

Deep Learning

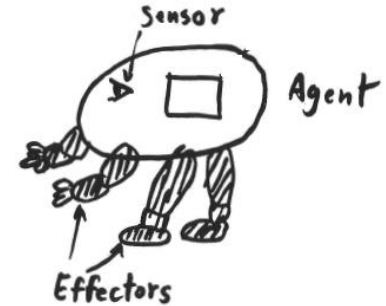
(01076533)

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Some slides are adapted from

- cs231n: Convolutional Neural Networks for Visual Recognition @Stanford University

Types of learning



1. Unsupervised learning

- The agent learns patterns in the input even though no explicit label is supplied.
- The most common unsupervised learning task is clustering.
- For example, a taxi agent might gradually develop a concept of “Good traffic days” and “Bad traffic days” without ever being given labeled examples of each by a teacher.
 - X1: Rain, BigEvent, WorkDay, MonthEnd
 - X2: NonRain, NonBigEvent, NonWorkDay, NonMonthEnd
 - X3: Rain, NonBigEvent, WorkDay, NonMonthEnd
 - X4: NonRain, BigEvent, NonWorkDay, MonthEnd

A taxi agent may cluster X1, X4 as one cluster and X2, X3 as another cluster.

2. Reinforcement learning

- The agent learns from a series of reinforcements – rewards or punishments.
- For example, the lack of a tip at the end of the journey gives the taxi agent an indication that it did something wrong.
- It is up to the agent to decide which of the actions prior to the reinforcement were most responsible for it.

3. Supervised learning

- The agent observes some example input-output pairs and learns a function that maps from input to output.
- For example, from a taxi agent problem. By using given labeled “input-output” examples, a taxi agent will learn a function that maps from input to the outputs “Good traffic days” and “Bad traffic days”.
 - X1: Rain, BigEvent, WorkDay, MonthEnd, “Bad traffic days”
 - X2: NonRain, NonBigEvent, NonWorkDay, NonMonthEnd, “Good traffic days”
 - X3: Rain, NonBigEvent, WorkDay, NonMonthEnd, “Good traffic days”
 - X4: NonRain, BigEvent, NonWorkDay, MonthEnd, “Bad traffic days”

Overfitting

- Overfitting occurs when a statistical learning model describes random errors or noises instead of the underlying relationship.
 - A learning model that has been **overfit** will generally have poor predictive performance, as it can exaggerate minor fluctuations in the data.
 - A good learning model should be **generalize** to both unseen and training data.

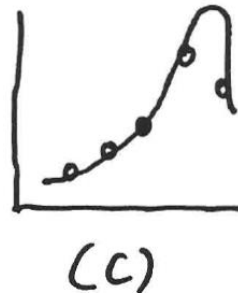
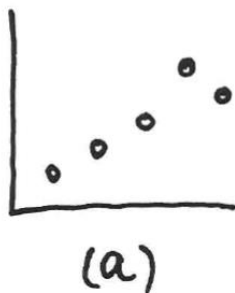


Fig. a : Training data

Fig. b and c tend to overfit the training data

Fig. d tends to generalize the training data (good hypothesis)

Evaluating the hypothesis

- We can simply use the error rate to check the quality of the hypothesis.
- Error rate =
$$\frac{\text{Number of examples which are wrong predicted}}{\text{Total number of examples}}$$
- However, a hypothesis h has a low error rate on the training set does not mean that it will generalize well.
- To get the more accurate evaluation, we need to test the hypothesis on an unseen set (test set) of examples.

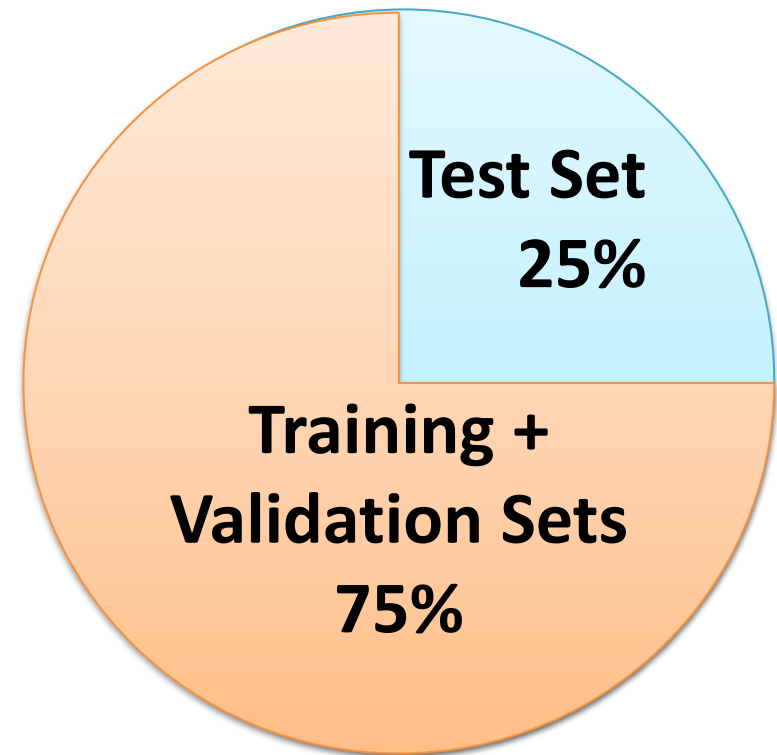
- **Holdout cross-validation :**

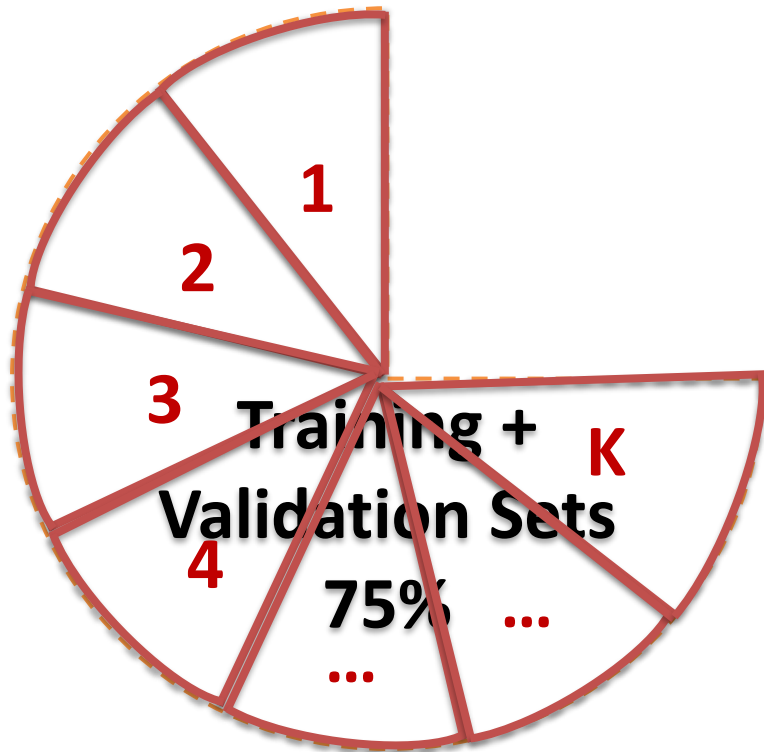
Randomly split the available data into a training set (e.g. 75%) and a test set (e.g. 25%).

- **K-fold cross-validation:**

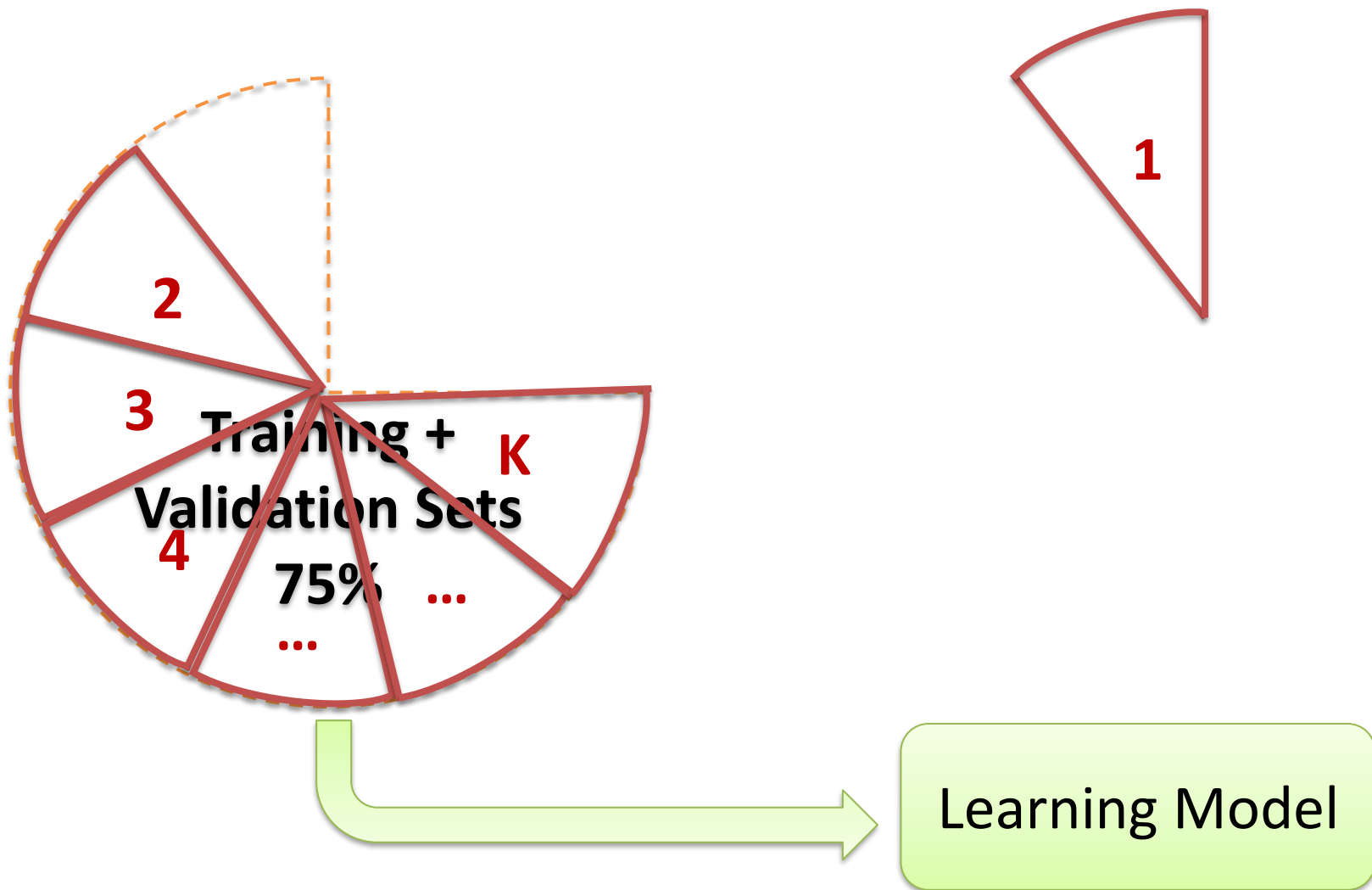
- Split the training data into k equal subsets.
- Then perform k rounds of learning. On each round, $1/k$ of the data is held out as a validation set and the remaining examples are used as training data.
- The average error rate of the k rounds is finally calculated. Popular values for k are 5 and 10. The extreme is $k=n$ (the total number of examples), also known as **leave-one-out cross-validation** or **LOOCV**.

K-Fold Cross Validation

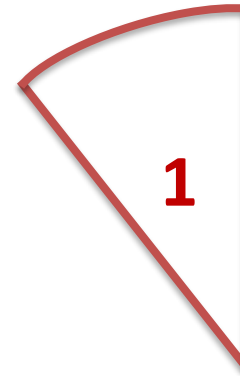
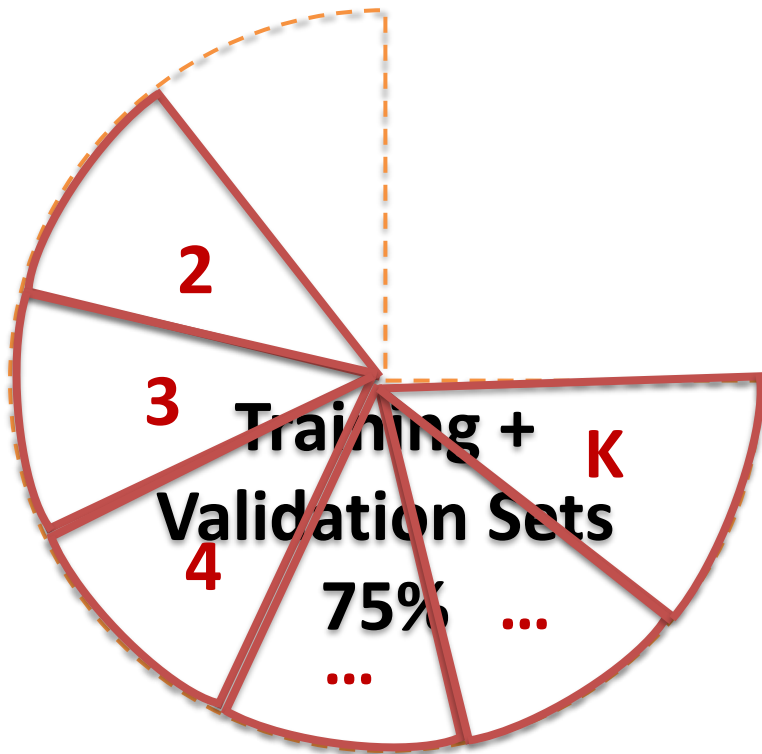




Learning Model

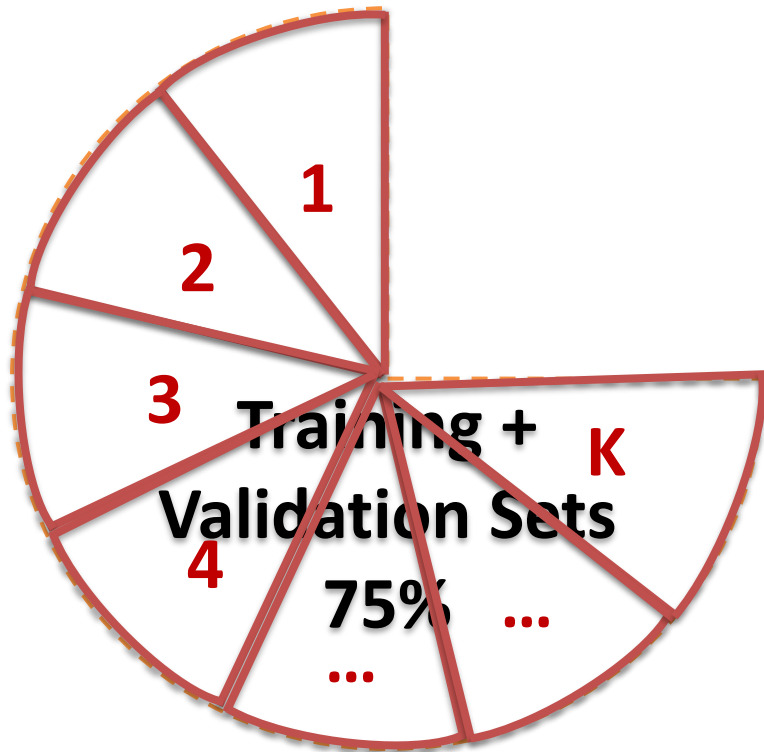


Training1 Accuracy/Error



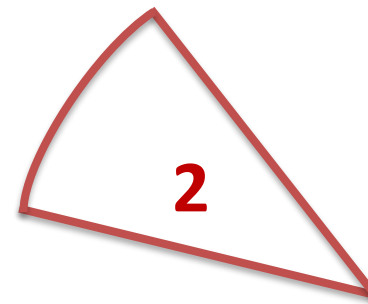
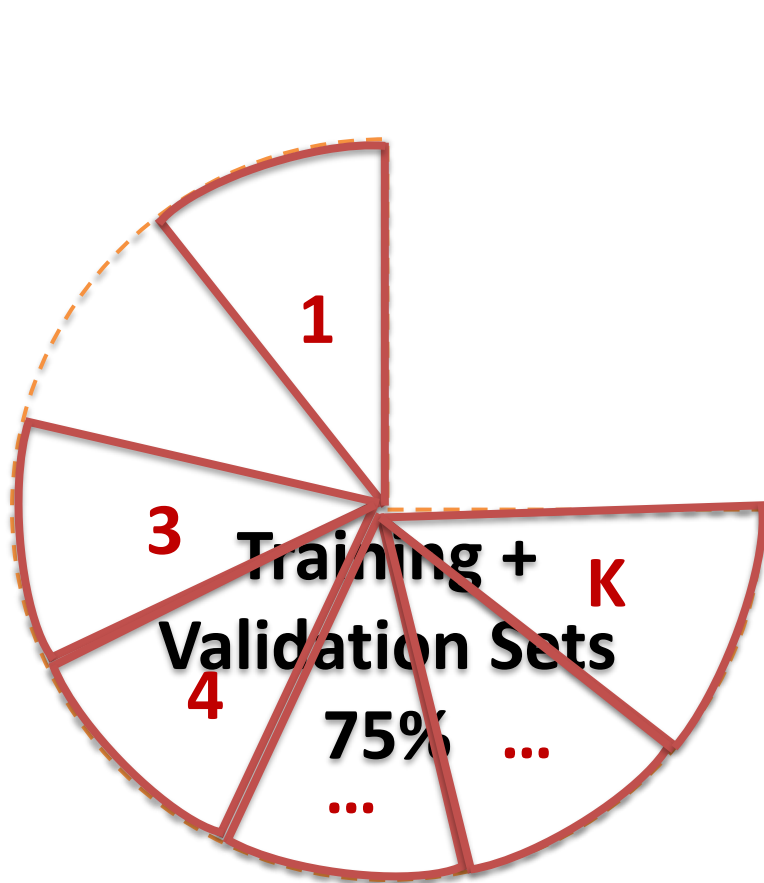
Learning Model

Validation1 Accuracy/Error₁



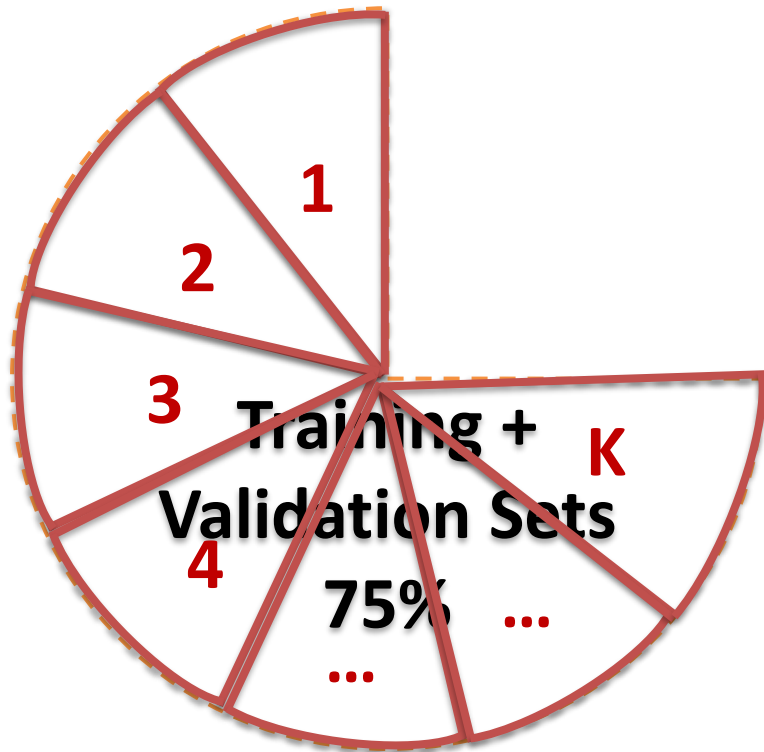
Learning Model

Training2 Accuracy/Error

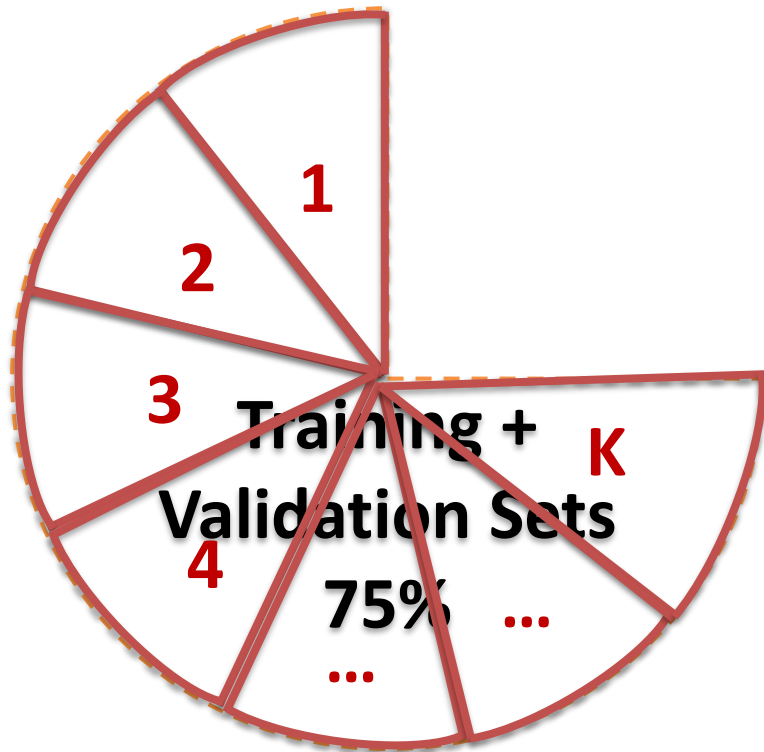


Learning Model

Validation₂ Accuracy/Error₃



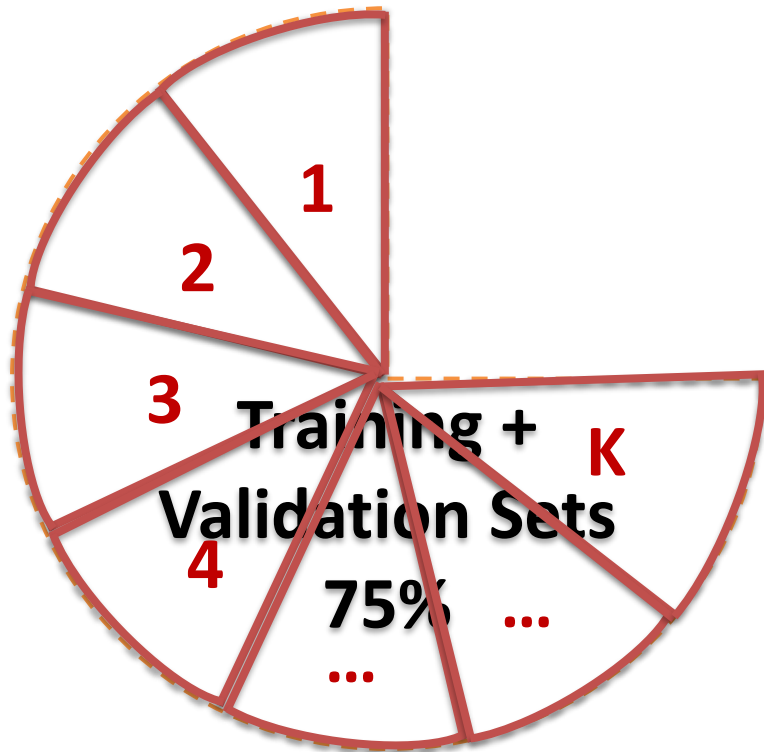
Learning Model



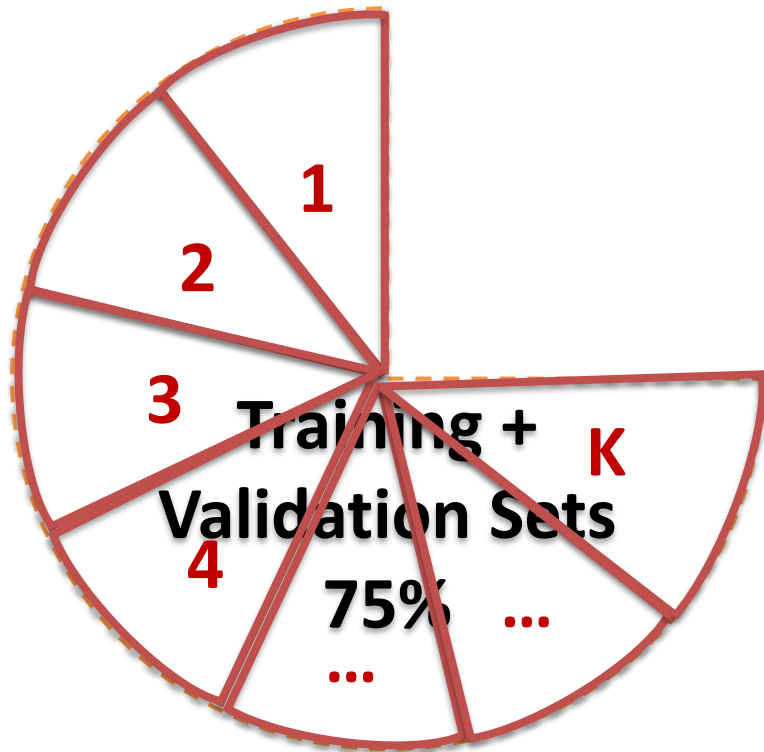
Learning Model



Learning Model

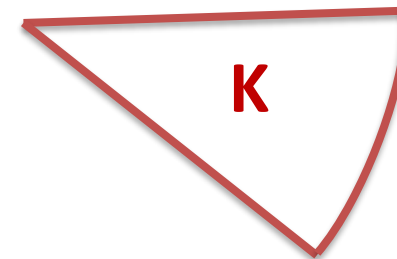
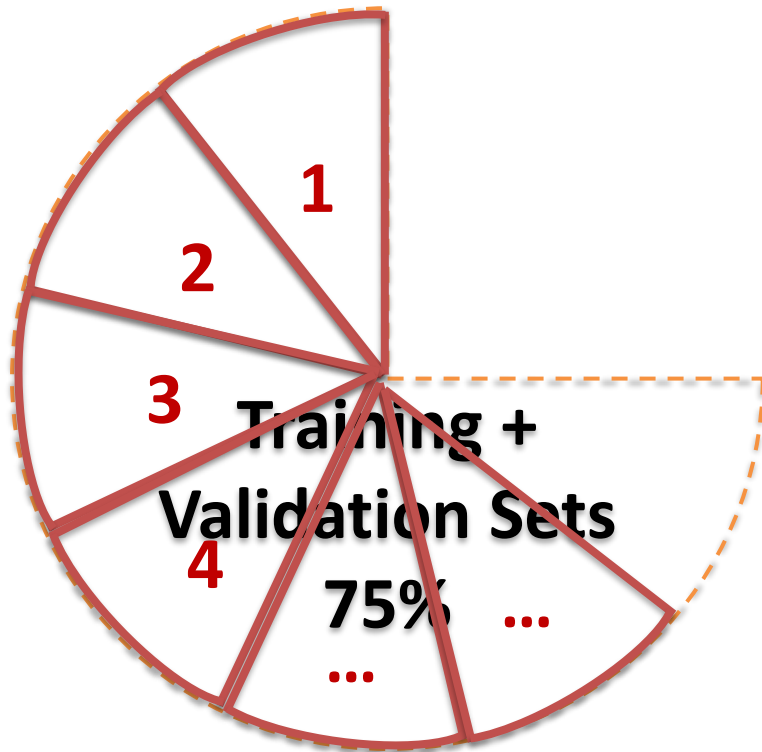


Learning Model



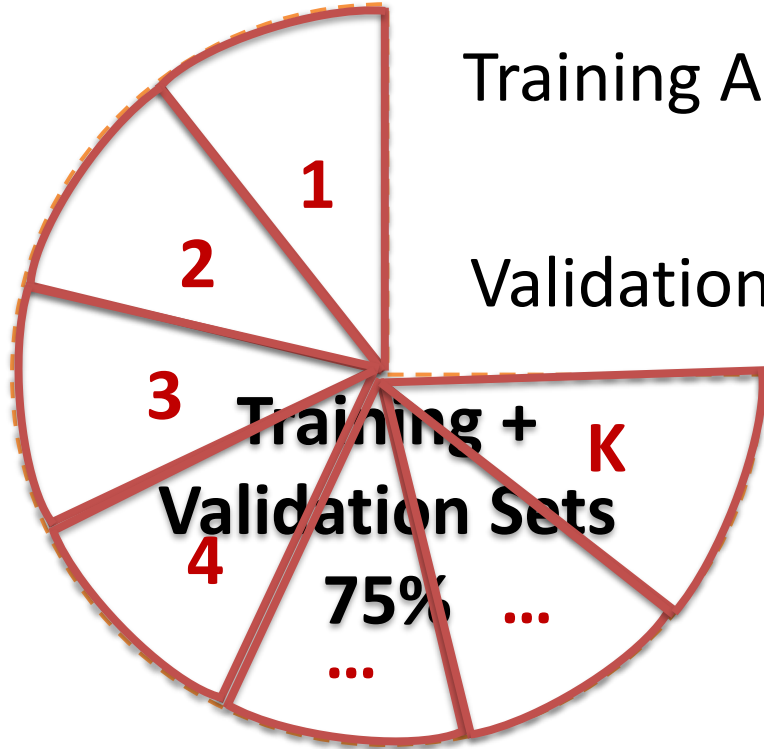
Learning Model

Training K Accuracy/Error



Learning Model

Validation K Accuracy/Error



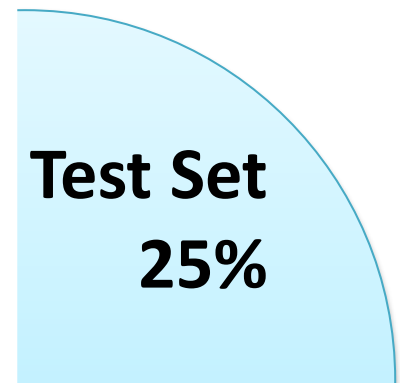
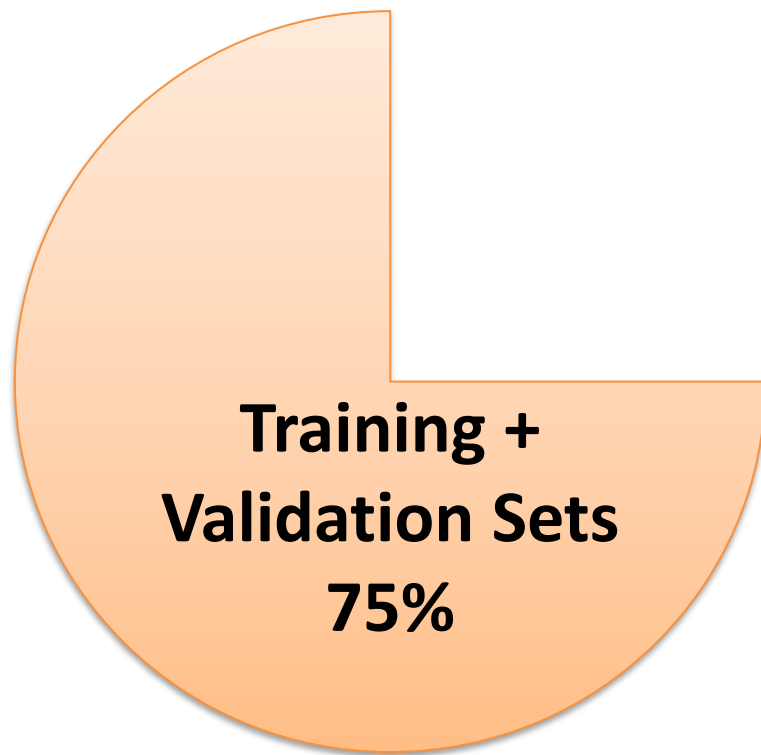
$$\text{Training Accuracy} = (\sum_{i=1}^K \text{Train}_i_Acc) / K$$

$$\text{mean}_t = \text{avg}(\text{train_acc})$$

$$\text{Validation Accuracy} = (\sum_{i=1}^K \text{Valid}_i_Acc) / K$$

$$\text{mean}_v = \text{avg}(\text{val_acc})$$

next step : find best params \Rightarrow train \Rightarrow test



Note: Percentage of test set can be varied, depends on how many total of instances we have.

Test Accuracy/Error

Deep learning

(from wikipedia)

Deep learning (also known as **deep structured learning** or **hierarchical learning**)

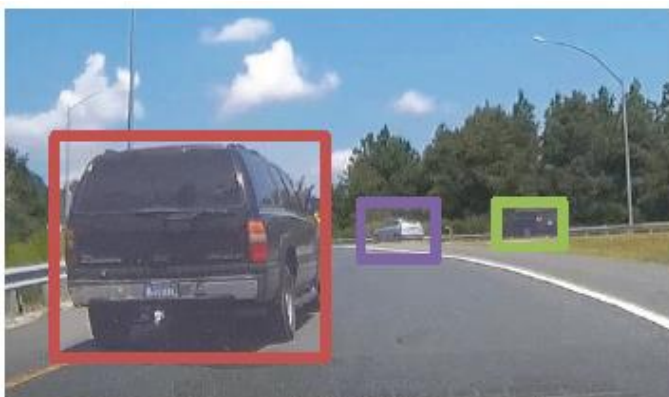
- Use **artificial neural networks** (ANNs) to learning tasks that contain more than one **hidden layer**.
- Deep learning is part of a broader family of **machine learning** methods based on learning data.
- Learning can be **supervised**, partially supervised or **unsupervised**.

Most popular applications of deep learning is **computer vision**.

Other applications are **speech recognition, natural language processing, audio recognition, social network filtering, machine translation and bioinformatics**.

This course will mainly focus on the **convolutional neural network** for the **classification problem** on **image datasets**.

There is a number of visual recognition problems that are related to image classification, such as **object detection**, **image captioning**.



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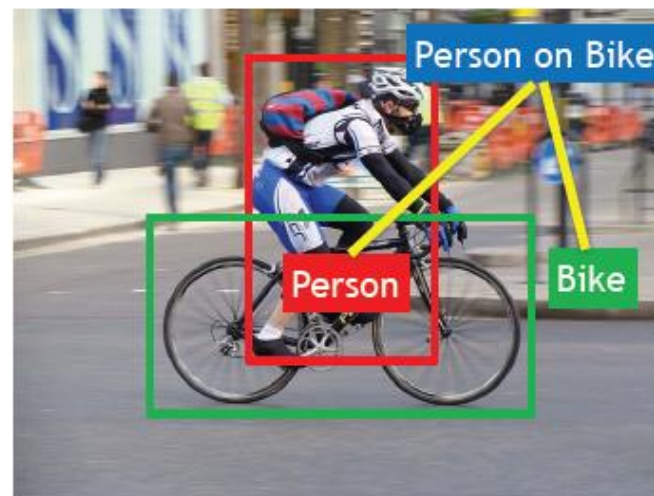


Person

Hammer

<https://youtu.be/yQwfDxBMtXg>

- Object detection
- Action classification
- Image captioning
- ...

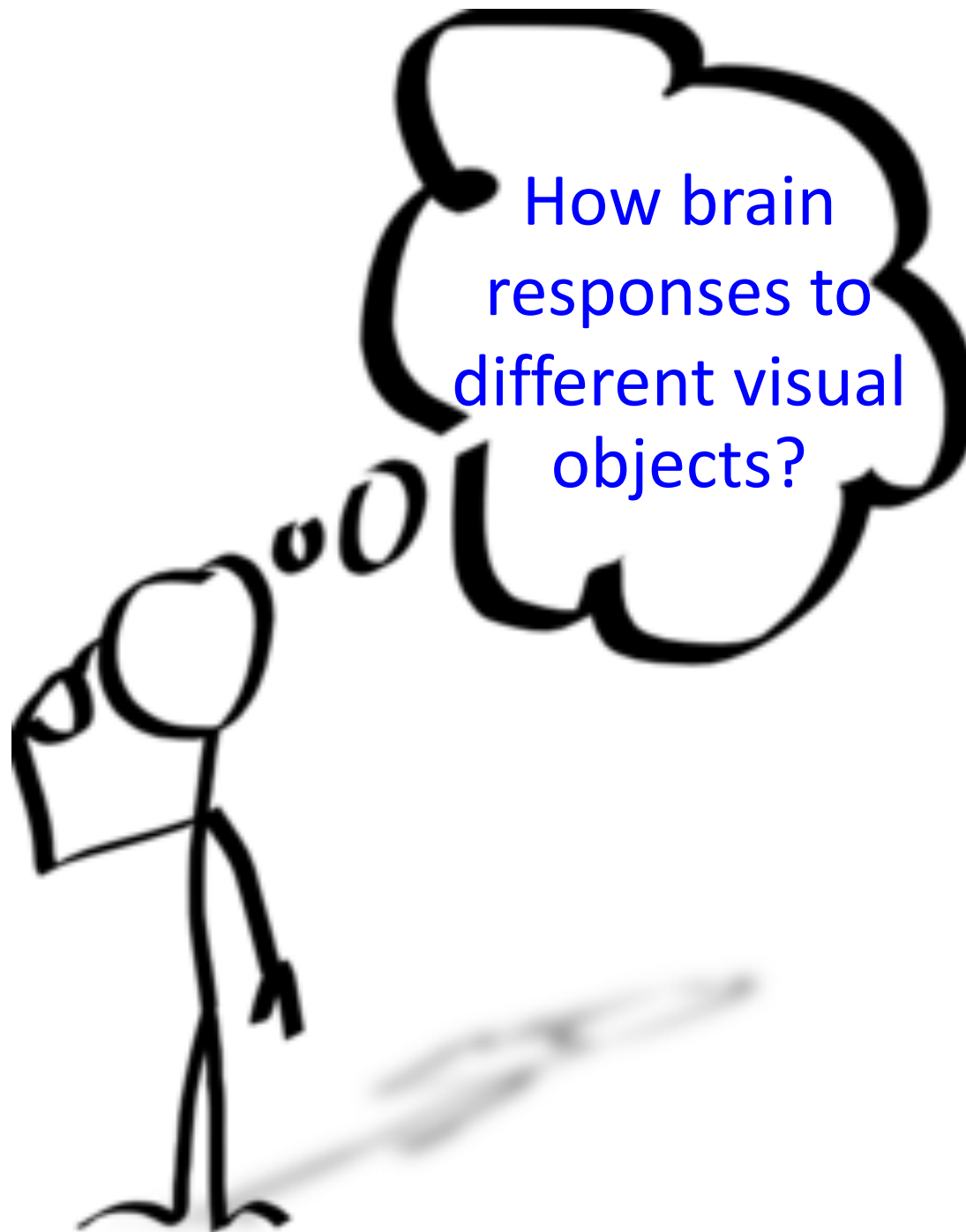


Person on Bike

Person

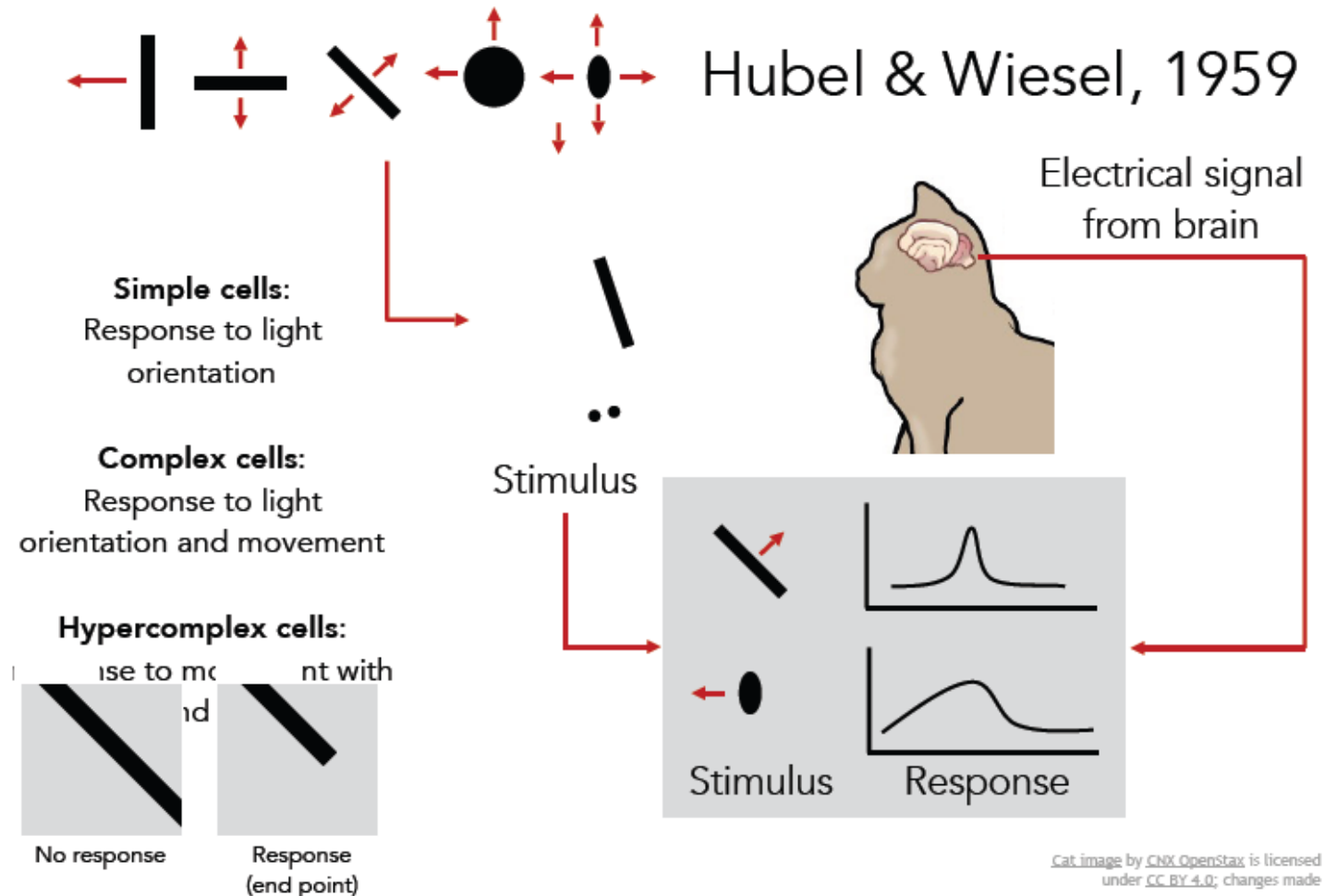
Bike

Images from cs231n @Stanford



How brain
responses to
different visual
objects?

Visual Cortex Study



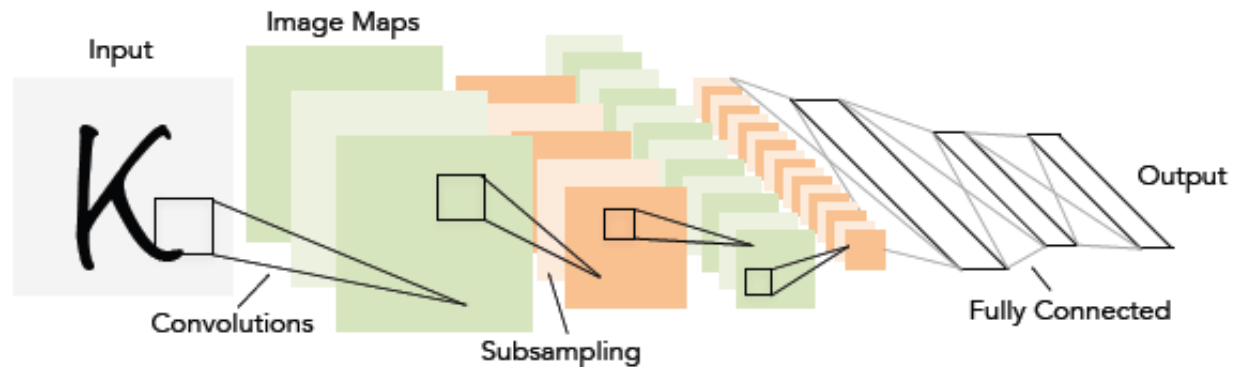
<https://youtu.be/IOHayh06LJ4>

<https://youtu.be/jw6nBWo21Zk>

As you will see later in the class, convolutional neural network imitates visual cortex in the brain

Evolution of Convolutional Neural Networks (CNN)

1998
LeCun et al.



of transistors

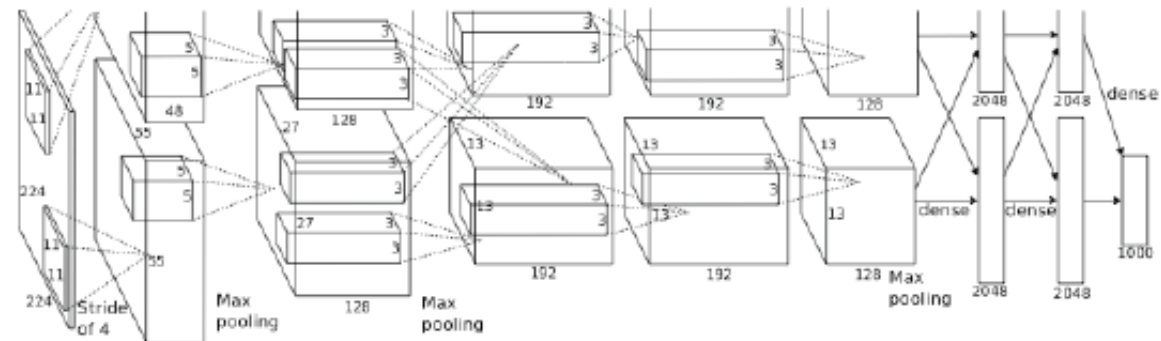


10^6

of pixels used in training

10^7 **NIST**

2012
Krizhevsky et al.



of transistors GPUs



10^9



of pixels used in training

10^{14} **IMAGENET**