# UAV Ground Detection

## **Distinguish Tree Species**

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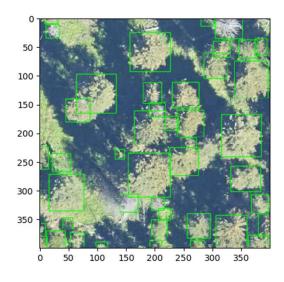
**Project 17** 



## Detecting Tree model

## **Deep Forest**

Training and predicting individual tree airborne RGB image

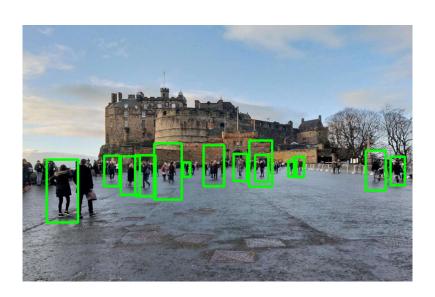


https://deepforest.readthedocs.io/en/latest/landing.html

## Detect Objects in Real Time

#### **Using OpenCV and Python**

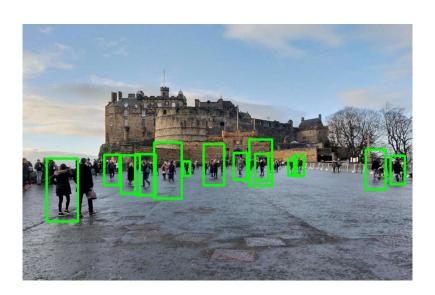
- When using UAV ground detecting we need to use real time object detection
- OpenCV?
- library of programming functions mainly aimed at realtime computer vision.



## Detect Objects in Real Time

#### **Using OpenCV and Python**

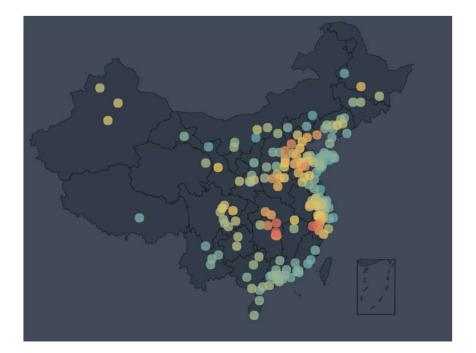
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## Tree data with GPS

#### We need to use tree data with GPS

- Then we can make GEO charts.
- Maybe we can use some libraries like pyecharts.
- But, how to get this data?



## Collecting data using UAV

## **Collecting data using UAV**

- But we think it is hard to use UAV in Korea forest and gathering data.
- So, we try to find some new method.
- Finally, we find a solution





## Google map trick

## We'll use google map api

- We can get satellite picture of forest.
- It contains RGB and GPS data.
- Then now, we have modeling data.



## Plan

Step 1

Get data from gMap

Make modeling system

Step 2

Classify data (Distinguish Tree Species)

Modeling data

Step 3

Real time receive data from UAV

Add/Del data from GEO chart

## Step 1

#### How do we collect map data?





From Google Map API





#### Covertype Data Set Download: Data Folder, Data Set Description

Abstract: Forest CoverType dataset



Data Set Characteristics:	Multivariate	Number of Instances:	581012	Area:	Life
Attribute Characteristics:	Categorical, Integer	Number of Attributes:	54	Date Donated	1998-08-01
Associated Tasks:	Classification	Missing Values?	No	Number of Web Hits:	334249

**External Dataset** 



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## **NEXT**

#### What about UAV?



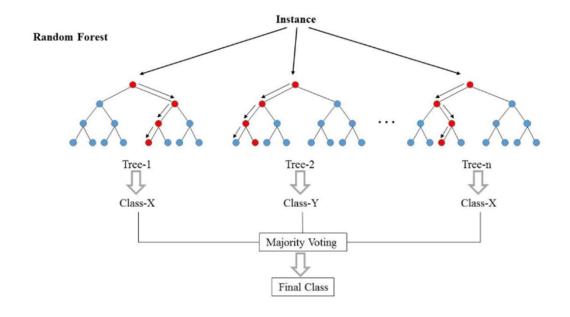


#### We have to build drones

## Step 2

Classify data (Distinguish Tree Species)

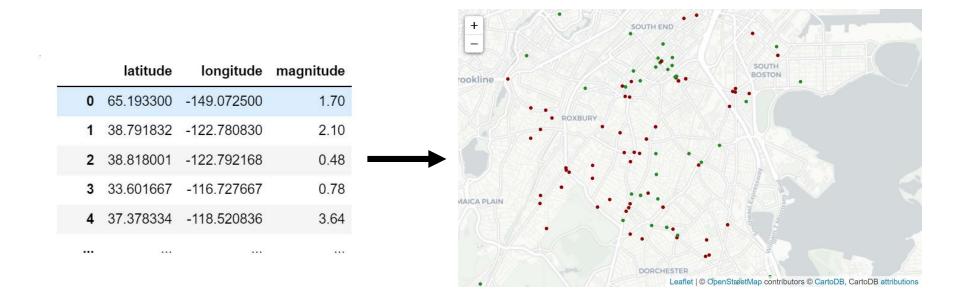
#### Modeling data



#### Classification

## Step 3

#### **Data Visualization**



#### Marker on Map



## Thank you

**Questions?** 

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