

Let  $\mathcal{H} \in \mathbb{R}^{m \times n \times m}$  be the ground truth tensor of  $n$  different Hessian matrices of the dimension  $m \times m$ , where the lateral slices represent Hessian matrices generated from the chemical reaction systems. We assume the ground truth tensor  $\mathcal{H}$  admits the following Tucker decomposition, for  $1 \leq i_1, i_3 \leq m$  and  $1 \leq i_2 \leq n$ ,

$$\mathcal{H}(i_1, i_2, i_3) = \sum_{j_1=1}^{r_1} \sum_{j_2=1}^{r_2} \sum_{j_3=1}^{r_3} \mathbf{X}_1(i_1, j_1) \mathbf{X}_2(i_2, j_2) \mathbf{X}_3(i_3, j_3) \mathcal{G}(j_1, j_2, j_3), \quad (1)$$

namely,  $\mathcal{H} = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3) \cdot \mathcal{G}$ , where  $\mathcal{G} \in \mathbb{R}^{r_1 \times r_2 \times r_3}$  is the core tensor of multilinear rank  $\mathbf{r} = (r_1, r_2, r_3)$ ,  $r_k = \text{rank}(\mathbf{H}_{(k)})$  for  $k = 1, 2, 3$ , and  $\mathbf{X}_1 \in \mathbb{R}^{m \times r_1}$ ,  $\mathbf{X}_2 \in \mathbb{R}^{n \times r_2}$ ,  $\mathbf{X}_3 \in \mathbb{R}^{m \times r_3}$  are factor matrices of each mode.

**Several perturbation bounds.** We now introduce several perturbation bounds that will be used repeatedly in the proof. Without loss of generality, assume that  $\hat{\mathbf{F}} = (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3, \hat{\mathcal{G}})$  and  $\mathbf{F} = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3, \mathcal{G})$  are aligned, and introduce the following notation that will be used repeatedly:

$$\Delta_{\hat{\mathbf{X}}_1} := \hat{\mathbf{X}}_1 - \mathbf{X}_1, \quad \Delta_{\hat{\mathbf{X}}_2} := \hat{\mathbf{X}}_2 - \mathbf{X}_2, \quad \Delta_{\hat{\mathbf{X}}_3} := \hat{\mathbf{X}}_3 - \mathbf{X}_3 \quad (2)$$

$$\check{\mathbf{X}}_1 := (\hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3) \mathcal{M}_1(\hat{\mathcal{G}})^\top, \quad \check{\mathbf{X}}_2 := (\hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_1) \mathcal{M}_2(\hat{\mathcal{G}})^\top, \quad \check{\mathbf{X}}_3 := (\hat{\mathbf{X}}_3 \otimes \hat{\mathbf{X}}_1) \mathcal{M}_3(\hat{\mathcal{G}})^\top \quad (3)$$

$$\bar{\mathbf{X}}_1 := (\mathbf{X}_2 \otimes \mathbf{X}_3) \mathcal{M}_1(\mathcal{G})^\top, \quad \bar{\mathbf{X}}_2 := (\mathbf{X}_2 \otimes \mathbf{X}_1) \mathcal{M}_2(\mathcal{G})^\top, \quad \bar{\mathbf{X}}_3 := (\mathbf{X}_3 \otimes \mathbf{X}_1) \mathcal{M}_3(\mathcal{G})^\top \quad (4)$$

$$\mathcal{T}_{\hat{\mathbf{X}}_1} := (\mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1}, \mathbf{I}_{r_2}, \mathbf{I}_{r_3}) \cdot \mathcal{G}, \quad \mathcal{T}_{\hat{\mathbf{X}}_2} := (\mathbf{I}_{r_1}, \mathbf{X}_2^\top \Delta_{\hat{\mathbf{X}}_2}, \mathbf{I}_{r_3}) \cdot \mathcal{G}, \quad \mathcal{T}_{\hat{\mathbf{X}}_3} := (\mathbf{I}_{r_1}, \mathbf{I}_{r_2}, \mathbf{X}_3^\top \Delta_{\hat{\mathbf{X}}_3}) \cdot \mathcal{G}. \quad (5)$$

To begin, we define the scaled distance between  $\hat{\mathbf{F}} = (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3, \hat{\mathcal{G}})$  and  $\mathbf{F} = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3, \mathcal{G})$  as:

$$\text{dist}^2(\hat{\mathbf{F}}, \mathbf{F}) := \inf_{\mathbf{Q}_k \in \text{GL}(r_k)} \left\| (\hat{\mathbf{X}}_1 \mathbf{Q}_1 - \mathbf{X}_1) \Sigma_1 \right\|_F^2 + \left\| (\hat{\mathbf{X}}_2 \mathbf{Q}_2 - \mathbf{X}_2) \Sigma_2 \right\|_F^2 + \left\| (\hat{\mathbf{X}}_3 \mathbf{Q}_3 - \mathbf{X}_3) \Sigma_3 \right\|_F^2 + \left\| (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G} \right\|_F^2, \quad (6)$$

where we call the matrices  $\{\mathbf{Q}_k\}_{k=1,2,3}$  that attain the infimum the optimal alignment matrices between  $\hat{\mathbf{F}}$  and  $\mathbf{F}$ ; in particular,  $\hat{\mathbf{F}}$  and  $\mathbf{F}$  are said to be aligned if the optimal alignment matrices are identity matrices. The core tensor  $\mathcal{G}$  is related to the singular values in each mode as  $\mathbf{G}_{(k)} \mathbf{G}_{(k)}^\top = \Sigma_k^2$ ,  $k = 1, 2, 3$ , where  $\Sigma_k := \text{diag}[\sigma_1(\mathbf{H}_{(k)}), \dots, \sigma_{r_k}(\mathbf{H}_{(k)})]$  is a diagonal matrix where the diagonal elements are composed of the nonzero singular values of  $\mathbf{H}_{(k)}$ .

Following basic relations, which follow straightforwardly from analogous matrix relations after applying matricizations, will be proven useful:

$$(\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3) \cdot ((\mathbf{Q}_1, \mathbf{Q}_2, \mathbf{Q}_3) \cdot \mathcal{G}) = (\mathbf{X}_1 \mathbf{Q}_1, \mathbf{X}_2 \mathbf{Q}_2, \mathbf{X}_3 \mathbf{Q}_3) \cdot \mathcal{G} \quad (7)$$

$$\langle (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3) \cdot \mathcal{G}, \mathcal{H} \rangle = \langle \mathcal{G}, (\mathbf{X}_1^\top, \mathbf{X}_2^\top, \mathbf{X}_3^\top) \cdot \mathcal{H} \rangle, \quad (8)$$

$$\|(\mathbf{Q}_1, \mathbf{Q}_2, \mathbf{Q}_3) \cdot \mathcal{G}\|_F \leq \|\mathbf{Q}_1\| \|\mathbf{Q}_2\| \|\mathbf{Q}_3\| \|\mathcal{G}\| \quad (9)$$

In [1], it is proven the following bound holds regarding the Frobenius norm when  $\epsilon \leq 0.2$ :

$$\left\| (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - \mathcal{H} \right\|_F \leq 3 \text{dist}(\hat{\mathbf{F}}, \mathbf{F}). \quad (10)$$

Hence, we serve the scaled distance in (6) as a metric to gauge the quality of the tensor recovery in our paper.

## 0.1. Useful Lemmas

In what follows, we provide several useful lemmas whose proof can be found in [1]. We start with a lemma that ensures the attainability of the infimum in the definition in (6) as long as  $\text{dist}(\hat{\mathbf{F}}, \mathbf{F})$  is sufficiently small.

**Lemma 1.** Fix any factor quadruple  $\hat{\mathbf{F}} = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3, \mathcal{G})$ . Suppose that  $\text{dist}(\hat{\mathbf{F}}, \mathbf{F}) < \sigma_{\min}(\mathcal{H})$ , then the infimum of (6) is attained at some  $\mathbf{Q}_k \in \text{GL}(r_k)$ , i.e., the alignment matrices between  $\hat{\mathbf{F}}$  and  $\mathbf{F}$  exist.

With the existence of the optimal alignment matrices in place, the following lemma delineates the optimality conditions they need to satisfy.

**Lemma 2.** The optimal alignment matrices  $\{\mathbf{Q}_k\}_{k=1,2,3}$  between  $\hat{\mathbf{F}}$  and  $\mathbf{F}$ , if exist, must satisfy

$$(\hat{\mathbf{X}}_1 \mathbf{Q}_1)^\top (\hat{\mathbf{X}}_1 \mathbf{Q}_1 - \mathbf{X}_1) \Sigma_1^2 = \mathcal{M}_1 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G} \right) \mathcal{M}_1 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \mathcal{G} \right)^\top, \quad (11)$$

$$(\hat{\mathbf{X}}_2 \mathbf{Q}_2)^\top (\hat{\mathbf{X}}_2 \mathbf{Q}_2 - \mathbf{X}_2) \Sigma_2^2 = \mathcal{M}_2 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G} \right) \mathcal{M}_2 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \mathcal{G} \right)^\top, \quad (12)$$

$$(\hat{\mathbf{X}}_3 \mathbf{Q}_3)^\top (\hat{\mathbf{X}}_3 \mathbf{Q}_3 - \mathbf{X}_3) \Sigma_3^2 = \mathcal{M}_3 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G} \right) \mathcal{M}_3 \left( (\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \mathcal{G} \right)^\top. \quad (13)$$

**Lemma 3.** Suppose  $\hat{\mathbf{F}} = (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3, \hat{\mathcal{G}})$  and  $\mathbf{F} = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3, \mathcal{G})$  are aligned and satisfy  $\text{dist}(\hat{\mathbf{F}}, \mathbf{F}) \leq \epsilon \sigma_{\min}(\mathcal{H})$  for some  $\epsilon < 1$ . Then, the following bounds hold regarding the spectral norm:

$$\left\| \Delta_{\hat{\mathbf{X}}_1} \right\| \vee \left\| \Delta_{\hat{\mathbf{X}}_2} \right\| \vee \left\| \Delta_{\hat{\mathbf{X}}_3} \right\| \vee \left\| \mathcal{M}_k (\Delta_{\hat{\mathcal{G}}})^\top \Sigma_k^{-1} \right\| \leq \epsilon, \quad k = 1, 2, 3 \quad (14)$$

Now, we prove Theorem 1 via recursion. Recall Theorem 1 in the main paper.

**Theorem 1.**

Suppose that for some  $t \geq 0$ , one has  $\text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) \leq \epsilon \sigma_{\min}(\mathcal{H})$  for some sufficiently small  $\epsilon$  whose size will be specified later in the proof. The goal is to bound the scaled distance from the ground truth to the next iterate, i.e.,  $\text{dist}(\hat{\mathbf{F}}_{t+1}, \mathbf{F})$ . Since  $\text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) \leq \epsilon \sigma_{\min}(\mathcal{H})$ , Lemma 1 ensures that the optimal alignment matrices  $\{\mathbf{Q}_{t,k}\}_{k=1,2,3}$  between  $\hat{\mathbf{F}}_t$  and  $\mathbf{F}$  exist. Therefore, in view of the definition of  $\text{dist}(\hat{\mathbf{F}}_{t+1}, \mathbf{F})$ , one has

$$\begin{aligned} \text{dist}^2(\hat{\mathbf{F}}_{t+1}, \mathbf{F}) &\leq \left\| (\hat{\mathbf{X}}_{t+1,1} \mathbf{Q}_{t,1} - \mathbf{X}_1) \Sigma_1 \right\|_F^2 + \left\| (\hat{\mathbf{X}}_{t+1,2} \mathbf{Q}_{t,2} - \mathbf{X}_2) \Sigma_2 \right\|_F^2 + \left\| (\hat{\mathbf{X}}_{t+1,3} \mathbf{Q}_{t,3} - \mathbf{X}_3) \Sigma_3 \right\|_F^2 \\ &\quad + \left\| (\mathbf{Q}_{t,1}^{-1}, \mathbf{Q}_{t,2}^{-1}, \mathbf{Q}_{t,3}^{-1}) \cdot \hat{\mathcal{G}}_{t+1} - \mathcal{G} \right\|_F^2. \end{aligned} \quad (15)$$

To avoid notational clutter, we denote  $\hat{\mathbf{F}} := (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3, \mathcal{G})$  with

$$\hat{\mathbf{X}}_1 := \hat{\mathbf{X}}_{t,1} \mathbf{Q}_{t,1}, \quad \hat{\mathbf{X}}_2 := \hat{\mathbf{X}}_{t,2} \mathbf{Q}_{t,2}, \quad \hat{\mathbf{X}}_3 := \hat{\mathbf{X}}_{t,3} \mathbf{Q}_{t,3}, \quad \hat{\mathcal{G}} := (\mathbf{Q}_{t,1}^{-1}, \mathbf{Q}_{t,2}^{-1}, \mathbf{Q}_{t,3}^{-1}) \cdot \mathcal{G}_t \quad (16)$$

and adopt the set of notation defined in ?? for the rest of the proof. Clearly,  $\hat{\mathbf{F}}$  is aligned with  $\mathbf{F}$ . With these notation, we can rephrase the consequences of Lemma 2 as:

$$\hat{\mathbf{X}}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1^2 = \mathcal{M}_1 (\Delta_{\hat{\mathcal{G}}}) \mathcal{M}_1 (\hat{\mathcal{G}})^\top, \quad (17)$$

$$\hat{\mathbf{X}}_2^\top \Delta_{\hat{\mathbf{X}}_2} \Sigma_2^2 = \mathcal{M}_2 (\Delta_{\hat{\mathcal{G}}}) \mathcal{M}_2 (\hat{\mathcal{G}})^\top, \quad (18)$$

$$\hat{\mathbf{X}}_3^\top \Delta_{\hat{\mathbf{X}}_3} \Sigma_3^2 = \mathcal{M}_3 (\Delta_{\hat{\mathcal{G}}}) \mathcal{M}_3 (\hat{\mathcal{G}})^\top. \quad (19)$$

**Proof of Theorem 1.** Utilize the gradient descent update rule to write

$$\begin{aligned} & \left( \hat{\mathbf{X}}_{t+1,1} \mathbf{Q}_{t,1} - \mathbf{X}_1 \right) \Sigma_1 \\ &= \left( \hat{\mathbf{X}}_1 - \eta \mathcal{M}_1 \left( 2\alpha \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\hat{\mathcal{Q}}\mathbf{S}}) \right) + 2\beta \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \right) \hat{\mathbf{X}}_1 - \mathbf{X}_1 \right) \Sigma_1, \end{aligned} \quad (20)$$

where we use the decomposition of the mode-1 matricization

$$\mathcal{M}_1 \left( 2\alpha \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\hat{\mathcal{Q}}\mathbf{S}}) \right) + 2\beta \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \right) \quad (22)$$

$$= 2\alpha \mathcal{M}_1 \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\hat{\mathcal{Q}}\mathbf{S}}) \right) + 2\beta \mathcal{M}_1 \left( (\hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3) \cdot \hat{\mathcal{G}} - (\mathcal{H} + \mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \quad (23)$$

$$= 2 \hat{\mathbf{X}}_1 \mathcal{M}_1 (\hat{\mathcal{G}}) (\hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3)^\top - 2 \mathbf{X}_1 \mathcal{M}_1 (\mathcal{G}) (\mathbf{X}_2 \otimes \mathbf{X}_3)^\top - 2\alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathcal{Q}}\mathbf{S}}) - 2\beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \quad (24)$$

$$= \Delta_{\hat{\mathbf{X}}_1} \hat{\mathbf{X}}_1^\top + \mathbf{X}_1 (\hat{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top - 2\alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathcal{Q}}\mathbf{S}}) - 2\beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \quad (25)$$

By plugging (25) into (21), we have

$$\left( \hat{\mathbf{X}}_{t+1,1} \mathbf{Q}_{t,1} - \mathbf{X}_1 \right) \boldsymbol{\Sigma}_1 \quad (26)$$

$$= \left( \hat{\mathbf{X}}_1 - \eta \mathcal{M}_1 \left( 2\alpha \left( \left( \hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3 \right) \cdot \hat{\mathcal{G}} - \left( \mathcal{H} + \mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}} \right) \right) + 2\beta \left( \left( \hat{\mathbf{X}}_1, \hat{\mathbf{X}}_2, \hat{\mathbf{X}}_3 \right) \cdot \hat{\mathcal{G}} - \left( \mathcal{H} + \mathcal{E}_{\mathcal{C}\hat{\Lambda}_T} \right) \right) \right) \check{\mathbf{X}}_1 - \mathbf{X}_1 \right) \boldsymbol{\Sigma}_1 \quad (27)$$

$$= \left( \hat{\mathbf{X}}_1 - \eta \left( \Delta_{\hat{\mathbf{X}}_1} \check{\mathbf{X}}_1^\top + \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top - 2\alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) - 2\beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \check{\mathbf{X}}_1 - \mathbf{X}_1 \right) \boldsymbol{\Sigma}_1 \quad (28)$$

$$= (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 + 2\alpha \eta \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 + 2\beta \eta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1. \quad (29)$$

Then, we have

$$\left\| \left( \hat{\mathbf{X}}_{t+1,1} \mathbf{Q}_{t,1} - \mathbf{X}_1 \right) \boldsymbol{\Sigma}_1 \right\| \quad (30)$$

$$= \left\| (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 + 2\alpha \eta \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 + 2\beta \eta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\| \quad (31)$$

$$\leq \underbrace{\left\| (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|}_{\odot} + \left\| 2\alpha \eta \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 + 2\beta \eta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\| \quad (32)$$

Let  $\odot := (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1$ . Taking squared on each side,

$$\left\| \left( \hat{\mathbf{X}}_{t+1,1} \mathbf{Q}_{t,1} - \mathbf{X}_1 \right) \boldsymbol{\Sigma}_1 \right\|^2 \quad (33)$$

$$\leq \|\odot\|^2 + 2 \left\langle \odot, 2\eta \left( \alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle + \left\| 2\eta \left( \alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right) \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2 \quad (34)$$

$$\leq \|\odot\|^2 + 4\eta \|\odot\| \left\| \alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right\| \|\check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1\| + 4\eta^2 \left\| \alpha \mathcal{M}_1 (\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1 (\mathcal{E}_{\mathcal{C}\hat{\Lambda}_T}) \right\|^2 \|\check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1\|^2. \quad (35)$$

Now, we bound  $\odot = (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1$ .

$$\|\odot\|^2 = \left\| (1 - \eta) \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 - \eta \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2 \quad (36)$$

$$= (1 - \eta)^2 \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|^2 - \eta(1 - \eta) \underbrace{\left\langle \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle}_{\odot_1} + \eta^2 \underbrace{\left\| \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2}_{\odot_2}. \quad (37)$$

$\odot_1$  is expressed as

$$\odot_1 = \left\langle \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle \quad (38)$$

$$= \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle \quad (39)$$

$$= \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathcal{M}_1 (\mathcal{G}) \left( \hat{\mathbf{X}}_2 \otimes \Delta_{\hat{\mathbf{X}}_3} + \Delta_{\hat{\mathbf{X}}_2} \otimes \mathbf{X}_3 \right)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle}_{\odot_{1,1}} + \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathcal{M}_1 (\Delta_{\hat{\mathcal{G}}}) \left( \hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3 \right)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle}_{\odot_{1,2}}. \quad (40)$$

Then, we have

$$\odot_{1,1} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathcal{M}_1 (\mathcal{G}) \left( \hat{\mathbf{X}}_2 \otimes \Delta_{\hat{\mathbf{X}}_3} + \Delta_{\hat{\mathbf{X}}_2} \otimes \mathbf{X}_3 \right)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\rangle \quad (41)$$

$$= \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathcal{M}_1 (\mathcal{G}) \left( \mathbf{X}_2 \otimes \Delta_{\hat{\mathbf{X}}_3} + \Delta_{\hat{\mathbf{X}}_2} \otimes \mathbf{X}_3 \right)^\top \bar{\mathbf{X}}_1 \boldsymbol{\Sigma}_1^{-1} \right\rangle}_{\odot_{1,1,1}} + \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1, \mathcal{M}_1 (\mathcal{G}) \left( \mathbf{X}_2 \otimes \Delta_{\hat{\mathbf{X}}_3} \right)^\top (\check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 - \bar{\mathbf{X}}_1 \boldsymbol{\Sigma}_1^{-1}) \right\rangle}_{\odot_{1,1,2}} \quad (42)$$

$$+ \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\mathcal{G}) \left( \Delta_{\hat{\mathbf{X}}_2} \otimes \mathbf{X}_3 \right)^\top (\check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1}) \right\rangle}_{\odot_{1,1,3}} + \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\mathcal{G}) \left( \Delta_{\hat{\mathbf{X}}_2} \otimes \Delta_{\hat{\mathbf{X}}_3} \right)^\top \check{\mathbf{X}}_1 \Sigma_1 \right\rangle}_{\odot_{1,1,4}}. \quad (43)$$

Utilizing the definition of  $\bar{\mathbf{X}}_1$ ,  $\odot_{1,1,1}$  can be rewritten as an inner product in the tensor space:

$$\odot_{1,1,1} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\mathcal{G}) \left( \mathbf{X}_2 \otimes \Delta_{\mathbf{X}_3} + \Delta_{\hat{\mathbf{X}}_2} \otimes \mathbf{X}_3 \right)^\top \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\rangle \quad (44)$$

$$= \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \mathcal{M}_1(\mathcal{G}), \mathcal{M}_1(\mathcal{G}) \left( \mathbf{I}_{r_3} \otimes \Delta_{\hat{\mathbf{X}}_3}^\top \mathbf{X}_3 + \Delta_{\hat{\mathbf{X}}_2}^\top \mathbf{X}_2 \otimes \mathbf{I}_{r_2} \right) \right\rangle \quad (45)$$

$$= \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_3} + \mathcal{T}_{\hat{\mathbf{X}}_2} \right\rangle \quad (46)$$

To control the other three terms,  $\odot_{1,1,2}$ ,  $\odot_{1,1,3}$ ,  $\odot_{1,1,4}$ , Lemma 3 turns out to be useful. For example,  $\odot_{1,1,2}$  is bounded by

$$|\odot_{1,1,2}| \leq \left\| \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \mathcal{M}_1(\mathcal{G}) \left( \mathbf{X}_2 \otimes \Delta_{\hat{\mathbf{X}}_3} \right)^\top \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\| \quad (47)$$

$$\leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\|, \quad (48)$$

we bound,

$$\left\| \check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\| = \left\| \check{\mathbf{X}}_1 \Sigma_1 - \check{\mathbf{X}}_1 \Sigma_1^{-1} + \check{\mathbf{X}}_1 \Sigma_1^{-1} - \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\| \quad (49)$$

$$\leq \left\| \check{\mathbf{X}}_1 (\Sigma_1 - \Sigma_1^{-1}) \right\| + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\| \quad (50)$$

$$\leq (3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\|. \quad (51)$$

Therefore,  $\odot_{1,1,2}$  is bounded as

$$|\odot_{1,1,2}| \leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1} \right\| \quad (52)$$

$$\leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\| \right). \quad (53)$$

In a similar way,

$$|\odot_{1,1,3}| \leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_2} \Sigma_3 \right\|_F \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\| \right) \quad (54)$$

$$|\odot_{1,1,4}| \leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F. \quad (55)$$

Therefore, combining (46), (53), (54) and (55),  $\odot_{1,1}$  is bounded as

$$\odot_{1,1} \leq \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_3} + \mathcal{T}_{\hat{\mathbf{X}}_2} \right\rangle + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\| \right) \quad (56)$$

$$+ \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_2} \Sigma_3 \right\|_F \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\| \right) + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F. \quad (57)$$

Next,  $\odot_{1,2}$  can be rewritten as

$$\odot_{1,2} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}}) \left( \hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3 \right)^\top \check{\mathbf{X}}_1 \Sigma_1 \right\rangle \quad (58)$$

$$= \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}}) \mathcal{M}_1(\mathcal{G})^\top \Sigma_1^{-1} \right\rangle + \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}}) (\mathbf{X}_2 \otimes \mathbf{X}_3)^\top (\check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1}) \right\rangle}_{\odot_{1,2,1}} \quad (59)$$

$$+ \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}}) \left( \hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3 - \mathbf{X}_2 \otimes \mathbf{X}_3 \right)^\top \check{\mathbf{X}}_1 \Sigma_1 \right\rangle}_{\odot_{1,2,2}} \quad (60)$$

$$= \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{g}}) \mathcal{M}_1(\hat{g})^\top \Sigma_1^{-1} \right\rangle - \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{g}}) \mathcal{M}_1(\Delta_{\hat{g}})^\top \Sigma_1^{-1} \right\rangle}_{\odot_{1,2,3}} + \odot_{1,2,1} + \odot_{1,2,2} \quad (61)$$

$$= \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \hat{\mathbf{X}}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\rangle + \odot_{1,2,1} + \odot_{1,2,2} + \odot_{1,2,3} \quad (62)$$

$$= \left\| \mathcal{T}_{\hat{\mathbf{X}}_1} \right\|_F^2 + \odot_{1,2,1} + \odot_{1,2,2} + \odot_{1,2,3} + \underbrace{\left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \Delta_{\hat{\mathbf{X}}_1}^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\rangle}_{\odot_{1,2,4}}. \quad (63)$$

Now, we bound  $\odot_{1,2,1}$ ,  $\odot_{1,2,2}$ ,  $\odot_{1,2,3}$  and  $\odot_{1,2,4}$ .

$$\odot_{1,2,1} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{g}}) (\mathbf{X}_2 \otimes \mathbf{X}_3)^\top (\check{\mathbf{X}}_1 \Sigma_1 - \bar{\mathbf{X}}_1 \Sigma_1^{-1}) \right\rangle \quad (64)$$

$$\leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F ((3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| \check{\mathbf{X}}_1 (\Sigma_1 - \Sigma_1^{-1}) \right\|) \quad (65)$$

$$\odot_{1,2,2} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{g}}) (\hat{\mathbf{X}}_2 \otimes \hat{\mathbf{X}}_3 - \mathbf{X}_2 \otimes \mathbf{X}_3)^\top \check{\mathbf{X}}_1 \Sigma_1 \right\rangle \quad (66)$$

$$\leq \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F (2\epsilon + \epsilon^2) \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\| \quad (67)$$

$$\odot_{1,2,3} = \left\langle \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1, \mathcal{M}_1(\Delta_{\hat{g}}) \mathcal{M}_1(\Delta_{\hat{g}})^\top \Sigma_1^{-1} \right\rangle \quad (68)$$

$$\leq \left\| \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \mathcal{M}_1(\Delta_{\hat{g}}) \right\|_F \left\| \mathcal{M}_1(\Delta_{\hat{g}})^\top \Sigma_1^{-1} \right\|_F \quad (69)$$

$$\leq \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F \quad (70)$$

$$\odot_{1,2,4} \leq \left\| \mathbf{X}_1^\top \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_1} \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \leq \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F^2 \quad (71)$$

To this end,

$$\odot_{1,2} \leq \left\| \mathcal{T}_{\hat{\mathbf{X}}_1} \right\|_F^2 + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F ((3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| \check{\mathbf{X}}_1 (\Sigma_1 - \Sigma_1^{-1}) \right\|) \quad (72)$$

$$+ \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F (2\epsilon + \epsilon^2) \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\| + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F^2. \quad (73)$$

To this end,  $\odot_1$  is bounded with and as

$$\odot_1 = \odot_{1,1} + \odot_{1,2} \quad (74)$$

$$= \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_3} + \mathcal{T}_{\hat{\mathbf{X}}_2} \right\rangle + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F ((3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\|) \quad (75)$$

$$+ \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_2} \Sigma_3 \right\|_F ((3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \Sigma_1^{-1} \right\|) + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F \quad (76)$$

$$+ \left\| \mathcal{T}_{\hat{\mathbf{X}}_1} \right\|_F^2 + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F ((3\epsilon + 3\epsilon^2 + \epsilon^3) + \left\| \check{\mathbf{X}}_1 (\Sigma_1 - \Sigma_1^{-1}) \right\|) + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F (2\epsilon + \epsilon^2) \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F^2 \quad (77)$$

$$= \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_1} + \mathcal{T}_{\hat{\mathbf{X}}_2} + \mathcal{T}_{\hat{\mathbf{X}}_3} \right\rangle + (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \quad (78)$$

$$+ (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_2} \Sigma_3 \right\|_F + \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \Sigma_2 \right\|_F \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F \quad (79)$$

$$+ (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F + (2\epsilon + \epsilon^2) \left\| \check{\mathbf{X}}_1 \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F \left\| \Delta_{\hat{g}} \right\|_F + \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \Sigma_1 \right\|_F^2 \quad (80)$$

Now, let us obtain bound for  $\odot_2$ .

$$\sqrt{\odot_2} = \left\| \mathbf{X}_1 (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2 \quad (81)$$

$$= \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1)^\top \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2 \quad (82)$$

$$\leq \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \right\|_F \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2 \quad (83)$$

$\left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2$  is bounded as

$$\left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2 = \frac{1}{\sigma_{\min}(\check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1^{-1})} \quad (84)$$

And,

$$\left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1^{-1} \right\| \leq \left\| \hat{\mathbf{X}}_2 \right\| \left\| \hat{\mathbf{X}}_3 \right\| \left\| \mathcal{M}_1(\hat{\mathcal{G}}) \boldsymbol{\Sigma}_1^{-1} \right\| \quad (85)$$

$$\leq \left\| \hat{\mathbf{X}}_2 \right\| \left\| \hat{\mathbf{X}}_3 \right\| \left\| (\mathcal{M}_1(\mathcal{G}) - \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}})) \boldsymbol{\Sigma}_1^{-1} \right\| \quad (86)$$

$$\leq \left\| \hat{\mathbf{X}}_2 \right\| \left\| \hat{\mathbf{X}}_3 \right\| (\left\| \mathcal{M}_1(\mathcal{G}) \boldsymbol{\Sigma}_1^{-1} \right\| + \left\| \mathcal{M}_1(\Delta_{\hat{\mathcal{G}}}) \boldsymbol{\Sigma}_1^{-1} \right\|) \quad (87)$$

$$= (1 + \epsilon)^3 \quad (88)$$

We have

$$\left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_2 = \frac{1}{\sigma_{\min}(\check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1^{-1})} \leq \frac{1}{(1 + \epsilon)^3} \quad (89)$$

Plugging (89) into (83), we have

$$\sqrt{\odot_2} \leq (1 + \epsilon)^{-3} \left\| (\check{\mathbf{X}}_1 - \bar{\mathbf{X}}_1) \right\|_F \quad (90)$$

$$\leq (1 + \epsilon)^{-3} \left( 1 + \epsilon + \frac{\epsilon^2}{3} \right) \left( \left\| \Delta_{\hat{\mathbf{X}}_3} \boldsymbol{\Sigma}_2 \right\|_F + \left\| \Delta_{\hat{\mathbf{X}}_2} \boldsymbol{\Sigma}_3 \right\|_F + \left\| \Delta_{\hat{\mathcal{G}}} \right\|_F \right) \quad (91)$$

$$= (1 + \epsilon)^{-3} \left( 1 + \epsilon + \frac{\epsilon^2}{3} \right) \left( \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) - \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \right) \quad (92)$$

$$\leq (1 + \epsilon)^{-3} \left( 1 + \epsilon + \frac{\epsilon^2}{3} \right) \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}). \quad (93)$$

Finally, we have

$$\odot_2 \leq (1 + \epsilon)^{-6} \left( 1 + \epsilon + \frac{\epsilon^2}{3} \right)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}). \quad (94)$$

To this end, we have

$$\|\odot\|^2 \leq (1 - \eta)^2 \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F^2 - \eta(1 - \eta) \left( \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_1} + \mathcal{T}_{\hat{\mathbf{X}}_2} + \mathcal{T}_{\hat{\mathbf{X}}_3} \right\rangle + (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \boldsymbol{\Sigma}_2 \right\|_F \right) \quad (95)$$

$$- \eta(1 - \eta) \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_2} \boldsymbol{\Sigma}_3 \right\|_F + \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \boldsymbol{\Sigma}_2 \right\|_F \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\| \right) \quad (96)$$

$$- \eta(1 - \eta) \left( (3\epsilon + 3\epsilon^2 + \epsilon^3) \left( 1 + \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|^2 \right) \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathcal{G}}} \right\|_F + (2\epsilon + \epsilon^2) \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathcal{G}}} \right\|_F \right) \quad (97)$$

$$- \eta(1 - \eta) \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathcal{G}}} \right\|_F - \eta(1 - \eta) \epsilon \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F^2 + \eta^2 (1 + \epsilon)^{-6} \left( 1 + \epsilon + \frac{\epsilon^2}{3} \right)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) \quad (98)$$

$$\leq (1 - \eta)^2 \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F^2 - \eta(1 - \eta) \left( \left\langle \mathcal{T}_{\hat{\mathbf{X}}_1}, \mathcal{T}_{\hat{\mathbf{X}}_1} + \mathcal{T}_{\hat{\mathbf{X}}_2} + \mathcal{T}_{\hat{\mathbf{X}}_3} \right\rangle + C_1 \epsilon \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \left\| \Delta_{\hat{\mathbf{X}}_1} \boldsymbol{\Sigma}_1 \right\|_F \left\| \Delta_{\hat{\mathbf{X}}_3} \boldsymbol{\Sigma}_2 \right\|_F \left\| \check{\mathbf{X}}_1 \boldsymbol{\Sigma}_1 \right\| \right) \quad (99)$$

$$+ \eta^2 (1 + \epsilon)^{-6} \left(1 + \epsilon + \frac{\epsilon^2}{3}\right)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) \quad \leq \quad (100)$$

$$\leq (1 - \eta)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + 4\eta^2 (1 + \epsilon)^{-6} (1 + 2\epsilon)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) \quad (101)$$

$$= \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) (1 - 2\eta + \eta^2 + 4\eta^2(1 + \epsilon)^{-6}(1 + 2\epsilon)^2) \quad (102)$$

If  $\eta < 1/(1 + 4(1 + \epsilon)^{-6}(1 + 2\epsilon)^2)$ , we have  $\|\odot\|^2 \leq (1 - \eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F})$ .

Recalling the bound of  $\left\|(\hat{\mathbf{X}}_{t+1,1}\mathbf{Q}_{t,1} - \mathbf{X}_1)\boldsymbol{\Sigma}_1\right\|_F^2$  in (83), given  $\eta < 1/(1 + 4(1 + \epsilon)^{-6}(1 + 2\epsilon)^2)$ , it can be finally bounded as

$$\left\|(\hat{\mathbf{X}}_{t+1,1}\mathbf{Q}_{t,1} - \mathbf{X}_1)\boldsymbol{\Sigma}_1\right\|_F^2 \quad (103)$$

$$\leq \|\odot\|^2 + 4\eta \|\odot\| \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \left\|\check{\mathbf{X}}_1\boldsymbol{\Sigma}_1\right\| + 4\eta^2 \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\|^2 \left\|\check{\mathbf{X}}_1\boldsymbol{\Sigma}_1\right\|^2 \quad (104)$$

$$\leq (1 - \eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{4\eta\sqrt{(1 - \eta)}}{(1 + \epsilon)^3} \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| + \frac{4\eta^2}{(1 + \epsilon)^6} \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\|^2 \quad (105)$$

$$\leq (1 - \eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \left( \frac{4\eta\sqrt{(1 - \eta)}}{(1 + \epsilon)^3} \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{4\eta^2}{(1 + \epsilon)^6} \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \right) \quad (106)$$

In a similar way, we can also obtain the same bound for  $\left\|(\hat{\mathbf{X}}_{t+1,2}\mathbf{Q}_{t,2} - \mathbf{X}_2)\boldsymbol{\Sigma}_2\right\|_F^2$  and  $\left\|(\hat{\mathbf{X}}_{t+1,3}\mathbf{Q}_{t,3} - \mathbf{X}_3)\boldsymbol{\Sigma}_3\right\|_F^2$ . For example,

$$\begin{aligned} & \left\|(\hat{\mathbf{X}}_{t+1,2}\mathbf{Q}_{t,2} - \mathbf{X}_2)\boldsymbol{\Sigma}_2\right\|_F^2 \\ & \leq (1 - \eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \left( \frac{4\eta\sqrt{(1 - \eta)}}{(1 + \epsilon)^3} \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{4\eta^2}{(1 + \epsilon)^6} \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \right). \end{aligned} \quad (107)$$

For  $\left\|(\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G}\right\|_F^2$ , we follow the bound in [], such that as long as  $\eta^2 \leq 2/5$  and  $\epsilon \leq 0.2/C$ , for  $C > 1$ , one has

$$\left\|(\mathbf{Q}_{t,1}^{-1}, \mathbf{Q}_{t,2}^{-1}, \mathbf{Q}_{t,3}^{-1}) \cdot \hat{\mathcal{G}}_{t+1} - \mathcal{G}\right\|_F^2 \leq (1 - \eta)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + 2\eta(1 - \eta)C_2\epsilon \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \eta^2 C_3\epsilon \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}). \quad (108)$$

$$\leq ((1 - \eta)^2 + 2\eta(1 - \eta)C\epsilon + \eta^2 C\epsilon) \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) \quad (109)$$

$$\leq (1 - 0.7\eta)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}). \quad (110)$$

For the proof, refer to []. Combining the bounds for  $\left\|(\hat{\mathbf{X}}_{t+1,1}\mathbf{Q}_{t,1} - \mathbf{X}_1)\boldsymbol{\Sigma}_1\right\|_F^2$ ,  $\left\|(\hat{\mathbf{X}}_{t+1,2}\mathbf{Q}_{t,2} - \mathbf{X}_2)\boldsymbol{\Sigma}_2\right\|_F^2$ ,  $\left\|(\hat{\mathbf{X}}_{t+1,3}\mathbf{Q}_{t,3} - \mathbf{X}_3)\boldsymbol{\Sigma}_3\right\|_F^2$  and  $\left\|(\mathbf{Q}_1^{-1}, \mathbf{Q}_2^{-1}, \mathbf{Q}_3^{-1}) \cdot \hat{\mathcal{G}} - \mathcal{G}\right\|_F^2$  in (106), (107) and (108), we can bound (15) as

$$\text{dist}^2(\hat{\mathbf{F}}_{t+1}, \mathbf{F}) \quad (111)$$

$$\leq \left\|(\hat{\mathbf{X}}_{t+1,1}\mathbf{Q}_{t,1} - \mathbf{X}_1)\boldsymbol{\Sigma}_1\right\|_F^2 + \left\|(\hat{\mathbf{X}}_{t+1,2}\mathbf{Q}_{t,2} - \mathbf{X}_2)\boldsymbol{\Sigma}_2\right\|_F^2 + \left\|(\hat{\mathbf{X}}_{t+1,3}\mathbf{Q}_{t,3} - \mathbf{X}_3)\boldsymbol{\Sigma}_3\right\|_F^2 + \left\|(\mathbf{Q}_{t,1}^{-1}, \mathbf{Q}_{t,2}^{-1}, \mathbf{Q}_{t,3}^{-1}) \cdot \hat{\mathcal{G}}_{t+1} - \mathcal{G}\right\|_F^2 \quad (112)$$

$$\leq 3(1 - \eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \left( \frac{12\eta\sqrt{(1 - \eta)}}{(1 + \epsilon)^3} \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{12\eta^2}{(1 + \epsilon)^6} \left\|\alpha\mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta\mathcal{M}_1(\mathcal{E}_{\mathcal{C}\hat{\Lambda}_x})\right\| \right) \quad (113)$$

$$+ (1 - 0.7\eta)^2 \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}), \quad (114)$$

if  $\eta \leq 4/49$ ,

$$\text{dist}^2(\hat{\mathbf{F}}_{t+1}, \mathbf{F}) \tag{115}$$

$$\leq 4(1-\eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \left\| \alpha \mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1(\mathcal{E}_{C\hat{\Lambda}_T}) \right\| \left( \frac{12\eta\sqrt{(1-\eta)}}{(1+\epsilon)^3} \text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{12\eta^2}{(1+\epsilon)^6} \left\| \alpha \mathcal{M}_1(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \mathcal{M}_1(\mathcal{E}_{C\hat{\Lambda}_T}) \right\| \right) \tag{116}$$

$$= 4(1-\eta)\text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{12\eta\sqrt{(1-\eta)}}{(1+\epsilon)^3} \left( \alpha \sigma_{\max}(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \sigma_{\max}(\mathcal{E}_{C\hat{\Lambda}_T}) \right) \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) \tag{117}$$

$$+ \frac{12\eta^2}{(1+\epsilon)^6} \left( \alpha \sigma_{\max}(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \sigma_{\max}(\mathcal{E}_{C\hat{\Lambda}_T}) \right)^2 \tag{118}$$

$$\leq (1-\eta) \left( 4 + \frac{12\eta}{(1+\epsilon)^3} \left( \alpha \sigma_{\max}(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \sigma_{\max}(\mathcal{E}_{C\hat{\Lambda}_T}) \right) \right) \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{12\eta^2}{(1+\epsilon)^6} \left( \alpha \sigma_{\max}(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \sigma_{\max}(\mathcal{E}_{C\hat{\Lambda}_T}) \right)^2. \tag{119}$$

Note that we suppose  $\text{dist}(\hat{\mathbf{F}}_t, \mathbf{F}) \leq \epsilon \sigma_{\min}(\mathcal{H})$  for some sufficiently small  $\epsilon$ . Then, according to (10), when  $\epsilon \leq 0.2$  and  $\eta \leq \min(4/49, 1/(1+4(1+\epsilon)^{-6}(1+2\epsilon^2)))$ , we have

$$\|(\hat{\mathbf{X}}_1^t, \hat{\mathbf{X}}_2^t, \hat{\mathbf{X}}_3^t) \cdot \hat{\mathcal{G}}^t - \mathcal{H}\|_F \leq (1-\eta)^t \left( 4 + \frac{12\eta\delta}{(1+\epsilon)^3} \right)^t \text{dist}^2(\hat{\mathbf{F}}_t, \mathbf{F}) + \frac{12\eta^2\delta^2}{(1+\epsilon)^6} \left( \sum_{k=0}^{t-1} (1-\eta)^k \left( 4 + \frac{12\eta\delta}{(1+\epsilon)^3} \right)^k \right) \tag{120}$$

$$\leq \epsilon(1-\eta)^t \left( 4 + \frac{12\eta\delta}{(1+\epsilon)^3} \right)^t \sigma_{\min}(\mathcal{H}) + \frac{12\eta^2\delta^2}{(1+\epsilon)^6} \left( \sum_{k=0}^{t-1} (1-\eta)^k \left( 4 + \frac{12\eta\delta}{(1+\epsilon)^3} \right)^k \right) \tag{121}$$

where  $\delta := \alpha \sigma_{\max}(\mathcal{E}_{\hat{\mathbf{Q}}\mathbf{S}}) + \beta \sigma_{\max}(\mathcal{E}_{C\hat{\Lambda}_T})$  and  $\alpha + \beta = 1$ . This concludes the proof of Theorem 1.



## 1. REFERENCES

- [1] Tian Tong, Cong Ma, Ashley Prater-Bennette, Erin Tripp, and Yuejie Chi, “Scaling and scalability: Provable nonconvex low-rank tensor estimation from incomplete measurements,” *Journal of Machine Learning Research*, vol. 23, no. 163, pp. 1–77, 2022.