

11.2 The Restricted Three-Body Problem (Earth-Moon-Spaceship Problem)

Assumptions

- Two masses are of finite size and move in coplanar circular orbits about the center of mass of the system.
- The third mass is of infinitesimal size.

$$\text{Define } \mu = \frac{m_2}{m_1 + m_2}$$

If $m_2 \leq m_1$, then $\mu \leq \frac{1}{2}$

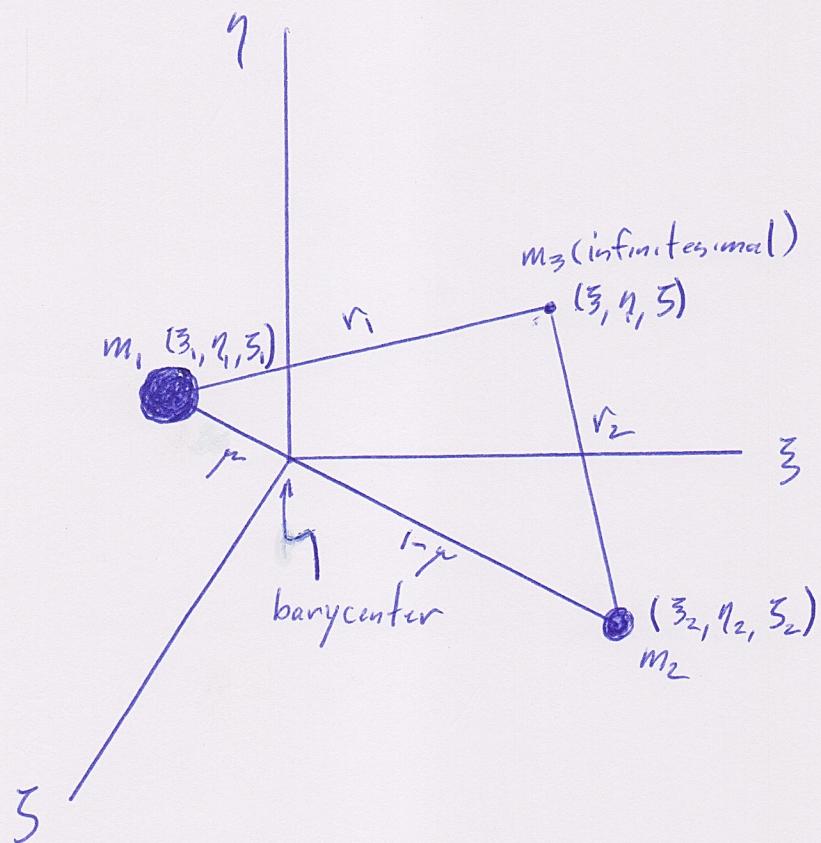
Non-dimensionalize distances by d (distance between m_1 and m_2)

Non-dimensionalize time t by $\left[\frac{d^3}{G(m_1 + m_2)} \right]^{1/2}$

The dimensionless angular velocity about the centre of mass is $\frac{d\theta}{dt} = 1$.

Coordinates of m_1 are (ξ_1, η_1, ζ_1)
 Coordinates of m_2 are (ξ_2, η_2, ζ_2)
 Coordinates of m_3 are (ξ, η, ζ)

} measured from
non-rotating coordinate
system at center of
mass.



The equations of motion of m_3 are

$$\ddot{\xi} = (1-\mu) \frac{\ddot{\xi}_1 - \ddot{\xi}}{r_1^3} + \mu \frac{\ddot{\xi}_2 - \ddot{\xi}}{r_2^3} \quad (11.26a)$$

$$\ddot{\eta} = (1-\mu) \frac{\ddot{\eta}_1 - \ddot{\eta}}{r_1^3} + \mu \frac{\ddot{\eta}_2 - \ddot{\eta}}{r_2^3} \quad (11.26b)$$

$$\ddot{\zeta} = (1-\mu) \frac{\ddot{\zeta}_1 - \ddot{\zeta}}{r_1^3} + \mu \frac{\ddot{\zeta}_2 - \ddot{\zeta}}{r_2^3} \quad (11.26c)$$

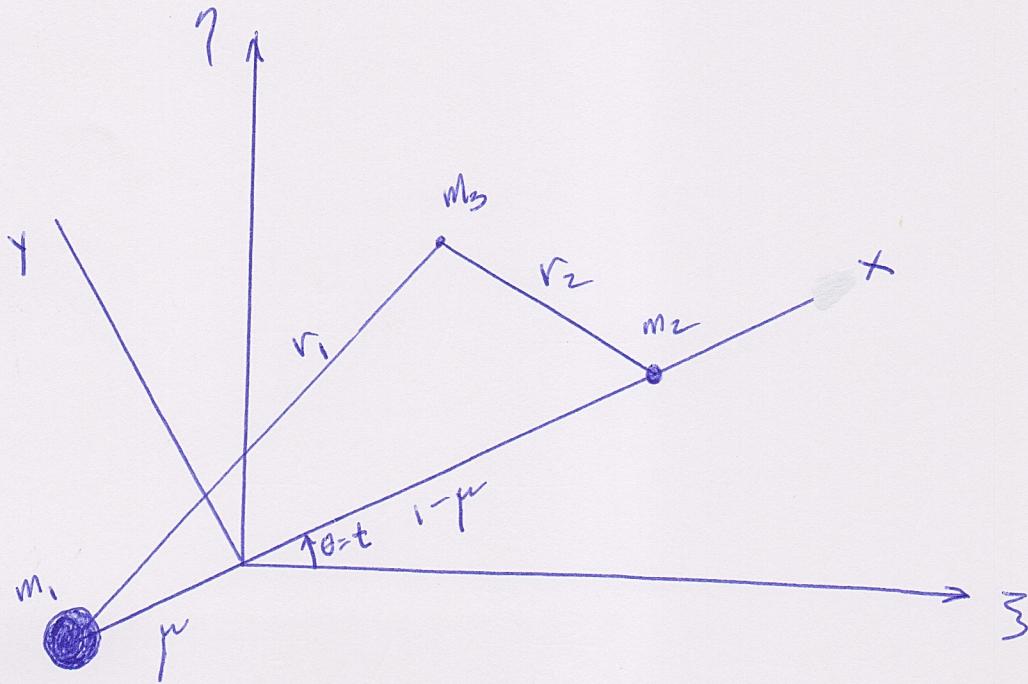
where

$$r_1^2 = (\xi_1 - \bar{\xi})^2 + (\eta_1 - \bar{\eta})^2 + (\zeta_1 - \bar{\zeta})^2$$

$$r_2^2 = (\xi_2 - \bar{\xi})^2 + (\eta_2 - \bar{\eta})^2 + (\zeta_2 - \bar{\zeta})^2$$

Without loss of generality, let the ζ -axis be perpendicular to the plane of rotation of the two massive particles so that $\xi_1 = \xi_2 = 0$

Introduce a rotating coordinate system (x, y, z) having origin at the barycenter with the z -axis coinciding with the ζ -axis (perpendicular to the plane of the paper).



In the rotating frame

Coordinates of m_1 are $(x_1, 0, 0)$

Coordinates of m_2 are $(x_2, 0, 0)$

Coordinates of m_3 are (x, y, z)

$$x_1 = -\mu \quad x_2 = 1 - \mu$$

$$\text{and } x_2 - x_1 = 1.$$

Can write

$$r_1^2 = (x_1 - x)^2 + y^2 + z^2$$

$$r_2^2 = (x_2 - x)^2 + y^2 + z^2$$

Coordinate transformation

$$\left. \begin{array}{l} \xi = x \cos t - y \sin t \\ \eta = x \sin t + y \cos t \\ \zeta = z \end{array} \right\} \quad (11.27)$$

Differentiate (11.27) twice and sub. into (11.26)

$$(\ddot{x} - z\dot{y} - x) \cos t - (\ddot{y} + z\dot{x} - y) \sin t =$$

$$\left[(1-\mu) \frac{x_1 - x}{r_1^3} + \mu \frac{x_2 - x}{r_2^3} \right] \cos t + \left[\frac{1-\mu}{r_1^3} + \frac{\mu}{r_2^3} \right] y \sin t \quad (11.28a)$$

$$(\ddot{x} - z\dot{y} - x) \sin t + (\ddot{y} + z\dot{x} - y) \cos t =$$

$$\left[(1-\mu) \frac{x_1 - x}{r_1^3} + \mu \frac{x_2 - x}{r_2^3} \right] \sin t - \left[\frac{1-\mu}{r_1^3} + \frac{\mu}{r_2^3} \right] y \cos t \quad (11.28b)$$

$$\ddot{z} = - \left[\frac{1-\mu}{r_1^3} + \frac{\mu}{r_2^3} \right] z \quad (11.28c)$$

Mult. (11.28a) by $\cos t$, (11.28b) by $\sin t$ and add,
then mult. (11.28a) by $-\sin t$, (11.28b) by $\cos t$ and add

$$\left. \begin{aligned} \ddot{x} - z\dot{y} - x &= - \left((1-\mu) \frac{x-x_1}{r_1^3} - \mu \frac{x-x_2}{r_2^3} \right) \\ \ddot{y} + z\dot{x} - y &= - \left(\frac{1-\mu}{r_1^3} + \frac{\mu}{r_2^3} \right) y \\ \ddot{z} &= - \left(\frac{1-\mu}{r_1^3} + \frac{\mu}{r_2^3} \right) z \end{aligned} \right\} \quad (11.29)$$

Eqs. (11.29) are the equations of motion of the infinitesimal body m_3 with respect to the rotating coordinates.

$$\text{Define } U = \frac{1}{2}(x^2 + y^2) + \frac{1-\mu}{r_1} + \frac{\mu}{r_2}$$

Eqs. (11.29) may be written as

$$\ddot{x} - z\dot{y} = \frac{\partial U}{\partial x} \quad (11.30a)$$

$$\ddot{y} + z\dot{x} = \frac{\partial U}{\partial y} \quad (11.30b)$$

$$\ddot{z} = \frac{\partial U}{\partial z} \quad (11.30c)$$

Mult. (11.30a) by \dot{x} , (11.30b) by \dot{y} , (11.30c) by \dot{z}
and add

$$\ddot{x}\dot{x} + \ddot{y}\dot{y} + \ddot{z}\dot{z} = \frac{\partial U}{\partial x}\dot{x} + \frac{\partial U}{\partial y}\dot{y} + \frac{\partial U}{\partial z}\dot{z}$$

which is an exact differential since U depends only on x, y, z .

Integrating

$$\dot{x}^2 + \dot{y}^2 + \dot{z}^2 = 2U - C \quad (11.31)$$

where C is a constant of integration called
Jacobi's constant

or

$$V^2 = 2U - C \quad (11.32)$$

where V is the velocity of the infinitesimal mass m_3
in the rotating frame.

or

$$V^2 = x^2 + y^2 + \frac{2(1-\mu)}{\nu_1} + \frac{2\mu}{\nu_2} - C \quad (11.33)$$

Jacobi's constant C is determined from initial
conditions.

For zero particle velocity in the rotating frame,
set $V=0$ in (11.32)

$$2U = C$$

or

$$x^2 + y^2 + \frac{2(1-\mu)}{v_1} + \frac{2\mu}{v_2} = C \quad (11.34)$$

For a given value of C , (11.34) defines the boundaries of regions in which the particle m_3 must be found.

In these regions, require $2U > C$ otherwise $V^2 < 0$
 $\Rightarrow V$ is imaginary (see eq. (11.32))

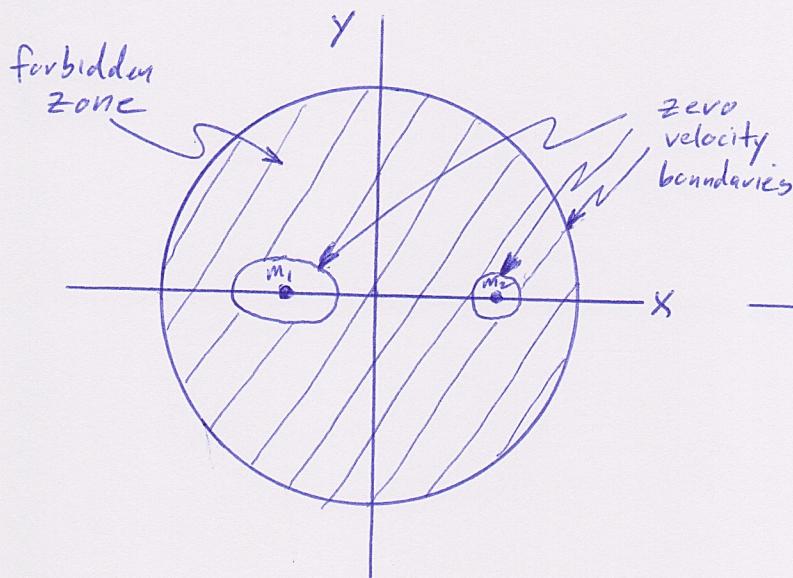
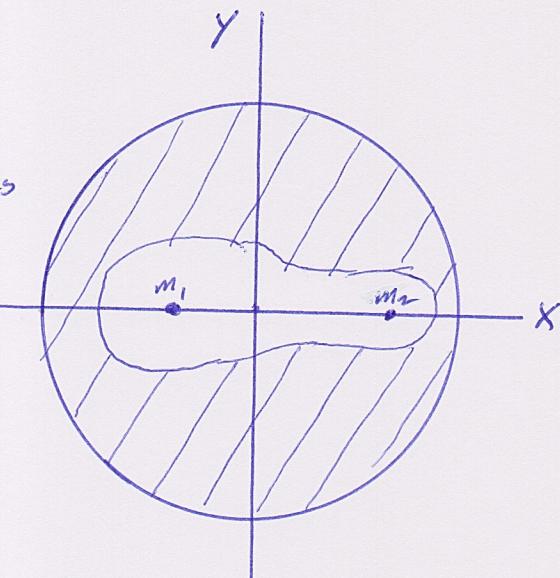
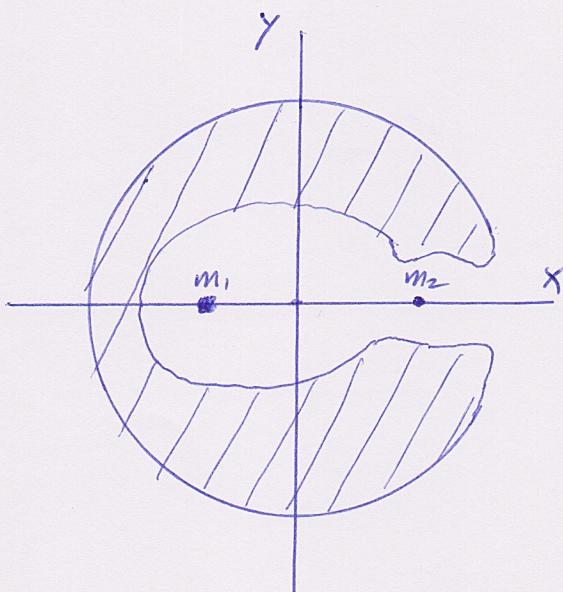
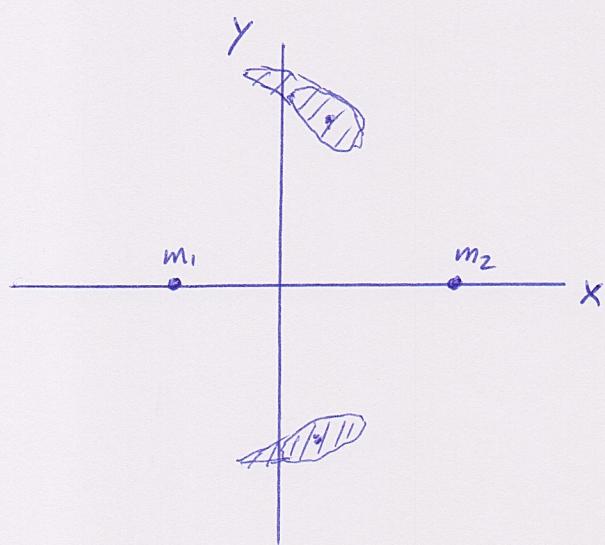
Suppose both C and $x^2 + y^2$ are large.

Then from (11.34) $x^2 + y^2 \sim C_1$

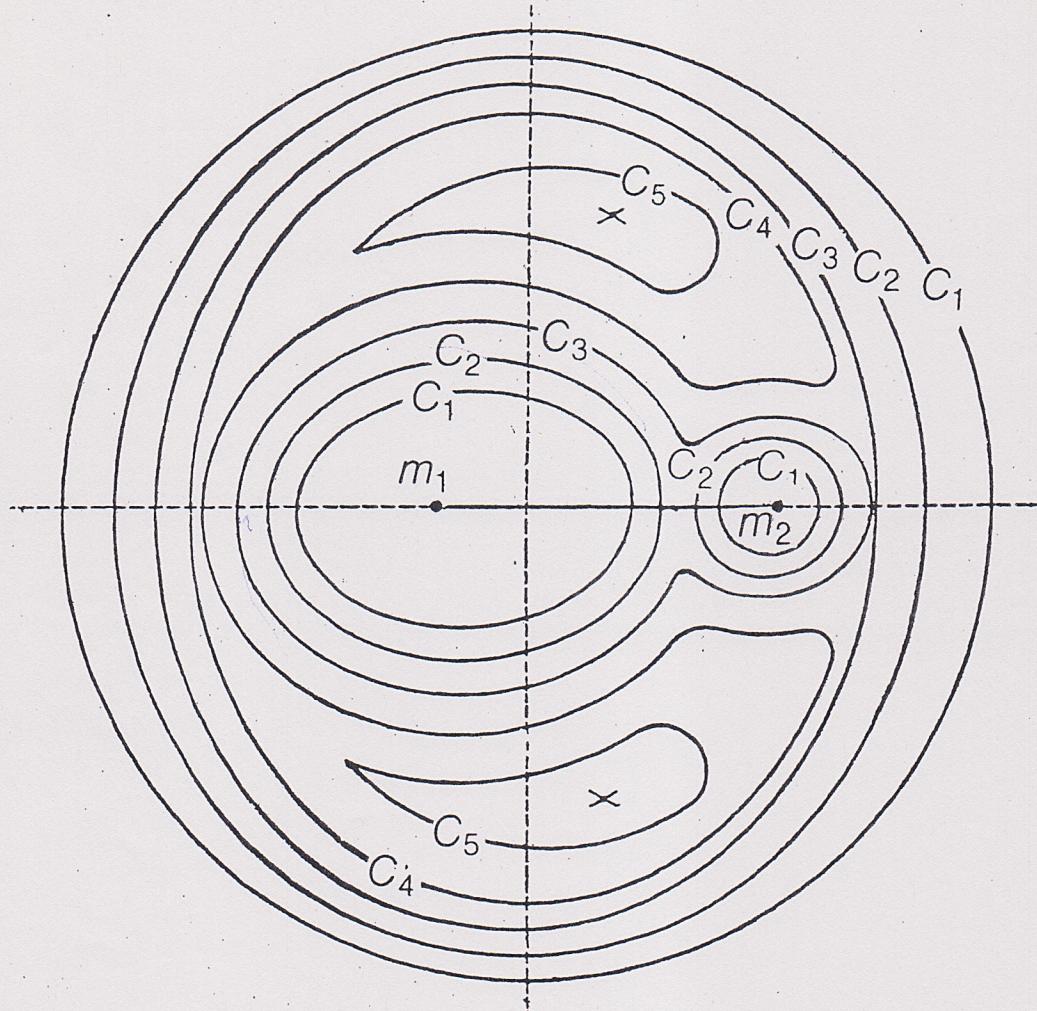
The region outside this circle is accessible.

If C is large and v_1 or v_2 are small

Then oval regions enclosing m_1 and m_2 are also accessible

C₁C₃C₄C₅

The Restricted Problem of Three Bodies
Contours of zero relative velocity in the plane $z=0$
 $(m_1 > m_2) \quad (m_3 \ll m_1 + m_2) \quad (C_1 > C_2 > C_3 > C_4 > C_5)$



Determination of the Location of the Lagrange Points

For stationary configurations, relative velocity and relative acceleration must be zero. From eq. (11.30) this requires

$$\frac{\partial V}{\partial x} = 0$$

$$\frac{\partial V}{\partial y} = 0$$

$$\frac{\partial V}{\partial z} = 0$$

$$V = \frac{1}{2}(x^2 + y^2) + \frac{1-\mu}{r_1} + \frac{\mu}{r_2}$$

$$\frac{\partial V}{\partial x} = x - \frac{1-\mu}{r_1^2} \frac{\partial r_1}{\partial x} - \frac{\mu}{r_2^2} \frac{\partial r_2}{\partial x}$$

$$\frac{\partial V}{\partial y} = y - \frac{1-\mu}{r_1^2} \frac{\partial r_1}{\partial y} - \frac{\mu}{r_2^2} \frac{\partial r_2}{\partial y}$$

$$\frac{\partial V}{\partial z} = -\frac{1-\mu}{r_1^2} \frac{\partial r_1}{\partial z} - \frac{\mu}{r_2^2} \frac{\partial r_2}{\partial z}$$

$$r_1^2 = (x_1 - x)^2 + y^2 + z^2 = (x + \mu)^2 + y^2 + z^2$$

$$r_2^2 = (x_2 - x)^2 + y^2 + z^2 = (x + \mu - 1)^2 + y^2 + z^2$$

$$\frac{\partial v_1}{\partial x} = \frac{x + \mu}{v_1}$$

$$\frac{\partial v_2}{\partial x} = \frac{x + \mu - 1}{v_2}$$

$$\frac{\partial v_1}{\partial y} = \frac{y}{v_1}$$

$$\frac{\partial v_2}{\partial y} = \frac{y}{v_2}$$

$$\frac{\partial v_1}{\partial z} = \frac{z}{v_1}$$

$$\frac{\partial v_2}{\partial z} = \frac{z}{v_2}$$

$$x - \frac{(1-\mu)}{v_1^3} (x + \mu) - \frac{\mu}{v_2^3} (x + \mu - 1) = 0 \quad]$$

$$y - \frac{(1-\mu)}{v_1^3} y - \frac{\mu}{v_2^3} y = 0 \quad \left. \right\} (11.35)$$

$$- \frac{(1-\mu)}{v_1^3} z - \frac{\mu}{v_2^3} z = 0$$

The solution of (11.35) gives the location of the Lagrange points.

For L_1, L_2, L_3 , set $y = z = 0$ in (11.35)

$$x - \frac{(1-\mu)}{r_1^3} (x+\mu) - \frac{\mu}{r_2^3} (x+\mu-1) = 0 \quad (11.36)$$

where $r_1 = |x+\mu| \quad r_2 = |x+\mu-1|$

The roots of (11.36) give the location of L_1, L_2, L_3 .

For L_4, L_5 , setting $z=0$ in (11.35) shows

$$r_1 = r_2 = 1$$

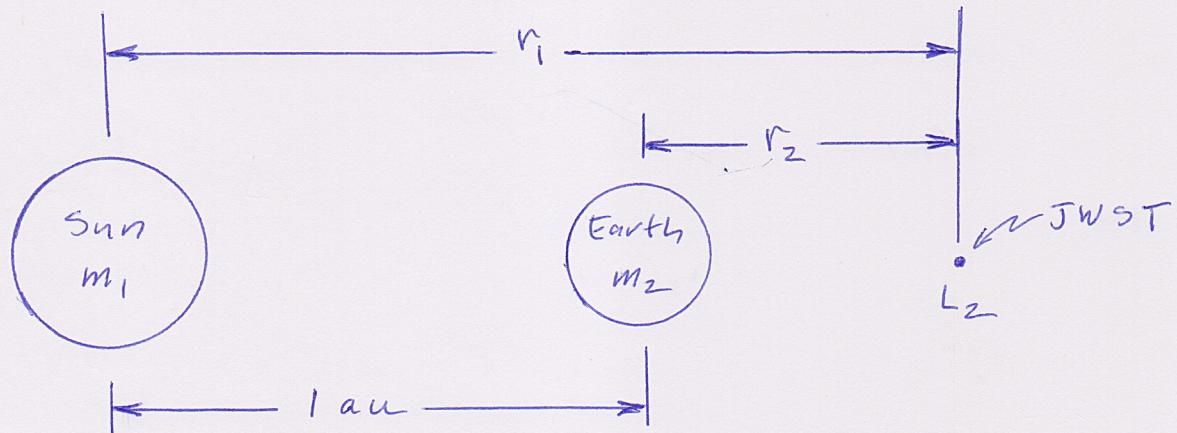
is a solution resulting in the equilateral triangle configuration.

EXAMPLE

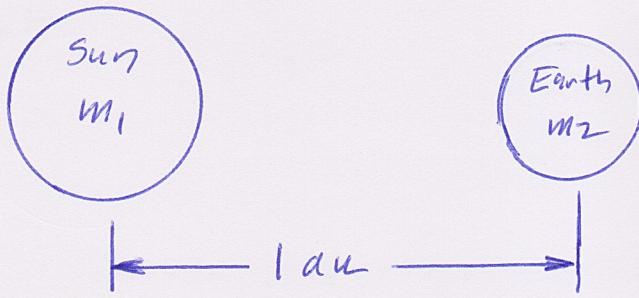
In 2021, the James Webb Space Telescope is scheduled to be launched and positioned at the earth-sun L_2 Lagrangian point, about 1.50×10^6 km from earth. (The moon's distance from the earth is 3.844×10^5 km) ($\sim 4x$)

- a) Calculate the distance from the center of the sun in an of the earth-sun barycenter.

- b) Determine the value of Jacobi's constant needed to reach L_2 with zero relative velocity.
- c) Determine the minimum burnout velocity of the Ariane 5 launch vehicle at an altitude of 300 km required for the JWST to reach L_2 .
- d) Compare the value of velocity obtained in part (c) with the burnout velocity required for a spacecraft to (i) escape the earth and (ii) escape the solar system.



a)



$$\mu = \frac{m_2}{m_1 + m_2} = \frac{5.974 \times 10^{24}}{1.989 \times 10^{30} + 5.974 \times 10^{24}} = 0.00000300351$$

Origin at center of sun

$$v_{cm} = \frac{\sum m_i v_i}{\sum m_i} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2} = \frac{m_1(0) + m_2(1)}{m_1 + m_2} = \mu$$

$$v_{cm} = 0.0000030051 \text{ au}$$

Sun's radius

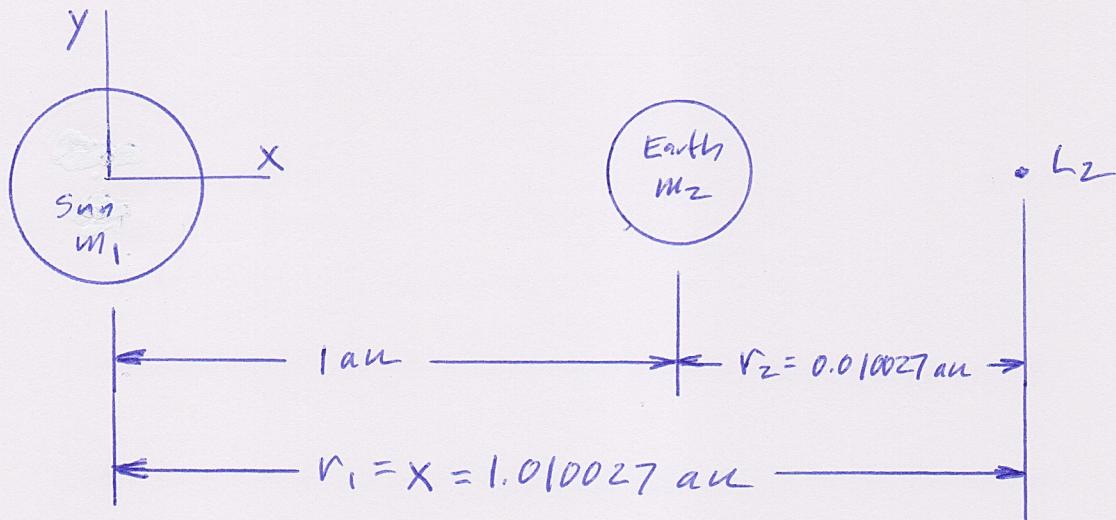
$$r_{sun} = \frac{6.9599 \times 10^5 \text{ km}}{1.495978 \times 10^8 \frac{\text{km}}{\text{au}}} = 0.004652 \text{ au}$$

$$\frac{v_{cm}}{r_{sun}} = \frac{0.0000030051}{0.004652} = 0.000646$$

b) From (11.34) for $V=0$ at L_2

$$C = x^2 + y^2 + \frac{2(1-\mu)}{v_1} + \frac{2\mu}{v_2}$$

$$\text{Distance of } L_2 \text{ from earth} = \frac{1.50 \times 10^6 \text{ km}}{1.495978 \times 10^8 \frac{\text{km}}{\text{au}}} = 0.010027 \text{ au}$$



Origin at barycenter (center of sun)

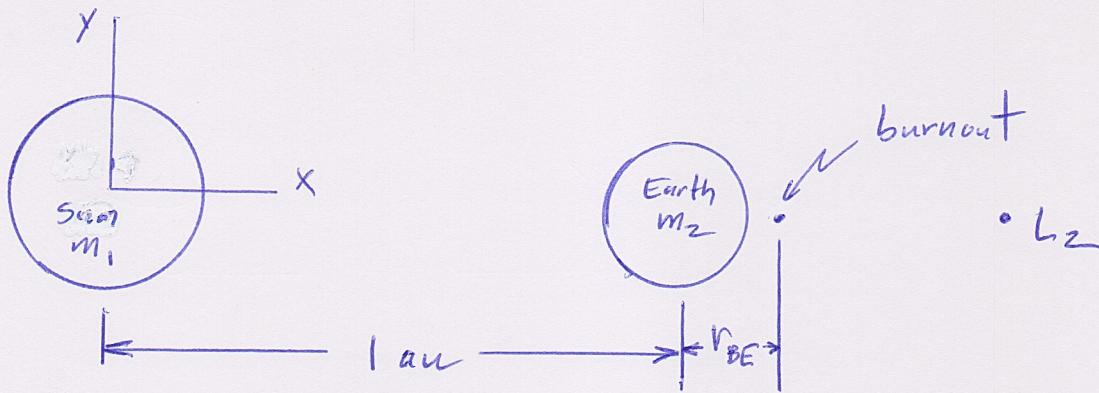
$$C = x^2 + y^2 + \frac{z(1-\mu)}{r_1} + \frac{z\mu}{r_2}$$

$$= (1.010027)^2 + (0)^2 + \frac{z(1 - 3.00351 \times 10^{-6})}{1.010027} + \frac{z(3.00351 \times 10^{-6})}{0.010027}$$

$$C = \underline{\underline{3.00089}}$$

c) Distance of burnout from earth

$$v_{BE} = \frac{6368 + 300}{1.495978 \times 10^8} = 4.65782 \times 10^{-5} \text{ au}$$



At burnout

$$X = 1 + r_{BE} = 1 + 4.65782 \times 10^{-5} = 1$$

$$Y = 0$$

$$r_1 = 1 + r_{BE} = 1$$

$$r_2 = r_{BE} = 4.65782 \times 10^{-5}$$

Applying (11.33) at burnout

$$V_B^2 = X^2 + Y^2 + \frac{2(1-\mu)}{r_1} + \frac{2\mu}{r_2} - C$$

$$= (1)^2 + 0 + \frac{2(1 - 3.00351 \times 10^{-6})}{1} + \frac{2(3.00351 \times 10^{-6})}{4.65782 \times 10^{-5}}$$

$$- 3.00089$$

$$= 1 + 2 + 0.128966 - 3.00089$$

$$V_B^2 = 0.128076$$

$$V_B = 0.357877 \quad (\text{dimensionless})$$

$$\tau = \left[\frac{d^3}{G(m_1 + m_2)} \right]^{1/2} = \left[\frac{(1.495978 \times 10^8 \text{ km})^3}{1.327 \times 10^{11} \text{ km}^3/\text{sec}^2} \right]^{1/2}$$

$$= 5.02287 \times 10^6 \text{ sec}$$

$$V_B = 0.357877 \left(\frac{1.495978 \times 10^8 \text{ km}}{5.02287 \times 10^6 \text{ sec}} \right)$$

$$V_B = 10.6588 \frac{\text{km}}{\text{sec}}$$

d) i) $V_{\text{esc earth}} = \sqrt{2} \sqrt{\frac{r_e}{V_{BE}}} = \sqrt{2} \sqrt{\frac{3.986 \times 10^5 \text{ km}^3/\text{sec}^2}{6368 + 300 \text{ km}}}$

$$V_{\text{esc earth}} = 10.9097 \frac{\text{km}}{\text{sec}}$$

ii) $V_{\text{esc sun}} = \sqrt{2} \sqrt{\frac{r_{\text{sun}}}{r_c}} = \sqrt{2} \sqrt{\frac{1.327 \times 10^{11} \text{ km}^3/\text{sec}^2}{1.495978 \times 10^8 \text{ km}}}$

$$V_{\text{esc sun}} = 42.12 \frac{\text{km}}{\text{sec}}$$