

Bisimilarity of diagrams

RAMiCS 2020

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Bisimilarity via open morphisms

Computing systems in the language of category theory

Mainly, two types:

- coalgebraic approach [Rutten, Jacobs, ...]
- lifting approach [Winskel, Joyal, Nielsen, ...]

approach	class type	system type	bisimulations
coalgebraic	category + functor (monad)	coalgebra	span of morphisms of coalgebras
lifting	category + sub-category	object	span of morphisms with lifting property w.r.t. the sub-category

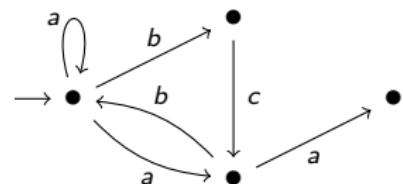
Example : TS I - category of TS

Fix an alphabet Σ .

Transition system :

A **TS** $T = (Q, i, \Delta)$ on Σ is the following data:

- a set Q (of states);
- a initial state $i \in Q$;
- a set of transitions $\Delta \subseteq Q \times \Sigma \times Q$.



Morphism of TS :

A **morphism of TS** $f : T_1 = (Q_1, i_1, \Delta_1) \longrightarrow T_2 = (Q_2, i_2, \Delta_2)$ is a function $f : Q_1 \longrightarrow Q_2$ such that $f(i_1) = i_2$ and for every $(p, a, q) \in \Delta_1$, $(f(p), a, f(q)) \in \Delta_2$.

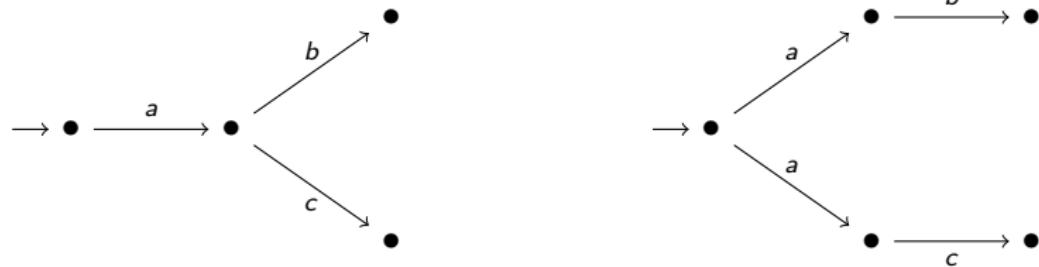
TS(Σ) = category of TS on Σ and morphisms of TS

Example : TS II - relational bisimulations

Bisimulations [Park]:

A **bisimulation** between $T_1 = (Q_1, i_1, \Delta_1)$ and $T_2 = (Q_2, i_2, \Delta_2)$ is a relation $R \subseteq Q_1 \times Q_2$ such that:

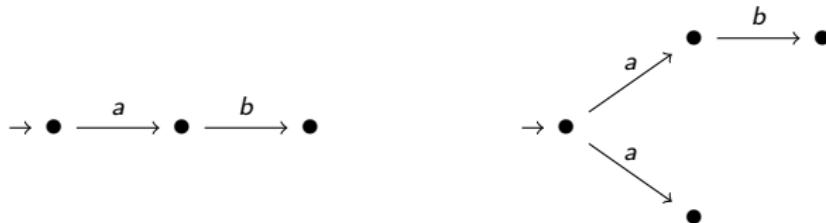
- (i) $(i_1, i_2) \in R$;
- (ii) if $(q_1, q_2) \in R$ and $(q_1, a, q'_1) \in \Delta_1$ then there is $q'_2 \in Q_2$ such that $(q_2, a, q'_2) \in \Delta_2$ and $(q'_1, q'_2) \in R$;
- (iii) if $(q_1, q_2) \in R$ and $(q_2, a, q'_2) \in \Delta_2$ then there is $q'_1 \in Q_1$ such that $(q_1, a, q'_1) \in \Delta_1$ and $(q'_1, q'_2) \in R$.



Example : TS III - morphisms and (bi)simulations

$$\text{Graph}(f) = \{(q, f(q)) \mid q \in Q\}$$

$\text{Graph}(f)$ is always a simulation. But bisimilarity \neq similarity in both directions.

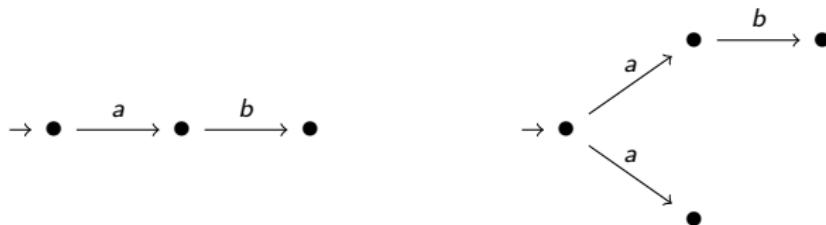


What are the morphisms whose graph is a bisimulation ?

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What are the morphisms whose graph is a bisimulation ?

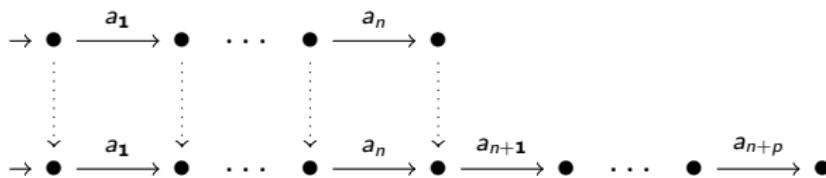
- the morphisms of coalgebras.
- the morphisms that lift transitions. ✓

Example : TS IV - lifting properties and open morphisms

f has the **right lifting property** with respect to g iff

$$\begin{array}{ccc} P & \xrightarrow{x} & X \\ g \downarrow & \nearrow \exists \theta & \downarrow f \\ Q & \xrightarrow{y} & Y \end{array}$$

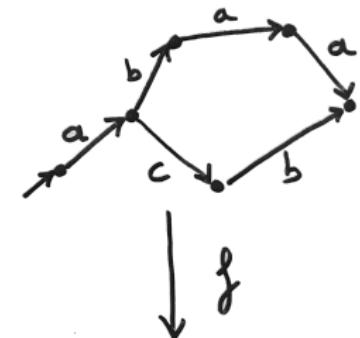
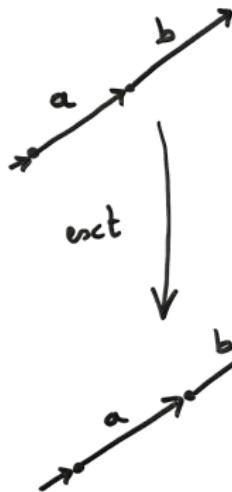
A morphism of TS is **open** [Joyal, Nielsen, Winskel] if it has the right lifting property with respect to every **branch extension**:



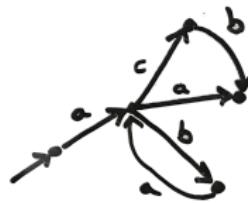
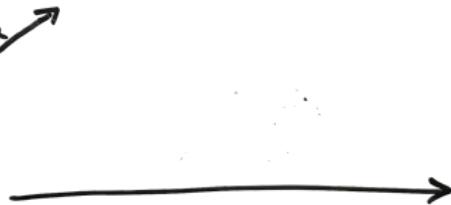
Observation:

Two systems are bisimilar iff there is a span of open morphisms between them.

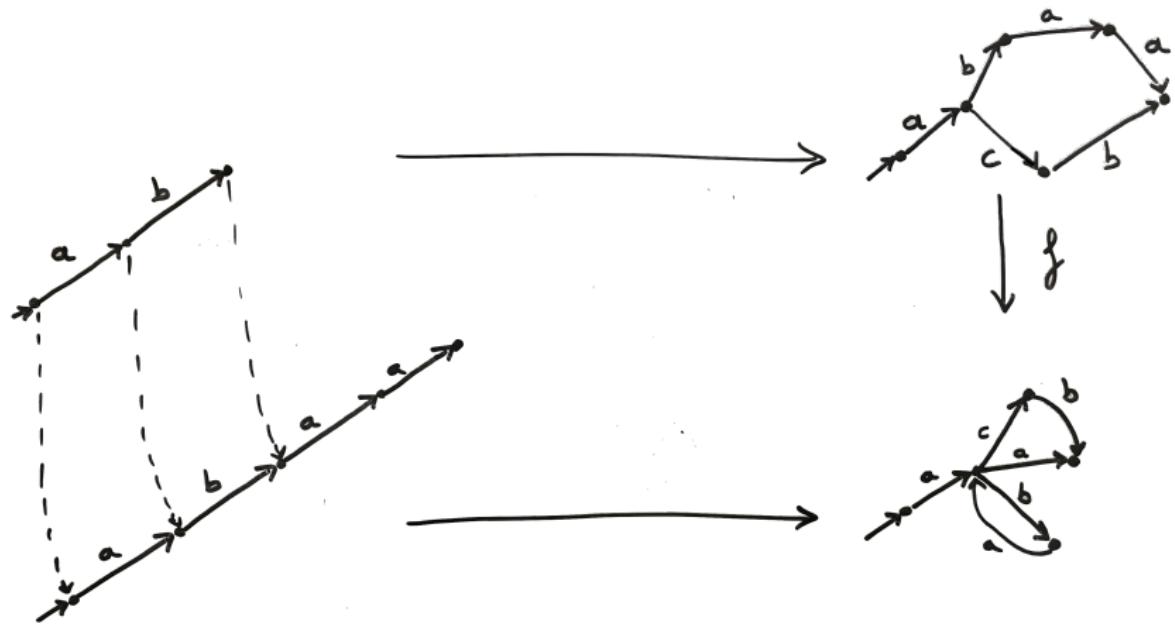
Example of a RLP



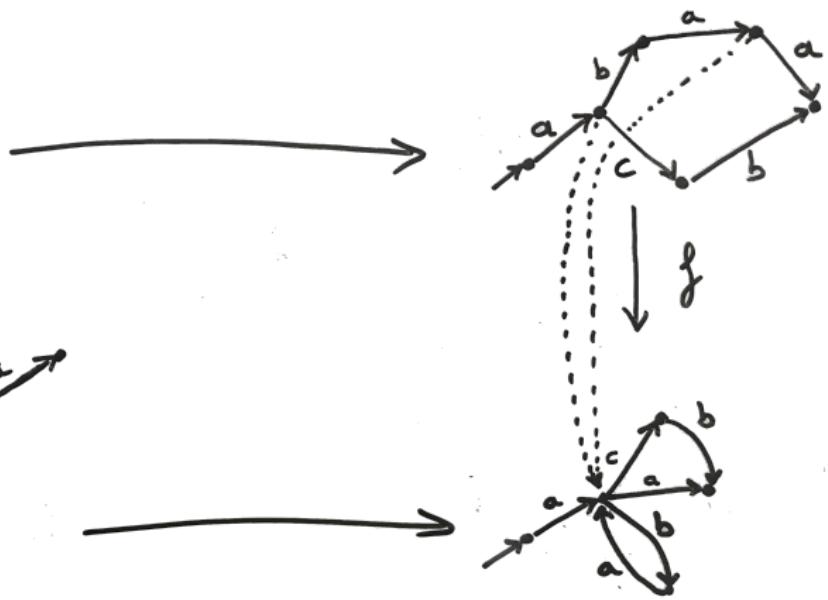
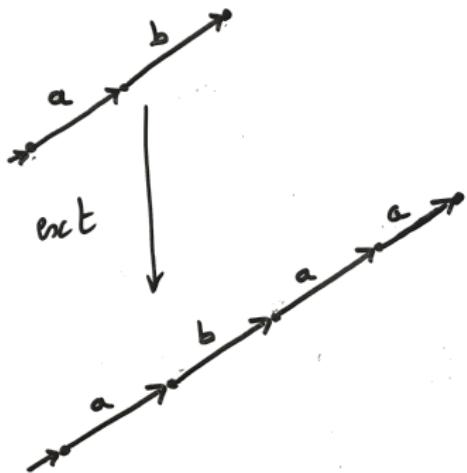
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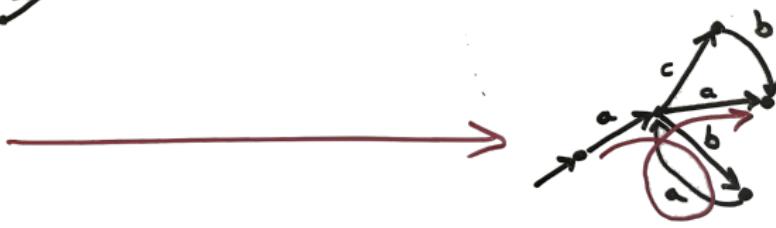
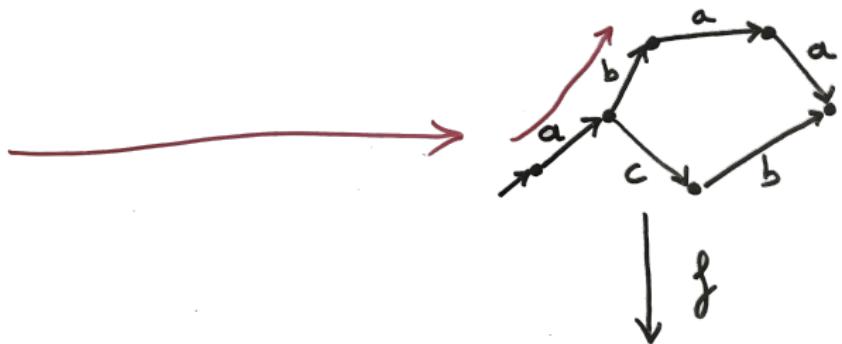
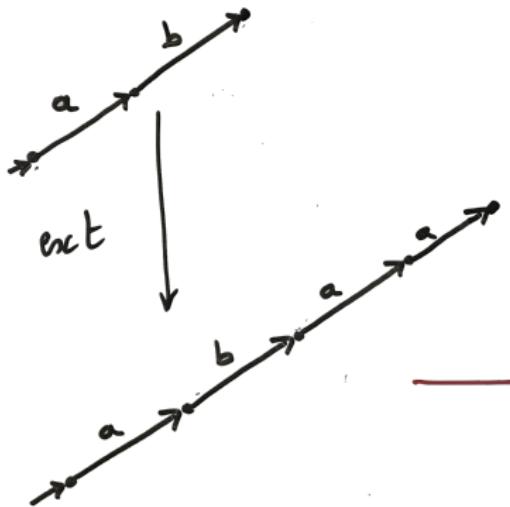
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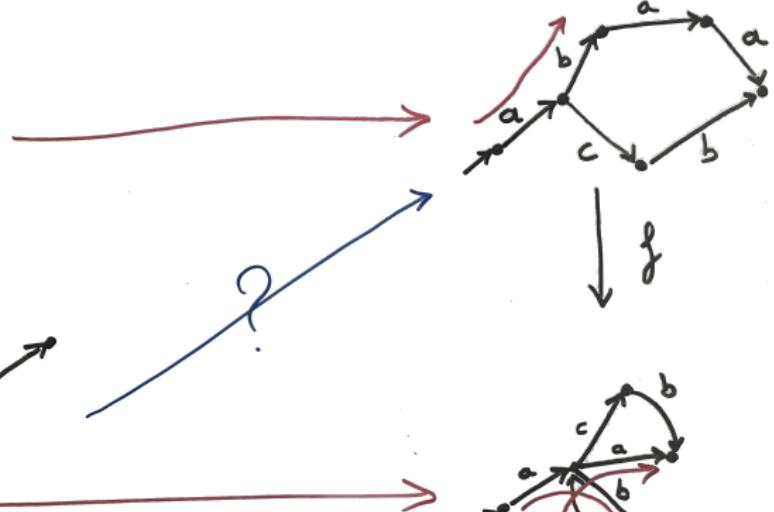
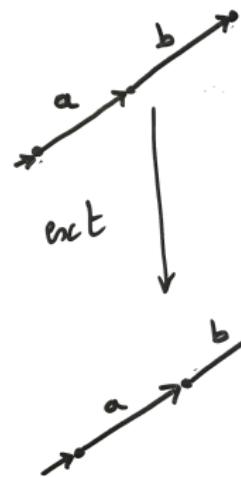
Example of a RLP



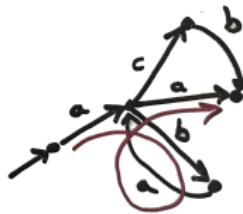
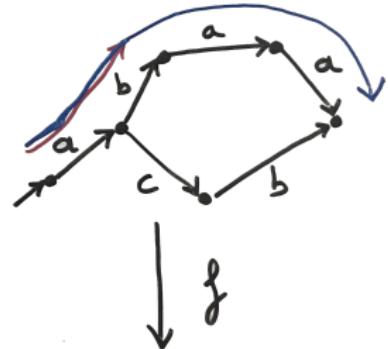
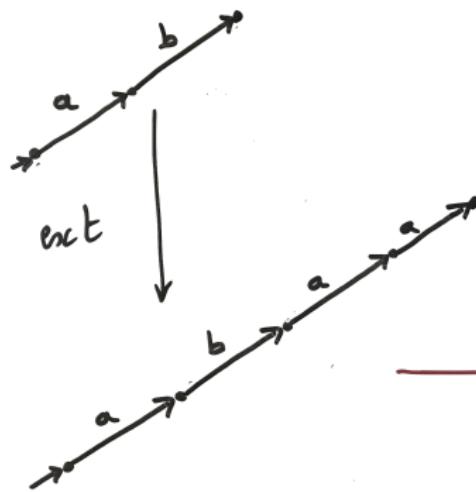
Example of a RLP



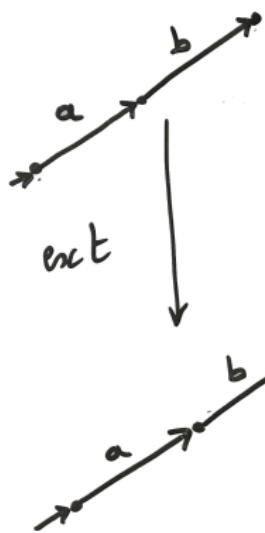
Example of a RLP



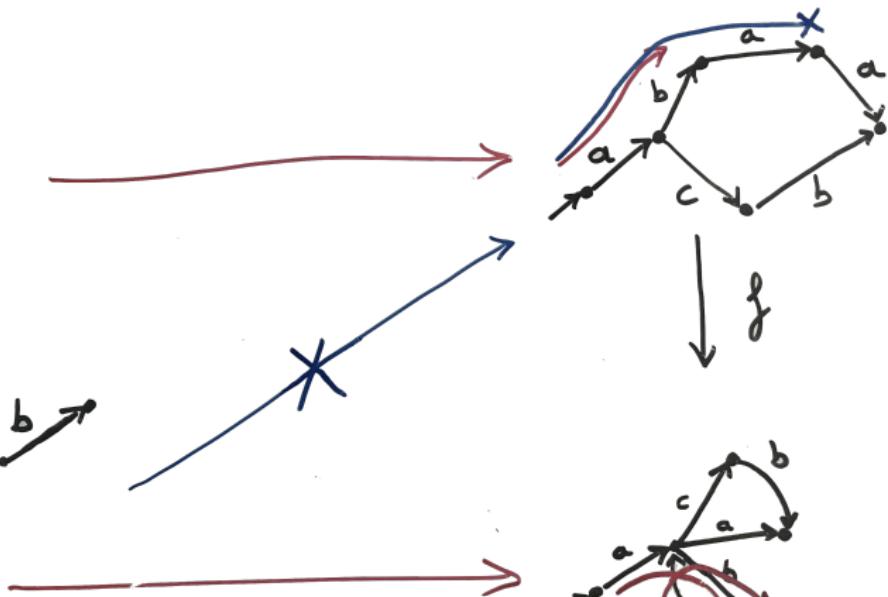
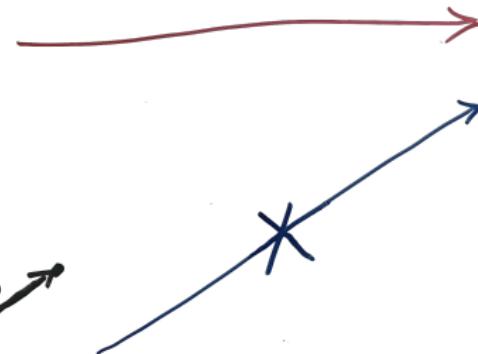
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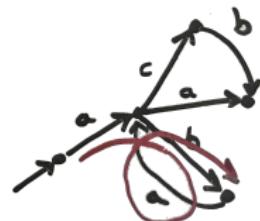
...but not an open map



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Categorical models

Categorical models:

A **categorical model** is a category \mathcal{M} with a subcategory \mathcal{P} which have a common initial object I .

- \mathcal{M} = category of systems (Ex : $\mathbf{TS}(\Sigma)$);
- \mathcal{P} = sub-category of **paths** (Ex : sub-category of branches);
- unique morphism $I \longrightarrow X$ = initial state of X (Ex : $I = *$).

Other examples : 1-safe Petri nets + event structures, event structures/transition systems with independence + pomsets, HDA + paths, presheaves models, ...

Bisimilarity as spans of open morphisms

\mathcal{P} -bisimilarity [J., N., W.]:

We say that a morphism $f : X \rightarrow Y$ of \mathcal{M} is **(\mathcal{P} -)open** if it has the right lifting property w.r.t. \mathcal{P} .

$$\begin{array}{ccc} P & \xrightarrow{x} & X \\ p \downarrow & \theta \nearrow & \downarrow f \\ Q & \xrightarrow{y} & Y \end{array}$$

We then say that two objects X and Y of \mathcal{M} are **\mathcal{P} -bisimilar** iff there exists a span $f : Z \rightarrow X$ and $g : Z \rightarrow Y$ where f and g are \mathcal{P} -open.

$$\begin{array}{ccc} & Z & \\ f \swarrow & & \searrow g \\ X & & Y \end{array}$$

Ex: strong history-preserving bisimilarity of ES/TSI, ...

Typically, bisimilarity defined by relation on runs.

Path bisimulations

Example : TS V - from states to runs

A bisimulation R between T_1 and T_2 induces a relation R_n between n -branches of T_1 and n -branches of T_2 by:

$$R_n = \{(f_1 : B \longrightarrow T_1, f_2 : B \longrightarrow T_2) \mid \forall i \in [n], (f_1(i), f_2(i)) \in R\}$$

Properties:

- $(\iota_{T_1}, \iota_{T_2}) \in R_0$ by (i);
- by (ii), if $(f_1, f_2) \in R_n$ and if $(f_1(n), a, q_1) \in \Delta_1$ then there is $q_2 \in Q_2$ such that $(f_2(n), a, q_2) \in \Delta_2$ and $(f'_1, f'_2) \in R_{n+1}$ where $f'_i(j) = f_i(j)$ if $j \leq n$, q_i otherwise;
- symmetrically with (iii);
- if $(f_1, f_2) \in R_{n+1}$ then $(f'_1, f'_2) \in R_n$ where f'_i is the restriction of f_i to $[n]$.

Fact:

Bisimilarity is equivalent to the existence of such a relation between branches.

Relational bisimilarities in categorical models

Let R be a set of elements of the form $X \xleftarrow{f} P \xrightarrow{g} Y$ with P object of \mathcal{P} .

Here are some properties that R may satisfy:

(a) $X \xleftarrow{\iota_X} I \xrightarrow{\iota_Y} Y$ belongs to R ;

(b) if $X \xleftarrow{f} P \xrightarrow{g} Y$ belongs to R then for every morphism $p : P \rightarrow Q$ in \mathcal{P} and every $f' : Q \rightarrow X$ such that $f' \circ p = f$ then there exists $g' : Q \rightarrow Y$ such that $g' \circ p = g$ and $X \xleftarrow{f'} Q \xrightarrow{g'} Y$ belongs to R ;

$$\begin{array}{ccccc} & & f & & g \\ & X & \xleftarrow{\quad} & P & \xrightarrow{\quad} Y \\ & \swarrow & p & \downarrow & \searrow \\ f' & & Q & & g' \end{array}$$

(c) symmetrically;

(d) if $X \xleftarrow{f} P \xrightarrow{g} Y$ belongs to R and if we have a morphism $p : Q \rightarrow P \in \mathcal{P}$ then $X \xleftarrow{f \circ p} Q \xrightarrow{g \circ p} Y$ belongs to R .

(Strong) path bisimulation [J., N., W.]

When R satisfies (a–c) (resp. (a–d)), we say that it is a **path-bisimulation** (resp. **strong path-bisimulation**).

Facts

To make real sense, \mathcal{P} is needed to be small. In this case:

- \mathcal{P} -bisimilarity \Rightarrow strong path-bisimilarity \Rightarrow path-bisimilarity [J., N., W.].
- In many cases, \mathcal{P} -bisimilarity is equivalent to strong path-bisimilarity. There is a general framework (\mathcal{P} -accessible categories) where it is the case [D., Goubault, Goubault].
- A Hennessy-Milner-like theorem holds for both (strong) path-bisimilarities [J., N., W.].

Bisimilarity of diagrams, via open maps

Category of diagrams

A **diagram** in a category \mathcal{A} is a functor F from any small category \mathcal{C} to \mathcal{A}

My view:

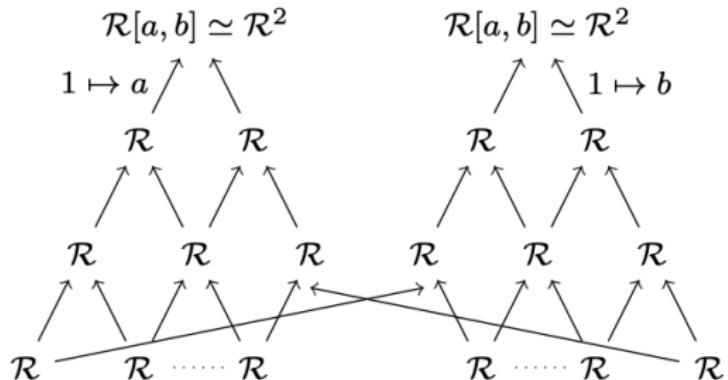
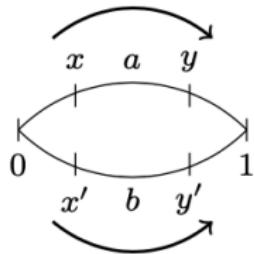
- \mathcal{C} = category of runs,
- \mathcal{A} = category of values (ex: words),
- F = describe the data of each run and how those data evolve (ex: labelling).

A **morphism of diagrams** from $F : \mathcal{C} \rightarrow \mathcal{A}$ to $G : \mathcal{D} \rightarrow \mathcal{A}$ is a pair (Φ, σ) of:

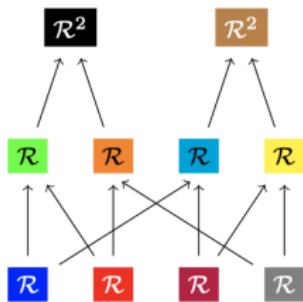
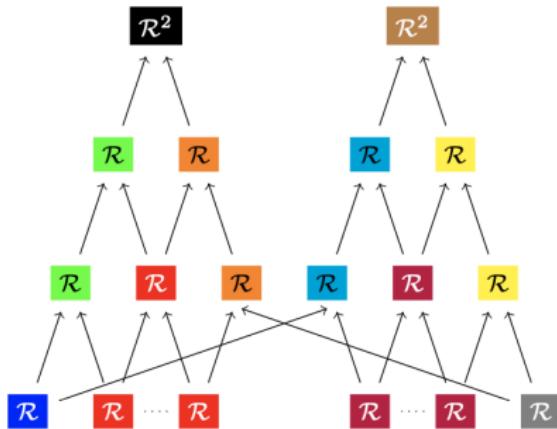
- a functor $\Phi : \mathcal{C} \rightarrow \mathcal{D}$,
- a natural *isomorphism* $\sigma : F \Rightarrow G \circ \Phi$.

We note **Diag(\mathcal{A})** this category.

Where is it from?



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Example : TS VI - from TS to diagrams

T a TS on Σ .

- \mathcal{C}_T = poset of runs, with the prefix order,
- \mathcal{A} = poset Σ^* , with the prefix order,
- F_T = maps a run on its labelling.

From small categorical model to diagrams

\mathcal{M} a categorical model, with a small subcategory \mathcal{P}

X object of \mathcal{M} .

- $\mathcal{C}_X = \mathcal{P} \downarrow X$, whose objects are morphisms in \mathcal{M} from an object of \mathcal{P} to X ,
- $\mathcal{A} = \mathcal{P}$,
- F_X = projection on the domain of the morphism.

Remarks:

- This defines a functor Π from \mathcal{M} to $\mathbf{Diag}(\mathcal{P})$.
- When \mathcal{M} is cocomplete, the colimit functor Γ from $\mathbf{Diag}(\mathcal{P})$ to \mathcal{M} is the left adjoint of Π and $\Gamma \circ \Pi$ is the unfolding.
- The counit $\epsilon_X : \Gamma \circ \Pi(X) \longrightarrow X$ is an open morphisms in many cases.

Lifting properties and open morphisms (in $\text{Diag}(\mathcal{A})$)

f has the **right lifting property** with respect to g iff

$$\begin{array}{ccc} P & \xrightarrow{x} & X \\ g \downarrow & \exists \theta \nearrow & \downarrow f \\ Q & \xrightarrow{y} & Y \end{array}$$

A morphism of **diagrams** is **open** if it has the right lifting property with respect to every **branch extension** ($n \geq 0$):

$$\begin{array}{ccccccc} A_1 & \xrightarrow{f_1} & A_2 & \cdots & A_{n-1} & \xrightarrow{f_n} & A_n \\ id \downarrow & id \downarrow & id \downarrow & & id \downarrow & & id \downarrow \\ A_1 & \xrightarrow{f_1} & A_2 & \cdots & A_{n-1} & \xrightarrow{f_n} & A_n \xrightarrow{f_{n+1}} A_{n+1} \cdots A_{n+p-1} \xrightarrow{f_{n+p}} A_{n+p} \end{array}$$

Definition:

Two **diagrams** are bisimilar iff there is a span of open morphisms between them.

Open maps of systems vs. open maps of diagrams

Remember the adjunction:

$$\Gamma : \mathbf{Diag}(\mathcal{P}) \longrightarrow \mathcal{M}$$

$$\begin{array}{c} \perp \\ \Pi : \mathcal{M} \longrightarrow \mathbf{Diag}(\mathcal{P}) \end{array}$$

Proposition [D.]:

If $f : X \longrightarrow Y$ is an open morphism of systems, then $\Pi(f) : \Pi(X) \longrightarrow \Pi(Y)$ is an open morphism of diagrams. In particular, if X and Y are bisimilar, then $\Pi(X)$ and $\Pi(Y)$ are bisimilar.

The converse is not true in general.

For example, that is not true in general that if $\Pi(X) \xleftarrow{\Phi} Z \xrightarrow{\Psi} \Pi(Y)$ is a span of open morphisms then $\Gamma \circ \Pi(X) \xleftarrow{\Gamma(\Phi)} \Gamma(Z) \xrightarrow{\Gamma(\Psi)} \Gamma \circ \Pi(Y)$ is a span of open morphisms.

Bisimilarity of diagrams, via bisimulations

Bisimulation of diagrams

Bisimulation between $F : \mathcal{C} \rightarrow \mathcal{A}$ and $G : \mathcal{D} \rightarrow \mathcal{A}$
= set R of triples (c, η, d) such that :

- c is an object of \mathcal{C} ,
- d is an object of \mathcal{D} ,
- $\eta : F(c) \rightarrow G(d)$ is an isomorphism of \mathcal{A}

satisfying :

- for every object c of \mathcal{C} , there exists d and η such that $(c, \eta, d) \in R$
-

$$(c, \eta, d) \in R$$

$$\begin{array}{ccccc} c & Fc & \xrightarrow{\eta} & Gd & d \\ i \downarrow & Fi \downarrow & & \downarrow Gj & \downarrow j \\ c' & Fc' & \cdots \cdots \cdots \xrightarrow{\eta'} & Gd' & d' \end{array}$$
$$(c', \eta', d') \in R$$

and symmetrically

Bisimilarity and bisimulations

Theorem [D.]:

Two diagrams are bisimilar if and only if there is a bisimulation between them.

Proof sketch:

⇒ Given a span $F \xleftarrow{(\Phi, \sigma)} (H : \mathcal{E} \longrightarrow \mathcal{A}) \xrightarrow{(\Psi, \tau)} G$ of open maps:

$$\{(\Phi(e), \tau_e \circ \sigma_e^{-1}, \Psi(e)) \mid e \in Ob(\mathcal{E})\}$$

⇐ Given a bisimulation R , construct a diagram H :

- ▶ whose domain is R ,
- ▶ which maps (c, η, d) to $F(c)$.

The projections from H to F and G are open.

A word on (un)decidability

Bisimulation = relation + isomorphisms

In a finite case: guess the relation \Rightarrow problem of isomorphisms in \mathcal{A} .

For example, in a vector spaces, we are left with this problem:

Data: a set of equations in matrices of the $X.A = B.Y$

Question: are there invertible matrices X, Y, \dots that satisfy the equations ?

A word on (un)decidability

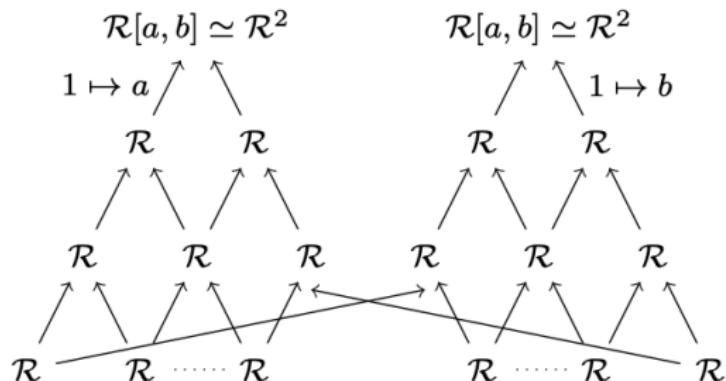
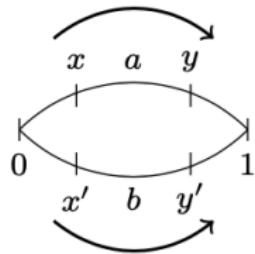
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Question: are there invertible matrices X, Y, \dots that satisfy the equations ?

Proposition [D.]:

In a finite case, bisimilarity is:

- decidable if \mathcal{A} is finite or **FinSet**,
 - ▶ a finite number of possible solutions
- undecidable if $\mathcal{A} = \text{category of finitely presented groups} + \text{group morphisms}$,
 - ▶ isomorphism is undecidable
- decidable if $\mathcal{A} = \text{category of finite dimensional real (rational) vector spaces}$,
 - ▶ can be reduced to polynomial equations in reals
- open if $\mathcal{A} = \text{category of Abelian groups of finite type}$.

Bisimulations of systems vs. bisimulations of diagrams

Remember the adjunction, again:

$$\Gamma : \mathbf{Diag}(\mathcal{P}) \longrightarrow \mathcal{M}$$

$$\perp$$
$$\Pi : \mathcal{M} \longrightarrow \mathbf{Diag}(\mathcal{P})$$

Proposition [D.]:

Bisimulations of diagrams between $\Pi(X)$ and $\Pi(Y)$ are precisely path-bisimulations between X and Y .

Corollary:

$\Pi(X)$ and $\Pi(Y)$ are bisimilar iff X and Y are path-bisimilar.

Remarks:

- This explains why open in systems \neq open in diagrams.
- For transition systems, this implies that two systems are bisimilar iff the diagrams are bisimilar.

What about strong path-bisimulations ?

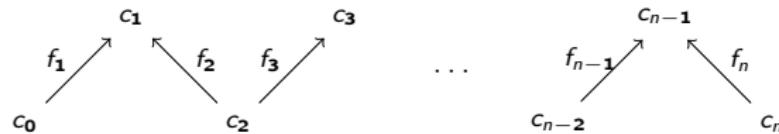
What is missing ?

Being able to reverse paths.

Solution: just add reverse of paths !

Given a category \mathcal{C} , define $\overline{\mathcal{C}}$ as the category generated by $\mathcal{C} \cup \mathcal{C}^{op}$, i.e.:

- objects are those of \mathcal{C} ,
- morphisms are zigzags of morphisms of \mathcal{C}



A functor $F : \mathcal{C} \rightarrow \mathcal{A}$ induces a functor $\overline{F} : \overline{\mathcal{C}} \rightarrow \overline{\mathcal{A}}$ and this extends to a functor $\Delta : \mathbf{Diag}(\mathcal{A}) \rightarrow \mathbf{Diag}(\overline{\mathcal{A}})$.

Instead of looking at $\Pi(X)$, we look at $\Delta \circ \Pi(X)$.

Bisimulations of systems vs. bisimulations of diagrams II

We still have a adjunction:

$$\begin{array}{c} \Gamma' : \mathbf{Diag}(\overline{\mathcal{P}}) \longrightarrow \mathcal{M} \\ \perp \\ \Delta \circ \Pi : \mathcal{M} \longrightarrow \mathbf{Diag}(\overline{\mathcal{P}}) \end{array}$$

Proposition [D.]:

Bisimulations of diagrams between $\Delta \circ \Pi(X)$ and $\Delta \circ \Pi(Y)$ are precisely strong path-bisimulations between X and Y .

Corollary:

$\Delta \circ \Pi(X)$ and $\Delta \circ \Pi(Y)$ are bisimilar iff X and Y are strong path-bisimilar.

Remarks:

- In many cases, $\Delta \circ \Pi(X)$ and $\Delta \circ \Pi(Y)$ are bisimilar iff X and Y are \mathcal{P} -bisimilar.
- In the \mathcal{P} -accessible case, Γ' maps open maps to open maps.

Conclusion

Conclusion

We have a theory of bisimilarity of diagrams:

- defined using open maps,
- equivalent characterization using bisimulations,
- decidability is essentially a problem of isomorphism in the category of values,
- models (strong) path-bisimilarities,
- useful in directed algebraic topology (not too much in this talk),
- admits a Hennessy-Milner-like theorem (not in this talk).

What is left (*inter alia*):

- open morphisms acts like trivial fibrations. Can we make that explicit ?
- (un)decidability in the case of Abelian groups.
- relation between our decision procedure to usual ones.