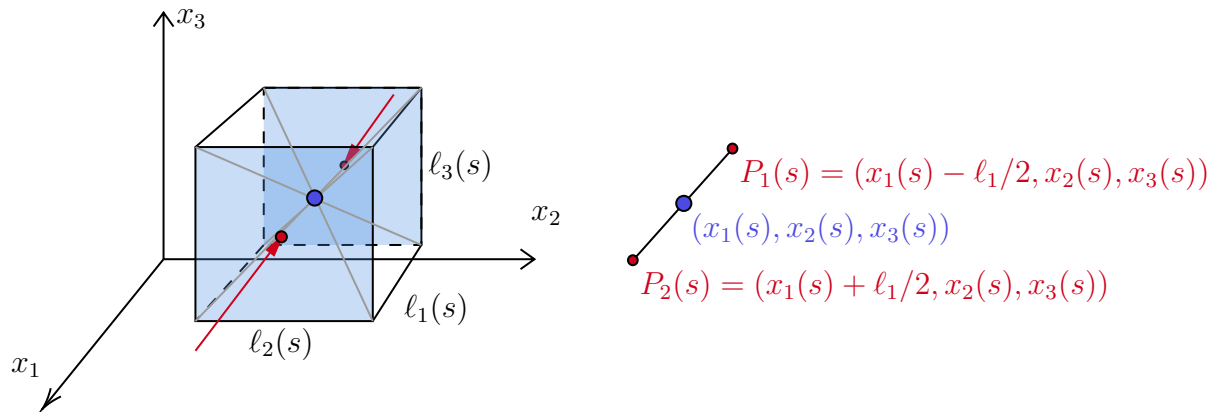
so that

$$\frac{d(\delta V)}{dt} = \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) \delta x_1 \delta x_2 \delta x_3 = (\nabla \cdot \mathbf{u}) \delta V \quad (13)$$

1.1.2.5 Note



Consider a tagged (marked) portion Σ of fluid with center of mass at $(x_1(s), x_2(s), x_3(s))$ at time s . Let $m(x)$ and $V(s)$ be the mass and volume of this portion Σ of fluid at time s . The portion of fluid particle moves along with fluid. see as (2/21 fig1)



For a time $t > 0$, suppose at time t , the tagged portion Σ of fluid particles is a cube centered at (x_1, x_2, x_3) with side length ℓ_1, ℓ_2, ℓ_3 , see as (2/21 fig2 - textbook p.4), where

$$\begin{aligned} P_1(s) &= \left(x_1(s) - \frac{\ell_1(s)}{2}, x_2(s), x_3(s) \right) \\ P_2(s) &= \left(x_1(s) + \frac{\ell_1(s)}{2}, x_2(s), x_3(s) \right) \end{aligned} \quad (14)$$

We assume that Σ remain a cube for $s \approx t$ with side length, $\ell_1(s), \ell_2(s), \ell_3(s)$, then $V(s) = \ell_1(s) \cdot \ell_2(s) \cdot \ell_3(s)$

$$\left. \frac{dV(s)}{ds} \right|_{s=t} = \left. \frac{d\ell_1(s)}{ds} \right|_{s=t} \ell_2(s)\ell_3(s) + \left. \frac{d\ell_2(s)}{ds} \right|_{s=t} \ell_1(s)\ell_3(s) + \left. \frac{d\ell_3(s)}{ds} \right|_{s=t} \ell_1(s)\ell_2(s) \quad (15)$$

where

$$\begin{aligned} \left. \frac{d\ell_1(s)}{ds} \right|_{s=t} &= u_1(P_2(t), t) - u_1(P_1(t), t) \\ &= u_1 \left(x_1(s) + \frac{\ell_1(s)}{2}, x_2(s), x_3(s), t \right) - u_1 \left(x_1(s) - \frac{\ell_1(s)}{2}, x_2(s), x_3(s), t \right) \\ &\approx \frac{\partial u_1}{\partial x_1} (x_1, x_2, x_3, t) \cdot \ell_1 \end{aligned} \quad (16)$$

Similarly

$$\left. \frac{d\ell_i}{ds} \right|_{s=t} = \frac{\partial u_i}{\partial x_i} (x_1, x_2, x_3) \cdot \ell_i, \quad \forall i = 1, 2, 3. \quad (17)$$

Now we write $\left. \frac{d}{ds} \right|_{s=t} = \frac{d}{dt}$, combined with equation

1.1.3 Continuity equation

Let $\rho(\mathbf{x}, t)$ be the density of fluid at time s . Since $M(s) = \text{const.}$, $\forall s > 0$ and $\frac{dM(s)}{ds} = 0$, $\forall s > 0$. Therefore, since it is similar to the cube, the density is

$$\rho(\mathbf{x}, s) \approx \frac{M(s)}{V(s)} \quad (18)$$

and the derivative is

$$\begin{aligned}
\left. \frac{d}{ds} \rho(\mathbf{x}, s) \right|_{s=t} &\approx \left. \frac{d}{ds} \frac{M(s)}{V(s)} \right|_{s=t} \\
&= \left. \frac{M'(s)V(s) - M(s)V'(s)}{V^2(s)} \right|_{s=t} \\
&= \left. \frac{0 - M(s) \frac{d}{ds} V(s)}{V^2(s)} \right|_{s=t} \\
&= - \left. \frac{M(s)(\operatorname{div} \mathbf{u})V(s)}{V^2(s)} \right|_{s=t} \\
&= - \left. \frac{M(s)}{V(s)} (\operatorname{div} \mathbf{u}(s)) \right|_{s=t} \\
&= - \left. \rho(\mathbf{x}(s), s) (\operatorname{div} \mathbf{u}(s)) \right|_{s=t}
\end{aligned} \tag{19}$$

we get

$$-\frac{d}{dt} \rho(\mathbf{x}(t), t) = \rho \cdot (\nabla \cdot \mathbf{u}(t)) \tag{20}$$

On the other hand, by chain rule

$$\frac{d}{dt} \rho(\mathbf{x}(t), t) = \rho_t + (\nabla \rho) \cdot \mathbf{u}(t) \tag{21}$$

combining together we have

$$\begin{aligned}
&\Rightarrow \rho_t + (\nabla \rho) \cdot \mathbf{u} = \rho \cdot (\nabla \cdot \mathbf{u}) \\
&\Rightarrow \rho_t + (\nabla \rho) \cdot \mathbf{u} - \rho \cdot (\nabla \cdot \mathbf{u}) = 0 \\
&\Rightarrow \rho_t + \nabla \cdot (\rho \mathbf{u}) = 0
\end{aligned} \tag{22}$$

and the equation $\rho_t + \nabla \cdot (\rho \mathbf{u}) = 0$ is called the *continuity equation*.

1.1.4 Heuristic proof of the Euler equation

In the ansense of an externally applied forces, the net force \mathbf{F} , acting on δV , is due to the pressure field.

Write $\mathbf{F} = (F_1, F_2, F_3)$, we get

$$\begin{aligned}
\mathbf{F}(x_1, x_2, x_3, t) &\approx \left(P \left(x_1 - \frac{\delta x_1}{2}, x_2, x_3, t \right) - P \left(x_1 + \frac{\delta x_1}{2}, x_2, x_3, t \right) \right) \delta x_2 \delta x_3 \\
&= - \frac{\partial P}{\partial x_1} (\zeta_1, x_2, x_3, t) \delta x_1 \delta x_2 \delta x_3, \quad \delta x_1, \delta x_2, \delta x_3 \rightarrow 0 \\
&= \frac{\partial P}{\partial x_1} (\zeta_1, x_2, x_3, t) \delta V
\end{aligned} \tag{23}$$

for some $\zeta_1 \in (x_1 - \frac{\delta x_1}{2}, x_1 + \frac{\delta x_1}{2})$.

By Newton's second law, the equation of motion for the element of fund mass δm , at point $\mathbf{x}(t)$ is

$$\frac{d}{dt}(\delta m \cdot \mathbf{u}(\mathbf{x}, t)) = \mathbf{F} = -(\nabla P)\delta V \quad (24)$$

also

$$\frac{d}{dt}(\delta m \cdot \mathbf{u}(\mathbf{x}, t)) = \delta m \frac{d}{dt} \mathbf{u}(\mathbf{x}, t) = \delta m (\mathbf{u}_t + (\nabla \cdot \mathbf{u})) \mathbf{u} \quad (25)$$

then

$$\begin{aligned} \delta m (\mathbf{u}_t + (\nabla \cdot \mathbf{u})) \mathbf{u} &= -(\nabla P)\delta V \\ \mathbf{u}_t + (\nabla \cdot \mathbf{u}) \mathbf{u} &= -(\nabla P) \frac{\delta V}{\delta m} = -(\nabla P) \frac{1}{\delta m / \delta V} \end{aligned} \quad (26)$$

we get a equation

$$\mathbf{u}_t + (\nabla \cdot \mathbf{u}) \mathbf{u} = -\frac{\nabla P}{\rho} \quad (27)$$

called *Euler's equation*.

Notice that

$$\begin{aligned} (\nabla \cdot \mathbf{u}) \mathbf{u} &= \left(\sum_{i=1}^3 u_i \frac{\partial}{\partial x_i} \right) \mathbf{u} \\ &= \left(u_1 \frac{\partial}{\partial x_1} + u_2 \frac{\partial}{\partial x_2} + u_3 \frac{\partial}{\partial x_3} \right) \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \\ &= \begin{pmatrix} \left(u_1 \frac{\partial}{\partial x_1} + u_2 \frac{\partial}{\partial x_2} + u_3 \frac{\partial}{\partial x_3} \right) u_1 \\ \left(u_1 \frac{\partial}{\partial x_1} + u_2 \frac{\partial}{\partial x_2} + u_3 \frac{\partial}{\partial x_3} \right) u_2 \\ \left(u_1 \frac{\partial}{\partial x_1} + u_2 \frac{\partial}{\partial x_2} + u_3 \frac{\partial}{\partial x_3} \right) u_3 \end{pmatrix} \end{aligned} \quad (28)$$

1.1.5 Lemma

Let D be a bounded domain and $F : \bar{D} \times [0, a_0] \rightarrow \mathbb{R}$ be a smooth function (or C^∞), then

$$\frac{d}{dt} \int_D F(x, t) dx = \int_D \frac{dF(x, t)}{dt} dx \quad (29)$$

1.1.5.1 proof

we have

$$\begin{aligned} \frac{d}{dt} \int_D F(x, t) dx &= \lim_{\Delta t \rightarrow 0} \left[\frac{1}{\Delta t} \int_D F(x, t + \Delta t) dx - \frac{d}{dt} \int_D F(x, t) dx \right] \\ &= \lim_{\Delta t \rightarrow 0} \frac{d}{dt} \int_D \frac{F(x, t + \Delta t) - F(x, t)}{\Delta t} dx \\ &= \text{By M.V.T.} \\ &= \lim_{\Delta t \rightarrow 0} \int_D \frac{\frac{\partial}{\partial t} F(x, \xi) \Delta t}{\Delta t} dx, \quad \text{for some } \xi, \text{ where } t < \xi < t + \Delta \\ &= \lim_{\Delta t \rightarrow 0} \int_D \frac{\partial}{\partial t} F(x, \xi) dx \end{aligned} \quad (30)$$

Denote, $\frac{\partial}{\partial t}F(x, t) = F_t(x, t)$ and $\frac{\partial^2}{\partial t^2}F(x, t) = F_{tt}(x, t)$, so

$$\begin{aligned}
& \left| \frac{1}{\Delta t} \int_D [F(x, t + \Delta t) - F(x, t)] - \int_D \frac{\partial}{\partial t} F(x, t) dx \right| \\
&= \left| \int_D F_t(x, \xi) dx - \int_D F_t(x, t) dx \right| \\
&= \text{By MVT} \\
&= \left| \int_D [F_t(x, \xi) - F_t(x, t)] dx \right| \tag{31} \\
&= \text{By MVT} \\
&= \left| \int_D F_{tt}(x, z)(t - \xi) dz \right|, \quad z \text{ between } t \text{ and } \xi \\
&\leq M|t - \xi||D| \rightarrow 0, \quad \text{where } |D| \text{ is volume of } D
\end{aligned}$$

where $M = \sup_{(x,t) \in D \times (0,a)} F_{tt}(x, t)$.

