

RAY-CASTING & RAY-TRACING WITH VTK

Adamos Kyriakou (IT'IS Foundation)

VTK has long evolved beyond just visualization. It offers some amazing functionality that just cannot be found elsewhere. Two examples are the 'ray-casting' and, consequentially, 'ray-tracing' capabilities provided by the `vtkOBBTree` class. In this article, I would like to introduce these capabilities and show examples of ray-casting and ray-tracing performed exclusively through Python, a dash of NumPy, and VTK.

Disclaimer: The ray-casting and ray-tracing examples I will be presenting here are severely condensed versions of my posts 'Ray Casting with Python and VTK: Intersecting lines/ rays with surface meshes' and 'From Ray Casting to Ray Tracing with Python and VTK' that appear on my blog, <http://pyscience.wordpress.com>. If they pique your interest, please visit the aforementioned posts, where you can find all of the material, code (in the form of IPython Notebooks), and an excruciating amount of detail pertaining to each aspect of the process (as these posts were written for people with little to no experience in VTK).

RAY-CASTING VS. RAY-TRACING

I would like to emphasize a pivotal difference between 'ray-casting' and 'ray-tracing.' In the case of the former, we only 'cast' a single ray, test for its intersection with objects, and retrieve information regarding the intersection. Ray-tracing, on the other hand, is more physically accurate, as it applies laws of physics (e.g., reflection, refraction, attenuation, etc.) to the rays to 'trace' (i.e., follow that ray and its derivative rays). However, ray-casting is the natural precursor to ray-tracing, as it tells us with what part of which object the ray intersects and provides all necessary information to cast subsequent rays.

THE `vtkOBBTree` CLASS

The star of this post is the `vtkOBBTree` class, which generates an oriented bounding-box (OBB) 'tree' for a given geometry under a `vtkPolyData` object. Upon generation of this OBB tree, the `vtkOBBTree` class allows us to perform intersection tests between the mesh and the lines of finite length, as well as intersection tests between different meshes. It can then return the point coordinates where intersections were detected, as well as the polydata cell IDs where the intersections occurred.

RAY-CASTING WITH `vtkOBBTree`

For this demonstration, we are assuming that we have a surface model of a human skull stored in an `.stl` file, whose contents we have loaded into a `vtkPolyData` object, named `mesh`, through the `vtkSTLReader` class. A rendering of this model through the `vtkPolyDataMapper` class can be seen in Figure 1.



Figure 1. Rendering of the surface model of a human skull, which we will use to demonstrate ray-casting.

The center of the skull is centered around the cartesian origin, i.e., the (0.0, 0.0, 0.0) point. Now let's assume we want to cast a ray emanating from (100.0, 100.0, 0.0) and ending at (0.0, 0.0, 0.0) and retrieve the coordinates of the points where this ray intersects with the skull's surface. A rendering including the ray, prior to actually casting it, can be seen in Figure 2.

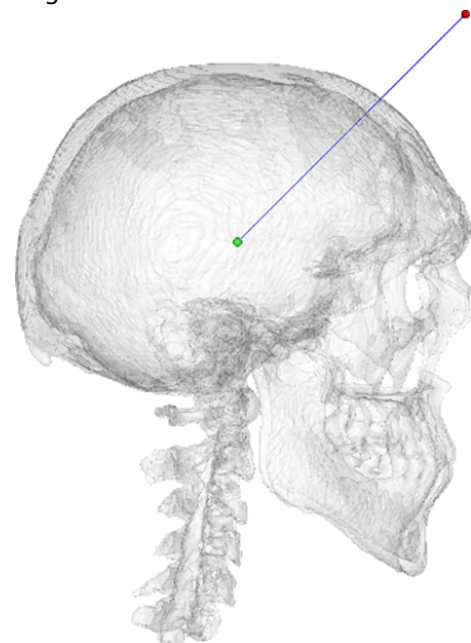


Figure 2. The ray that will be tested for intersection with the skull model. The 'source' point of the ray is rendered as red, while the 'target' point is rendered as green.

Prior to intersection, we need to create and initialize a new `vtkOBBTree` with the `vtkPolyData` object of our choice. In our case, this is called `mesh` and is done as follows:

```
obbTree = vtk.vtkOBBTree()
obbTree.SetDataSet(mesh)
obbTree.BuildLocator()
```

Note the call to the `BuildLocator` method, which creates the OBB tree.

That's it! We now have a world-class intersection tester at our disposal. At this point, we can use the `IntersectWithLine` method of the `vtkOBBTree` class to test for intersection with the aforementioned ray. We merely need to create a `vtkPoints` and a `vtkIdList` object to store the results of the intersection test.

```
points = vtk.vtkPoints()
cellIds = vtk.vtkIdList()

code = obbTree.IntersectWithLine((100.0, 100.0, 0.0),
                                (0.0, 0.0, 0.0),
                                points,
                                cellIds)
```

As mentioned above, the points and cellIds now contain the point coordinates and cell IDs with which the ray intersected, as it was emanated from the first point, i.e., (100.0, 100.0, 0.0), onto the second point, i.e., (0.0, 0.0, 0.0), in the order they were 'encountered.' The return value code is an integer, which would be equal to 0 if no intersections were found. A rendering showing the intersection points can be seen in Figure 3.

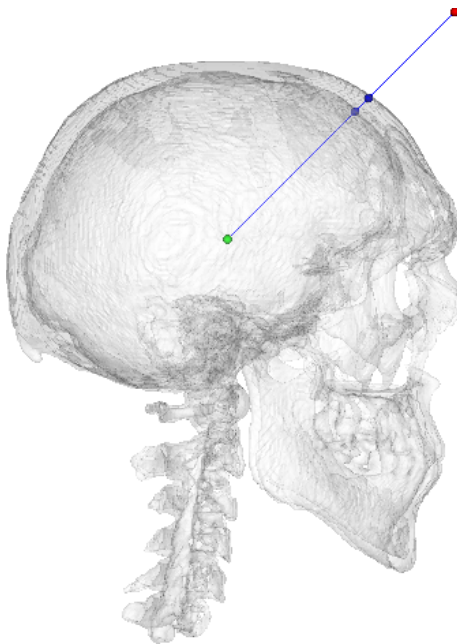


Figure 3. Result of the ray-casting operation and intersection test between the skull model and the ray. The blue points depict the detected intersection points.

The Python package `pycaster` wraps the functionality shown above, assuming no VTK experience, and provides additional methods to calculate the distance a given ray has 'traveled' within a closed surface. It is currently being served through PyPI. The `repository` can be found on BitBucket.

As I mentioned at the beginning of this article, the entire process shown above, including all of the material and code needed to reproduce it, is detailed in my post '[Ray Casting with Python and VTK: Intersecting lines/rays with surface meshes.](#)'

RAY-TRACING WITH VTKOBBTREE

Now, in order to perform ray-tracing, we can take the lessons learned from ray-casting and apply them to a more convoluted scenario. The rationale behind ray-tracing with the `vtkOBBTree` class is the following:

- Cast rays from every 'ray source' and test for their intersection with every 'target' mesh in the scene.
- If a given ray intersects with a given 'target,' then use the intersection points and intersected cells to calculate the normal at that cell, calculate the vectors of the reflected/refracted rays, and cast subsequent rays off the target.
- An excellent, freely available article entitled '[Reflections and Refractions in Ray-Tracing](#)' (Bram de Greve, 2006) provides a good overview of the math and the physics behind ray-tracing.
- Repeat this process for every ray cast from the 'ray source.'

Let's assume a scene is comprised of a half-sphere dubbed `sun`, which will act as the ray-source, and a larger nicely textured sphere called `earth`, which will be the target of those rays. This 'environment' can be seen in Figure 4.

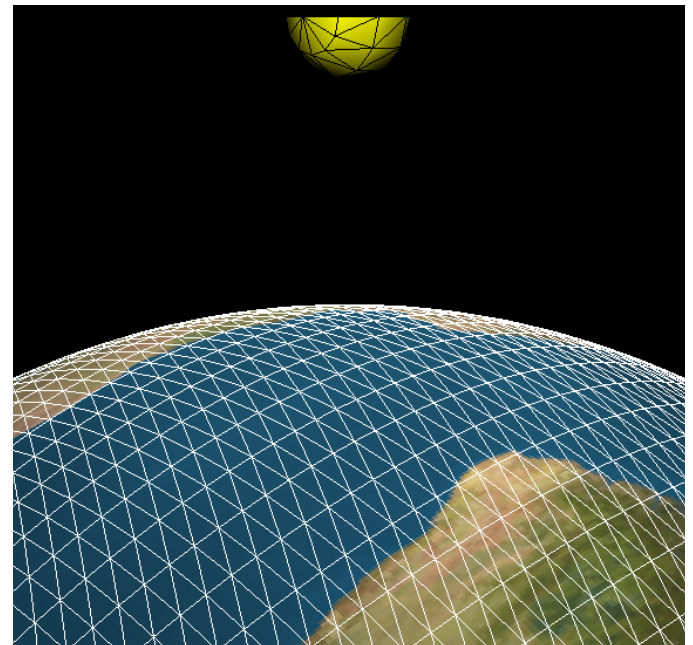


Figure 4. Scene defined for the ray-tracing example. The yellow half-sphere, `sun`, acts as the ray-source, while the textured sphere, `earth`, will be the target of those rays.

In this example, we will be casting a ray from the center of each triangular cell on the sun's surface along the direction of that cell's normal vector. The cell-centers of the sun were calculated through the `vtkCellCenters` class and stored under `pointsCellCentersSun` (of type `vtkPolyData`). The cell-normals of the sun were calculated through the `vtkPolyDataNormals` class and stored under `normalsSun` (of type `vtkFloatArray`). A rendering of the cell-centers as points and cell-normals as glyphs through the `vtkGlyph3D` class can be seen in Figure 5.

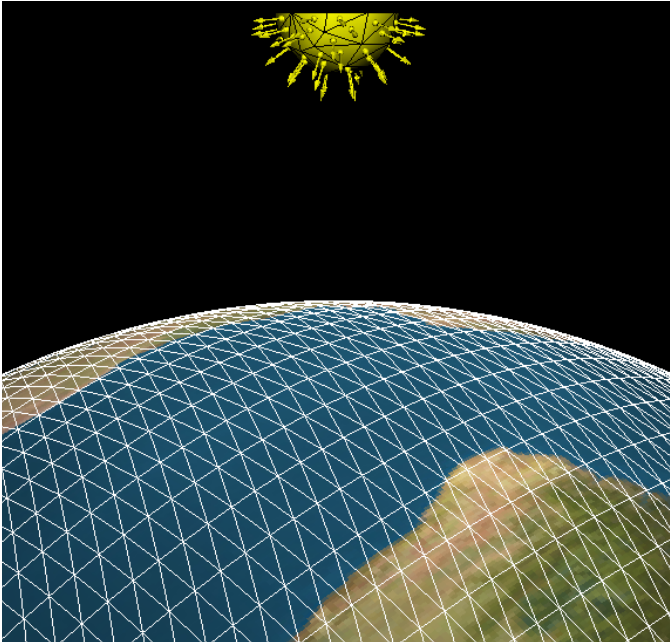


Figure 5. Rendering of the cell-centers of the sun that will act as source-points for the rays and the cell-normals along which the rays will be cast.

Similarly to what was done in the previous example, prior to ray-casting, we first need to create a `vtkOBBTree` object for the earth:

```
obbEarth = vtk.vtkOBBTree()
obbEarth.SetDataSet(earth.GetOutput())
obbEarth.BuildLocator()
```

Now, since we will be casting a large number of rays, let's wrap the `vtkOBBTree` functionality in two convenient functions:

```
def isHit(obbTree, pSource, pTarget):
    code = obbTree.IntersectWithLine(pSource,
                                      pTarget,
                                      None,
                                      None)

    if code==0:
        return False
    return True

def GetIntersect(obbTree, pSource, pTarget):
    points = vtk.vtkPoints()
    cellIds = vtk.vtkIdList()
```

```
# Perform intersection test
code = obbTree.IntersectWithLine(pSource,
                                  pTarget,
                                  points,
                                  cellIds)

pointData = points.GetData()
noPoints = pointData.GetNumberOfTuples()
noIds = cellIds.GetNumberOfIds()

pointsInter = []
cellIdsInter = []
for idx in range(noPoints):
    pointsInter.append(pointData.GetTuple3(idx))
    cellIdsInter.append(cellIds.GetId(idx))

return pointsInter, cellIdsInter
```

The `isHit` function will simply return True or False, depending on whether a given ray intersects with `obbTree`, which, in our case, will only be `obbEarth`.

The `GetIntersect` function simply wraps the functionality we saw in the first example. In a nutshell, it will return two list objects: `pointsInter` and `cellIdsInter`. The former will contain a series of tuple objects with the coordinates of the intersection points. The latter will contain the 'id' of the mesh cells that were 'hit' by that ray. This information is vital as, through these ids, we will be able to get the correct normal vector for that earth cell and calculate the appropriate reflected vector, as we will see below.

At this point, we are ready to perform the ray-tracing. Let's take a look at a condensed version of the code:

```
for idx in range(pointsCellCentersSun.
    GetNumberOfPoints()):
    pointSun = pointsCellCentersSun.GetPoint(idx)
    normalSun = normalsSun.GetTuple(idx)

    # Calculate the 'target' of the 'sun' ray based
    # on 'RayCastLength'
    pointRayTarget = list(numpy.array(pointSun) +
                          RayCastLength*numpy.
                          array(normalSun))

    if isHit(obbEarth, pointSun, pointRayTarget):
        pointsInter, cellIdsInter =
            GetIntersect(obbEarth,
                        pointSun,
                        pointRayTarget)

        # Get the normal vector at the earth cell
        # that intersected with the ray
        normalEarth =
            normalsEarth.GetTuple(cellIdsInter[0])
```



```

# Calculate the incident ray vector
vecInc = (numpy.array(pointRayTarget) -
          numpy.array(pointSun))

# Calculate the reflected ray vector
vecRef = (vecInc - 2*numpy.dot(vecInc,
                               numpy.array(normalEarth)) *
          numpy.array(normalEarth))

# Calculate the 'target' of the reflected
ray based on 'RayCastLength'
pointRayReflectedTarget =
    (numpy.array(pointsInter[0]) +
     RayCastLength*12n(vecRef))

```

Please note that all rendering code was removed from the above snippet. What is done above is the following:

We looped through every cell-center on the **sun** mesh (**pointSun**), stored under **pointsCellCentersSun**.

We casted a ray along the direction of that sun cell's normal vector, stored under **normalsSun**. The ray emanates from **pointSun** to **pointRayTarget**.

As the **vtkOBbTree** class only allows for intersection tests with lines of finite length, not semi-infinite rays, the rays cast in the code above are given a large (relative to the scene) length to ensure that failure to intersect with **earth** would only be due to the ray's direction and not an insufficient length.

Every ray was tested for intersection with the **earth** through the **isHit** function and the **obbEarth** object defined above.

If a ray intersected with the **earth**, the intersection test was repeated through the **GetIntersect** function in order to retrieve the intersection point coordinates and the intersected cell IDs on the **earth** mesh. The intersection point coordinates, as well as the intersected earth cell normal vector (**normalEarth**), were used to calculate the normal vector of the reflected ray and cast that ray off the earth's surface.

The cell normals on the earth's surface were calculated through the **vtkPolyDataNormals** class and stored under **normalsEarth** (of type **vtkFloatArray**). This is the same way that **normalSun** was calculated.

A render of the ray-tracing result can be seen in Figure 6.

As I mentioned at the beginning of this article, the entire process shown above, including all of the material and code needed to reproduce it, is detailed in my post **'From Ray Casting to Ray Tracing with Python and VTK.'**

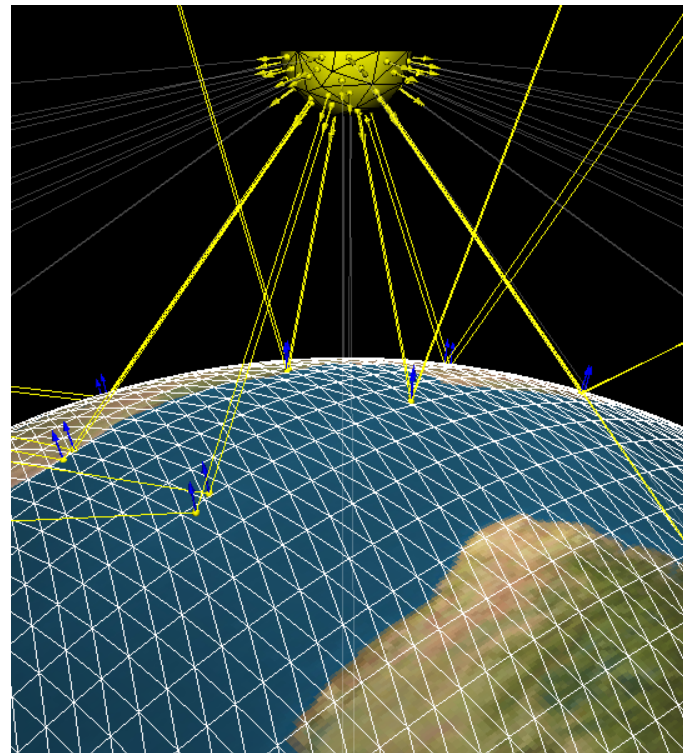


Figure 6. Result of the ray-tracing example. Rays cast from the **sun** that missed the **earth** are rendered as white. Rays that intersected with earth are rendered as yellow. The intersection points, normal vectors at the intersected earth cells, and the reflected rays can also be seen.

CONCLUSION

As you can see, VTK provides some little-known pearls that offer some fantastic functionality.

While the above examples fall short of real-world ray-tracing applications, as one would need to account for effects like refraction and energy attenuation, the sky is the limit!



Adamos Kyriakou is an Electrical & Computer Engineer with an MSc. in Telecommunications and a Ph.D. in Biomedical Engineering. He is currently working as a Research Associate in Computational Multiphysics at the IT'IS Foundation (ETH Zurich), where his work and research are primarily focused on computational algorithm development, high-performance computing, multi-physics simulations, big-data analysis, and medical imaging/therapy modalities. He has collaborated with medical and technical personnel, researchers, and industrial partners on large international projects that involve safety evaluation of medical devices, treatment planning and optimization of therapeutic modalities, and development of next-generation simulation platforms.