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Report Tutorial Course 4 (Part B)

Algorithmics and Advanced Programming

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Dijkstra algorithm for weighted digraphs

```
function Dijkstra(Graph, source):
 2
 3
         create vertex set Q
 4
 5
                                                     // Initialization
         for each vertex v in Graph:
                                                       // Unknown distance
             dist[v] \leftarrow INFINITY
from source to v
             prev[v] \leftarrow UNDEFINED
                                                      // Previous node in
optimal path from source
             add v to Q
                                                       // All nodes initially
in Q (unvisited nodes)
         dist[source] \leftarrow 0
                                                       // Distance from source
10
to source
11
12
         while Q is not empty:
             u \leftarrow \text{vertex in } Q \text{ with min dist[u]} // Node with the least
distance will be selected first
             remove u from O
14
15
16
             for each neighbor v of u:
                                                     // where v is still in
Q.
17
                  alt \leftarrow dist[u] + length(u, v)
18
                  if alt < dist[v]:
                                                       // A shorter path to v
has been found
                       dist[v] \leftarrow alt
20
                       prev[v] \leftarrow u
21
22
         return dist[], prev[]
```

Create a class called DijkstraSP. This class will implement the Dijkstra algorithm for detecting shortest paths in weighted-digraphs. This class will contain the following functions:

- 1. 3 arrays: **boolean**[] marked, **int**[] previous and **int**[] distance as for the unweighted graphs.
- 2. A function called verifyNonNegative(*WDGraph* G) which takes as input a weidhted-directed graph and verifies than all weights in the graph are non negative.
- 3. Create a function called DijkstraSP(*WDgraph* G, **int** s)which implements the Dijkstra algorithm for shortest paths studied in lecture 4. The input arguments are a weighted-digraph and a root vertex s.
- 4. As for the previous section, create the functions hasPathTo(**int** v), distTo(**int** v) and printSP(**int** v).

```
import java.util.*;
public class DijkstraSP {
    private int sourceNode;
    private boolean[] marked;
   private int[] previous;
   private double[] distance;
   private boolean verifyNonNegative(WDGraph G) {
        for (LinkedList<WDGraph.DirectedEdge> edges: G.adj) {
            for (WDGraph.DirectedEdge n : edges) {
                if (n.weight() <= 0) {
                    return false;
        }
        return true;
   public ArrayList<Integer> DijkstraSP(WDGraph G, int s) {
         / To ensure all weights of edges are positive.
       if (!verifyNonNegative(G)) {
            return null;
        sourceNode = s;
        int v = G.V + 1;
        marked = new boolean[v];
        previous = new int[v];
        distance = new double[v];
        // Use an array to store unvisited nodes
       HashSet<Integer> openedNodes = new HashSet<>();
        // Open all nodes
        for (int i = 0; i < v; i++) {
            previous[i] = -1; // UNDEFINED
            distance[i] = Double.MAX_VALUE; // +INFINITY
            openedNodes.add(i);
        // Use an array list to record visit orders.
       ArrayList<Integer> visitOrder = new ArrayList<>();
        // Distance from source to source
       distance[s] = 0; // distance
       marked[s] = true; // mark
        visitOrder.add(s); // visit
       while (!openedNodes.isEmpty()) {
             / Choose the smallest distance.
            double smallestDistance = Double.MAX_VALUE;
            int smallestNode = -1;
            for (Integer thisNode : openedNodes) {
                if (distance[thisNode] < smallestDistance) {</pre>
                    smallestDistance = distance[thisNode];
```

```
}
            }
            // Go to the smallest one.
            openedNodes.remove(smallestNode);
            visitOrder.add(smallestNode);
            // If remained nodes are not available, it is not a connected graph,
terminate the progress.
            if (smallestNode == -1) {
                break:
            // Check all neighbours and update distances
            for (WDGraph.DirectedEdge directedEdge : G.adj[smallestNode]) {
                int childNode = directedEdge.to();
                double alt = distance[smallestNode] + directedEdge.weight();
                if (alt < distance[childNode]) {</pre>
                    marked[childNode] = true;
                    previous[childNode] = smallestNode;
                    distance[childNode] = alt;
                }
            }
        }
        return visitOrder;
    public boolean hasPathTo(int v) {
        return marked[v];
    public double distTo(int v) {
        return distance[v];
    public void printSP(int v) {
        ArrayList<Integer> shortestPath = new ArrayList<>();
        int thisNode = v;
        while (thisNode > -1) {
            shortestPath.add(thisNode);
            thisNode = previous[thisNode];
            if (thisNode == sourceNode) {
                shortestPath.add(sourceNode);
                break;
            }
        Collections.reverse(shortestPath);
        System.out.println(shortestPath);
}
Test the previous functions with the graph graph-WDG.txt. The result of this test is:
0:
1: (2, 9.0), (6, 14.0), (7, 15.0),
2: (3, 24.0),
3: (5, 2.0), (8, 19.0),
4: (3, 6.0), (8, 6.0),
5: (4, 11.0), (8, 16.0),
6: (3, 18.0), (5, 30.0), (7, 5.0),
7: (5, 20.0), (8, 44.0),
```

smallestNode = thisNode;

```
8:
true
50.0
[1, 6, 3, 5, 8]
```