



```
on start program
main LED
speak Ready set go and wait
roll 0° at 63 speed for 10.5s
delay for 1s
roll 90° at 61 speed for 6s
delay for 1s
roll 180° at 63 speed for 10.5s
delay for 1s
roll 270° at 61 speed for 6s
delay for 1s
main LED
speak I'm done and I need water and wait
stop
```



roll 0° at 0 speed for 0s

stop

speed 0

heading 0°

spin 0° for 0s

raw motor left 0 right 0 for 0s

stabilization on

reset aim

main LED

fade from to