# CENG 3420 Computer Organization & Design

## Lecture 08: Datapath

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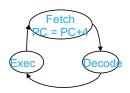
(Textbook: Chapters 4.1 - 4.4)

2024 Spring

#### The Processor: Datapath & Control



- We're ready to look at an implementation of RISC-V
- Simplified to contain only:
  - Memory-reference instructions: lw, sw
  - Arithmetic-logical instructions: add, addu, sub, subu, and, or, xor, nor, slt, sltu
  - Arithmetic-logical immediate instructions: addi, addiu, andi, ori, xori, slti, sltiu
  - Control flow instructions: beq, j
- Generic implementation:
  - Use the program counter (PC)
  - To supply the instruction address and fetch the instruction from memory (and update the PC)
  - Decode the instruction (and read registers)
  - Execute the instruction

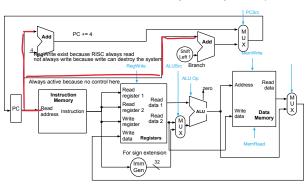


#### **Abstract Implementation View**



- Two types of functional units:
  - elements that operate on data values (combinational)
  - elements that contain state (sequential) shift left exist because RISC-V default setting ignores the rightmost 0 by default

Always active

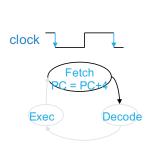


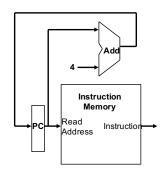
- Single cycle operation
- Split memory (Harvard) model one memory for instructions and one for data

#### **Fetching Instructions**



- Reading the instruction from the Instruction Memory
- 2 Updating the PC value to be the address of the next (sequential) instruction
- 3 PC is updated every clock cycle, so it does not need an explicit write control signal
- Instruction Memory is read every clock cycle, so it doesn't need an explicit read control signal





#### **Decoding Instructions**



- 1 Sending the fetched instruction's opcode and function field bits to the control unit
- 2 Reading two values from the Register File
- (Register File addresses are contained in the instruction)



#### Reading Registers "Just in Case"



- Both RegFile read ports are active for all instructions during the Decode cycle
- Using the rs1 and rs2 instruction field addresses
- Since haven't decoded the instruction yet, don't know what the instruction is
- Just in case the instruction uses values from the RegFile do "work ahead" by reading the two source operands

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#### Question

Which instructions do make use of the RegFile values?



#### EX-1

All instructions (except j) use the ALU after reading the registers. Please analyze memory-reference, arithmetic, and control flow instructions.

Memory reference use ALU to compute addresses e.g. lw sw

Arithmetic use the ALU to do the require arithmetic, ALU add the 2 reg then activate path to mux instead to data memory than back to register file again to write to rd.

Control use the ALU to compute branch conditions e.g. beq (ALU substraction = 0, no path after ALU int data part activate, activate the pc adder path(instruction pass thu Imm Gen and generate immediate PC to pass to the non-default PC adder path, which is controlled by pcsrc in MUX))

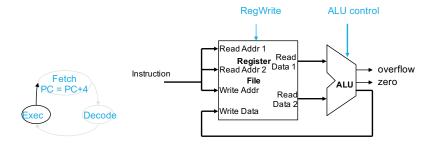
#### Executing R Format Operations



R format operations: add, sub, sll, slt, xor, srl, sra, or, and

31	25	24 20	) 19 15	5 14 12	2 11 7	6 0	
	funct7	rs2	rs1	funct3	rd	opcode	R-type

- Perform operation (op, funct3 or funct7) on values in rs1 and rs2
- Store the result back into the Register File (into location rd)
- Note that Register File is not written every cycle (e.g. sw), so we need an explicit write control signal for the Register File



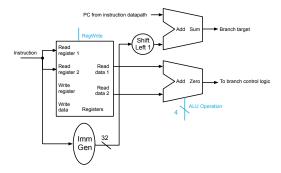
#### Consider the slt Instruction



• Remember the R format instruction slt

```
slt t0, s0, s1 # if s0 < s1 # then t0 = 1 # else t0 = 0
```

• Where does the 1 (or 0) come from to store into t0 in the Register File at the end of the execute cycle?



### **Executing Load and Store Operations**



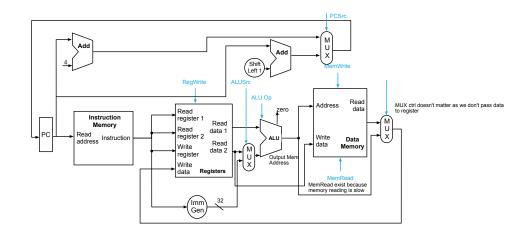
imm[11:	rs1	funct3	rd	opcode	I-type	
imm[11:5]	rs2	rs1	funct3	imm[4:0]	opcode	S-type

#### Load and store operations have to

- compute a memory address by adding the base register (in rs1) to the 12-bit signed offset field in the instruction
  - base register was read from the Register File during decode
  - offset value in the low order 12 bits of the instruction must be sign extended to create a 32-bit signed value
- store value, read from the Register File during decode, must be written to the Data Memory
   Load: I-Type Store: S-Type
- load value, read from the Data Memory, must be stored in the Register File

#### Executing Load and Store Operations (cont.)





#### **Executing Branch Operations**



S type may have final byte non-zero so that it is stored in S type

This final-zero byte is being discarded and therefore not stored in B type

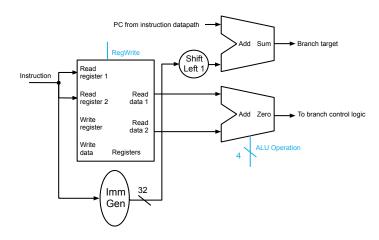
imm[12] $imm[10:5]$	rs2	rs1	funct3	imm[4:1]	imm[11]	opcode	B-type
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#### Branch operations have to

- compare the operands read from the Register File during decode (rs1 and rs2 values) for equality (zero ALU output)
- The 12-bit B-immediate encodes signed offsets in multiples of 2 bytes.
- The 12-bit immediate offset is sign-extended and added to the address of the branch instruction to give the target address.

#### Executing Branch Operations (cont.)





#### **Executing Jump Operations**



imm[20]	imm[10:1]	imm[11]	imm[19:12]	rd	opcode	J-type

- jal
- The J-immediate encodes a signed offset in multiples of 2 bytes.
- The offset is sign-extended and added to the address of the jump instruction to form the jump target address.

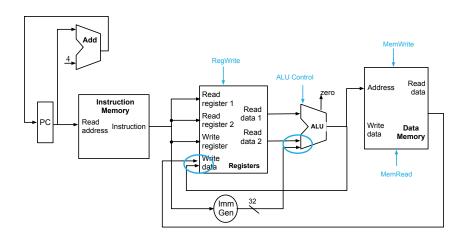
#### Creating a Single Datapath from the Parts



- Assemble the datapath elements, add control lines as needed, and design the control
  path
- Fetch, decode and execute each instruction in one clock cycle single cycle design
  - no datapath resource can be used more than once per instruction, so some must be duplicated (e.g., why we have a separate Instruction Memory and Data Memory)
  - to share datapath elements between two different instruction classes will need multiplexors at the input of the shared elements with control lines to do the selection
- Cycle time is determined by length of the longest path

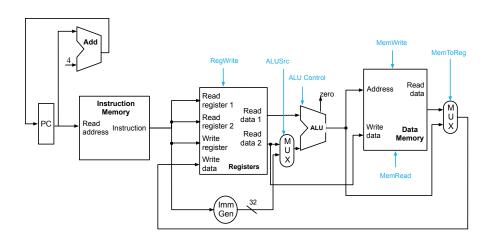
#### Multiplex Insertion





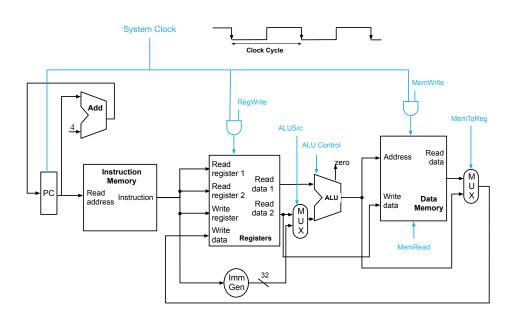
#### Multiplex Insertion





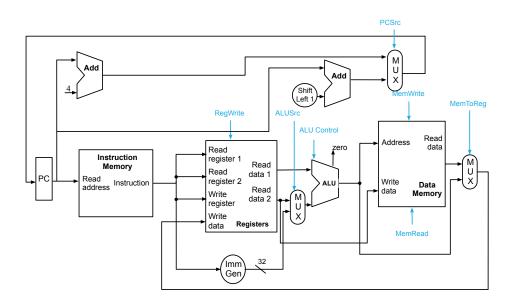
#### **Clock Distribution**





#### Adding the Branch Portion





#### Our Simple Control Structure



- We wait for everything to settle down
  - ALU might not produce "right answer" right away
  - Memory and RegFile reads are combinational (as are ALU, adders, muxes, shifter, signextender)
  - Use write signals along with the clock edge to determine when to write to the sequential elements (to the PC, to the Register File and to the Data Memory)
- The clock cycle time is determined by the logic delay through the longest path
- (We are ignoring some details like register setup and hold times)

#### Summary: Adding the Control



- Selecting the operations to perform (ALU, Register File and Memory read/write)
- Controlling the flow of data (multiplexor inputs)
- Information comes from the 32 bits of the instruction

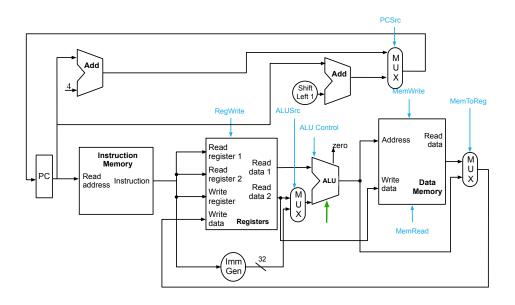
	31	25	24 20	19 15	14 12	11 7	6 0	
[		funct7	rs2	rs1	funct3	$\operatorname{rd}$	opcode	R-type
		imm[11:	0]	rs1	funct3	rd	opcode	I-type

#### **Observations:**

- opcode field always in bits 6-0
- address of two registers to be read are always specified by the rs1 and rs2 fields (bits 19–15 and 24–20)
- base register for lw and sw always in rs1 (bits 19–15)

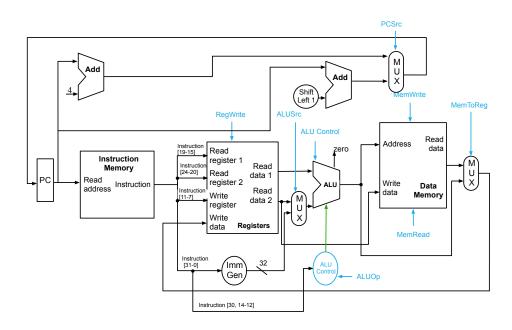
## (Almost) Complete Single Cycle Datapath





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#### **ALU Control**



ALU's operation based on instruction type and function code

ALU Control	Function
0000	and
0001	or
0010	add
0110	subtract

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ALU's operation based on instruction type and function code

ALU Control	Function		
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#### ALU Control



#### Controlling the ALU uses of multiple decoding levels

- main control unit generates the ALUOp bits
  - ALUOp: add (00), subtract (01), determined by funct field (10),
- ALU control unit generates ALUcontrol bits

Instruction	Function	ALUOp	funct7	funct3	ALUcontrol
lw	add	00	xxxxxxx	xxx	0010
sw	add	00	xxxxxxx	xxx	0010
beq	subtract	01	xxxxxxx	xxx	0110
add	add	10	0000000	000	0010
sub	subtract	10	0100000	000	0110
and	and	10	0000000	111	0000
or	or	10	0000000	110	0001



