NumPy & SciPy in Python

Computer Science & Engineering Department
The Chinese University of Hong Kong

Scientific Computing

- With its popular acceptance by scientific community, Python is being used extensively in scientific computing
- open-source add-on modules to Python that provide common mathematical and numerical routines in precompiled, fast functions.
- Numpy: provides basic routines for manipulating large arrays and matrices of numeric data
- Mimic Matlab operations

Numpy & Matplotlib

- Matrix/array manipulations are needed frequently in scientific computing
- Plotting of charts are also critical in monitoring the machine learning or other applications

- Python use Numpy as building blocks for many AI applications
- Matplotlib is an essential tool to plot a chart easily

 provides basic routines for manipulating large arrays and matrices of numeric data

 a table of elements (usually numbers), all of the same type, indexed by a tuple of positive integers.

- dimensions are called axes.
- number of axes is rank.

• E.g., coordinates of a point in 3D [1, 2, 1]: an array of rank 1, (it has one axis)

That axis has a length of 3.

- eg. [[1.0, 1.0, 2.0], [0.0, 2.0, 1.0]] rank of 2 (or 2 dimensions)
- first dimension (or axis) : length = 2
- Second dimension (or axis): length = 3

```
import numpy as np
a = np.array([1, 4, 5, 8], float)
print(a)
print (type(a))
```

```
[1. 4. 5. 8.]
<class 'numpy.ndarray'>
```

We can index array just like we have done to list in Python a = [1. 4. 5. 8.]

```
1 print(a[:2])
2 print(a[3])
3 a[3] = 100.0
4 print(a)
5
6
7
```

```
[1. 4.]
8.0
[ 1. 4. 5. 100.]
```

• Let's try higher dimensional array

```
a = [[1. 2. 3.]

[4. 5. 6.]]

a = [[15. 2. 3.]

[12. 5. 6.]]
```

we can even using slicing

```
1  a = np.array([[1,2,3], [4,5,6]], float) # define 2x3 array
2  print('a[1,:]=', a[1,:])
3  print('a[:,2]=', a[:,2])
4  print('a[-1:,-2:]=', a[-1:, -2:])
5
6
7
```

```
a[1,:]= [4. 5. 6.]
a[:,2]= [3. 6.]
a[-1:,-2:] = [[5. 6.]]
```

Methods on Array

To find out the "dimension" of an array

```
a = np.array([[1,2,3], [4,5,6]], float) # define 2x3 array

print(a.shape)
print (a.dtype)

print('length of the first axis =', len(a))
print('length of the second axis =', len(a[0])) # length of the 2nd axis
```

```
(2,3)
float64
length of the first axis = 2
length of the second axis = 3
```

Methods on Array

test whether an element is in the array

```
a = np.array([[1,2,3], [4,5,6]], float) # define 2x3 array
print ("Is 2 in a? ", 2 in a) # test for membership

print ("Is 9 in a? ", 9 in a)

a = np.array(range(10), float) # generate float array with a single item

print('float a =', a)

a = np.array([range(3), range(3)], int) # generate integer array with 2 items

print('integer a = ', a)
```

```
Is 2 in a? True
Is 9 in a? False
float a = [0. 1. 2. 3. 4. 5. 6. 7. 8. 9.]
integer a = [[0 1 2]
  [0 1 2]]
```

Methods on Array

use reshape() method to re-arrange an array

```
a = np.array(range(10), float)
print('Before reshape(), a =', a)
a = a.reshape(2,5)
print('After 1st reshape(), a =', a)
a = a.reshape(5,2)
print('After 2nd reshape(), a =', a)
```

Reference to Array

Array assignment is just a reference copy

```
a= [0. 1. 2. 3. 4.] b= [0. 1. 2. 3. 4.] a= [10. 1. 2. 3. 4.] b= [10. 1. 2. 3. 4.]
```

Reference to Array

• If we want to have another array, use copy method

```
a= [0. 1. 2. 3. 4.] b= [0. 1. 2. 3. 4.] c= [0. 1. 2. 3. 4.]
a= [10. 1. 2. 3. 4.] b= [10. 1. 2. 3. 4.] c= [0. 1. 2. 3. 4.]
```

Define an array and fill it with some entries

```
a = np.array(range(5), float)
print('a =', a)
a.fill(0) # use fill method to initialize the array
print('a =', a)
a.fill(100.0)
print('a =', a)
```

```
a = [0. 1. 2. 3. 4.]
a = [0. 0. 0. 0. 0.]
a = [100. 100. 100. 100.]
```

Concatenate

```
a = [1. 2.]
b = [3. 4. 5.]
c = [ 7 8 9 10]
d = [ 1. 2. 3. 4. 5. 7. 8. 9. 10.]
```

• arange() similar to range() function except it returns an array.

```
a = [0. 1. 2. 3. 4.]
type of a: <class 'numpy.ndarray'>
b = [0. 1. 2. 3. 4.]
type of b: <class 'numpy.ndarray'>
```

Zeros and ones set value 0, 1 accordingly

```
a = np.zeros(7,dtype=int)
   print('a=',a)
    b = np.zeros((2,3),dtype=int)
    print('b=',b)
6
   c = np.ones((3,2),dtype=float)
   print('c=',c)
    a= [0 0 0 0 0 0 0]
    b= [[0 0 0]
     [0 0 0]]
    c= [[1. 1.]
     [1. 1.]
                                                                                                  18
```

Matrix/Vector methods

eye: returns matrices with ones along the k-th diagonal

```
a = np.identity(3, dtype=float) # create a 3x3 identity matrix
    print('a=',a)
    a = np.eye(3, k=1, dtype=float) # create a 3x3 matrix with 1st diagonal being 1
    print('a=',a)
6
8
    a= [[1. 0. 0.]
         [0. 1. 0.]
         [0. 0. 1.]]
    a= [[0. 1. 0.]
         [0. 0. 1.]
                                                                                                 19
         [0. 0. 0.]
```

Matrix/Vector Operations

for higher dimension arrays, it remains to be an element-wise operation

```
c = np.array([[1,2,3,4,5],[1,1,1,1,1]],int)
d = np.array([[5,4,3,2,1],[2,2,2,2,2]],float)
print('c+d=', c+d)
print('c-d = ', c-d)
print('c*d = ', c*d)
print('c/d = ', c/d)
print('c\%d =', c\%d)
print('c^{**}d = ', c^{**}d)
c+d = [[6. 6. 6. 6. 6.]]
                                                c/d = [[0.2 \ 0.5 \ 1. \ 2. \ 5.]
                                                        [0.5 0.5 0.5 0.5 0.5]]
        [3. 3. 3. 3. 3.]]
                                                c%d = [[1. 2. 0. 0. 0.]]
c-d = [[-4. -2. 0. 2. 4.]]
        [-1. -1. -1. -1. -1.]
                                                        [1. 1. 1. 1. 1.]]
                                                c^{**}d = [[ 1. 16. 27. 16. 5.]
c*d = [[5. 8. 9. 8. 5.]]
                                                                                             20
        [2. 2. 2. 2. 2.]]
                                                          [1. 1. 1. 1. 1.]
```

Matrix/Vector methods

Arrays that do not match in number of dimensions will be broadcasted

```
a = np.array([[1,2], [3,4], [5,6]], int) # 3 x 2 array
    b = np.array([-1,3], float)
                                #1x2
    print('a =', a)
    print('b = ', b, end = '\n\n')
    print('a+b =', a+b, end='\n\n') # 3 x 2
    print('a*b =', a*b, end='\n\n')
8
    a = [[1 \ 2]]
                                                 a*b = [[-1. 6.]]
        [5 6]]
                                                          [-3. 12.]
    b = [-1. 3.]
                                                          [-5. 18.]]
    a+b = [[0.5.]]
                                                                                                  21
          [4.9.1]
```

Matrix/Vector methods

Array iterations

```
number = [1 2]
number = [3 4]
number = [5 6]
```

Supplementary

More Array/Matrix/Vector Operations, Polynomial & SciPy

b = [[1. 2.]]

element sum of a = 9.0

element sum of b = 10.0

element prduct of a = 24.0

element product of b = 24.0

[3. 4.]]

```
a = np.array([2,4,3], dtype=float)
b = np.array([[1,2],[3,4]], dtype=float)
print('a = ', a)
print('b = ', b, end='\n\n')
print('element sum of a = ', a.sum()) # sum all elements
print('element sum of b = ', b.sum()) # sum all elements
print('element prduct of a = ', a.prod()) # multiply all elements
print('element product of b = ', b.prod()) # multiply all elements
a = [2, 4, 3, 1]
```

Another way is to use NumPy method with array as argument

```
1  a = np.array([2,4,3], dtype=float)
2  b = np.array([[1,2],[3,4]], dtype=float)
3
4  print('element sum of a = ', np.sum(a)) # sum all elements
5  print('element sum of b = ', np.sum(b)) # sum all elements
6  print('element prduct of a = ', np.prod(a)) # multiply all elements
7  print('element product of b = ', np.prod(b)) # multiply all elements
8
```

```
element sum of a = 9.0
element sum of b = 10.0
element prduct of a = 24.0
element product of b = 24.0
```

sort all entries in an array

```
1  a = np.array([6, 2, 5, -1, 0],float)
2  print('a =', a)
3
4  print('sorted form of a =', sorted(a))
5  print('clipped form of a =', a.clip(0,4.1)) # specify lower/upper bound
6
7
8
```

```
a = [ 6. 2. 5. -1. 0.]
sorted form of a = [-1.0, 0.0, 2.0, 5.0, 6.0]
clipped form of a = [4.1 2. 4.1 0. 0. ]
```

finding unique entries in an array

```
1  a = np.array([1, 1, 2, 2, 3, 4, 4, 5, 5, 5],float)
2  print('a =', a)
3  print('unqiue entries of a :', np.unique(a))
5  6  7  8
```

```
a = [1. 1. 2. 2. 3. 4. 4. 5. 5. 5.]
unqiue entries of a : [1. 2. 3. 4. 5.]
```

finding diagonal entries in an array

```
1  a = np.array([[1,2,3],[4,5,6],[7,8,9]], int)
2  print('a =', a)
3  print('diagonal entries of a are :', a.diagonal())
4  
5  
6  
7  
8
```

```
a = [[1 2 3]
      [4 5 6]
      [7 8 9]]
diagonal entries of a are : [1 5 9]
```

a= [1. 3. 0.]; b= [0. 3. 2.]

Is a > b: [True False False]

Is a == b: [False True False]

Is a <= b: [False True True]</pre>

```
1    a = np.array([1, 3, 0], float)
2    b = np.array([0, 3, 2], float)
3    print('a=',a, '; b=', b)
4    print('ls a > b: ', a>b) # a>b returns an array of boolean
6    print('ls a == b:', a==b)
7    print('ls a <= b:', a<=b)
8
```

```
29
```

use of logical_and, logical_or and logical_not in array

```
a = np.array([1,3,0], float)
print('a =', a)

b = np.logical_and(a>0, a<3)
print('Are entries in a > 0 AND a < 3: ', b)

c = np.logical_not(b)
print('Use of logical_not in a: ', c)
print('Use of logical_or: ', np.logical_or(b,c))

print('Use of logical_or: ', np.logical_or(b,c))
```

```
a = [1. 3. 0.]
Are entries in a > 0 AND a < 3: [ True False False]
Use of logical_not in a: [False True True]
Use of logical_or: [ True True True]</pre>
```

 where forms a new array from two arrays of equivalent size using a Boolean filter to choose between elements of the two

np.where (boolarray, truearray, falsearray)

```
1    a = np.array([1, 3, 0], float)

2    b = np.where(a > 0, a+1, a)

3    c = np.where(a > 0, 5.0, -1.0)

4    print('a = ', a)

5    print('b = ', b)

6    print('c = ', c)
```

```
a = [1. 3. 0.]
b = [2. 4. 0.]
c = [5. 5. -1.]
```

• test whether or not values are NaN ("not a number") or finite

```
1  a = np.array([2, np.NaN, np.Inf], float)
2  print('a =', a)
3  print('Entry is not a number :', np.isnan(a))
4  print('Entry is finite :', np.isfinite(a))
5
6
7
8
```

```
a = [ 2. nan inf]
Entry is not a number : [False True False]
Entry is finite : [ True False False]
```

Statistics in an array

find the mean and variance of a series

```
1  a = np.array([2, 1, 3, 10.0, 5.3, 18.2, 16.3],dtype=float)
2  mean = a.sum()/len(a)
3  print('mean of a =', mean)
4  print('mean of a =', a.mean(), end='\n')
5  print('variance of a =', a.var())
6  print('my standard deviation of a =', np.sqrt(a.var()))
7  print('standard deviation of a =', a.std())
8
```

```
mean of a = 7.971428571428571
mean of a = 7.971428571428571
variance of a = 42.03061224489795
my standard deviation of a = 6.483102054178844
standard deviation of a = 6.483102054178844
```

Statistics in an array

• find the min or max or argmin or argmax in a series

```
a = np.array([2, 1, 3, 10.0, 5.3, 18.2, 16.3],dtype=float)

print('a =', a)

print('minimum element in a =', a.min())

print('minimum occurs in index:', a.argmin())

print('maximum element in a =', a.max())

print('maximum occurs in index:', a.argmax())
```

```
a = [ 2.  1.  3.  10.  5.3 18.2 16.3]
minimum element in a = 1.0
minimum occurs in index: 1
maximum element in a = 18.2
maximum occurs in index: 5
```

Statistics in an array

can even control which axis to take the statistics

```
a = np.array([[0,2],[3,-1],[3,5]], dtype=float)
print('a =', a)
print('mean in axis 0 = ', a.mean(axis=0))
print('mean in axis 1 = ', a.mean(axis=1))
print('min in axis 0 = ', a.min(axis=0))
print('min in axis 1 = ', a.min(axis=1))
print('max in axis 0 = ', a.max(axis=0))
print('max in axis 1 = ', a.max(axis=1))
```

```
 a = [[ 0.  2.] \\ [ 3. -1.] \\ [ 3. 5.] ] \\ mean in axis 0 = [ 2. 2.] \\ mean in axis 1 = [ 1. 1. 4.]  min in axis 0 = [ 0. -1.] \\ min in axis 0 = [ 0. -1. ] \\ min in axis 0 = [ 0. -1. ] \\ max in axis 1 = [ 0. -1. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 2. 3. 5. ] \\ max in axis 1 = [ 3. 5. ] \\ max in axis 1 = [ 3. 5. ] \\ max in axis 1 = [ 3. 5. ] \\ max in axis 1 = [ 3. 5. ] \\ max in axis 1 = [ 3. 5. ] \\ max in axis 2 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in axis 3 = [ 3. 5. ] \\ max in
```

Array item selection & Manipulation

```
1    a = np.array([[6,4], [5,9]], float) # define a 2x2 array
2    print('a=', a)
3    
4    b = (a >= 6)
5    print('b = ', b, '. Type of b:', type(b))
6    
7    c = a[b]
8    print('c = ', c, '. Type of c:', type(c))
```

```
a= [[6. 4.]
     [5. 9.]]
b = [[ True False]
     [False True]] . Type of b: <class 'numpy.ndarray'>
c = [6. 9.] . Type of c: <class 'numpy.ndarray'>
36
```

Array item selection & Manipulation

```
1    a = np.array([[6,4], [5,9]], float) # define a 2x2 array
2    print('a=', a)
3    b = a[np.logical_and(a > 5, a < 9)]
5    print('b = ', b, '. Type of b:', type(b))
6    7
8
```

```
a= [[6. 4.]
[5. 9.]]
b = [6.] . Type of b: <class 'numpy.ndarray'>
```

Array item selection & Manipulation

```
1    a = np.array([2, 4, 6, 8], float)
2    print('a=', a, '; b=', b)
3    b = np.array([0, 0, 1, 3, 2, 1], int) # it has to be an integer array
4    c = a[b] # create array c
5    print('c = ', c, '. Type of c:', type(c))
6
7
8
```

```
a= [2. 4. 6. 8.]; b= [6.]
c = [2. 2. 4. 8. 6. 4.] . Type of c: <class 'numpy.ndarray'>
```

Array item selection & Manipulation

• For multidimensional arrays, we have to use multiple one-dimensional integer array to the selection bracket, one for each axis

```
1  a = np.array([[1,4], [9,16]], float)
2  b = np.array([0, 0, 1, 1, 0], int)
3  c = np.array([0, 1, 1, 1, 1], int)
4  d = a[b,c]
5
6  print('a =', a)
7  print('d =', d, '; type of d is:', type(d))
8
```

```
a = [[ 1. 4.]
  [ 9. 16.]]
d = [ 1. 4. 16. 16. 4.]; type of d is: <class 'numpy.ndarray'>
```

Math functions also apply to array

```
a = np.array([1,4,9,16,25],float)
   print ('Square root of a =', np.sqrt(a)) # use square root
   print ('Sign of a =', np.sign(a)) # use sign
   print ('exp of a =', np.exp(a)) # use exponential
   print ('log of a =', np.log(a))
                              # use log
   print ('log10 of a =', np.log10(a)) # use log10
8
   Square root of a = [1, 2, 3, 4, 5]
   Sign of a = [1. 1. 1. 1. 1.]
   exp of a = [2.71828183e+00 5.45981500e+01 8.10308393e+03 8.88611052e+06]
   7.20048993e+10]
   log of a = [0.
                   1.38629436 2.19722458 2.77258872 3.21887582
   log10 of a = [0.
                             0.60205999 0.95424251 1.20411998 1.39794001]
                                                                                        40
```

• can do dot products and matrix multiplication,...etc

```
a = np.array([[1,2], [3,4]], float)
    b = np.array([2,3], float)
    c = np.array([[1,1], [4,0]], float)
    print('a=', a, end='\n\n')
    print('b=', b, end='\n\n')
   print('c=', c, end='\n\n')
   print('b*a = ', np.dot(b,a))
   print('a*b =', np.dot(a,b))
    print('a*c =', np.dot(a,c))
a = [[1. 2.]]
                                             b*a = [11. 16.]
                                             a*b = [ 8. 18.]
     [3. 4.]]
                                             a*c = [[ 9. 1.]
b = [2. 3.]
c = [[1. 1.]]
                                             c*a = [[4. 6.]]
     [4. 0.1]
                                               [4. 8.]]
```

inner, outer and cross prodcuts of matrices and vectors

```
a= [1. 4. 0.]; b= [2. 2. 1.]

np.outer(a,b)= [[2. 2. 1.]

[8. 8. 4.]

[0. 0. 0.]]

np.inner(a,b)= 10.0

np.cross(a,b)= [ 4. -1. -6.]
```

• Determinants, inverse and eigenvalues

a = np.array([[4, 2, 0], [9, 3, 7], [1, 2, 1]], float)

```
print ('a =', a)
    print('determinant of a is: ', np.linalg.det(a)) # get determinant
    vals, vecs = np.linalg.eig(a) # get eigenvalues/engenvectors
    print('eigenalues: ', vals)
   print('eigenvectors: ', vecs)
   b = np.linalg.inv(a) # compute inverse of a
    print('inverse of a = ', b)
    print("let's check, a * b = ", np.dot(a,b))
a = [[4. 2. 0.]]
                                                     inverse of a = [[ 0.22916667  0.04166667 -0.29166667]
[9. 3. 7.]
                                                      [ 0.04166667 -0.08333333  0.58333333]
 [1. 2. 1.]
                                                                   0.125
                                                                               0.125
                                                      [-0.3125]
determinant of a is: -48.000000000000003
                                                     let's check, a * b = [[1.000000000e+00 5.55111512e-17]]
                                                     0.00000000e+001
eigenalues: [ 8.85591316 1.9391628 -2.79507597]
                                                      [0.00000000e+00 1.00000000e+00 2.22044605e-16]
eigenvectors: [[-0.3663565 -0.54736745 0.25928158]
                                                      [0.00000000e+00 1.38777878e-17 1.00000000e+00]]
 [-0.88949768 0.5640176 -0.88091903]
                                                                                                         43
 [-0.27308752 0.61828231 0.39592263]]
```

Singular Value Decomposition (SVD)

```
a = np.array([[1,3,4], [5,2,3]], float)
U, s, Vh = np.linalg.svd(a) # get SVD of a
print ('U is:', U)
print('s is:', s)
print('Vh is:', Vh)
U is: [[-0.6113829 -0.79133492]
                                     Vh is: [[-0.61169129 -0.45753324 -
                                      0.64536587]
 [-0.79133492 0.6113829 ]]
                                         0.78971838 -0.40129005 -0.46401635]
s is: [7.46791327 2.86884495]
                                       [-0.046676 -0.79349205 0.60678804]]
                                                                                   44
```

- Evaluate polynomial at a given point
- Let's say we want to evaluate x^3-2x^2+2 at x=4.

- for the polynomial: $x^4-11x^3+9x^2+11x-10$.
- If we know the roots are (-1, 1, 1, 10), poly method can find coefficient.

```
print('Polynomial coefficients are: ', np.poly([-1, 1, 1, 10]))

print('Polynomial coefficients are: ', np.poly([-1, 1, 1, 10]))

print('Polynomial coefficients are: ', np.poly([-1, 1, 1, 10]))
```

Polynomial coefficients are: [1. -11. 9. 11. -10.]

- Given a set of coefficients in a polynomial, we can find the roots
- x^3+4x^2-2x+3

```
1 np.roots([1, 4, -2, 3]) # get roots
2 3 4 5 6
```

```
array([-4.5797401 +0.j , 0.28987005+0.75566815j, 0.28987005-0.75566815j])
```

- For polynomial: $x^4+x^3+x^2+x+1$
- derivative

```
np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)

np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)

np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)

np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)

np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)

np.polyder([1/4, 1/3, 1/2, 1, 0]) # perform derivative of polynomial (specify coefficients)
```

array([1., 1., 1., 1.])

- For polynomial: x^3+x^2+x+1
- If we integrate it, we should have $x^4/4+x^3/3+x^2/2+x+C$, where C is a constant

```
np.polyint([1,1,1,1]) # perform integration on a polynomial (specify coefficients)
                                                                                 ])
array([0.25]
                     , 0.33333333, 0.5
                                                                  , 0.
                                                   , 1.
                                                                                          49
```

• can use polyfit() method, which fits a polynomial of specified order to a set of data using the least-square method.

```
1  x = [1, 2, 3, 4, 5, 6, 7, 8]

2  y = [0, 2, 1, 3, 7, 10, 11, 19]

3  # use polyfit to find the least square fit using polynomail of degree 2

5  np.polyfit(x,y,2)  # it returns all coefficients

6  array([ 0.375 , -0.88690476, 1.05357143])
```

- Note that there are other polynomial methods
- polyadd
- polysub
- polymul
- polydiv
- Polyval
- Read the documentation of Numpy

SciPy

- Greatly extends the functionality of NumPy
- We can use "import scipy" to import the module
- SciPy has many packages
- To explore, do help(scipy)

SciPy (Linear Algebra scipy.linalg)

#Matrix determinant

```
import numpy as np
from scipy import linalg
arr = np.array([[1,2], [3,4]], float)
print('arr =\n', arr)
print("arr's determinant is: ", linalg.det(arr))
```

```
arr =
  [[1. 2.]
  [3. 4.]]
arr's determinant is: -2.0
```

SciPy (Linear Algebra scipy.linalg)

Matrix inverse

```
1  arr_inv = linalg.inv(arr)
2  print("arr's inverse is:\n", arr_inv)
3  
4  # Let's do a test
5  print("\narr * arr_inv is:\n", np.dot(arr, arr_inv))
6
```

SciPy (Linear Algebra scipy.linalg)

Finding the roots of a scalar function

```
from scipy import optimize # import optimization package

def f(x):
    return x**2 + 10*np.sin(x)

root = optimize.fsolve(f,1) # our initial guess
print("Guess from 1: ", root)

root = optimize.fsolve(f, -2.5) # another quess
print("guess from -2.5:", root)
```

```
Guess from 1: [0.] guess from -2.5: [-2.47948183]
```