Systems I – CS 6013 Computer Architecture and Operating Systems Lecture 6: System Calls in ASM

MASTER OF SOFTWARE DEVELOPMENT (MSD) PROGRAM

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Miscellaneous

- Have you started the assembly code project?
- Have you finished Week 2 readings?
 - 4 Processes
 - 5 Process API
 - 6 Direct Execution
- Begin Week 3 readings...
- Questions on Makefiles or Name Mangling?

Lecture 5 – Topics

- System Calls
- Interrupts

Some More Assembly Instructions

- call func pushes the current instruction pointer (+1) onto the stack, then jumps to the label (in this case, func:) specified.
- Note, call and syscall are similar, but not the same...
- pop <reg> places the value at the top of the stack into reg
- pop rax ; eg: call placed the IP onto stack, so pop retrieves it
 ; Copy that value into rax
- jump rax; Now jump to the address stored in rax
 - What register does jump modify?
 - Places the value in rax into the rip (Instruction Pointer)
 - Note, the IP is often called the PC (Program Counter)
- ret Combination of the pop rax and jump rax instructions

System Calls – Why?

- User programs need to do "dangerous" things (like I/O, creating new processes, checking the time, etc)
- OS's don't (and shouldn't!) trust user programs to have free access to the resources necessary for these things
 - e.g. If a program could create new processes how would the OS manage them?
 - If a user writes to a directory structure wrong, it can break the filesystem!
- How do we let user programs do what they need in a (reasonably) safe way?

System Calls – What

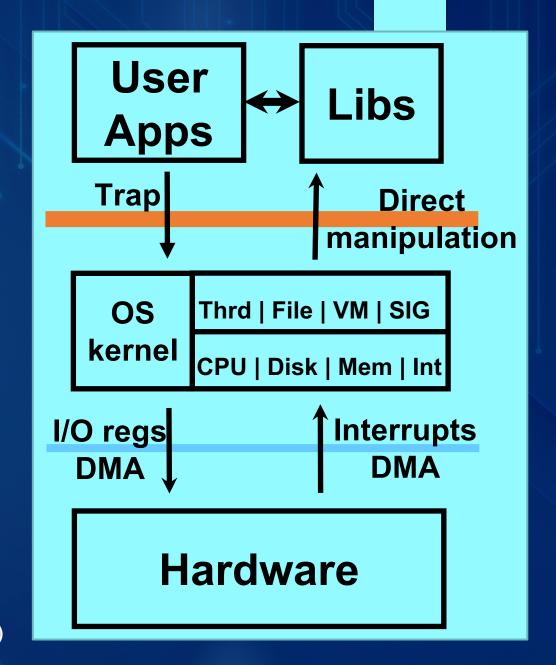
- A set of functions (basically) that user programs can call that request the kernel to do something for them
- The API looks like a normal function, but the ABI/implementation is subtly different.
- Recall that the CPU runs user programs in "user" mode, which does not allow some instructions (like the ones necessary for I/O)
- The code that actually performs I/O must be performed in kernel mode on the CPU
- When a syscall is made, the CPU switches to kernel mode, performs the task, then switches back to user mode when the syscall function returns

System Calls – Examples

- exit()
- fork()
- read() / write() / open() / close()
- chdir() / chmod()
- getpid()
- sbrk()
- sleep()

Standard OS Structure

- User-level
 - Applications
 - Libraries: many common "OS" functions
 - Example: malloc() vs sbrk()
- Kernel-level
 - Top-level: machine independent
 - Bottom-level: machine dependent
 - Runs in protected mode
 - Need a way to switch (user <-> kernel)
- Hardware-level
 - Device maker exports known interface
 - Device driver initiates operations by writing to device registers
 - Devices use interrupts to signal completion
 - DMA Direct Memory Access (offloads work, but has restrictions)



How Are Sys Calls Implemented?

- Like normal function calls (ABI describes where parameters go, where the return value goes, etc)
- However, CANNOT be exactly the same because we MUST somehow get the CPU in kernel mode.
- How do we get the CPU into kernel mode?
- interrupts, exceptions, and traps basically wakeup calls for the CPU
 - Interrupts: Some are hardware generated: key pressed, mouse moved, disk finished copying data, a timer went off, etc
 - Exceptions: Some are error reports: divide by 0, out of bounds memory access, etc (directly from the CPU or OS itself)
 - Traps: Some are caused by user mode programs calling privileged instructions: halt (the shutdown instruction), I/O type stuff, or the syscall instruction

Traps vs Interrupts vs Exceptions

- The main difference between a trap and an interrupt is...
 - A **trap** is triggered by a user program to invoke OS functionality while...
 - An *interrupt* is triggered by a hardware device to allow the processor to execute the corresponding interrupt handler routine.
- Exceptions are triggered inside the CPU itself (memory violations, divide by 0, etc) when running code.

The "Interrupt Vector"

- Each different type of *interrupt/trap* has a number associated with it. Some are defined by the hardware, some the OS decides what to do with
- When the computer boots up the OS, it will make/fill an array (vector). Each entry stores a pointer (address) to the code to run when that event occurs
- When an interrupt occurs, the CPU is switched into kernel mode and jumps to the appropriate **interrupt handler** code
- The interrupt handler has a special return-like instruction for setting the CPU back into user mode and returning.
- To make a system call, we set up the parameters we want, then trigger the interrupt that the OS knows is for syscalls. On x86_64, this is conveniently known as the syscall instruction.
 - Note older code uses int 0x80 instead of syscall

How to make a Syscall

- Put the syscall number in the appropriate registers (again, part of the ABI)
- Put the syscall parameters in the appropriate registers (there's an ABI for system calls)
- Execute the syscall ASM instruction which will switch the CPU to kernel mode and execute the interrupt handler
- The kernel actually executes the system call then returns to the next line
- Do whatever else is necessary (possibly moving the return value to the right spot)

- call function1vs
- syscall
- How does call know what to set the IP to?
- How does syscall?

System Calls

- Arguments passed in registers:
 - Integer constants (e.g., buffer size, file offset, file id)
 - Pointers to blocks of memory (e.g., strings, file buffers, ...)
 - Handles (e.g., file handle, socket handle, ...)
- OS typically returns:
 - Return code (value of -1 often denotes error)
 - Other results written into buffers in user space
 - You should always (always!) check syscall return values
- Principle: Dialogue between user-mode and kernel should be semantically simple
 - Simpler interfaces easier to work with
 - Simpler interfaces easier to implement correctly
 - Simpler interfaces tend to be easier to make efficient

Anatomy of a System Call

- User applications make system calls to execute privileged instructions
- Anatomy of a system call:
 - Program puts syscall params in registers
 - Program executes a trap:
 - Minimal processor state (PC, PSW) pushed on stack
 - CPU switches mode to KERNEL
 - CPU vectors to registered trap handler in the OS kernel
- Trap handler uses param to jump to desired handler (e.g., fork, exec, open, write, ...)
- When complete, reverse operation
 - Place return code in register
 - Return from exception

```
do foo:
                            14
        mov rdi, <param>
        mov rax, <func # of foo>
        syscall
                            User
                            Kernel
syscallhdlr() {
                     foo()
 switch (rax) {
                       return res;
   case: foo
    rax \leftarrow foo(...);
 asm ("sysret");
```

