

UAV Ground Detection

Distinguish Tree Species

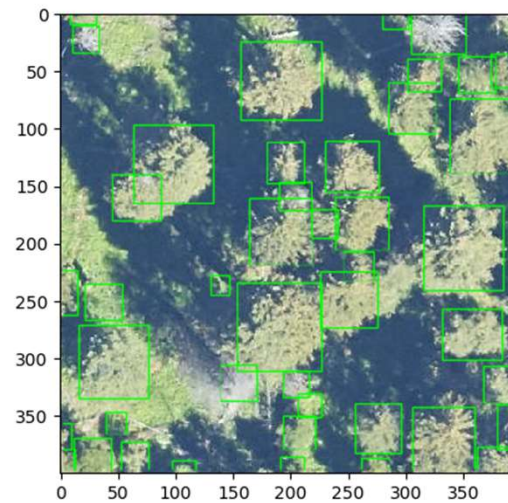
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Project 17

Detecting Tree model

Deep Forest

- Training and predicting individual tree airborne RGB image



<https://deepforest.readthedocs.io/en/latest/landing.html>

Detect Objects in Real Time

Using OpenCV and Python

- When using UAV ground detecting we need to use real time object detection
- OpenCV?
- library of programming functions mainly aimed at real-time computer vision.



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Using OpenCV and Python

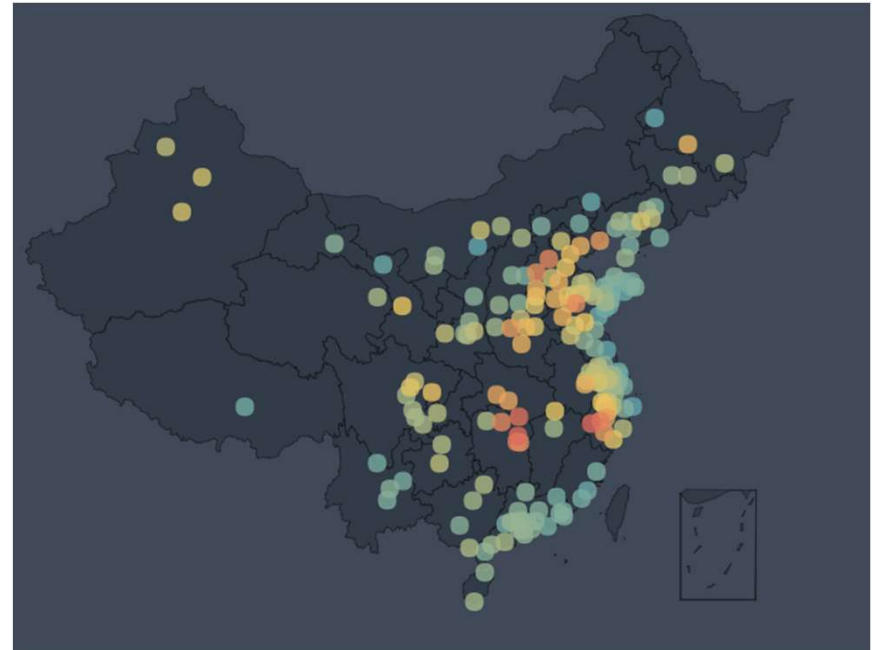
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Tree data with GPS

We need to use tree data with GPS

- Then we can make GEO charts.
- Maybe we can use some libraries like pyecharts.
- But, how to get this data?



Collecting data using UAV

Collecting data using UAV

- But we think it is hard to use UAV in Korea forest and gathering data.
- So, we try to find some new method.
- Finally, we find a solution



Google map trick

We'll use google map api

- We can get satellite picture of forest.
- It contains RGB and GPS data.
- Then now, we have modeling data.



Plan

Step 1

Get data from gMap

Make modeling system

Step 2

Classify data
(Distinguish Tree Species)

Modeling data

Step 3

Real time receive data
from UAV

Add/Del data from GEO
chart

Thank you

Questions?

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