

Racing Game Data 분석과 탄성체 Actuator 제작을 통한 체감형 Racing Simulator 제작

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TEXAS INSTRUMENTS

높은 비용



불편함

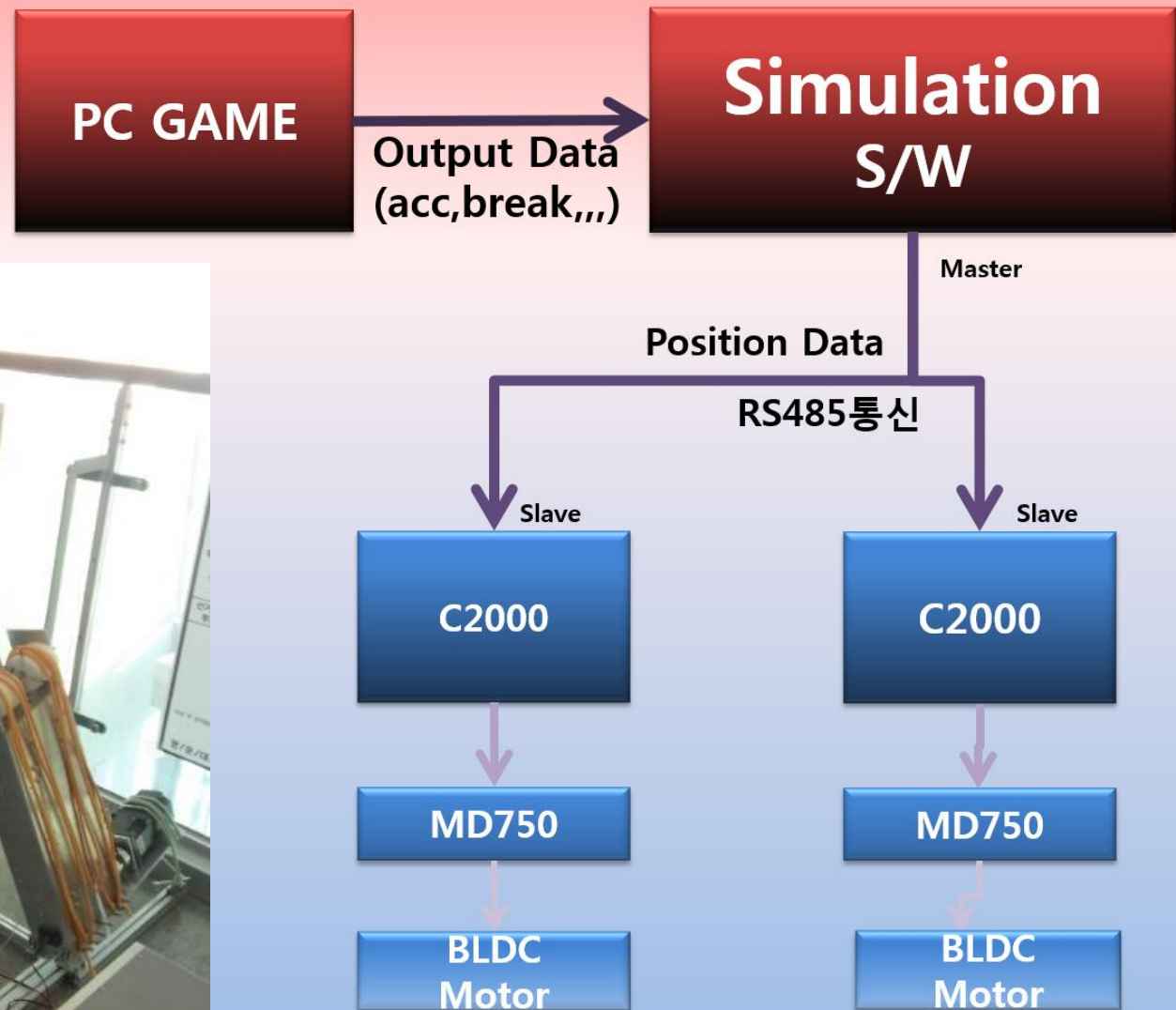


사고의 위험



하지만 레이싱을 즐기기는 쉽지가 않다

Racing Simulator System Architecture

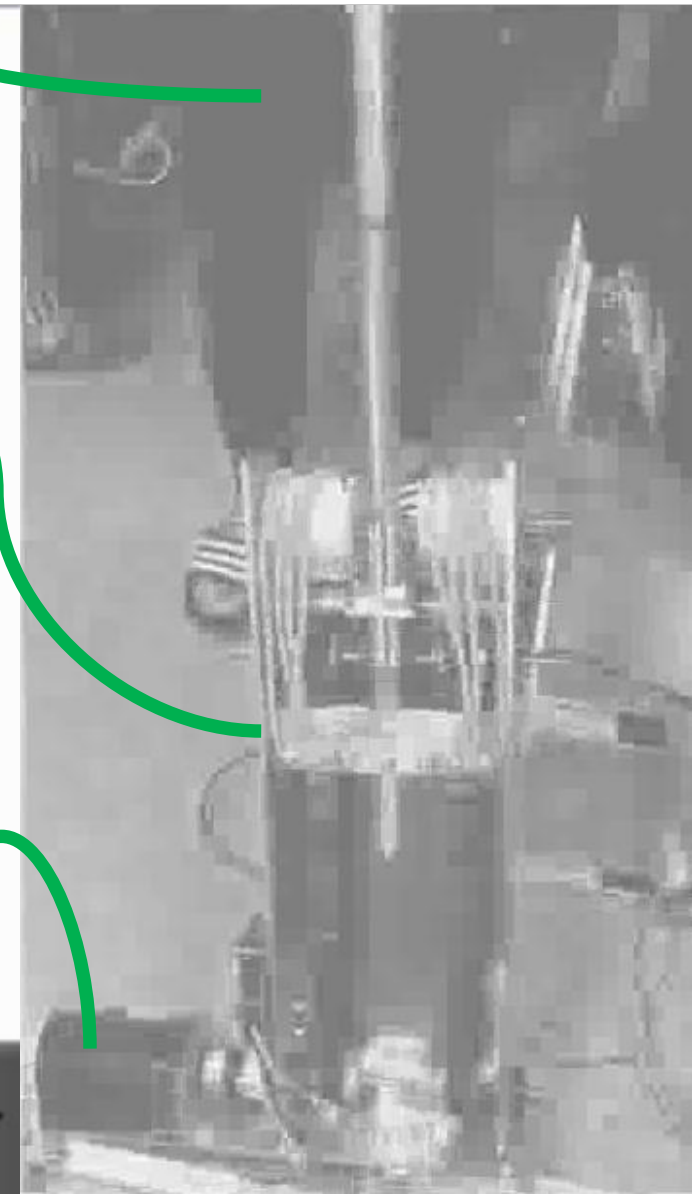
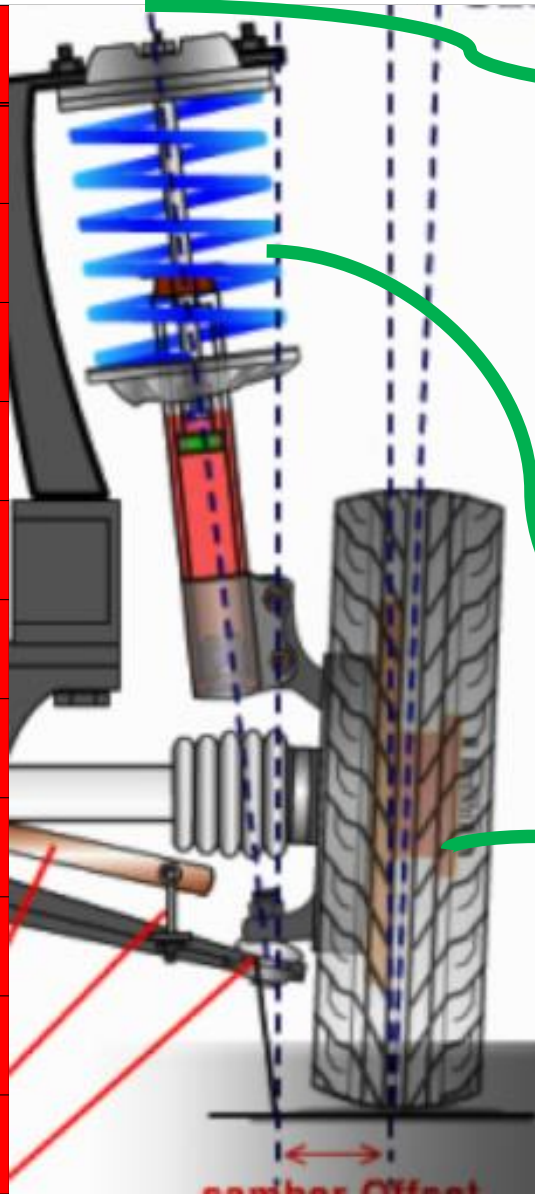


Racing Simulator S/W - UI



H/W - Elastic Acuator

Actuator 방식	제작 - 2축
	전기 타이밍벨트
단가	↓
속도	↑
Roll 정도	$\pm 30^\circ$
Pitch 정도	$\pm 30^\circ$
Yaw 정도	$\pm 10^\circ$
질감 충격 정도	↑
가속도 정도	↑
게임 호완성	↑
단가	↓
안정성	↓



Racing Simulator H/W - Racing Simulator



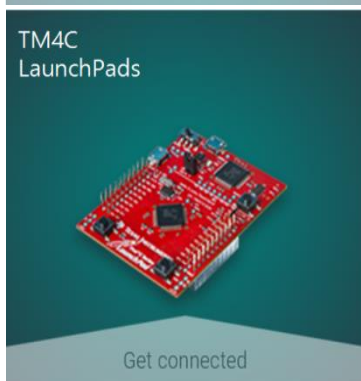
C2000 - Why?

- Need 1** Real time control → Can do exact control
- Need 2** Real time debugging → Catch problem easily
- Need 3** 3 External Interrupt → Can use BLDC motor



MSP : EXP430FR5969, EXP430F5529LP...

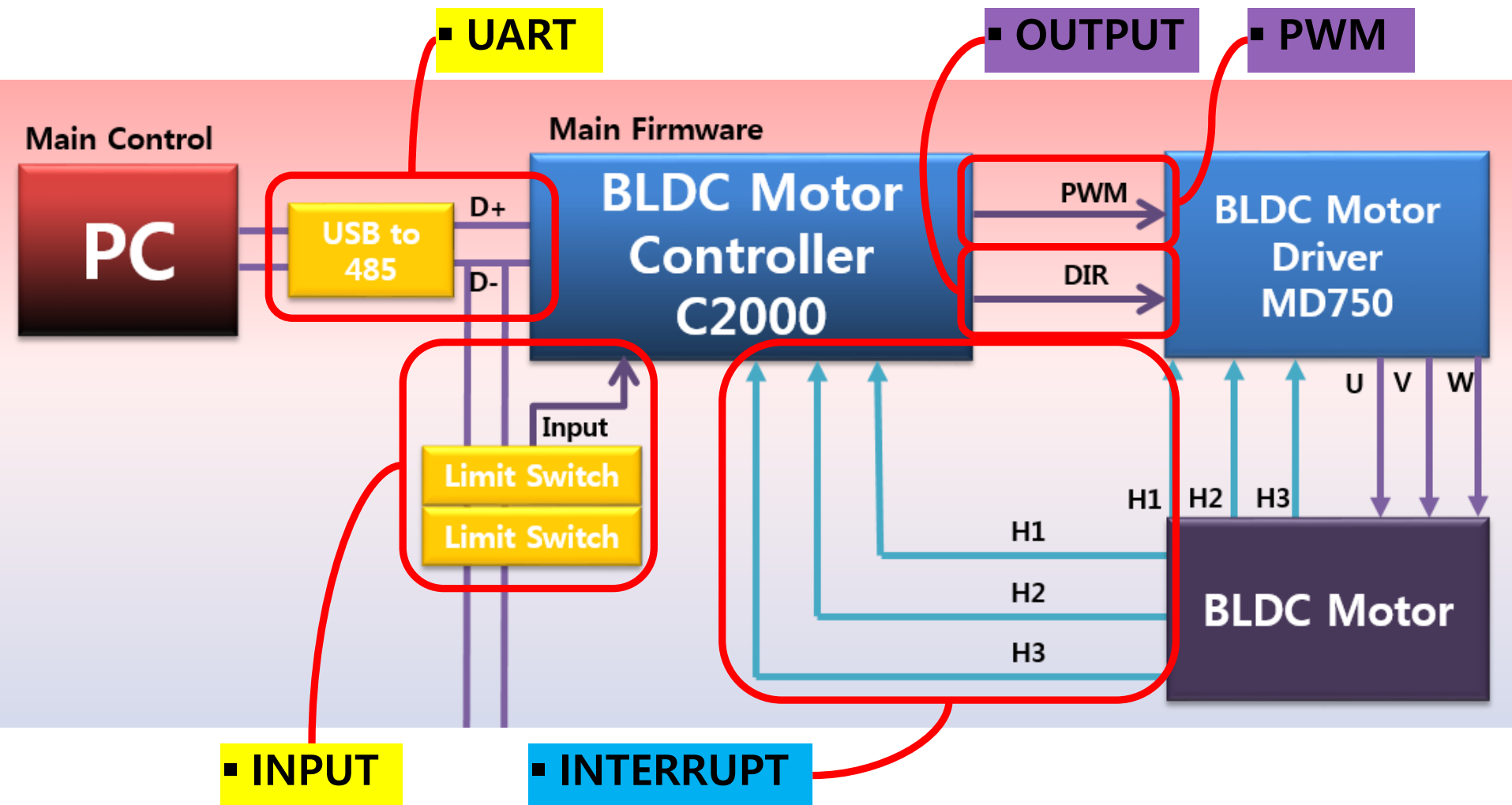
- ▶ Low-power, high performance
- ▶ Onboard emulator



TM4C : EK-TM4C123GXL

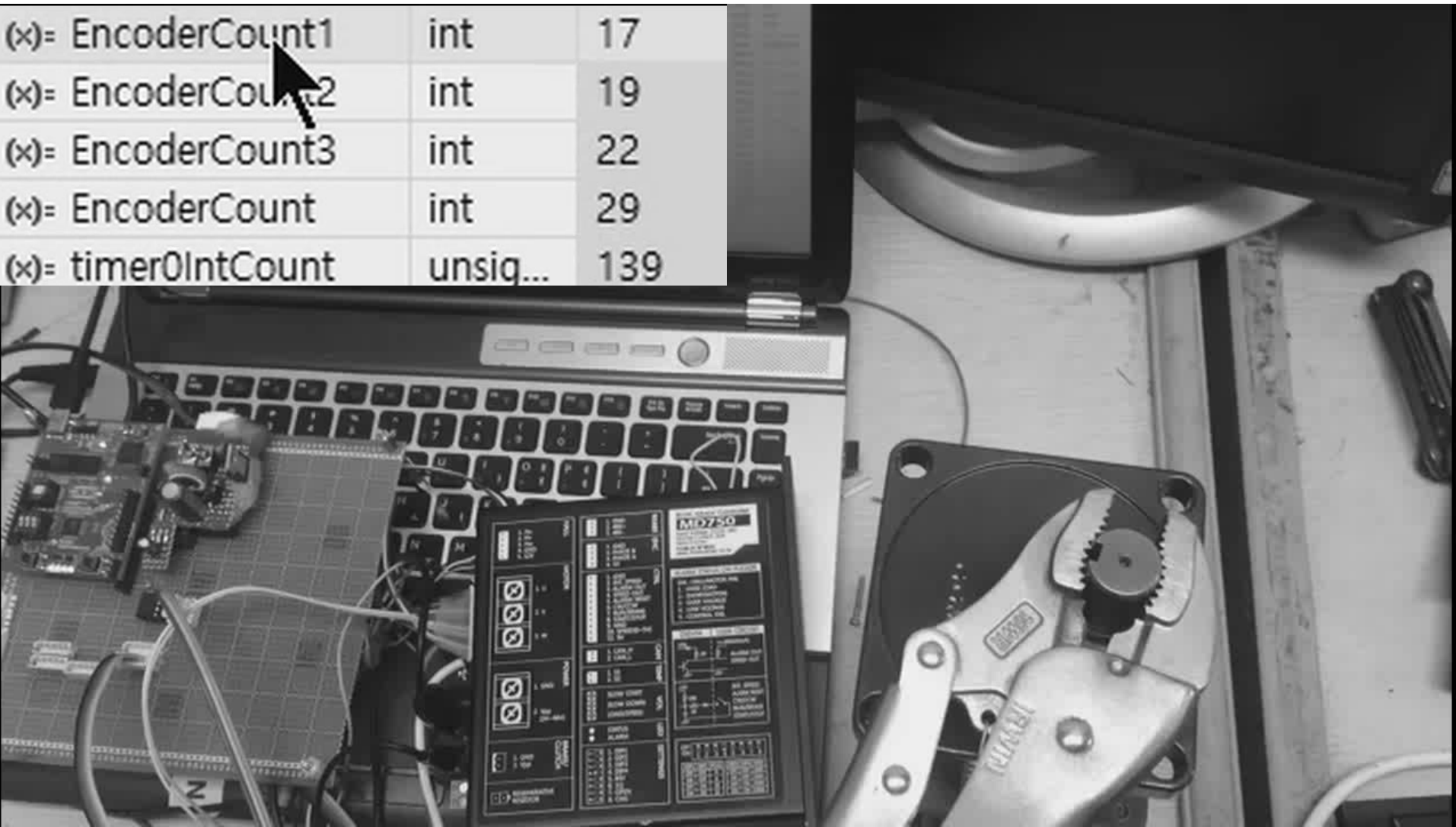
- ▶ Connectivity
- ▶ Two CAN modules
- ▶ 8 UART, 6 I2C, 4 SPI

C2000 - System Architecture



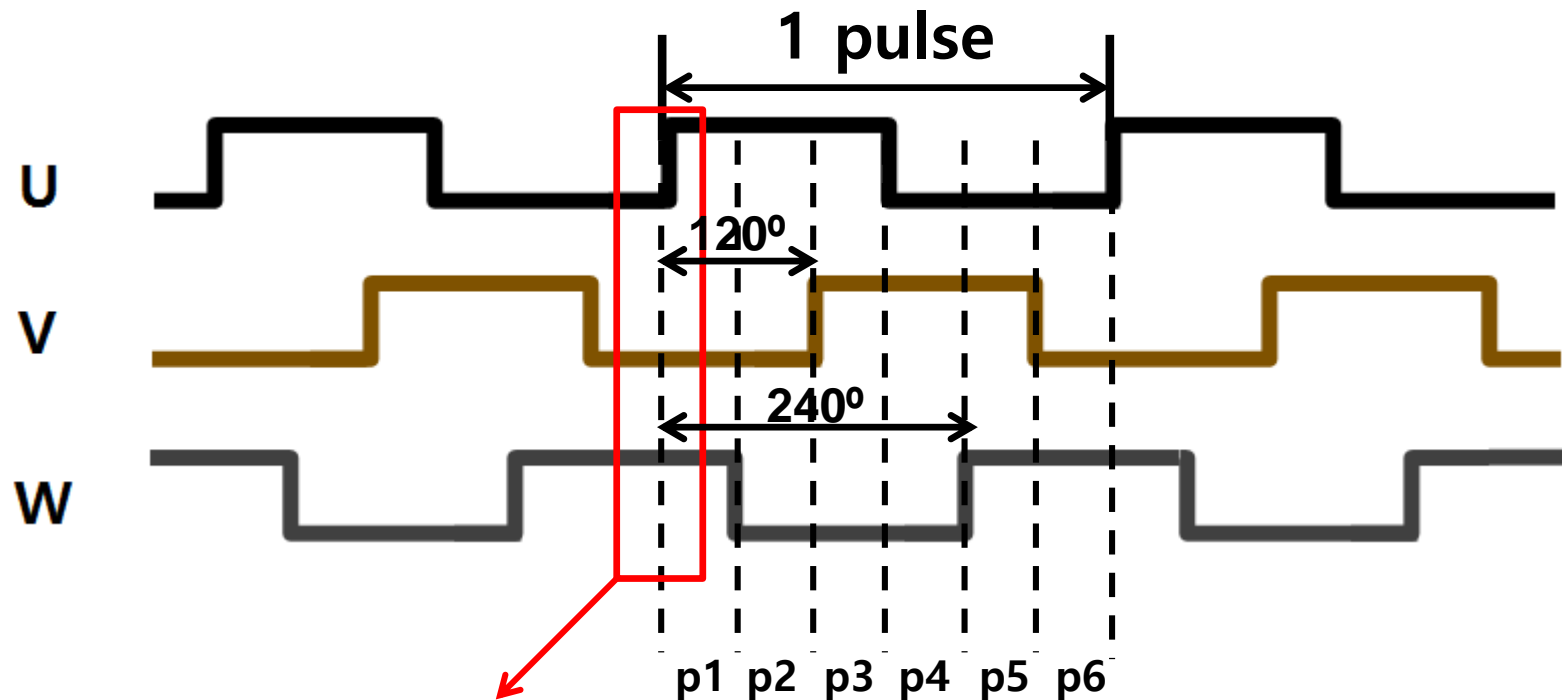
C2000 - Encoder (Interrupt)

(x)= EncoderCount1	int	17
(x)= EncoderCount2	int	19
(x)= EncoderCount3	int	22
(x)= EncoderCount	int	29
(x)= timer0IntCount	unsig...	139



C2000 - Motor PID Control (Timer)

▪ Hall sensor Resolution Multiplication (3-Phase)

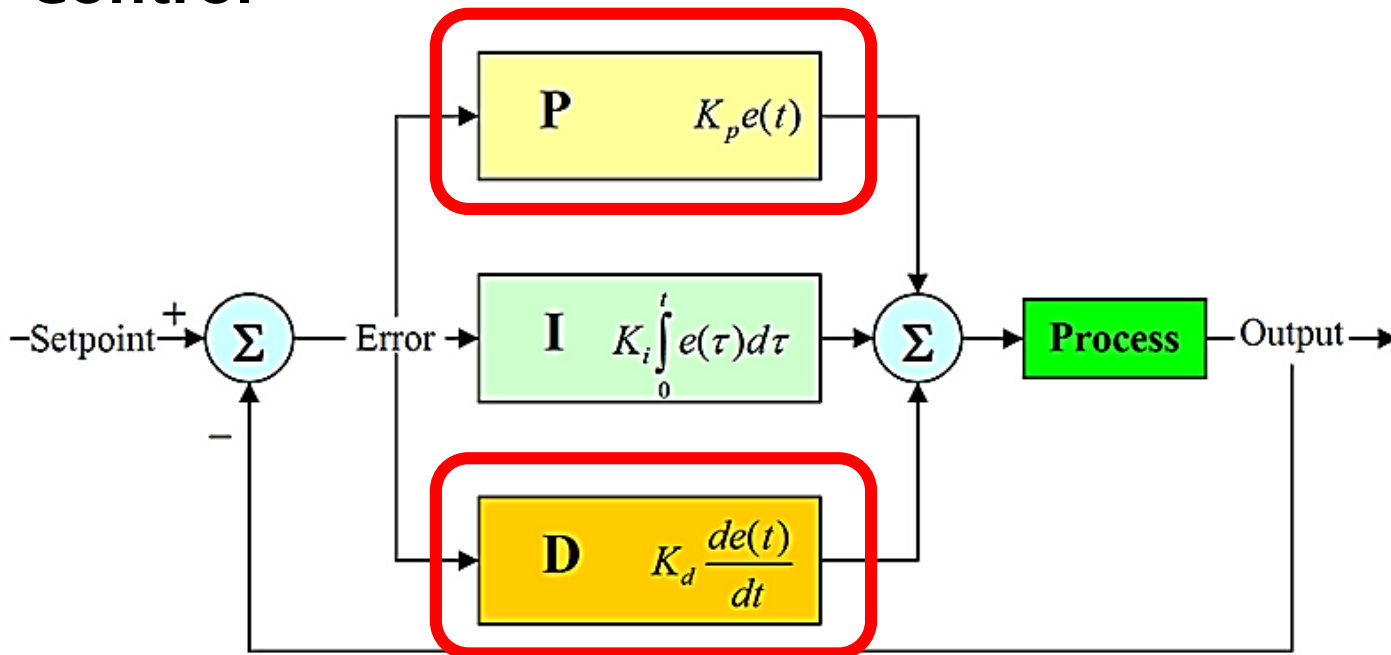


U → Rising Edge
V → Low
W → High

= 6 pulse (x6)

C2000 - Motor PID Control (Timer)

- Motor Position Control(BLDC Motor)
 - PD Control

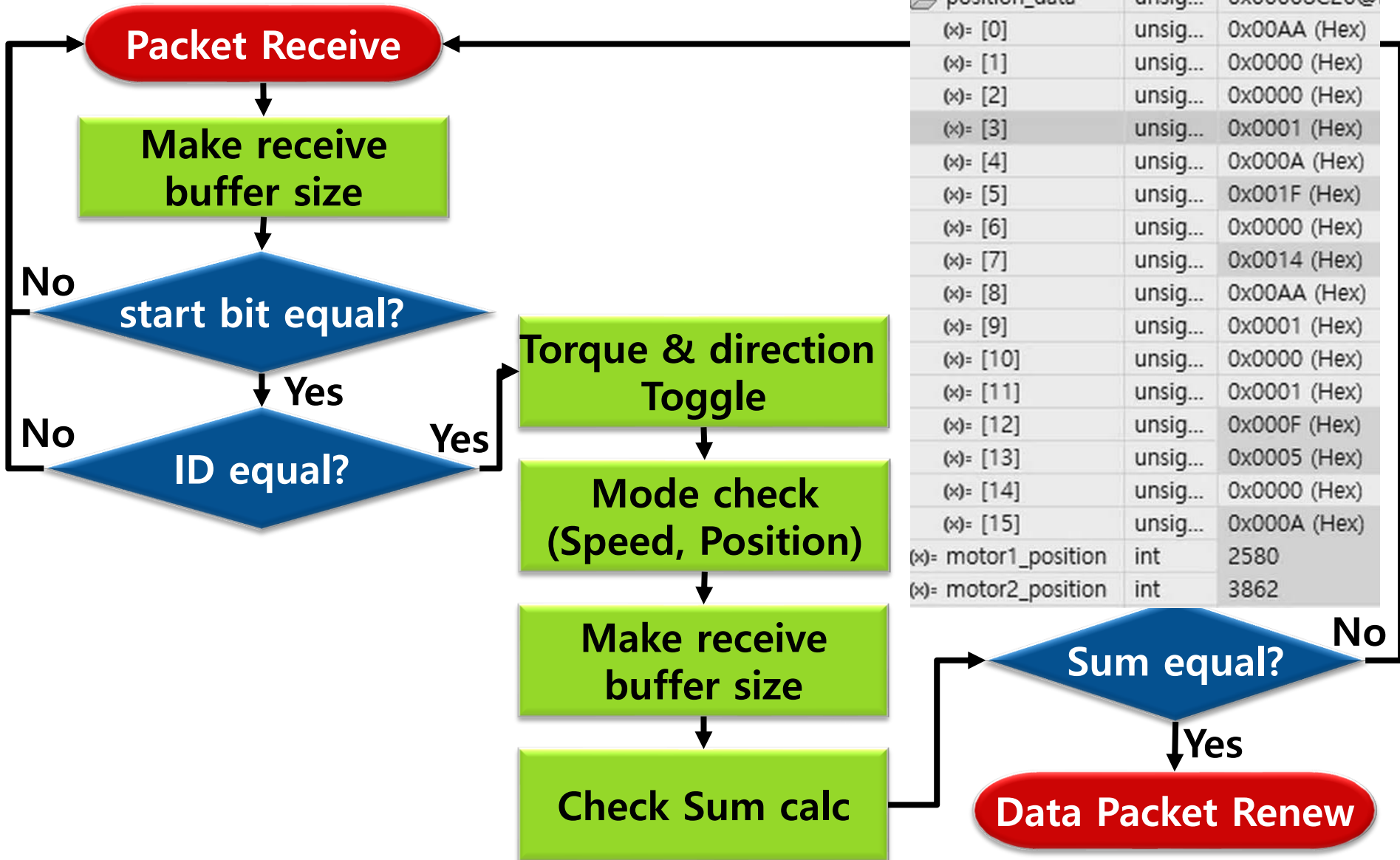


Set point : Hall Sensor Pulse

Output : PWM Pulse

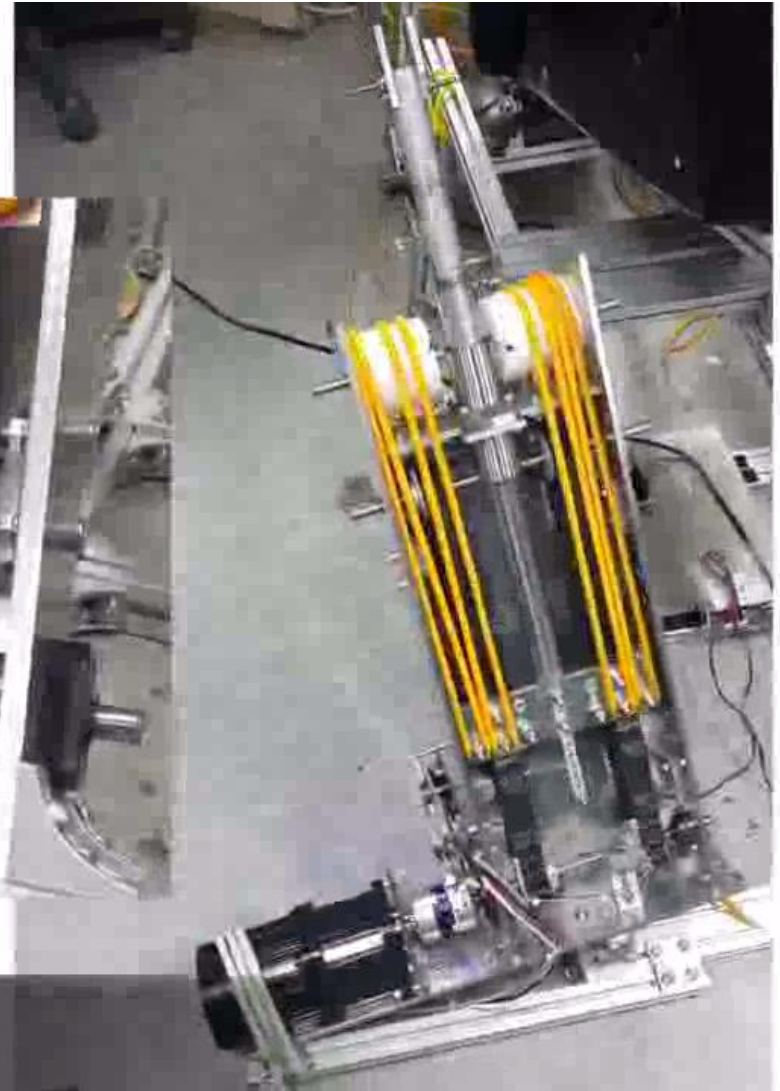
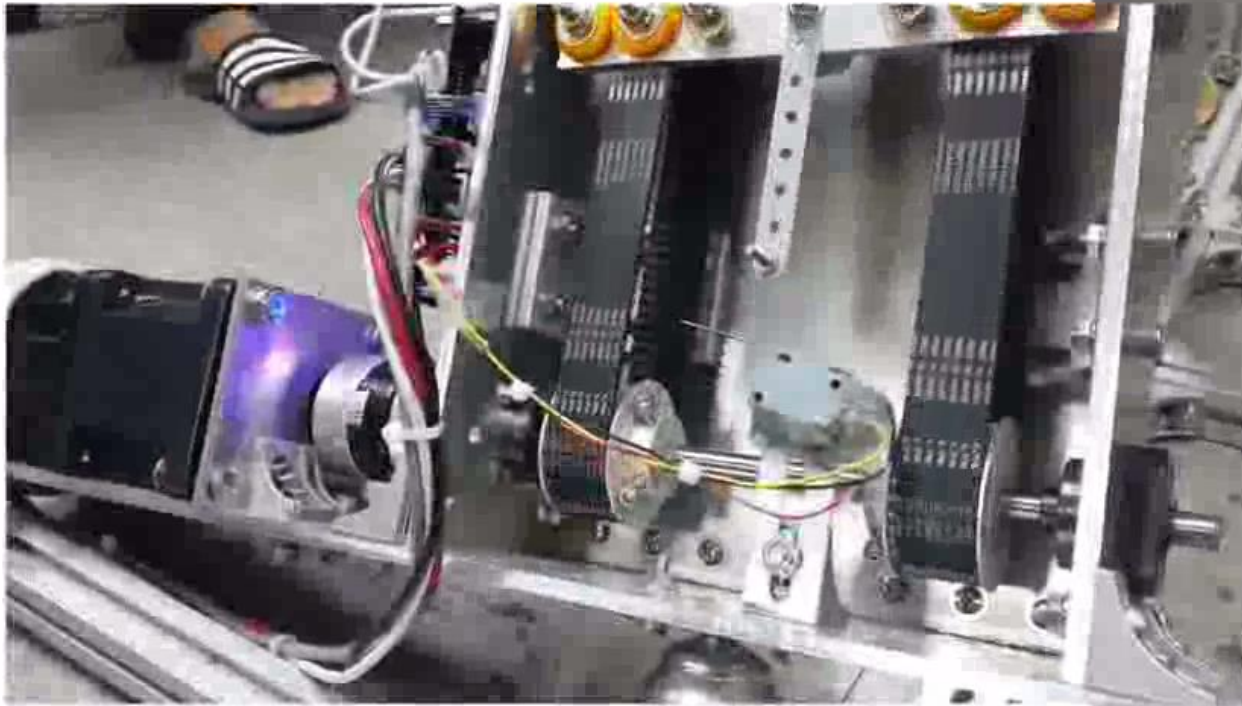


C2000 - Communication (UART)(PC to C2000)



position_data	unsig...	0x00008C26@
(x)= [0]	unsig...	0x00AA (Hex)
(x)= [1]	unsig...	0x0000 (Hex)
(x)= [2]	unsig...	0x0000 (Hex)
(x)= [3]	unsig...	0x0001 (Hex)
(x)= [4]	unsig...	0x000A (Hex)
(x)= [5]	unsig...	0x001F (Hex)
(x)= [6]	unsig...	0x0000 (Hex)
(x)= [7]	unsig...	0x0014 (Hex)
(x)= [8]	unsig...	0x00AA (Hex)
(x)= [9]	unsig...	0x0001 (Hex)
(x)= [10]	unsig...	0x0000 (Hex)
(x)= [11]	unsig...	0x0001 (Hex)
(x)= [12]	unsig...	0x000F (Hex)
(x)= [13]	unsig...	0x0005 (Hex)
(x)= [14]	unsig...	0x0000 (Hex)
(x)= [15]	unsig...	0x000A (Hex)
(x)= motor1_position	int	2580
(x)= motor2_position	int	3862

Racing Simulator C2000 - Switch (Input)



Actuator 영점 초기화

Problem & Solution

■ Hardware

- Heavy weight actuator
 - Use elastic holding

■ Control

- Interrupt signal not clear
 - Change internal to external pull-up resistor

■ Communication

- Not perfectly receive whole packet
 - Make checksum and buffer size system

Thank you