

AERO-THERMAL FLUIDS LABORATORY – ME43600

**THE CITY COLLEGE OF NEW YORK
DEPARTMENT OF MECHANICAL ENGINEERING
STEINMAN HALL 233
160 CONVENT AVENUE
NEW YORK CITY, NY 10031**

Sep 1, 2023

Course Outline

- Introduction – safety, lab reports, plotting, error analysis, signal processing, lab-specific hardware/software data acquisition, measurement devices, engineering principles
- Laboratory Experiments
 1. Wind Tunnel
 2. Viscous Pipe Flow
 3. Heat Exchanger
 4. Cross-Section Fin
 5. Pelton Wheel
- Design Project Presentation and Report
- Final Exam

Tell them what they will be doing

Then introduce them to the underlying physics

Tell them the instrumentation they will be using

Error Analysis

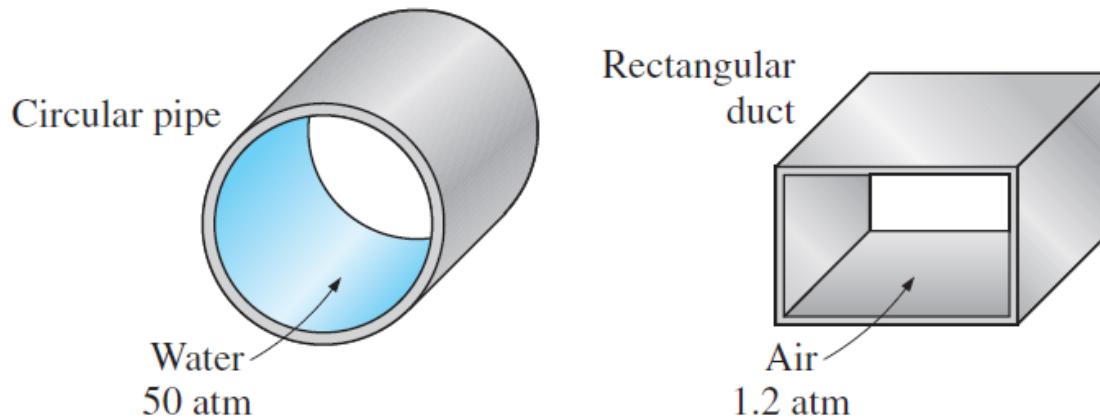
Background- *Internal Flow*

Here we will study the difference between laminar and turbulent flow in pipes, their major differences and analyze fully developed pipe flow.

Calculate head loss in pipe flows and determine pumping power requirements

Background- *Internal Flow*

- Liquid or gas flow through pipes or ducts is commonly used in heating and cooling applications and fluid distribution networks.
- The fluid in such applications is usually **forced to flow by a fan or pump** through a flow section.
- We pay particular attention to **friction, which is directly related to the pressure drop and head loss** during flow through pipes and ducts.
- The pressure drop is then used to determine the pumping power requirement.



Background- Internal Flow

Flow inside pipes are complicated and analytical solutions are only available for simplified flows.

Flow does not vary with x , it only varies in r direction i.e, radially. This type of flow is called as **uniform flow**.

x momentum:

$$\rho \left(\underbrace{\frac{\partial u}{\partial t}}_{\text{Assumption 2}} + \underbrace{u \frac{\partial u}{\partial r}}_{\text{Assumption 3}} + \underbrace{\frac{u_\theta}{r} \frac{\partial u}{\partial \theta}}_{\text{Assumption 6}} + \underbrace{u \frac{\partial u}{\partial x}}_{\text{Continuity}} \right) = - \underbrace{\frac{\partial P}{\partial x}}_{\text{Assumption 5}} + \underbrace{\rho g_x}_{\rho g \sin \alpha} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \underbrace{\frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}}_{\text{Assumption 6}} + \underbrace{\frac{\partial^2 u}{\partial x^2}}_{\text{Continuity}} \right)$$

or

Result of x momentum:

$$\frac{1}{r} \frac{d}{dr} \left(r \frac{du}{dr} \right) = \frac{-\rho g \sin \alpha}{\mu} \quad (3)$$

Background- Internal Flow

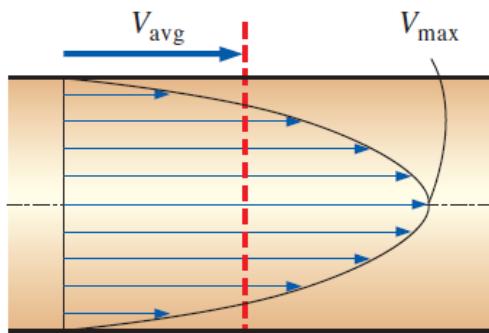
Here, we will rely on experimental and empirical methods to study pipe flows

$$\dot{m} = \rho V_{\text{avg}} A_c = \int_{A_c} \rho u(r) dA_c$$

Mass conservation should still be satisfied

$$V_{\text{avg}} = \frac{\int_{A_c} \rho u(r) dA_c}{\rho A_c} = \frac{\int_0^R \rho u(r) 2\pi r dr}{\rho \pi R^2} = \frac{2}{R^2} \int_0^R u(r) r dr$$

Average velocity

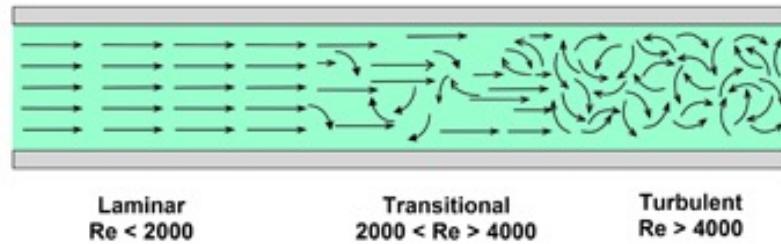


Average velocity V_{avg} is defined as the average speed through a cross section. For fully developed laminar pipe flow, V_{avg} is half of the maximum velocity.

Background- *Internal Flow*

Laminar flow think about **sheets**

Turbulent flows think about **eddies**



Laminar
 $Re < 2000$

Transitional
 $2000 < Re > 4000$

Turbulent
 $Re > 4000$

smooth streamlined flow influenced by viscosity

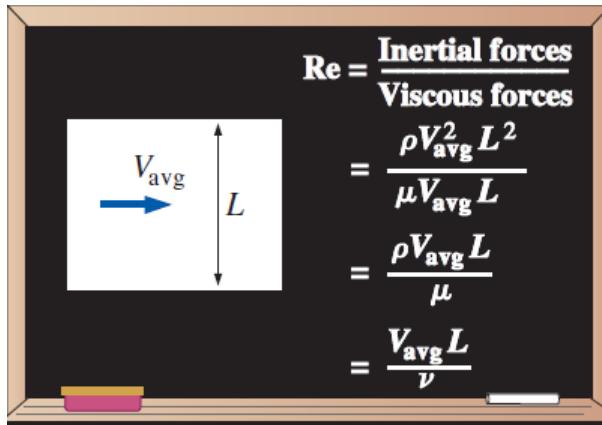
enhanced mixing and chaotic 3 dimensional flow field.

Background- Internal Flow

The transition from laminar to turbulent flow depends on the *geometry, surface roughness, flow velocity, surface temperature, and type of fluid*.

The flow regime depends mainly on the ratio of *inertial forces* to *viscous forces* (**Reynolds number**).

$$Re = \frac{\text{Inertial forces}}{\text{Viscous forces}} = \frac{V_{\text{avg}} D}{\nu} = \frac{\rho V_{\text{avg}} D}{\mu}$$



At large Reynolds numbers, the inertial forces, which are proportional to the fluid density and the square of the fluid velocity, are large relative to the viscous forces, and thus the viscous forces cannot prevent the random and rapid fluctuations of the fluid (**turbulent**).

At small or moderate Reynolds numbers, the viscous forces are large enough to suppress these fluctuations and to keep the fluid “in line” (**laminar**).

Critical Reynolds number, Re_{cr} :

The Reynolds number at which the flow becomes turbulent.

The value of the critical Reynolds number is different for different geometries and flow conditions.

Background- Internal Flow

For flow through noncircular pipes, the Reynolds number is based on the **hydraulic diameter**

$$D_h = \frac{4A_c}{p}$$

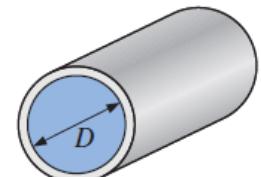
$Re \leq 2300$ laminar flow

$2300 \leq Re \leq 10,000$ transitional flow

$Re \geq 10,000$ turbulent flow

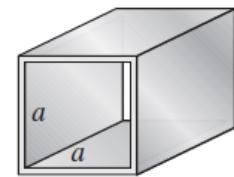
The hydraulic diameter $D_h = 4A_c/p$ is defined such that it reduces to ordinary diameter for circular tubes.

Circular tube:



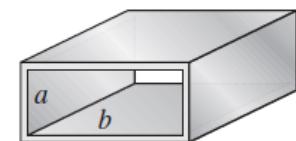
$$D_h = \frac{4(\pi D^2/4)}{\pi D} = D$$

Square duct:



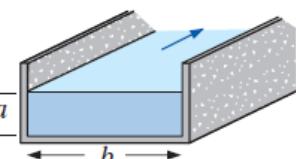
$$D_h = \frac{4a^2}{4a} = a$$

Rectangular duct:



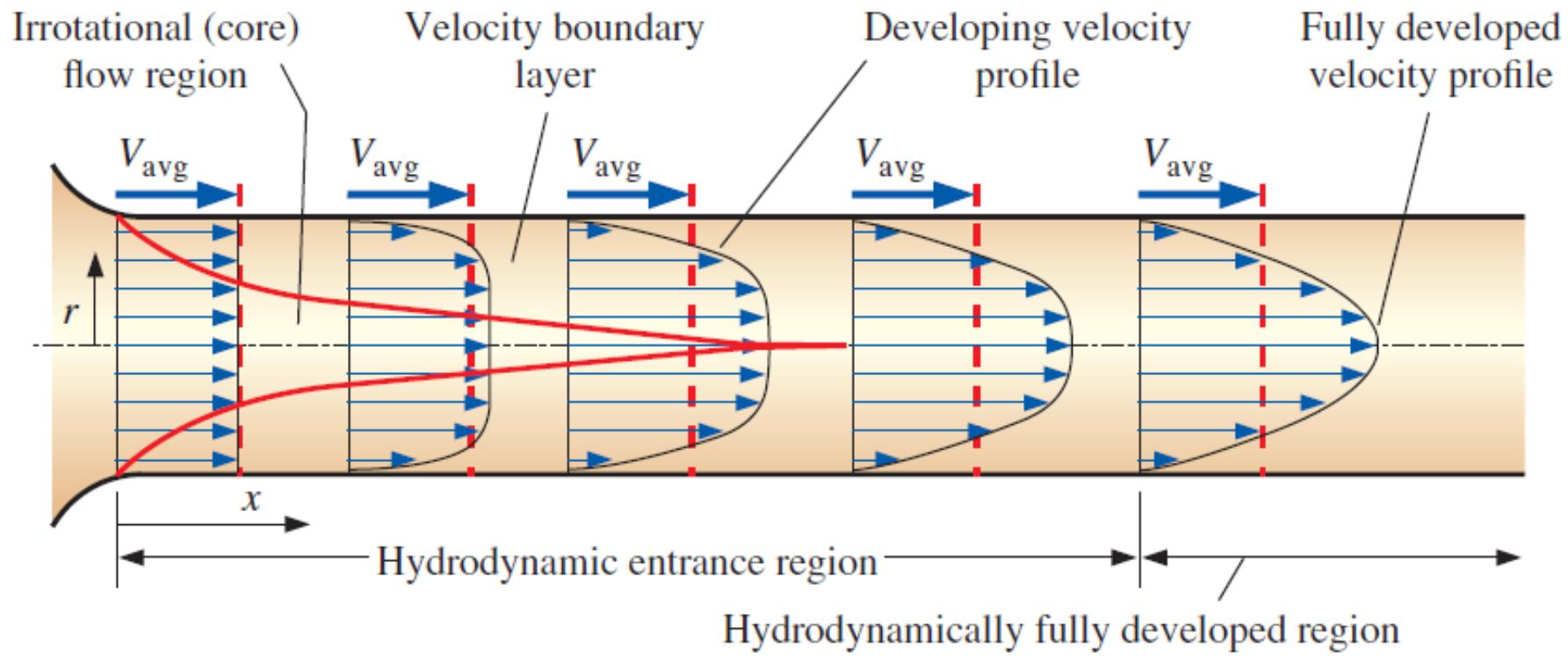
$$D_h = \frac{4ab}{2(a+b)} = \frac{2ab}{a+b}$$

Channel:



$$D_h = \frac{4ab}{2a+b}$$

Entrance Region



Velocity boundary layer: The region of the flow in which the effects of the viscous shearing forces caused by fluid viscosity are felt.

Boundary layer region: The viscous effects and the velocity changes are significant.

Irrational (core) flow region: The frictional effects are negligible and the velocity remains essentially constant in the radial direction.

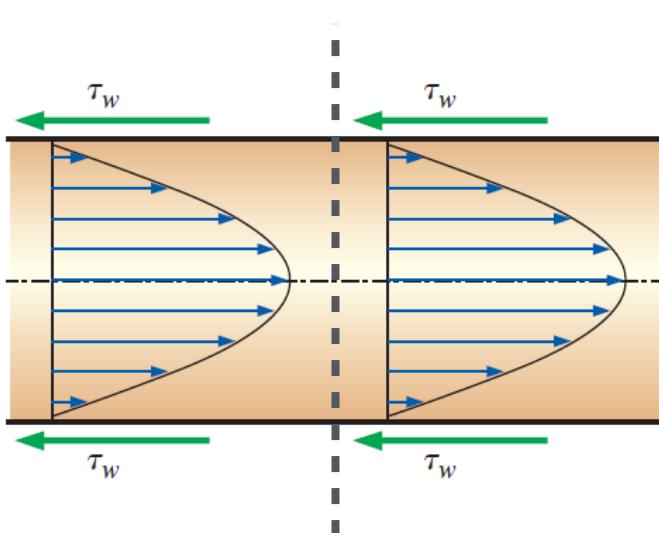
Hydrodynamic entrance region: The region from the pipe inlet to the point at which the boundary layer merges at the centerline.

Hydrodynamic entry length L_h : The length of this region.

Hydrodynamically developing flow: Flow in the entrance region. This is the region where the velocity profile develops.

Hydrodynamically fully developed region: The region beyond the entrance region in which the velocity profile is fully developed and remains unchanged.

Fully developed: When both the velocity profile the normalized temperature profile remain unchanged.

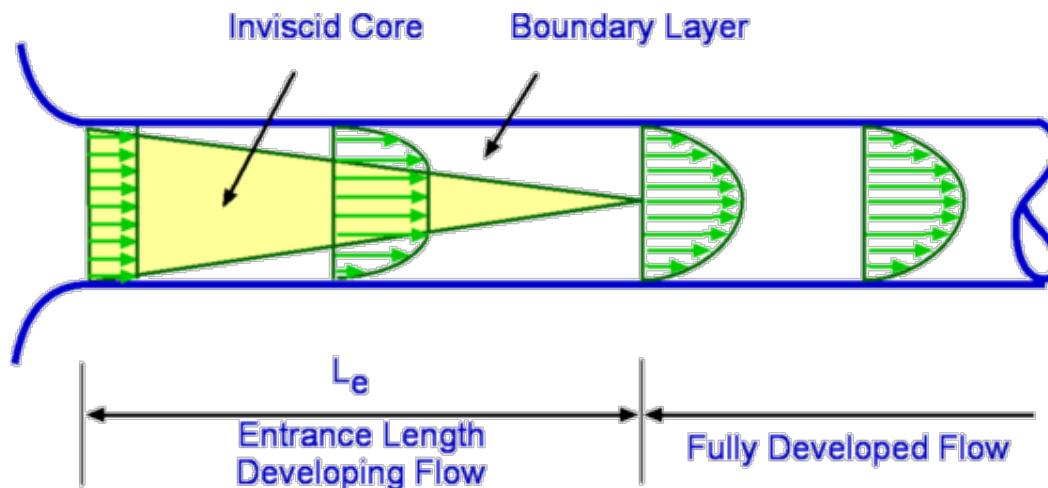


No Change

$$\frac{\partial u(r, x)}{\partial x} = 0 \quad \rightarrow \quad u = u(r)$$

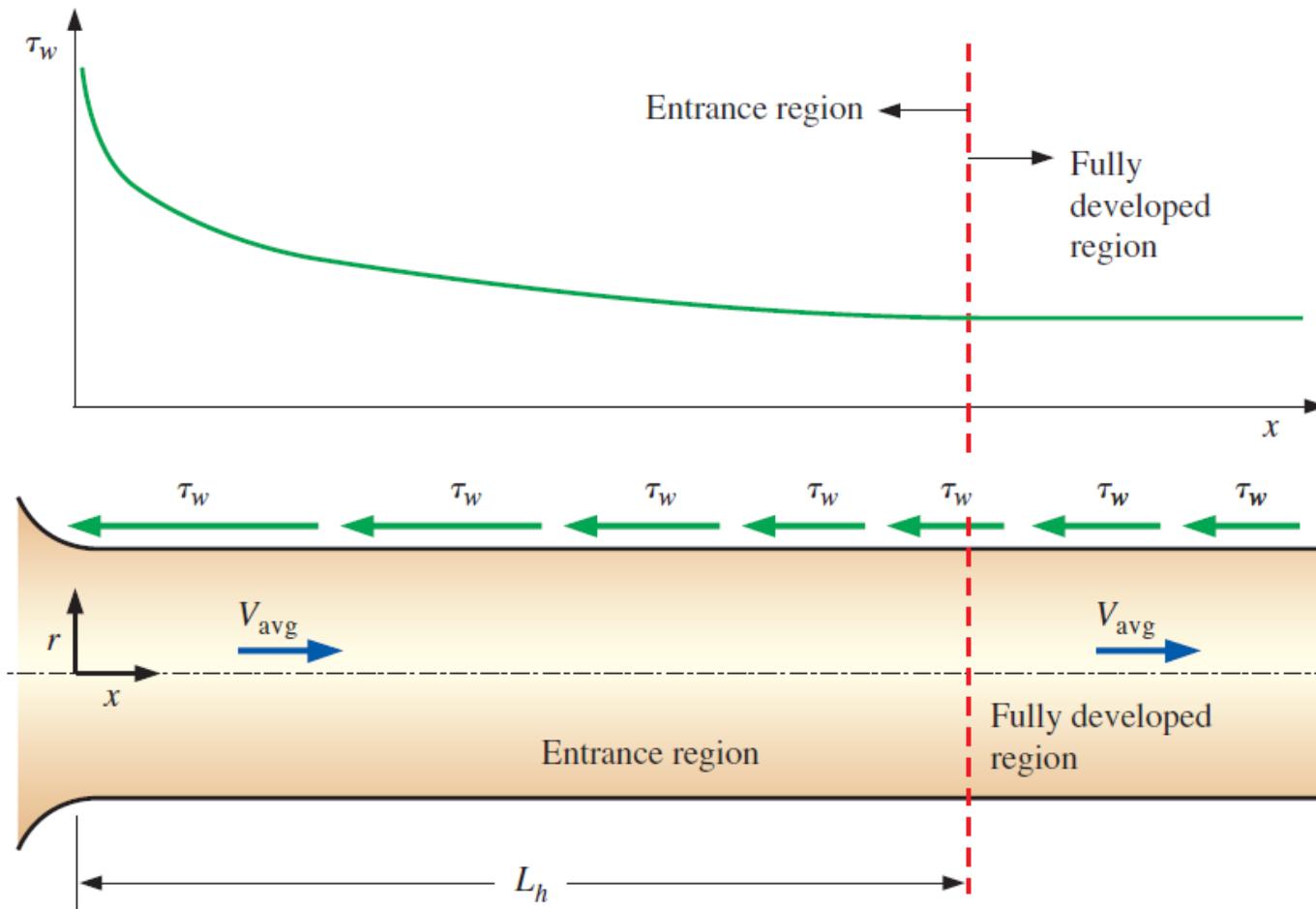
In the fully developed flow region of a pipe, the velocity profile does not change downstream, and thus the wall shear stress remains constant as well.

Evolution of Boundary Layer



"The boundary layer is not a static phenomenon; it is dynamic. It grows meaning that its thickness increases as we move downstream. From Fig. it is seen that the boundary layer from the walls grows to such an extent that they all merge on the centerline of the pipe. Once this takes place, inviscid core terminates and the flow is all viscous. The flow is now called a Fully Developed Flow. The velocity profile becomes parabolic. Once the flow is fully developed the velocity profile does not vary in the flow direction. In fact in this region the pressure gradient and the shear stress in the flow are in balance. The length of the pipe between the start and the point where the fully developed flow begins is called the Entrance Length."

pressure drop is high at the entrance region of the pipe



The boundary layer is not a static phenomenon; it is dynamic. It grows meaning that its thickness increases as we move downstream. From Fig. it is seen that the boundary layer from the walls grows to such an extent that they all merge on the centreline of the pipe. Once this takes place, inviscid core terminates and the flow is all viscous. The flow is now called a Fully Developed Flow. The velocity profile becomes parabolic. Once the flow is fully developed the velocity profile does not vary in the flow direction. In fact in this region the pressure gradient and the shear stress in the flow are in balance. The length of the pipe between the start and the point where the fully developed flow begins is called the Entrance Length.

Entry Length

The hydrodynamic entry length is usually taken to be the distance from the pipe entrance to where the wall shear stress (and thus the friction factor) reaches within about 2 percent of the fully developed value.

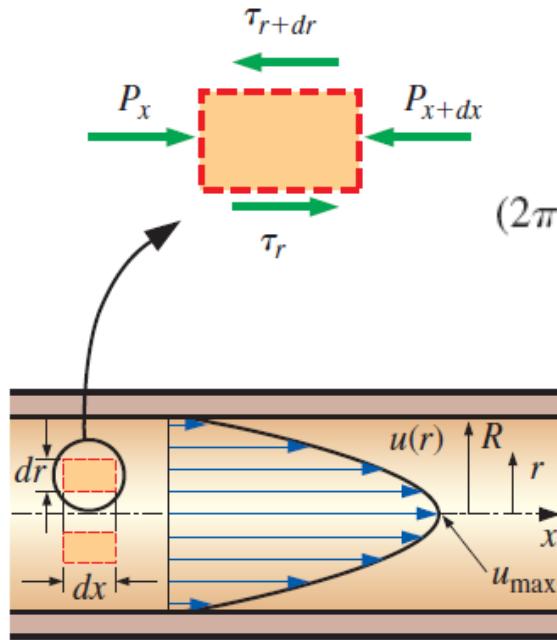
$$\frac{L_{h, \text{laminar}}}{D} \cong 0.05 \text{Re}$$

$$\frac{L_{h, \text{turbulent}}}{D} = 1.359 \text{Re}^{1/4}$$

The pipes used in practice are usually several times the length of the entrance region, and thus the flow through the pipes is often assumed to be fully developed for the entire length of the pipe.

This simplistic approach gives *reasonable* results for long pipes but sometimes poor results for short ones since it underpredicts the wall shear stress and thus the friction factor.

Laminar Flow



Method 1

$$(2\pi r dr P)_x - (2\pi r dr P)_{x+dx} + (2\pi r dx \tau)_r - (2\pi r dx \tau)_{r+dr} = 0$$

$$r \frac{P_{x+dx} - P_x}{dx} + \frac{(r\tau)_{r+dr} - (r\tau)_r}{dr} = 0$$

$$r \frac{dP}{dx} + \frac{d(r\tau)}{dr} = 0 \quad \tau = -\mu(du/dr)$$

$$\frac{\mu}{r} \frac{d}{dr} \left(r \frac{du}{dr} \right) = \frac{dP}{dx}$$

$$\rho \left(\underbrace{\frac{\partial u}{\partial t}}_{\text{Assumption 2}} + \underbrace{u \frac{\partial u}{\partial r}}_{\text{Assumption 3}} + \cancel{\underbrace{\frac{u_\theta}{r} \frac{\partial u}{\partial \theta}}_{\text{Assumption 6}}} + \underbrace{u \frac{\partial u}{\partial x}}_{\text{Continuity}} \right)$$

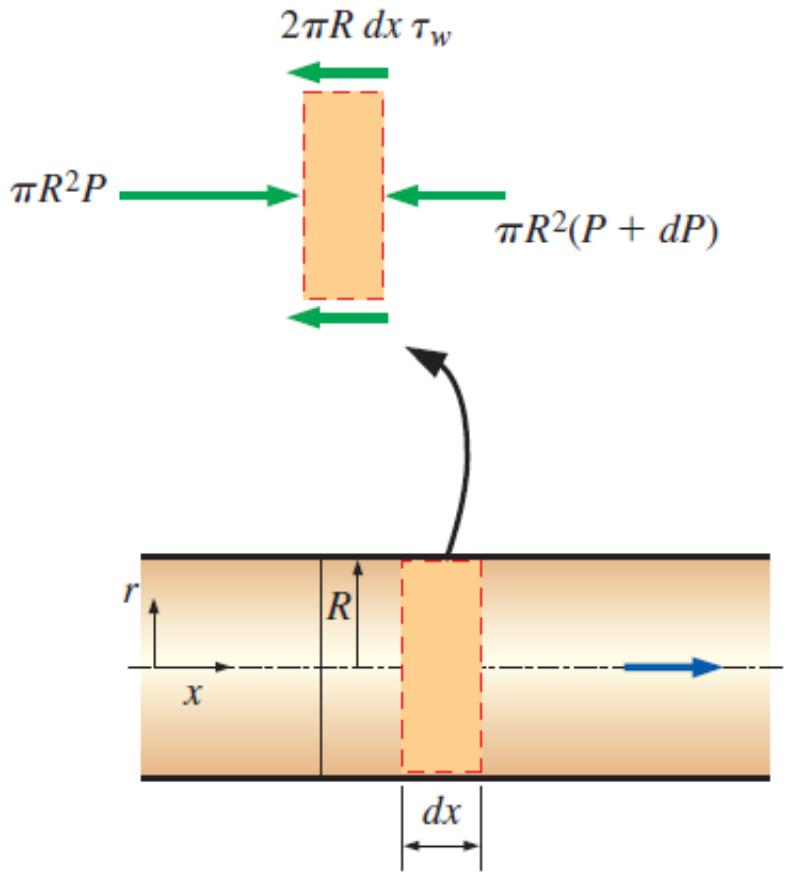
Method 2

$$= \cancel{\underbrace{\frac{\partial P}{\partial x}}_{\text{Assumption 5}}} + \rho g_x + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \cancel{\underbrace{\frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}}_{\text{Assumption 6}}} + \underbrace{\frac{\partial^2 u}{\partial x^2}}_{\text{Continuity}} \right)$$

Laminar Flow

We consider steady, laminar, incompressible flow of a fluid with constant properties in the fully developed region of a straight circular pipe.

In fully developed laminar flow, each fluid particle moves at a constant axial velocity along a streamline and the velocity profile $u(r)$ remains unchanged in the flow direction. There is no motion in the radial direction, and thus the velocity component in the direction normal to the pipe axis is everywhere zero. There is no acceleration since the flow is steady and fully developed.



Fully Developed

$$\frac{dP}{dx} = -\frac{2\tau_w}{R}$$

$$u(r) = \frac{r^2}{4\mu} \left(\frac{dP}{dx} \right) + C_1 \ln r + C_2$$

No Slip

$$\frac{\partial u}{\partial r} = 0 \text{ at } r = 0$$

$$u = 0 \text{ at } r = R$$

Boundary conditions

$$u(r) = -\frac{R^2}{4\mu} \left(\frac{dP}{dx} \right) \left(1 - \frac{r^2}{R^2} \right)$$

Average velocity

$$V_{\text{avg}} = \frac{2}{R^2} \int_0^R u(r)r dr = \frac{-2}{R^2} \int_0^R \frac{R^2}{4\mu} \left(\frac{dP}{dx} \right) \left(1 - \frac{r^2}{R^2} \right) r dr = -\frac{R^2}{8\mu} \left(\frac{dP}{dx} \right)$$

$$u(r) = 2V_{\text{avg}} \left(1 - \frac{r^2}{R^2} \right)$$

Velocity profile

$$u_{\text{max}} = 2V_{\text{avg}}$$

Maximum velocity at centerline

Force balance:

$$\pi R^2 P - \pi R^2(P + dP) - 2\pi R dx \tau_w = 0$$

Simplifying: Pressure Force

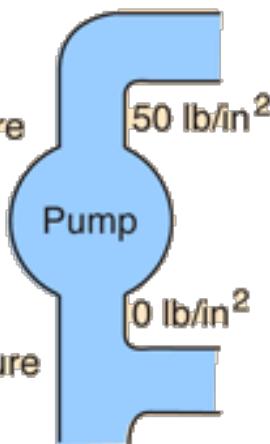
Shear Force

$$\frac{dP}{dx} = -\frac{2\tau_w}{R}$$

Pressure Drop & Head Loss

$$\text{pressure} = \frac{\text{energy}}{\text{volume}}$$

high pressure



$$\text{pressure} = \frac{F}{A}$$

$$\frac{F}{A} = \frac{Fd}{Ad} = \frac{W}{V}$$

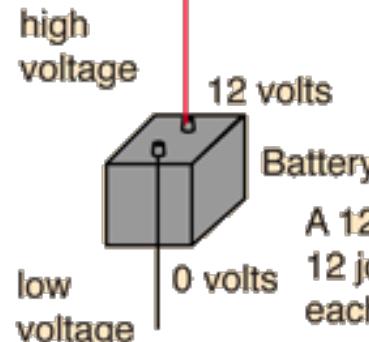
$$= \frac{\text{energy}}{\text{volume}} \quad \frac{\text{joule}}{\text{m}^3}$$



A closed faucet has pressure behind it, but no flow.
(resistance →)

$$\text{voltage} = \frac{\text{energy}}{\text{charge}}$$

$$\text{volt} = \frac{\text{joule}}{\text{coulomb}}$$



Battery
A 12 volt battery does 12 joules of work on each unit of charge which passes through it.



A receptacle has voltage behind it, but no current if nothing is plugged in.
(resistance →)

The Pressure loss is an important parameter in pipe flows. The pressure drop is directly related to the power requirements of a pump

$$\frac{dP}{dx} = \frac{P_2 - P_1}{L}$$

Laminar flow:

$$\Delta P = P_1 - P_2 = \frac{8\mu LV_{avg}}{R^2} = \frac{32\mu LV_{avg}}{D^2}$$

Pressure Loss

$$\Delta P_L = f \frac{L}{D} \frac{\rho V_{avg}^2}{2}$$

Friction factor

Dynamic Pressure

$$h_L = \frac{\Delta P_L}{\rho g}$$

Head Loss

$$f = \frac{8\tau_w}{\rho V_{avg}^2}$$

For Laminar flow in pipes

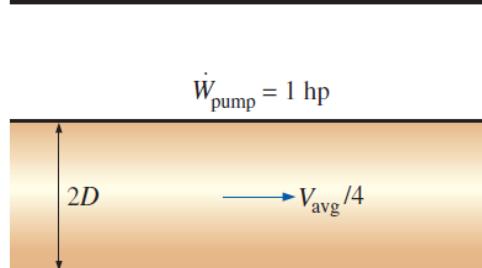
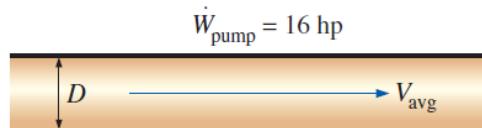
$$f = \frac{64}{Re}$$

In laminar flow, the friction factor is only a function of Reynolds Number and is independent of pipe roughness

$$\dot{W}_{pumpL} = \dot{V} \Delta P_L = \dot{V} \rho g h_L = \dot{m} g h_L$$

$$V_{\text{avg}} = \frac{(P_1 - P_2)R^2}{8\mu L} = \frac{(P_1 - P_2)D^2}{32\mu L} = \frac{\Delta P D^2}{32\mu L}$$

$$\dot{V} = V_{\text{avg}} A_c = \frac{(P_1 - P_2)R^2}{8\mu L} \pi R^2 = \frac{(P_1 - P_2)\pi D^4}{128\mu L} = \frac{\Delta P \pi D^4}{128\mu L}$$



The pumping power requirement for a laminar flow piping system can be reduced by a factor of 16 by doubling the pipe diameter.

For laminar flow in horizontal pipe, the pressure drop is directly proportional to pressure loss.

$$\frac{P_1}{\rho g} + \alpha_1 \frac{V_1^2}{2g} + z_1 + h_{pump} = \frac{P_2}{\rho g} + \alpha_2 \frac{V_2^2}{2g} + z_2 + h_{turbine} + h_L$$

energy equation for steady, incompressible one-dimensional flow

$$P_1 - P_2 = \cancel{\rho(\alpha_2 V_2^2 - \alpha_1 V_1^2)/2} + \cancel{\rho g[(z_2 - z_1) + h_{turbine, e}]} \cancel{+ h_{pump, u}} + h_L$$

If the z_2 and z_1 are equal and there is no external work and V_2 and V_1 are equal, the pressure drop is equal to the pressure loss $\rho g h_L$

Turbulent Boundary Layer

Wall Layer

$$u(y) = f(\mu, \tau_w, \rho, y)$$

$$u^+ = \frac{u}{u^*} = F\left(\frac{yu^*}{\nu}\right) \quad u^* = \left(\frac{\tau_w}{\rho}\right)^{1/2}$$

Outer Layer

$$U - u(y) = f(\delta, \tau_w, \rho, y)$$

$$\frac{U - u}{u^*} = G\left(\frac{y}{\delta}\right)$$

Overlap Layer

$$\frac{u}{u^*} = \frac{1}{\kappa} \ln \frac{yu^*}{\nu} + B$$

Viscous sublayer

$$u_* = \sqrt{\frac{\tau_w}{\rho}}$$

Viscous sublayer:

$$\frac{u}{u_*} = \frac{yu_*}{\nu}$$

Thickness of viscous sublayer:

$$y = \delta_{\text{sublayer}} = \frac{5\nu}{u_*} = \frac{25\nu}{u_\delta}$$

thickness of viscous sublayer is proportional to viscosity and inversely proportional to velocity

ν/u_* **Viscous length**; it is used to nondimensionalize the distance y from the surface.

Nondimensionalized variables:

$$y^+ = \frac{yu_*}{\nu} \quad \text{and} \quad u^+ = \frac{u}{u_*}$$

Normalized law of the wall:

$$u^+ = y^+$$

Outer layer

Outer turbulent layer:

$$\frac{u_{\max} - u}{u_*} = 2.5 \ln \frac{R}{R - r}$$

Power-law velocity profile:

$$\frac{u}{u_{\max}} = \left(\frac{y}{R}\right)^{1/n} \quad \text{or} \quad \frac{u}{u_{\max}} = \left(1 - \frac{r}{R}\right)^{1/n}$$

Deviation of velocity from the centerline velocity is called as **velocity defect** and these relationships are commonly known as velocity defect law

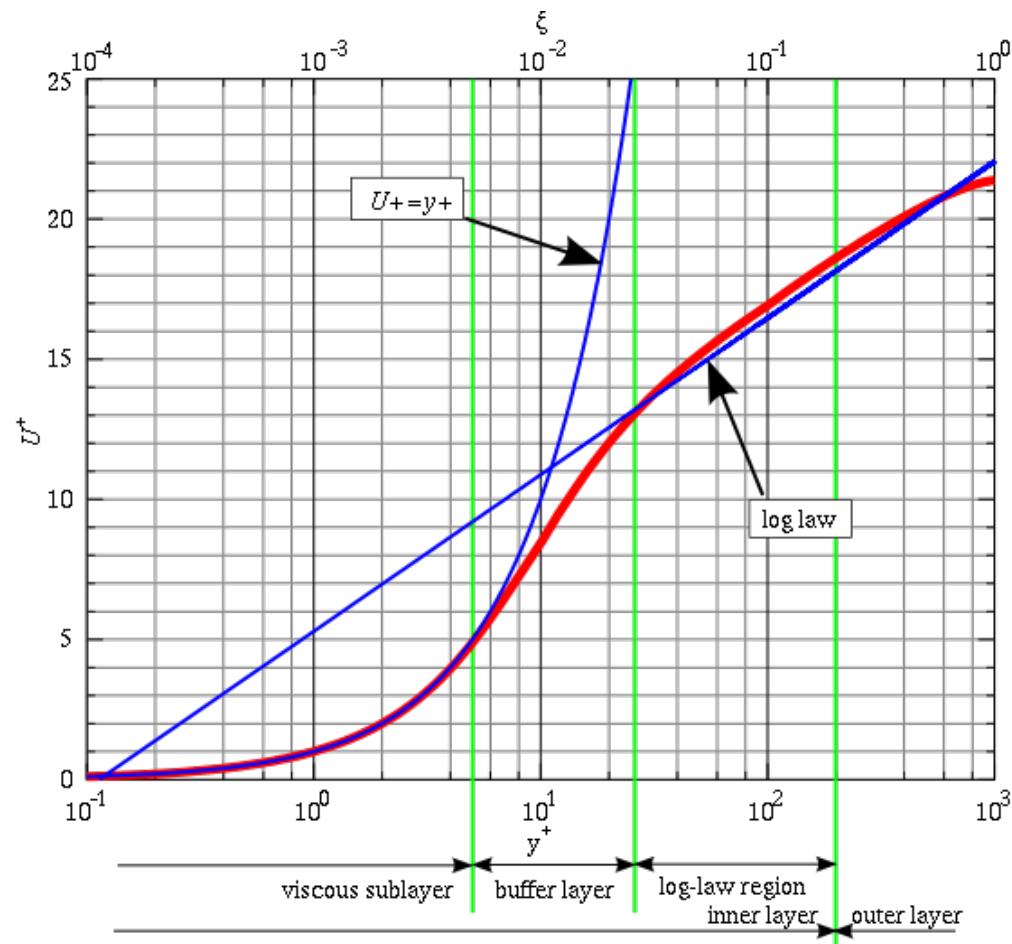
Overlap layer

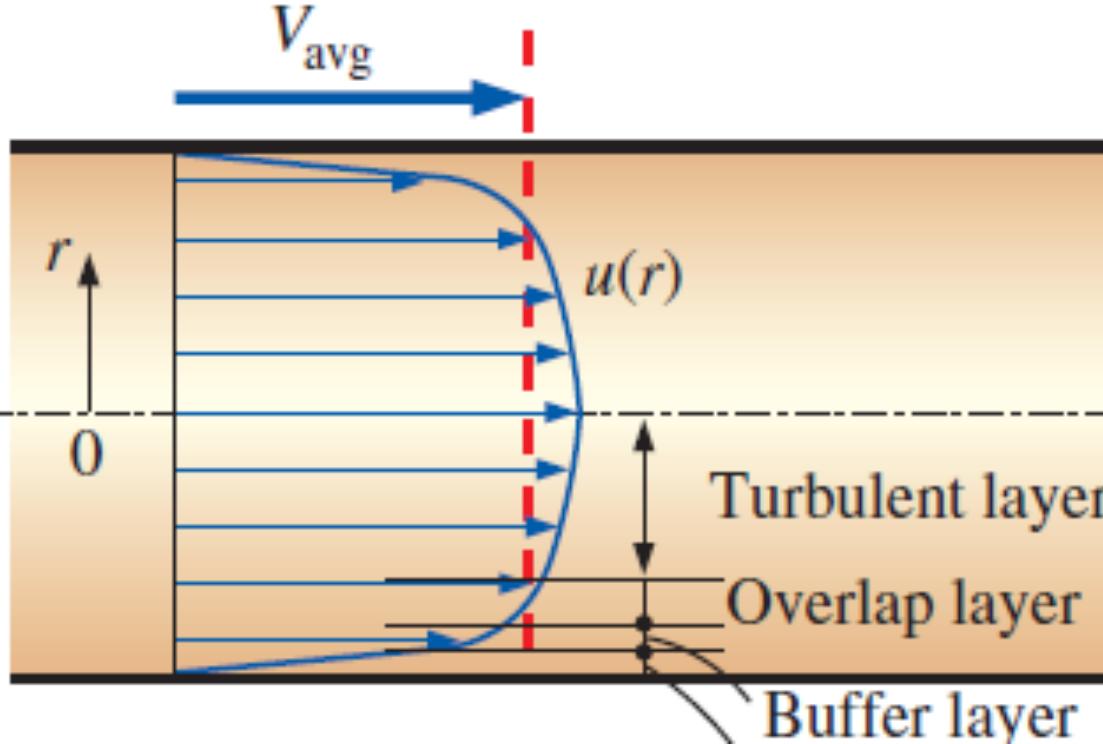
Overlap layer:

$$\frac{u}{u_*} = 2.5 \ln \frac{yu_*}{\nu} + 5.0 \quad \text{or} \quad u^+ = 2.5 \ln y^+ + 5.0$$

The logarithmic law:

$$\frac{u}{u_*} = \frac{1}{\kappa} \ln \frac{yu_*}{\nu} + B$$





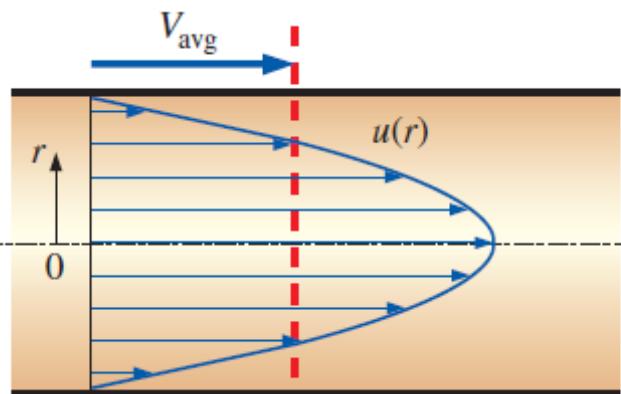
The very thin layer next to the wall where viscous effects are dominant is the **viscous** (or **laminar** or **linear** or **wall**) sublayer.

The velocity profile in this layer is very nearly *linear*, and the flow is streamlined.

Next to the viscous sublayer is the **buffer layer**, in which turbulent effects are becoming significant, but the flow is still dominated by viscous effects.

Above the buffer layer is the **overlap** (or **transition**) **layer**, also called the **inertial sublayer**, in which the turbulent effects are much more significant, but still not dominant.

Above that is the **outer** (or **turbulent**) **layer** in the remaining part of the flow in which turbulent effects dominate over molecular diffusion (viscous) effects.



Laminar flow

Turbulent Flow Solutions

Start from log law

$$\frac{u(r)}{u^*} \approx \frac{1}{\kappa} \ln \frac{(R - r)u^*}{\nu} + B$$

$$\begin{aligned} V = \frac{Q}{A} &= \frac{1}{\pi R^2} \int_0^R u^* \left[\frac{1}{\kappa} \ln \frac{(R - r)u^*}{\nu} + B \right] 2\pi r \, dr \\ &= \frac{1}{2} u^* \left(\frac{2}{\kappa} \ln \frac{Ru^*}{\nu} + 2B - \frac{3}{\kappa} \right) \end{aligned}$$

$$\frac{V}{u^*} = \left(\frac{\rho V^2}{\tau_w} \right)^{1/2} = \left(\frac{8}{f} \right)^{1/2}$$

$$\frac{1}{f^{1/2}} = 2.0 \log (\text{Re}_d f^{1/2}) - 0.8$$

Relative Roughness, ϵ/D	Friction Factor, f
0.0*	0.0119
0.00001	0.0119
0.0001	0.0134
0.0005	0.0172
0.001	0.0199
0.005	0.0305
0.01	0.0380
0.05	0.0716

* Smooth surface. All values are for $Re = 10^6$ and are calculated from the Colebrook equation.

Equivalent roughness values for new commercial pipes*		
Material	Roughness, ϵ	
	ft	mm
Glass, plastic	0 (smooth)	
Concrete	0.003–0.03	0.9–9
Wood stave	0.0016	0.5
Rubber, smoothed	0.000033	0.01
Copper or brass tubing	0.000005	0.0015
Cast iron	0.00085	0.26
Galvanized iron	0.0005	0.15
Wrought iron	0.00015	0.046
Stainless steel	0.000007	0.002
Commercial steel	0.00015	0.045

$$\frac{1}{\sqrt{f}} = -2.0 \log \left(\frac{\epsilon/D}{3.7} + \frac{2.51}{Re \sqrt{f}} \right) \quad (\text{turbulent flow})$$

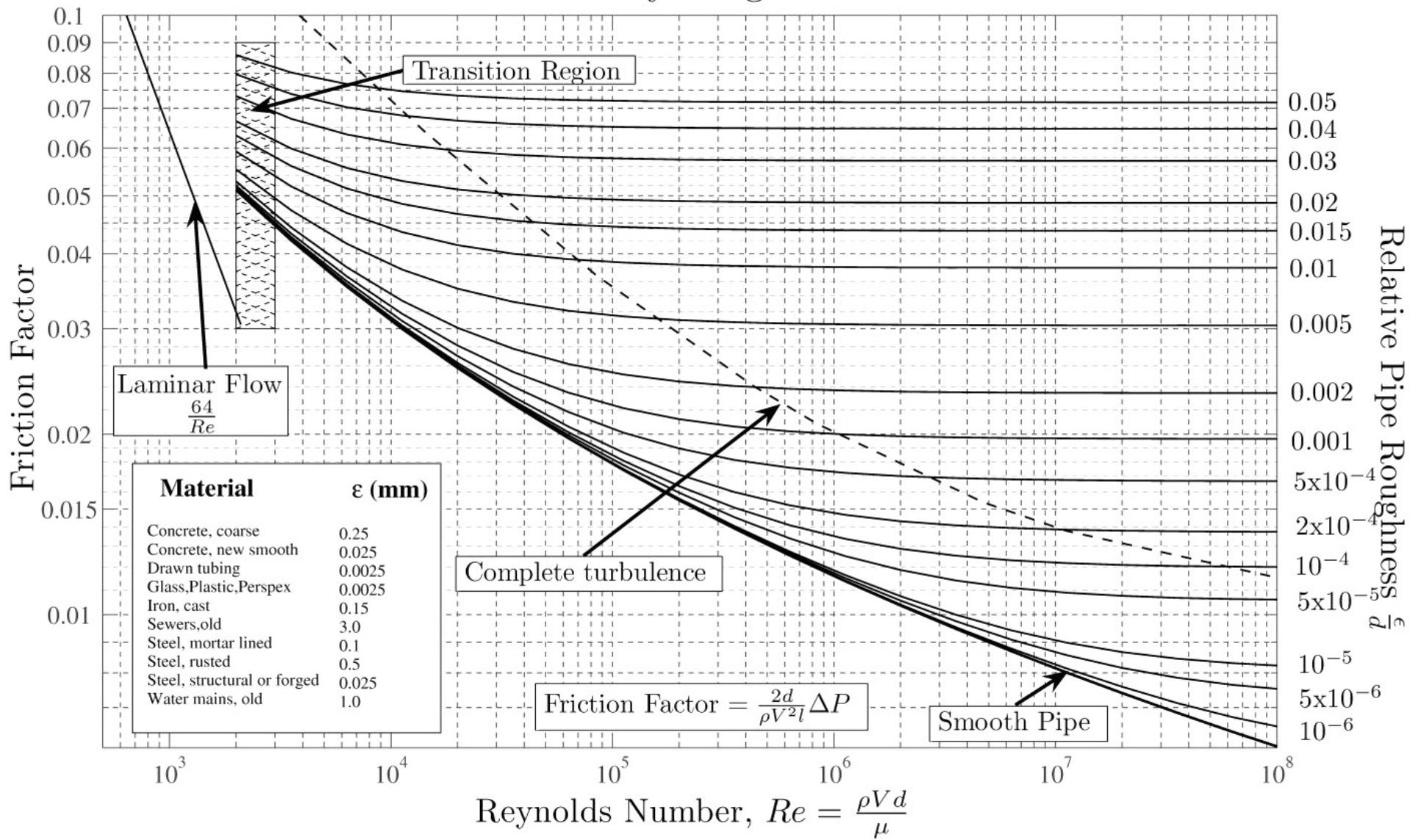
implicit Colebrook equation

The friction factor in fully developed turbulent pipe flows is dependent on Reynolds number and the relative roughness factor

$$\frac{1}{\sqrt{f}} \approx -1.8 \log \left[\frac{6.9}{Re} + \left(\frac{\epsilon/D}{3.7} \right)^{1.11} \right]$$

explicit Haaland equation

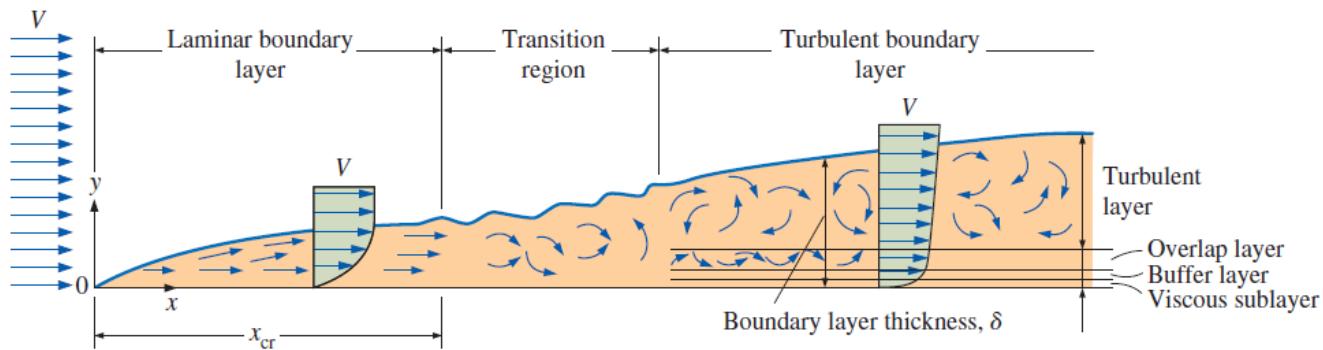
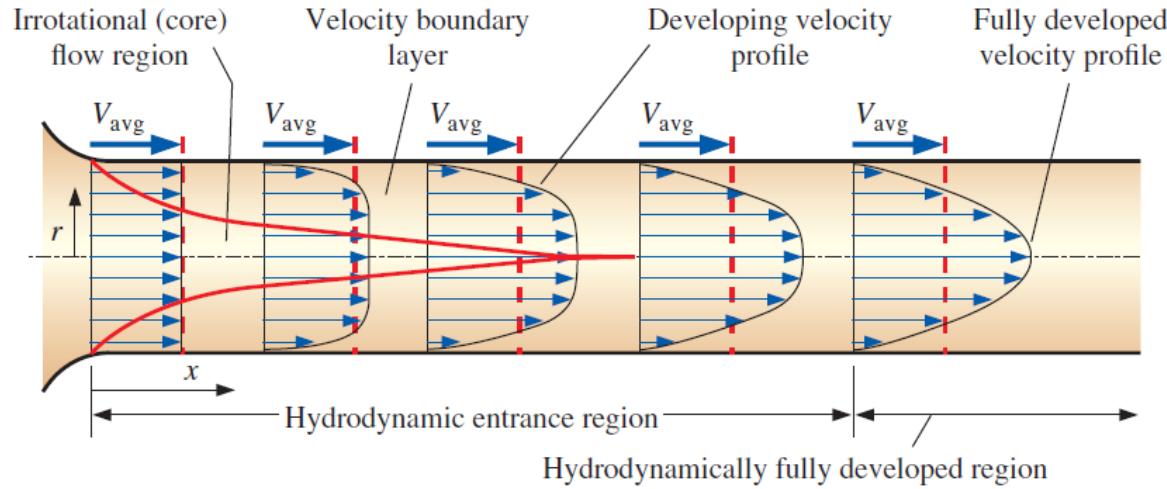
Moody Diagram

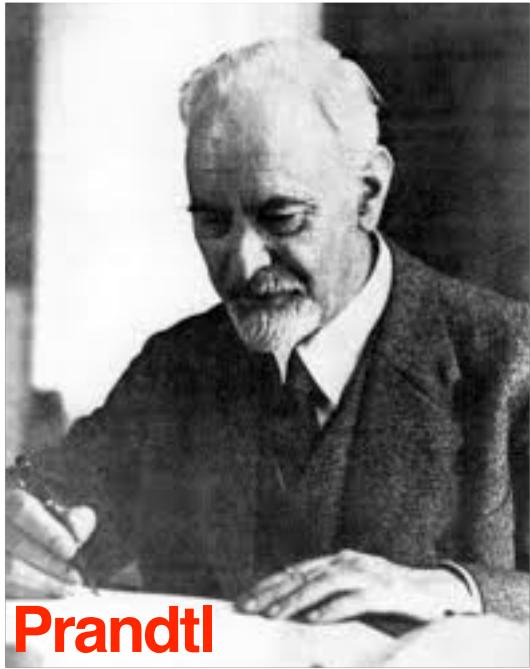


Background- *External Flow*

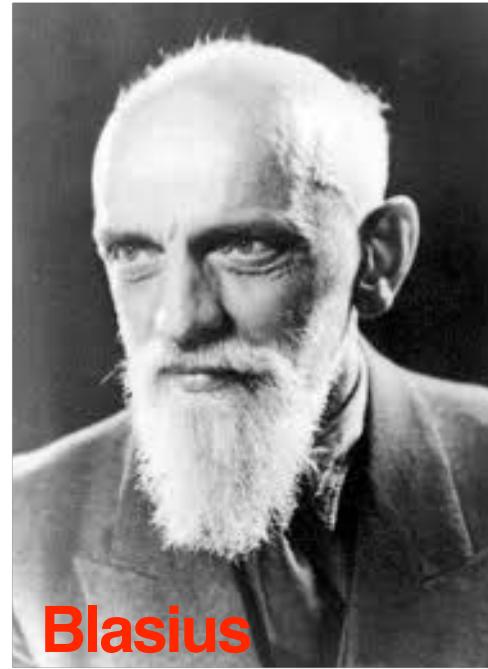


Internal Vs External





Prandtl



Blasius

$$u(y) = f(U_e, x, y, \rho, \mu)$$
$$\frac{u}{U_e} = f\left(\frac{U_e x}{v}, \frac{y}{x}\right)$$

$$u(\partial u / \partial x) + v(\partial u / \partial y) = v(\partial^2 u / \partial y^2)$$

$$\partial u / \partial x + \partial v / \partial y = 0$$

subject to the boundary conditions $u(y=0) = v(y=0) = 0$

$$\xi = (y/2)(U/vx)^{1/2} \quad \psi = (Ux/v)^{1/2} \zeta$$

$$\zeta \zeta'' + \zeta''' = 0$$

Blasius velocity profile

$y(U_e/vx)^{1/2}$	u/U_e	$y(U_e/vx)^{1/2}$	u/U_e
0.0	0.0	2.8	0.81152
0.2	0.06641	3.0	0.84605
0.4	0.13277	3.2	0.87609
0.6	0.19894	3.4	0.90177
0.8	0.26471	3.6	0.92333
1.0	0.32979	3.8	0.94112
1.2	0.39378	4.0	0.95552
1.4	0.45627	4.2	0.96696
1.6	0.51676	4.4	0.97587
1.8	0.57477	4.6	0.98269
2.0	0.62977	4.8	0.98779
2.2	0.68132	5.0	0.99155
2.4	0.72899	∞	1.00000
2.6	0.77246		

Analytical Approximation

$$\frac{F_v}{\rho W U_e^2} = \int_0^\delta \frac{u}{U_e} \left(1 - \frac{u}{U_e}\right) dy = \frac{2}{15} \delta$$

Assuming a parabolic velocity profile

$$F_v = \int_0^L \tau_w W dx$$

wall shear stress

$$\frac{1}{W} \frac{dF_v}{dx} = \tau_w = \mu \frac{du}{dy} = \frac{2\mu U_e}{\delta}$$

$$F_v = \sqrt{\frac{8}{15} \mu \rho U_e^3 W^2 L}$$

$$C_F = \frac{1.46}{\sqrt{Re_L}}$$

$$C_F = \frac{F_v}{\frac{1}{2}\rho U_e^2 LW} \quad \text{and} \quad Re_L = \frac{\rho U_e L}{\mu}$$

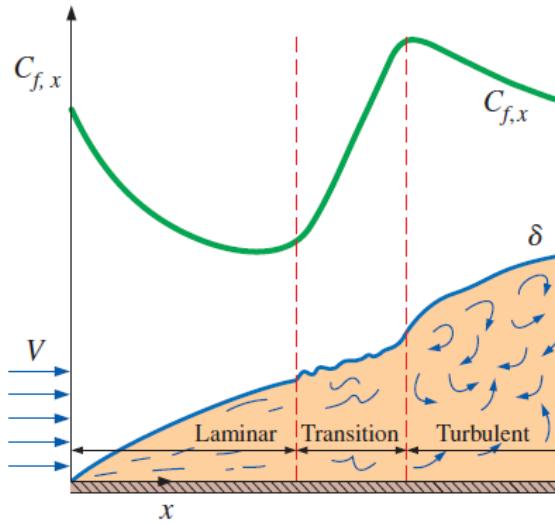
C_f is the total skin friction coefficient as it measures the total viscous drag on the plate. It can also be defined locally at every x location.

for a parabolic velocity profile

$$C_f = \frac{0.664}{\sqrt{Re_x}}$$

Coefficient of Friction

- The friction coefficient for **laminar flow** over a flat plate can be determined theoretically by solving the conservation of mass and momentum equations numerically.
- For **turbulent flow**, it must be determined experimentally and expressed by empirical correlations.



The variation of the local friction coefficient for flow over a flat plate. Note that the vertical scale of the boundary layer is greatly exaggerated in this sketch.

$$\text{Re}_x = Vx/\nu$$

$$\text{Laminar: } \delta = \frac{4.91x}{\text{Re}_x^{1/2}} \quad \text{and} \quad C_{f,x} = \frac{0.664}{\text{Re}_x^{1/2}}, \quad \text{Re}_x < 5 \times 10^5$$

$$\text{Turbulent: } \delta = \frac{0.38x}{\text{Re}_x^{1/5}} \quad \text{and} \quad C_{f,x} = \frac{0.059}{\text{Re}_x^{1/5}}, \quad 5 \times 10^5 \leq \text{Re}_x \leq 10^7$$

Average friction coefficient over the entire plate

Laminar:

$$C_f = \frac{1.33}{\text{Re}_L^{1/2}} \quad \text{Re}_L < 5 \times 10^5$$

Turbulent:

$$C_f = \frac{0.074}{\text{Re}_L^{1/5}} \quad 5 \times 10^5 \leq \text{Re}_L \leq 10^7$$

$$\text{Re}_{\text{cr}} = 5 \times 10^5 = Vx_{\text{cr}}/\nu$$

$$\begin{aligned} C_f &= \frac{1}{L} \int_0^L C_{f,x} dx \\ &= \frac{1}{L} \int_0^L \frac{0.664}{\text{Re}_x^{1/2}} dx \\ &= \frac{0.664}{L} \int_0^L \left(\frac{Vx}{\nu} \right)^{-1/2} dx \\ &= \frac{0.664}{L} \left(\frac{V}{\nu} \right)^{-1/2} \left. \frac{x^{1/2}}{\frac{1}{2}} \right|_0^L \\ &= \frac{2 \times 0.664}{L} \left(\frac{V}{\nu L} \right)^{-1/2} \\ &= \frac{1.328}{\text{Re}^{1/2}} \end{aligned}$$

When the laminar flow region is not disregarded

$$C_f = \frac{1}{L} \left(\int_0^{x_{\text{cr}}} C_{f,x, \text{laminar}} dx + \int_{x_{\text{cr}}}^L C_{f,x, \text{turbulent}} dx \right)$$

$$C_f = \frac{0.074}{\text{Re}_L^{1/5}} - \frac{1742}{\text{Re}_L} \quad 5 \times 10^5 \leq \text{Re}_L \leq 10^7$$

The average friction coefficient over a surface is determined by integrating the local friction coefficient over the entire surface. The values shown here are for a laminar flat plate boundary layer.

For **Laminar** flow **C_f only depends on Reynolds number.**

For **Turbulent** flows, **surface roughness causes C_f to increase**. For very high Reynolds number in Turbulent flows, C_f is almost just a function of surface roughness

Fully rough turbulent regime:

$$C_f = \left(1.89 - 1.62 \log \frac{\varepsilon}{L} \right)^{-2.5}$$

Relative Roughness, ε/L	Friction Coefficient, C_f
0.0*	0.0029
1×10^{-5}	0.0032
1×10^{-4}	0.0049
1×10^{-3}	0.0084

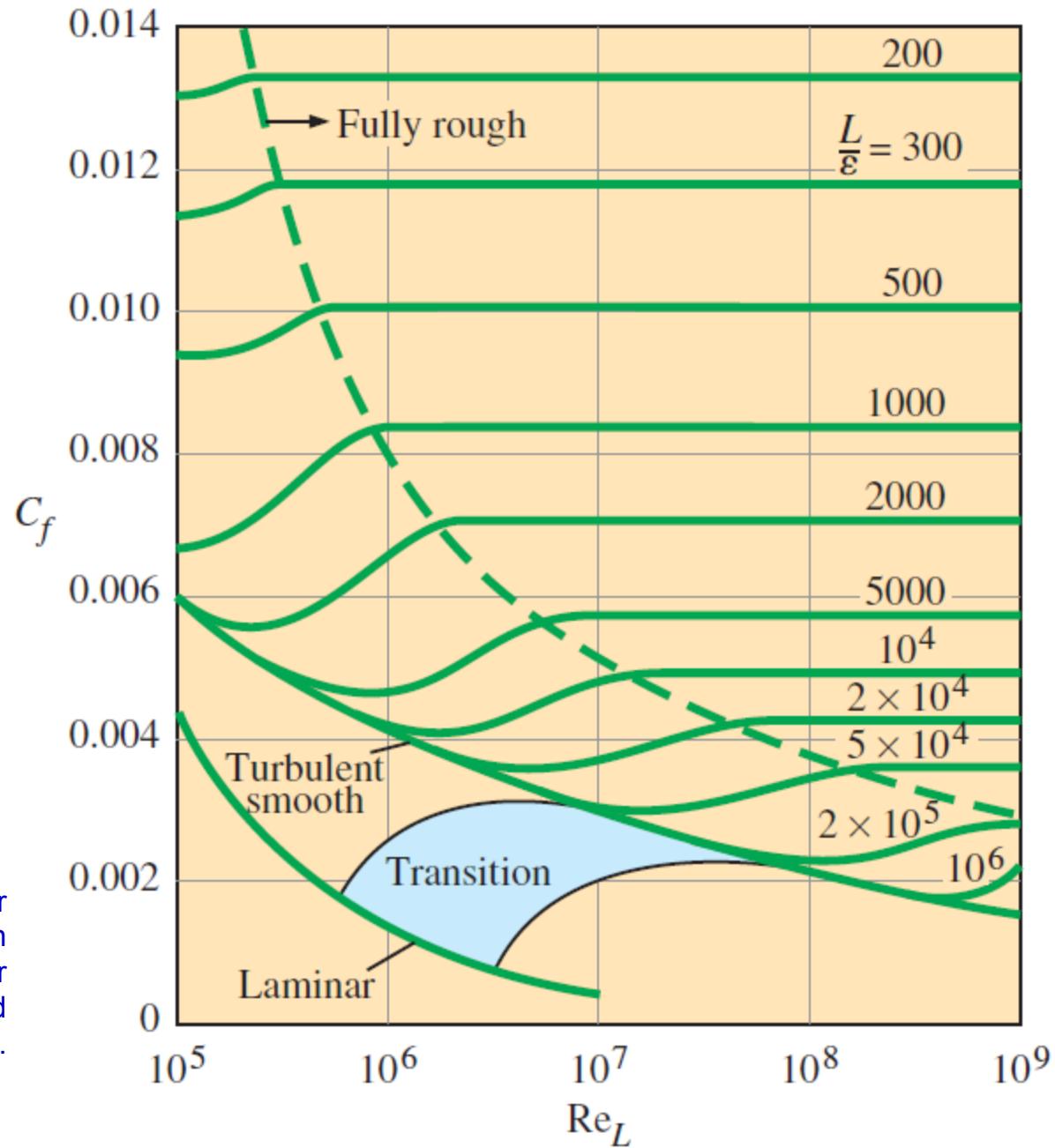
* Smooth surface for $Re = 10^7$. Others calculated from Eq. 11–23 for fully rough flow.

C_f increases severalfold with roughness in turbulent flow.

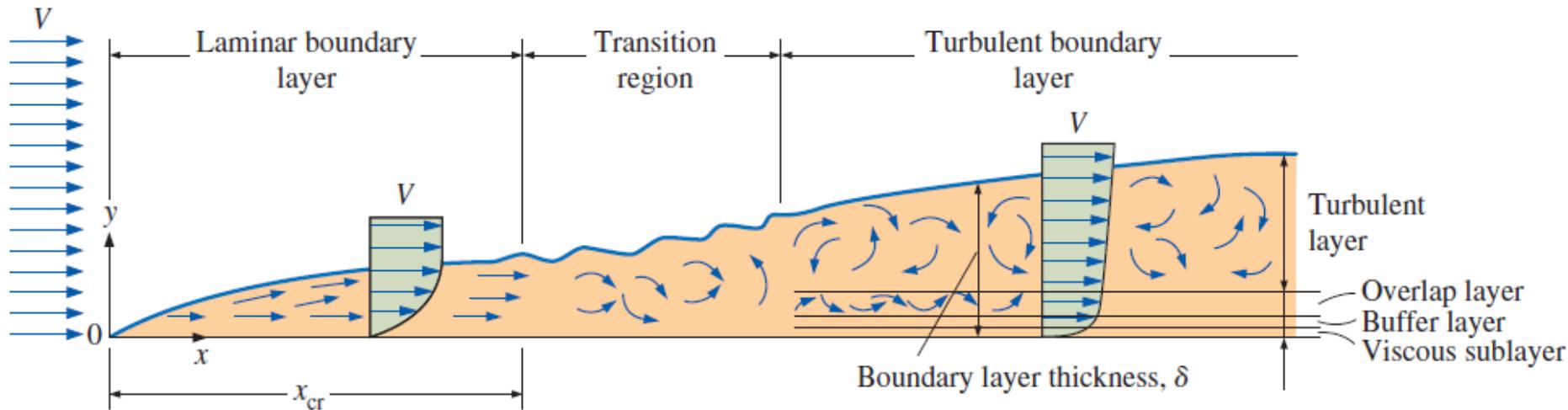
C_f is independent of the Reynolds number in the fully rough region.

This chart is the flat-plate analog of the Moody chart for pipe flows.

Friction coefficient for parallel flow over smooth and rough flat plates for both laminar and turbulent flows.



Flow over Flat Plate Summary



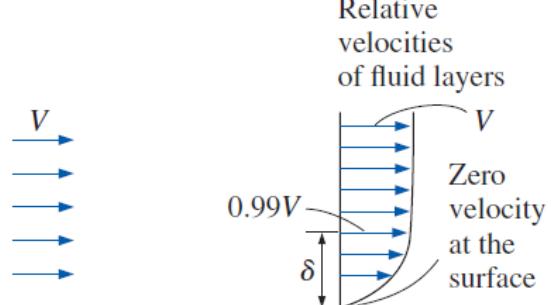
The turbulent boundary layer can be considered to consist of four regions, characterized by the distance from the wall:

- viscous sublayer
- buffer layer
- overlap layer
- turbulent layer

Friction coefficient on a flat plate

$$C_D = C_{D, \text{friction}} = C_f$$

$$F_D = F_f = \frac{1}{2} C_f A \rho V^2$$



Flow over a flat plate

$$C_{D, \text{pressure}} = 0$$

$$C_D = C_{D, \text{friction}} = C_f$$

$$F_{D, \text{pressure}} = 0$$

$$F_D = F_{D, \text{friction}} = F_f = C_f A \frac{\rho V^2}{2}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u\frac{\partial u}{\partial x}+v\frac{\partial u}{\partial y}=-\frac{\partial P}{\partial x}+\frac{\partial \tau}{\partial y}$$

$$\tau_{lam}=\mu\frac{\partial u}{\partial y}$$

$$\tau_{turb}=\mu\frac{\partial u}{\partial y}-\overline{\rho u'v'}$$

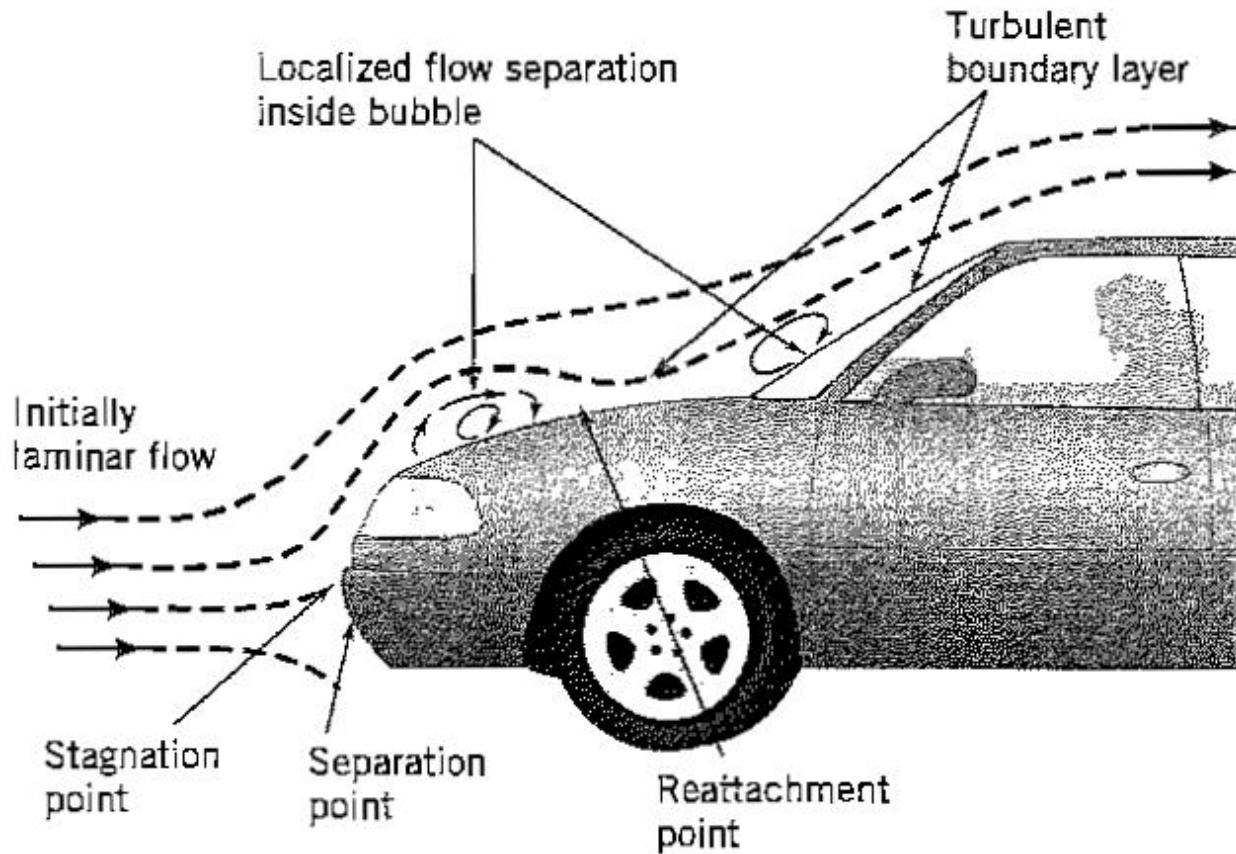
**C_f accounts for viscous drag
acting on the surface due to the
presence of boundary layer**

**Are there other effects that cause
drag?**

Separation, Reattachment & Wakes

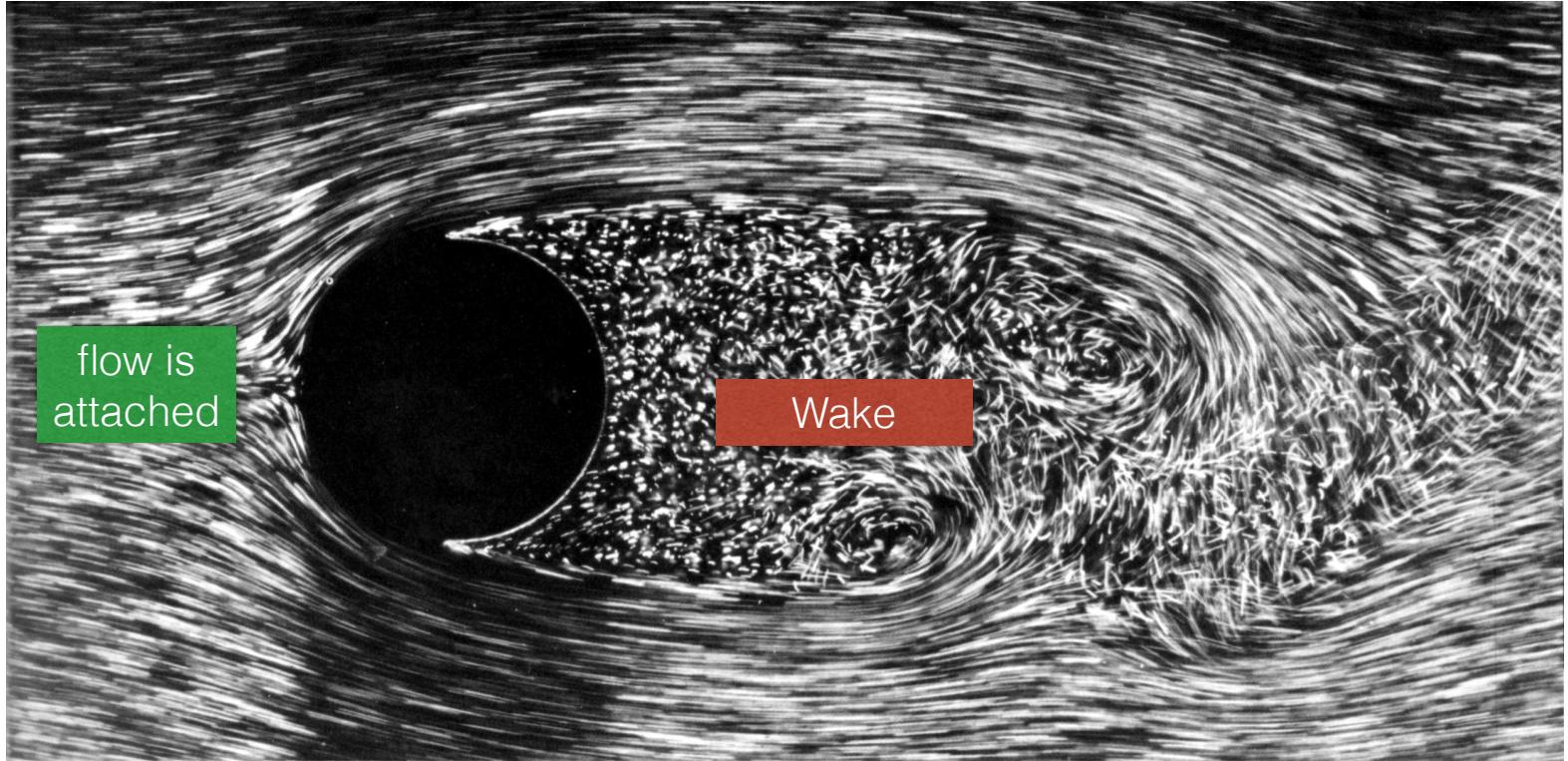
$\frac{dP}{dx} > 0$ Adverse

$\frac{dP}{dx} < 0$ Favourable



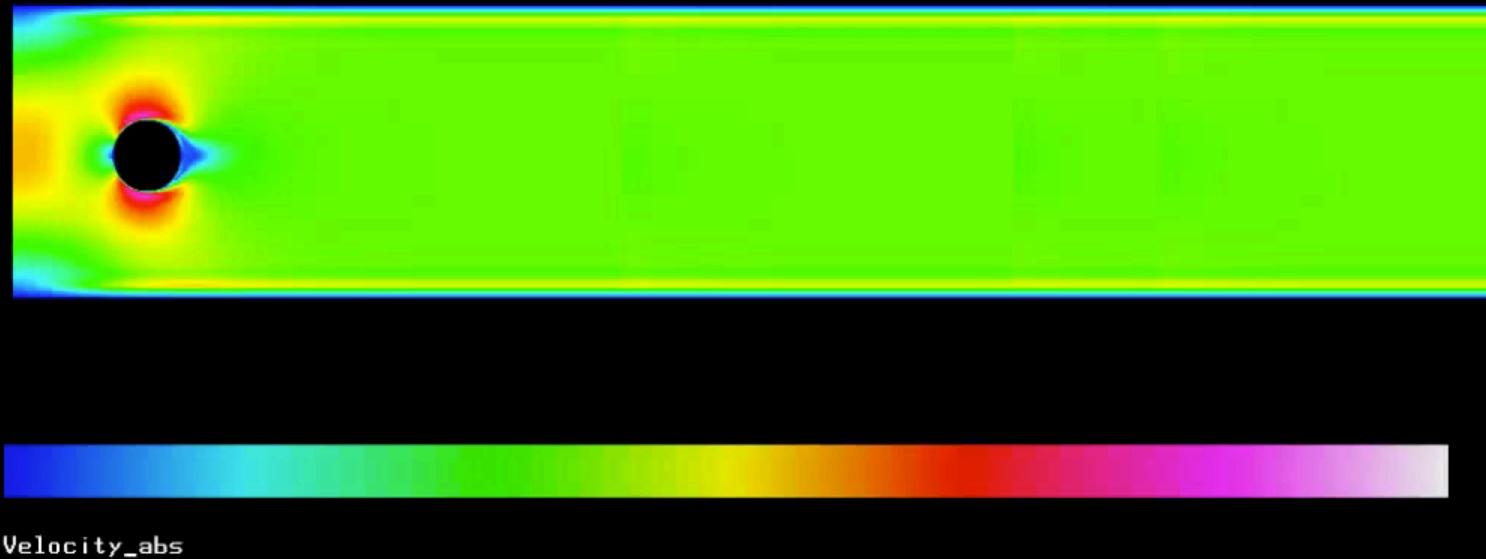
Sharp corners & Flow reversal give rise to adverse pressure gradient and causes flow to separate.

$Re \sim 2000$



The flow is separated in the wake zone which acts as a **momentum sink**, draining the kinetic energy in the flow.

The gradient colors are velocity and the green lines are constant pressure.



The eddying motion behind the flow produces **pressure disturbance** in the flow field.
(the whistling you hear from a tree dancing in the wind)

So the drag force experienced by bodies can be split in to two components; **Viscous** drag & **Pressure** drag

Viscous drag

Due to boundary layers

Important for attached flows

Scales with Reynolds number

Related to surface area exposed

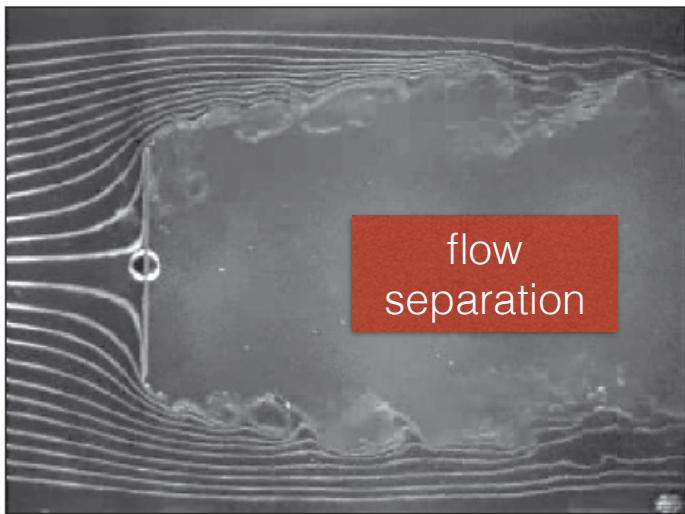
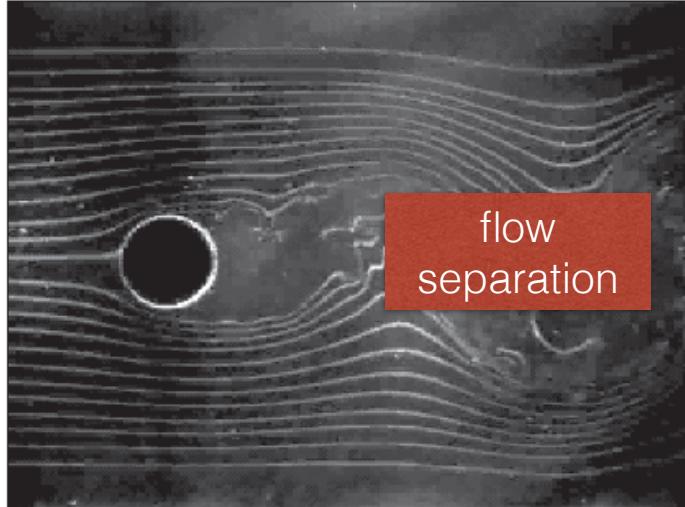
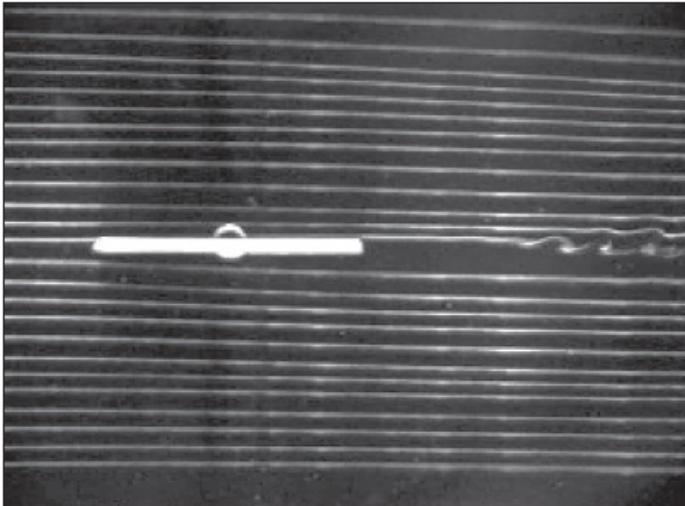
Pressure drag

vortex shedding flow separation

Separated flows

Cross section area & shape

Viscous drag

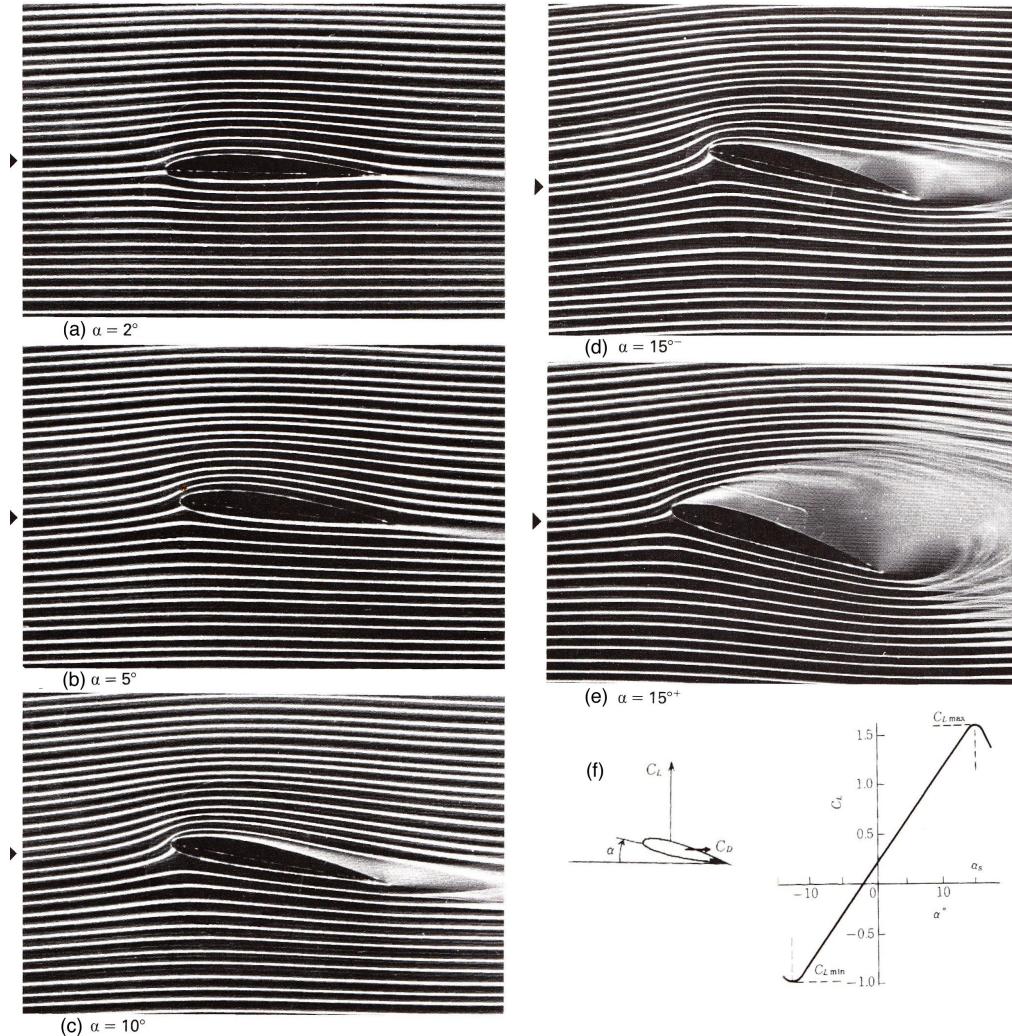


Pressure drag

Small pressure drag → Streamlined

Large pressure drag → Bluff body

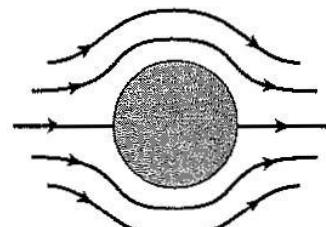
Flow over Airfoil



As angle of attack increases, the pressure gradient along the airfoil becomes less favorable, leading to separation of the flow

Flow over Cylinder

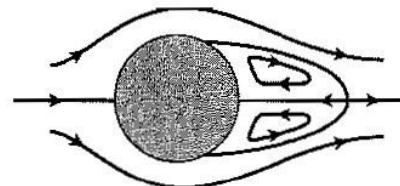
RE # 0.2



No separation

(a)

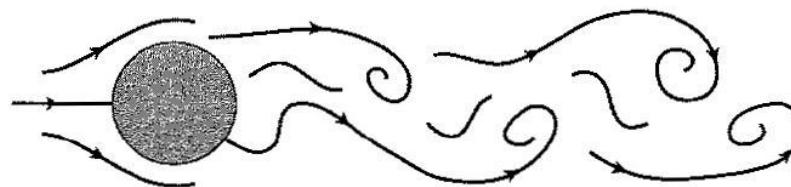
RE # 12



Steady separation bubble

(b)

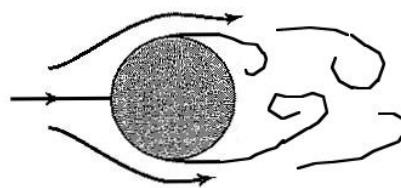
RE # 120



Oscillating Karman vortex street wake

(c)

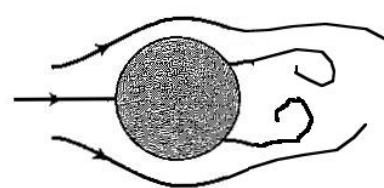
RE # 30000



Laminar boundary layer
wide turbulent wake

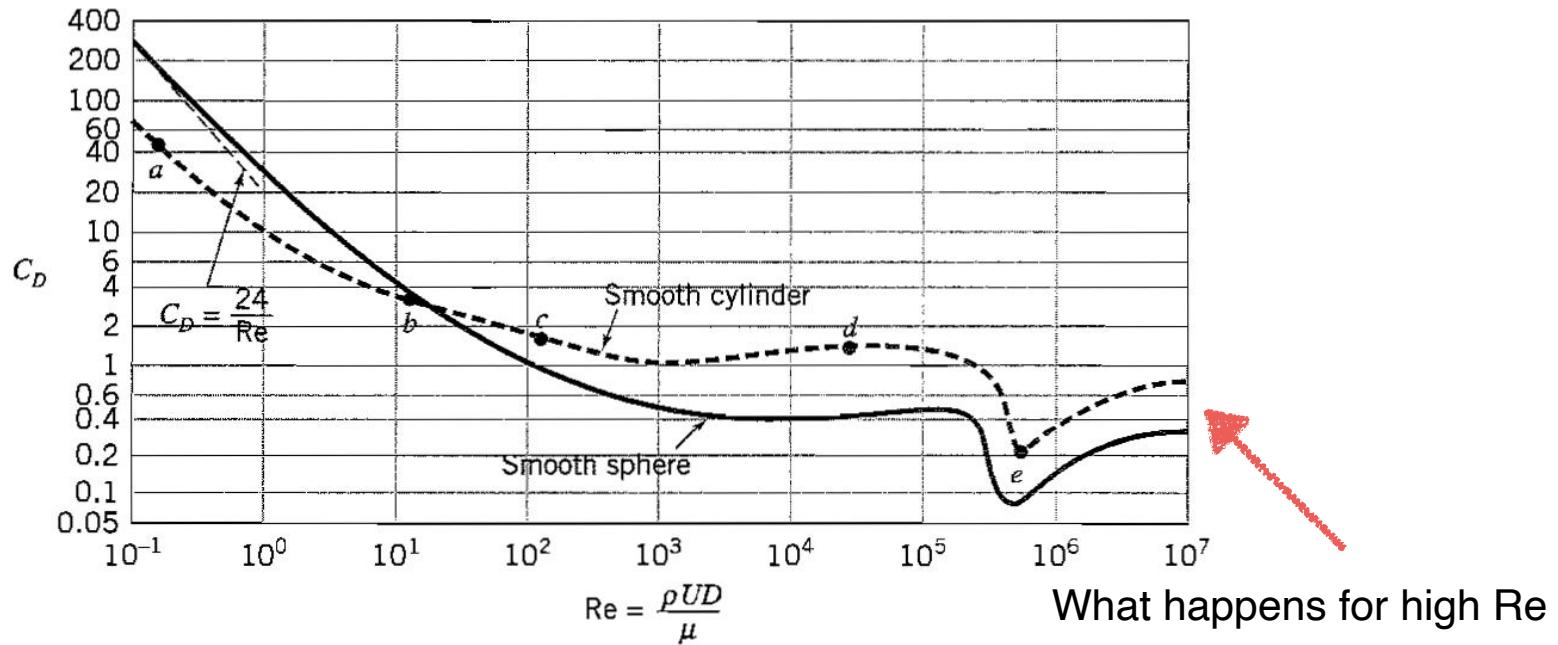
(d)

RE # 500000



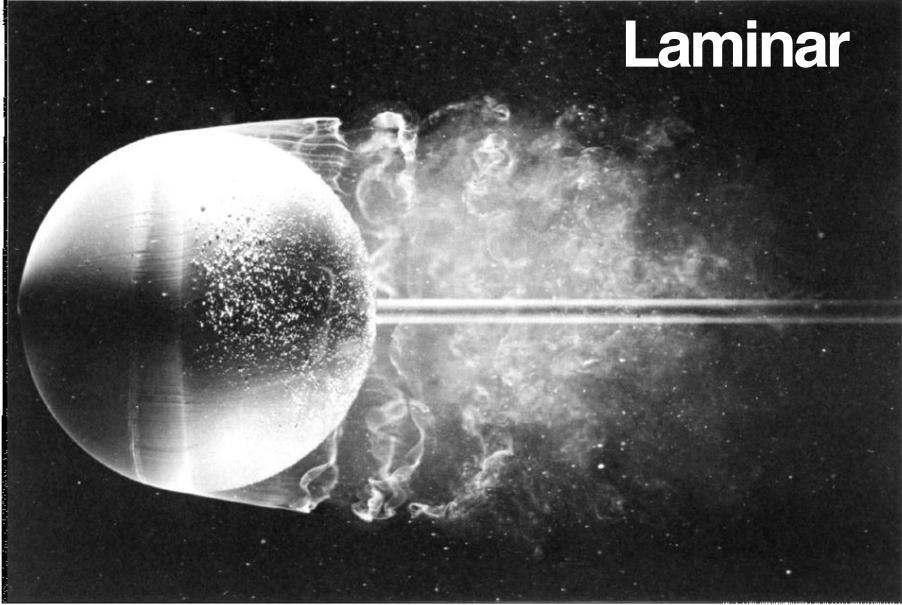
Turbulent boundary layer
narrow turbulent wake

(e)

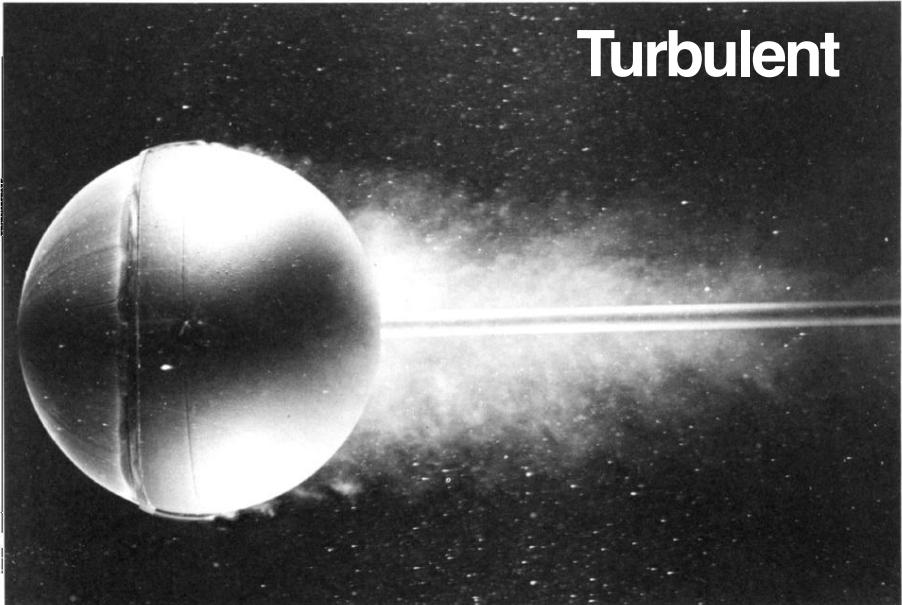


What causes C_D to decrease with $Re \#$

What causes C_d to decrease with $Re\#$?



Laminar



Turbulent

Turbulent BL has **more momentum near wall than a laminar BL** as turbulence is very effective in **mixing momentum**. This mixing replenishes lost momentum near wall due to viscous drag. So when the pressure gradient becomes adverse, the **turbulent boundary layer can persist longer** without separating.

How to estimate drag on bluff bodies?

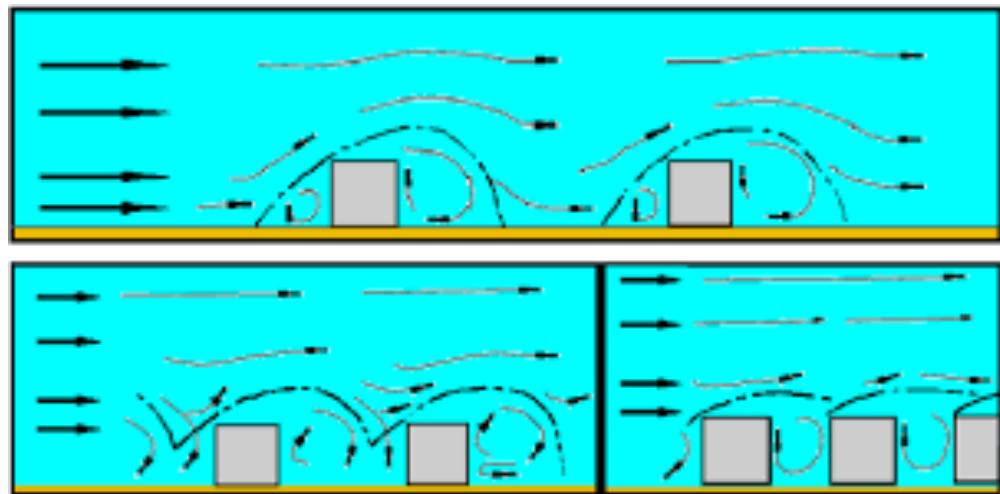
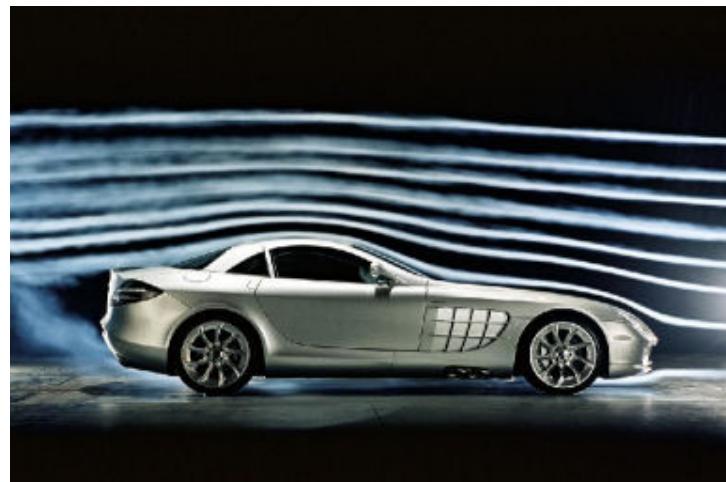
Important in aviation



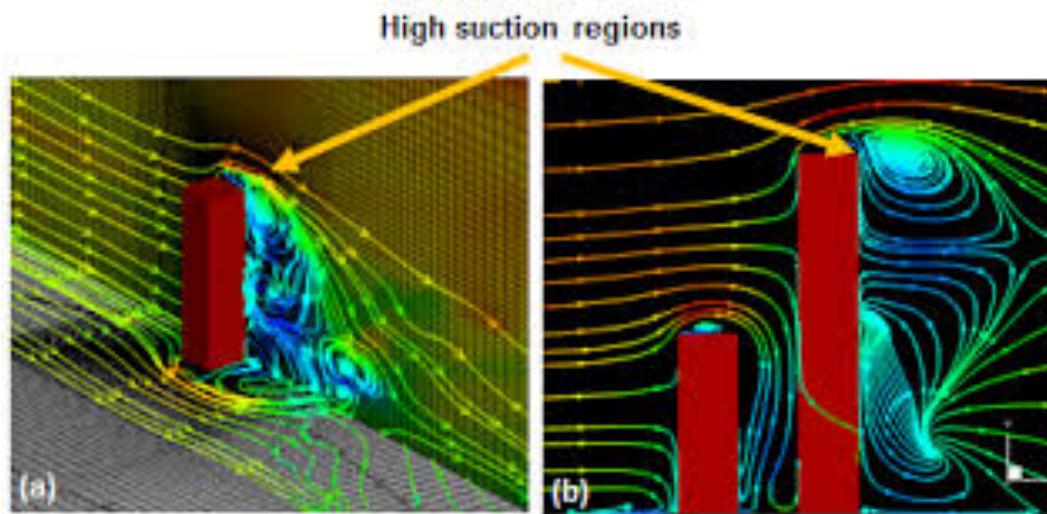
Common engineering use



Common engineering use



Urban Wind Flow Patterns With Various Simple Building Shapes and Spacings



Important in sports



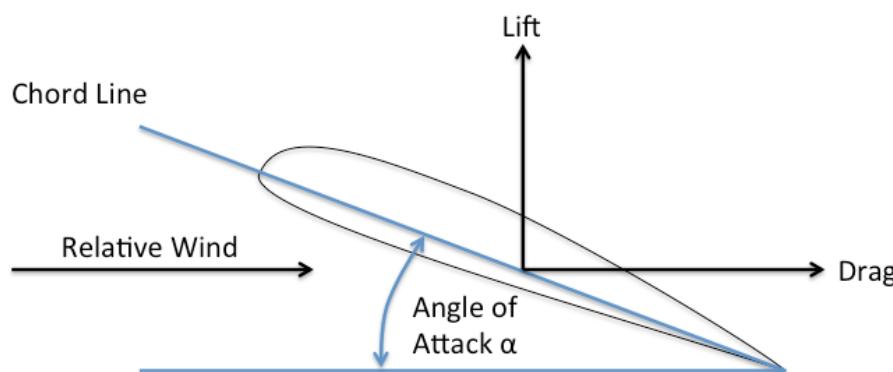
With dimples 250 yards,
without dimples 100 yards



In Cricket and Baseball, the uneven separation of the boundary layer is used to dip the ball sharply.

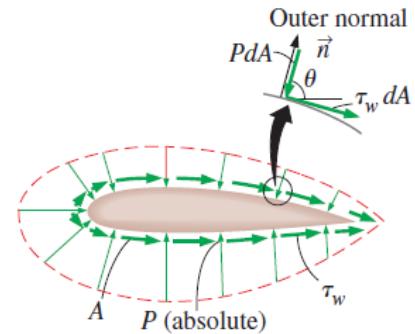
Aerodynamic forces are a result of surface forces, pressure force and shear stresses or viscous stresses.

$$\vec{F} = \int_{S_{wet}} \vec{\tau} dS - \int_{S_{wet}} p \vec{n} dS,$$



Both pressure and viscous stresses affect lift and drag.

Force acting on the body in the direction of flow is called drag and normal to the flow is called lift.

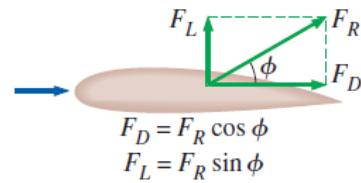


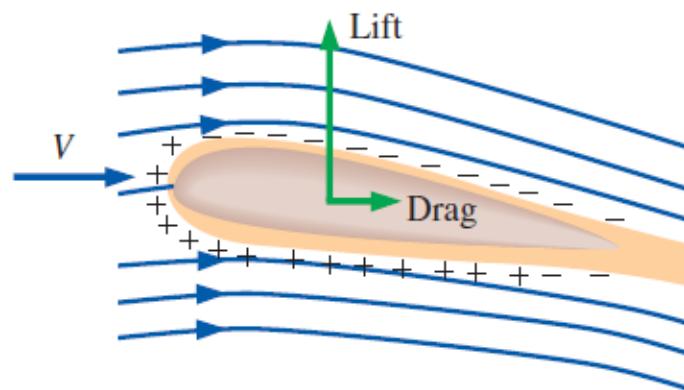
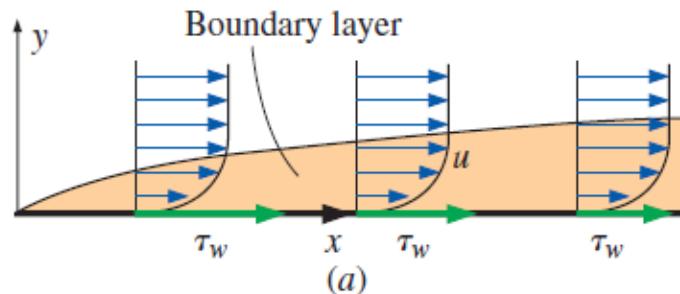
$$dF_D = -P dA \cos \theta + \tau_w dA \sin \theta$$

$$dF_L = -P dA \sin \theta - \tau_w dA \cos \theta$$

Drag force: $F_D = \int_A dF_D = \int_A (-P \cos \theta + \tau_w \sin \theta) dA$

Lift force: $F_L = \int_A dF_L = - \int_A (P \sin \theta + \tau_w \cos \theta) dA$





The drag and lift forces depend on size, shape and orientation of the object and on density of the fluid and the incident velocity.

To simplify the calculation, we simply used non-dimensional variables based on PI groups.

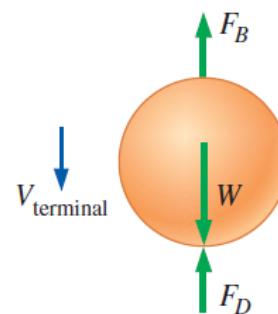
Drag coefficient:

$$C_D = \frac{F_D}{\frac{1}{2}\rho V^2 A}$$

Lift coefficient:

$$C_L = \frac{F_L}{\frac{1}{2}\rho V^2 A}$$

$$C_D = \frac{1}{L} \int_0^L C_{D,x} dx \quad C_L = \frac{1}{L} \int_0^L C_{L,x} dx$$

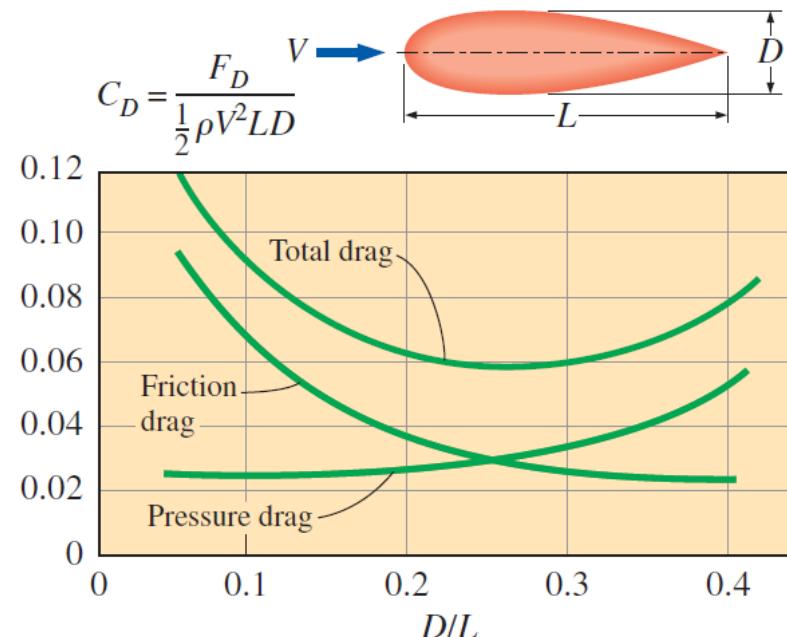


$$F_D = W - F_B$$

(No acceleration)

Reducing Drag by Streamlining

Streamlining decreases pressure drag by delaying boundary layer separation and thus reducing the pressure difference between the front and back of the body but increases the friction drag by increasing the surface area. The end result depends on which effect dominates.



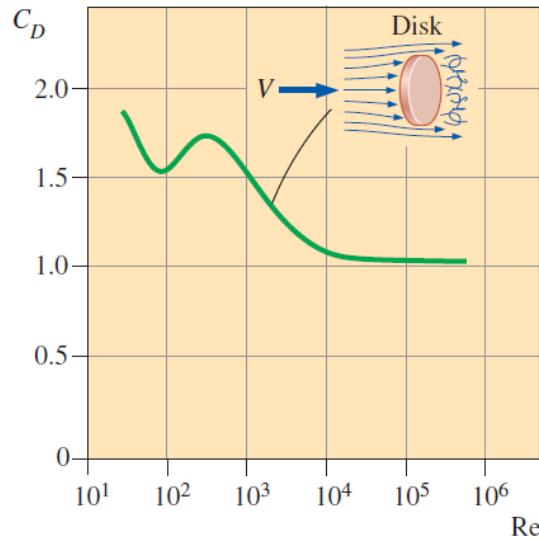
The variation of friction, pressure, and total drag coefficients of a streamlined strut with thickness-to-chord length ratio for $Re = 4 \times 10^4$. Note that C_D for airfoils and other thin bodies is based on *planform* area rather than frontal area.



DRAG COEFFICIENTS OF COMMON GEOMETRIES

The drag behavior of various natural and human-made bodies is characterized by their drag coefficients measured under typical operating conditions.

Usually the *total* (friction+pressure) drag coefficient is reported.



The drag coefficient for many (but not all) geometries remains essentially constant at Reynolds numbers above about 10^4 .

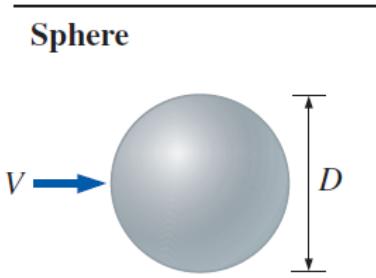
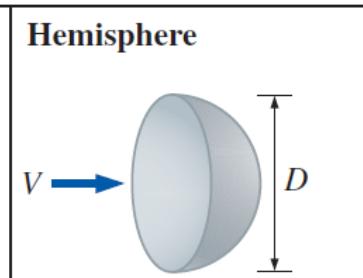
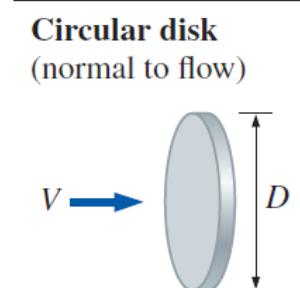
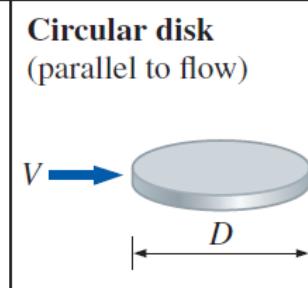
The drag coefficient exhibits different behavior in the low (creeping), moderate (laminar), and high (turbulent) regions of the Reynolds number.

The inertia effects are negligible in low Reynolds number flows ($Re < 1$), called *creeping flows*, and the fluid wraps around the body smoothly.

$$C_D = \frac{24}{Re} \quad (Re \leq 1)$$

$$F_D = C_D A \frac{\rho V^2}{2} = \frac{24}{Re} A \frac{\rho V^2}{2} = \frac{24}{\rho V D / \mu} \frac{\pi D^2}{4} \frac{\rho V^2}{2} = 3\pi \mu V D$$

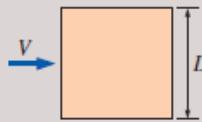
DRAG COEFFICIENTS OF COMMON GEOMETRIES

Sphere  $C_D = 24/\text{Re}$	Hemisphere  $C_D = 22.2/\text{Re}$
Circular disk (normal to flow)  $C_D = 20.4/\text{Re}$	Circular disk (parallel to flow)  $C_D = 13.6/\text{Re}$

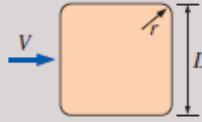
DRAG COEFFICIENTS OF COMMON GEOMETRIES

Drag coefficients C_D of various two-dimensional bodies for $Re > 10^4$ based on the frontal area $A = bD$, where b is the length in direction normal to the page (for use in the drag force relation $F_D = C_D A \rho V^2 / 2$ where V is the upstream velocity)

Square rod

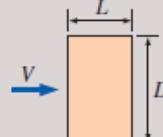


Sharp corners:
 $C_D = 2.2$

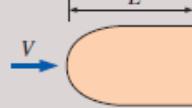


Round corners
($r/D = 0.2$):
 $C_D = 1.2$

Rectangular rod



Sharp corners:



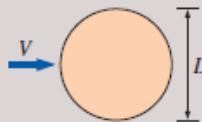
Round front edge:

L/D	C_D
0.0*	1.9
0.1	1.9
0.5	2.5
1.0	2.2
2.0	1.7
3.0	1.3

* Corresponds to thin plate

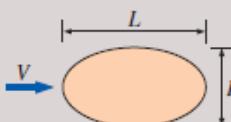
L/D	C_D
0.5	1.2
1.0	0.9
2.0	0.7
4.0	0.7

Circular rod (cylinder)



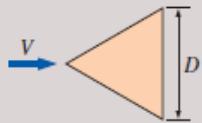
Laminar:
 $C_D = 1.2$
Turbulent:
 $C_D = 0.3$

Elliptical rod

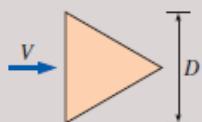


L/D	C_D	
	Laminar	Turbulent
2	0.60	0.20
4	0.35	0.15
8	0.25	0.10

Equilateral triangular rod



$C_D = 1.5$

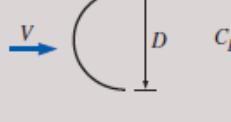


$C_D = 2.0$

Semicircular shell

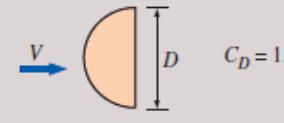


$C_D = 2.3$

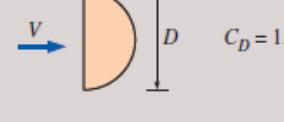


$C_D = 1.2$

Semicircular rod



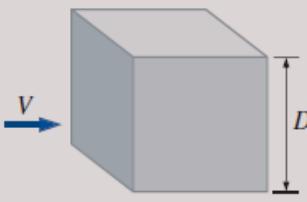
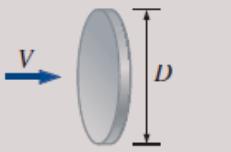
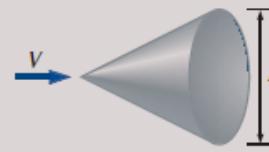
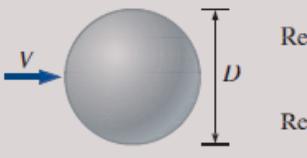
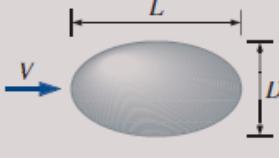
$C_D = 1.2$



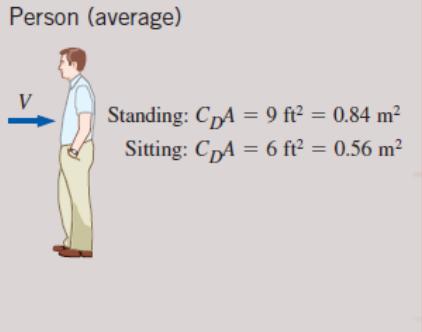
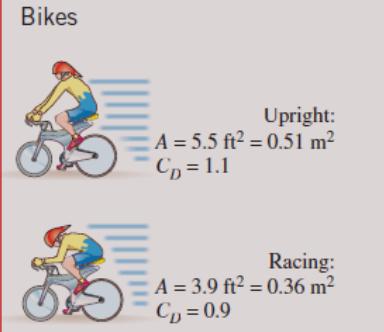
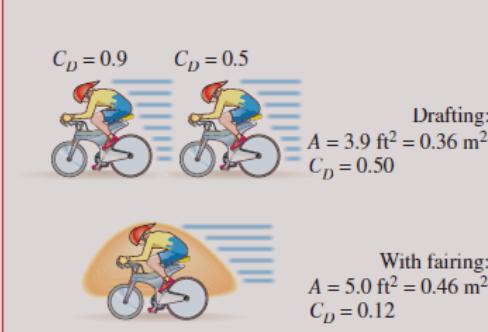
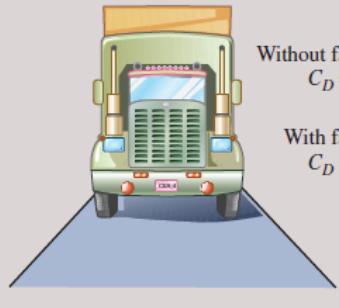
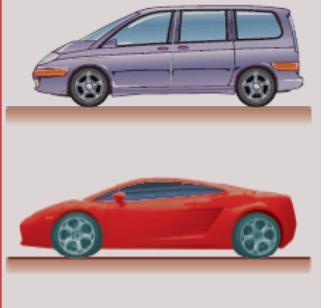
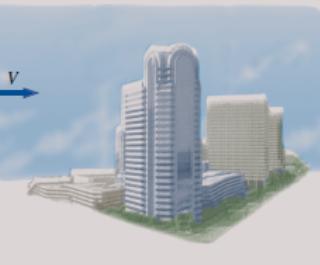
$C_D = 1.7$

DRAG COEFFICIENTS OF COMMON GEOMETRIES

Representative drag coefficients C_D for various three-dimensional bodies based on the frontal area for $Re > 10^4$ unless stated otherwise (for use in the drag force relation $F_D = C_D A \rho V^2 / 2$ where V is the upstream velocity)

Cube, $A = D^2$  $C_D = 1.05$	Thin circular disk, $A = \pi D^2/4$  $C_D = 1.1$	Cone (for $\theta = 30^\circ$), $A = \pi D^2/4$  $C_D = 0.5$																				
Sphere, $A = \pi D^2/4$  Laminar: $Re \approx 2 \times 10^5$ $C_D = 0.5$ Turbulent: $Re \gtrsim 2 \times 10^6$ $C_D = 0.2$ See Fig. 11–36 for C_D vs. Re for smooth and rough spheres.	Ellipsoid, $A = \pi D^2/4$ 	C_D <table border="1"> <thead> <tr> <th rowspan="2">L/D</th> <th colspan="2">C_D</th> </tr> <tr> <th>Laminar $Re \approx 2 \times 10^5$</th> <th>Turbulent $Re \gtrsim 2 \times 10^6$</th> </tr> </thead> <tbody> <tr> <td>0.75</td> <td>0.5</td> <td>0.2</td> </tr> <tr> <td>1</td> <td>0.5</td> <td>0.2</td> </tr> <tr> <td>2</td> <td>0.3</td> <td>0.1</td> </tr> <tr> <td>4</td> <td>0.3</td> <td>0.1</td> </tr> <tr> <td>8</td> <td>0.2</td> <td>0.1</td> </tr> </tbody> </table>	L/D	C_D		Laminar $Re \approx 2 \times 10^5$	Turbulent $Re \gtrsim 2 \times 10^6$	0.75	0.5	0.2	1	0.5	0.2	2	0.3	0.1	4	0.3	0.1	8	0.2	0.1
L/D	C_D																					
	Laminar $Re \approx 2 \times 10^5$	Turbulent $Re \gtrsim 2 \times 10^6$																				
0.75	0.5	0.2																				
1	0.5	0.2																				
2	0.3	0.1																				
4	0.3	0.1																				
8	0.2	0.1																				

DRAG COEFFICIENTS OF COMMON GEOMETRIES

<p>Person (average)</p>  <p>Standing: $C_D A = 9 \text{ ft}^2 = 0.84 \text{ m}^2$ Sitting: $C_D A = 6 \text{ ft}^2 = 0.56 \text{ m}^2$</p>	<p>Bikes</p>  <p>Upright: $A = 5.5 \text{ ft}^2 = 0.51 \text{ m}^2$ $C_D = 1.1$</p> <p>Racing: $A = 3.9 \text{ ft}^2 = 0.36 \text{ m}^2$ $C_D = 0.9$</p>	 <p>$C_D = 0.9$ $C_D = 0.5$ Drafting: $A = 3.9 \text{ ft}^2 = 0.36 \text{ m}^2$ $C_D = 0.50$</p>  <p>With fairing: $A = 5.0 \text{ ft}^2 = 0.46 \text{ m}^2$ $C_D = 0.12$</p>
<p>Semitrailer, A = frontal area</p>  <p>Without fairing: $C_D = 0.96$</p> <p>With fairing: $C_D = 0.76$</p>	<p>Automotive, A = frontal area</p>  <p>Minivan: $C_D = 0.4$</p> <p>Passenger car or sports car: $C_D = 0.3$</p>	<p>High-rise buildings, A = frontal area</p> <p>$C_D \approx 1.0$ to 1.4</p> 

Turbines

A turbine extracts energy from a fluid which possesses high head. There are two types, reaction and impulse, the difference lying in the manner of head conversion. In the reaction turbine, the fluid fills the blade passages, and the head change or pressure drop occurs within the impeller. Reaction designs are of the radial-flow, mixed-flow, and axial-flow types and are essentially dynamic devices designed to admit the high-energy fluid and extract its momentum. *An impulse turbine first converts the high head through a nozzle into a high- velocity jet, which then strikes the blades at one position as they pass by.* The impeller passages are not fluid-filled, and the jet flow past the blades is essentially at constant pressure. Reaction turbines are smaller because fluid fills all the blades at one time.

Turbines

Turbine parameters are dependent on the output brake horsepower, which depends upon the inlet flow rate Q , available head H , impeller speed n , and diameter D . The efficiency is the output brake horsepower divided by the available water horsepower $\rho \boxed{?} g Q H$. The dimensionless forms are C_Q , C_H , and C_P , defined just as for a pump, Eqs. (11.23). If we neglect Reynolds-number and roughness effects, the functional relationships are written with C_P as the independent variable:

$$C_H = C_H(C_P) \quad C_Q = C_Q(C_P) \quad \eta = \frac{\text{bhp}}{\rho g Q H} = \eta(C_P)$$

Turbines

Power Specific Speed

Rigorous form:

$$N'_{sp} = \frac{C_P^*^{1/2}}{C_H^*^{5/4}} = \frac{n(\text{bhp})^{1/2}}{\rho^{1/2}(gH)^{5/4}}$$

Lazy but common:

$$N_{sp} = \frac{(\text{r/min})(\text{bhp})^{1/2}}{[H \ (\text{ft})]^{5/4}}$$

Turbines- Pelton Wheel

Power Specific Speed

$$F = \rho Q(V_j - u)(1 - \cos \beta)$$

$$P = Fu = \rho Qu(V_j - u)(1 - \cos \beta)$$

$$u^* = 2\pi n^* r = \frac{1}{2}V_j$$

$$V_j = C_v(2gH)^{1/2} \quad 0.92 \leq C_v \leq 0.98$$

Turbine efficiency $\eta = 2(1 - \cos \beta)\phi(C_v - \phi)$

$\phi = \frac{u}{(2gH)^{1/2}}$ = peripheral-velocity factor

Course Outline

- **Introduction – safety, lab reports, plotting, error analysis, signal processing, lab-specific hardware/software data acquisition, measurement devices, engineering principles**
- **Laboratory Experiments**
 1. Wind Tunnel
 2. Viscous Pipe Flow
 3. Heat Exchanger
 4. Cross-Section Fin
 5. Pelton Wheel
- **Design Project Presentation and Report**
- **Final Exam**

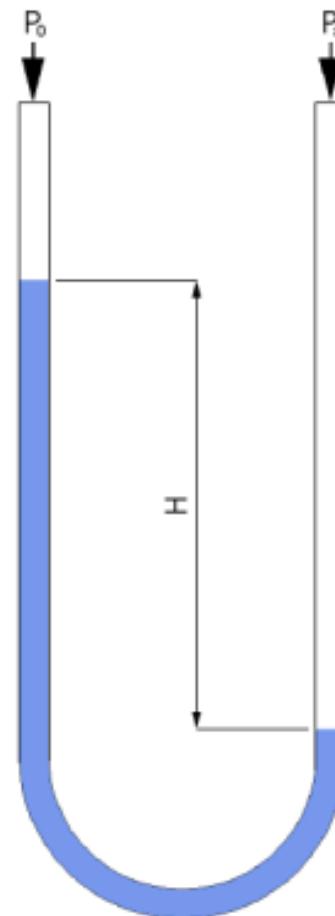
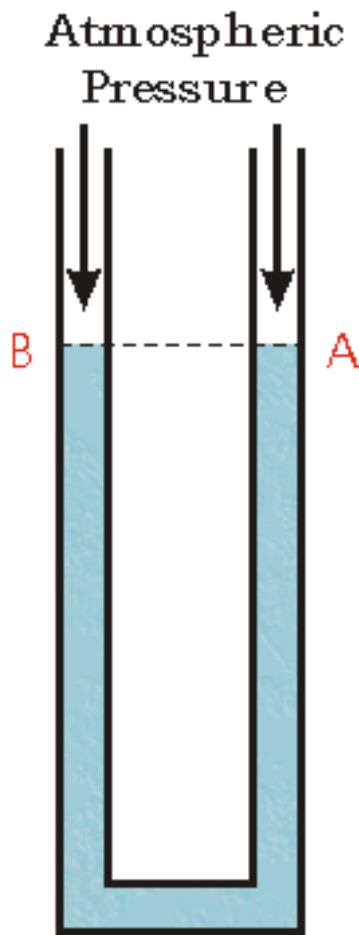


Measurement Devices

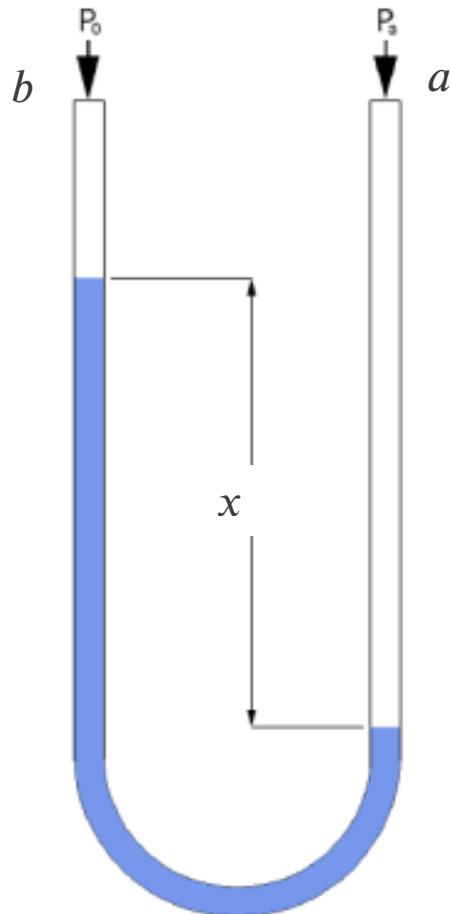
Physical Instruments

- Manometers
- Pitot Tubes
- Venturi Meters
- Thermocouples

Manometer



Manometer



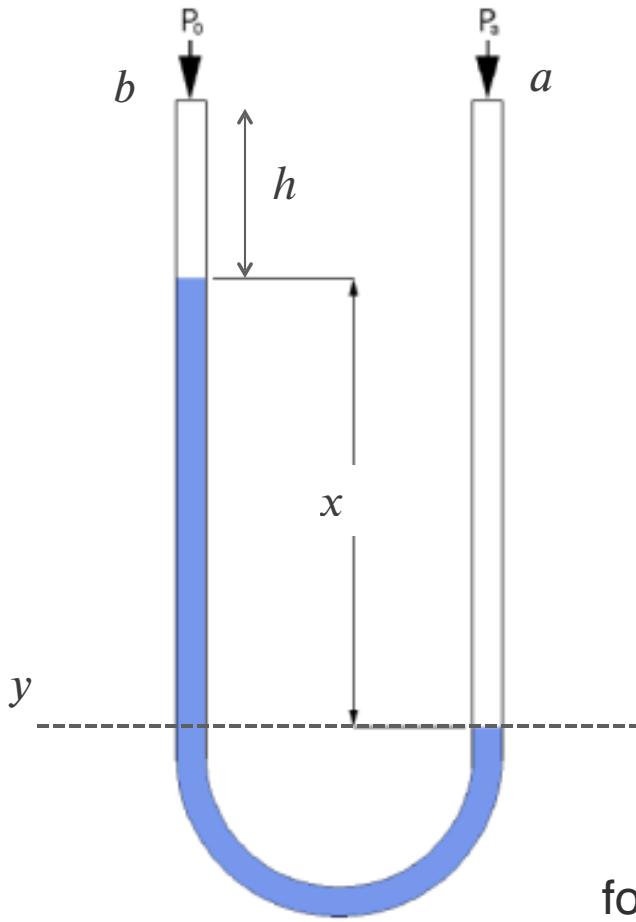
$$P_{a,tot} + \frac{1}{2} \rho_a v_a^2 + \rho_a g h_a = \text{const}$$

Keep in mind dynamic pressure and total pressure

$$P_{a,tot} = P_0 + P_a$$

$$P_b - P_a = ?$$

Manometer



$$P_{a,y} = P_{b,y}$$

$$P_{a,y} = P_0 + P_a + \rho_a g(h + x)$$

$$P_{b,y} = P_0 + P_b + \rho_a gh + \rho_b gx$$

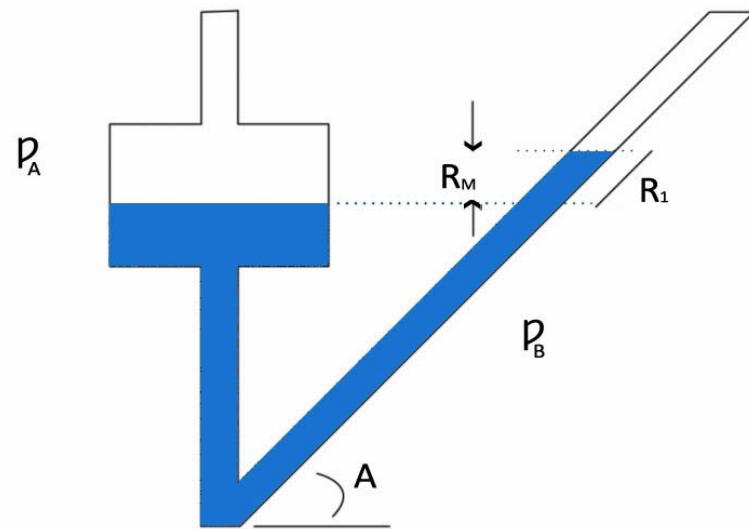
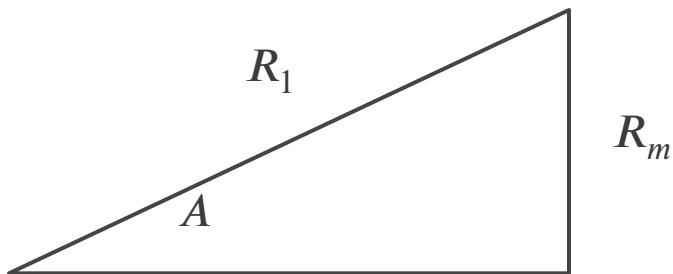
$$P_b - P_a = \rho_a gx - \rho_b gx = gx(\rho_a - \rho_b)$$

$$P_{a,y} = P_{b,y}$$

for continuous fluid

$$P_b - P_a = gx(\rho_a - \rho_b)$$

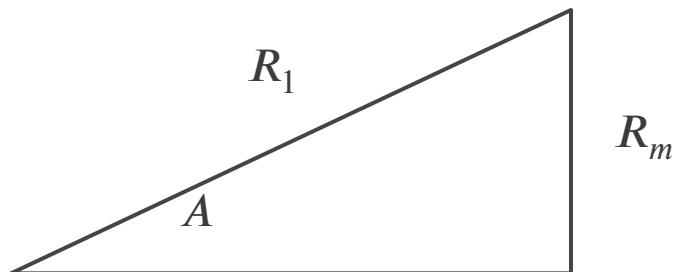
Manometer



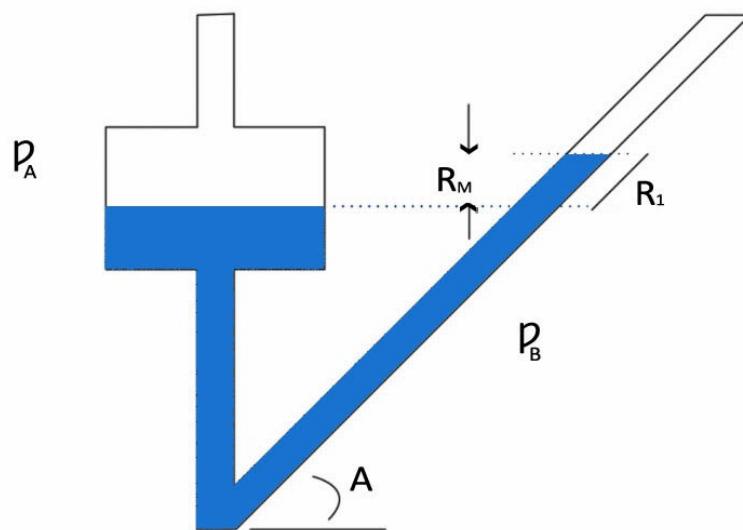
$$R_M = R_1 \cdot \sin A$$

$$P_A - P_B = ?$$

Manometer



$$R_M = R_1 \cdot \sin A$$

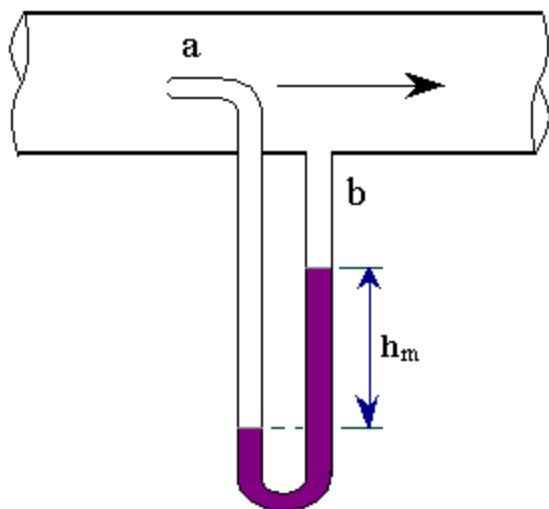


$$P_A - P_B = R_1 \cdot \sin(A) \cdot g \cdot (P_B - P_A)$$

P_A DENSITY OF FLUID A

P_B DENSITY OF MANOMETRIC FLUID B

Pitot Tube

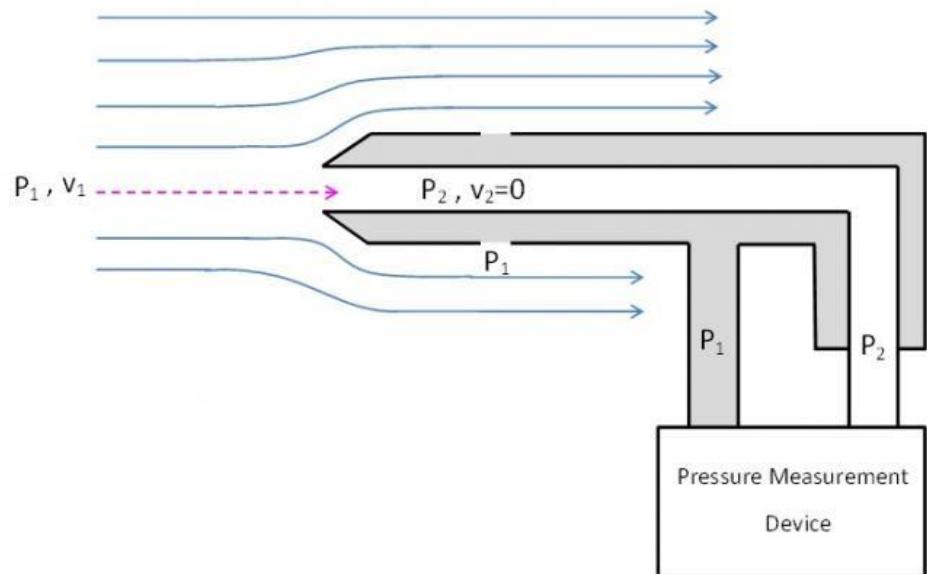
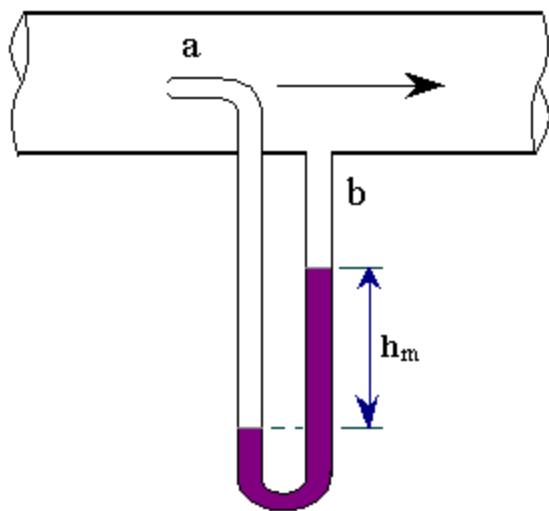


Simple Pitot
tube

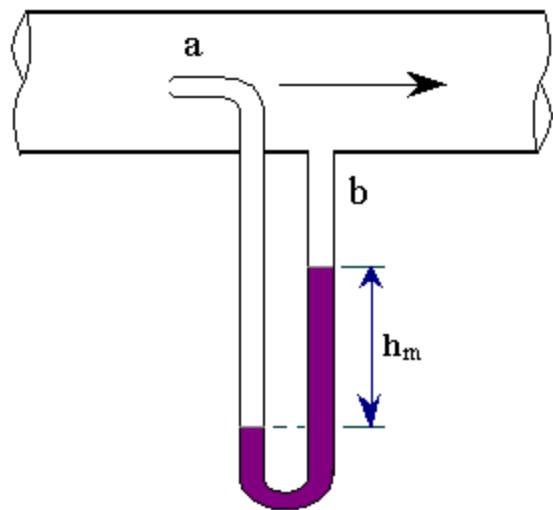
Static
source

Pitot-static
tube

Pitot Tube

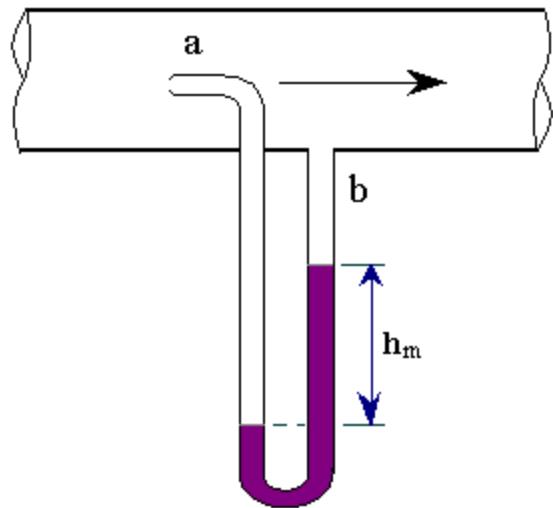


Pitot Tube



Using Bernoulli → Calculate velocity

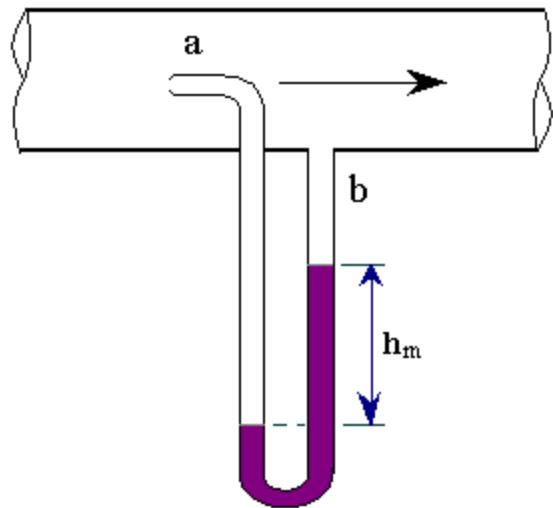
Pitot Tube



For measurement at static point in bend:

$$P_a = P_{static} + \frac{1}{2}\rho_a v_a^2$$

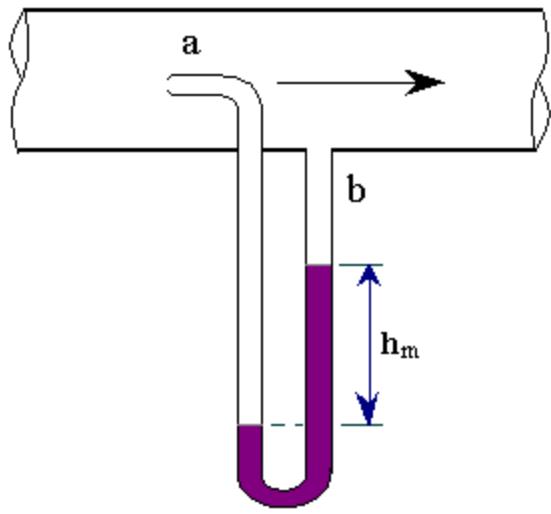
Pitot Tube



Static pressure (b):

$$P_b = P_{static} = P_a + gh(\rho_a - \rho_b)$$

Pitot Tube



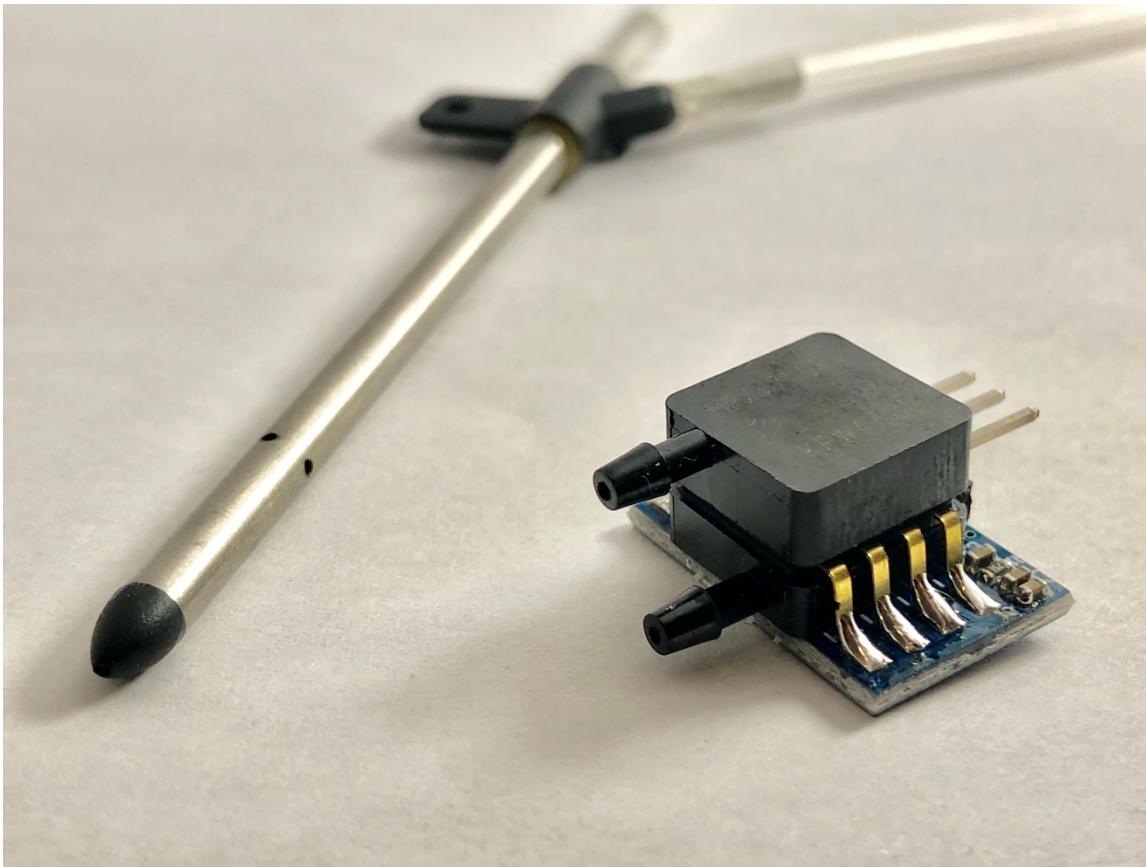
Velocity:

$$P_a = P_{static} + \frac{1}{2}\rho_a v_a^2$$

$$v_a = \sqrt{\frac{2(P_a - P_{static})}{\rho_a}}$$

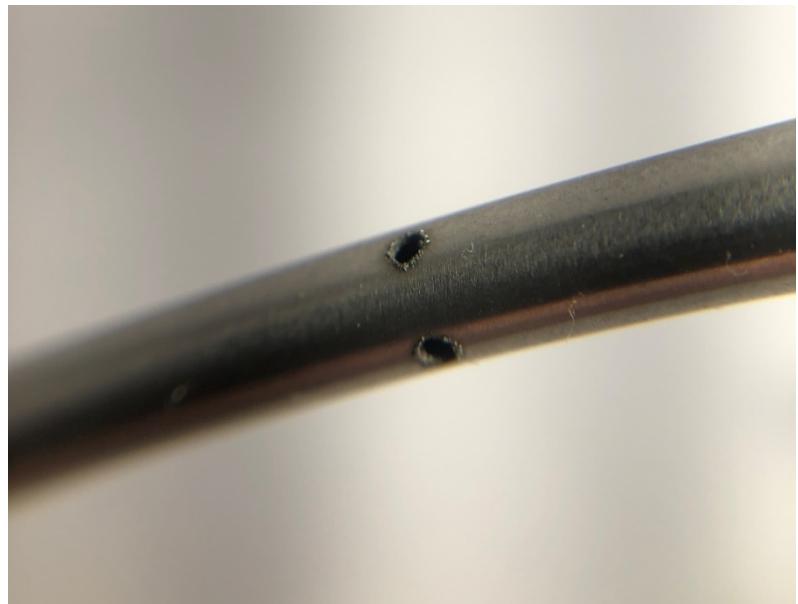
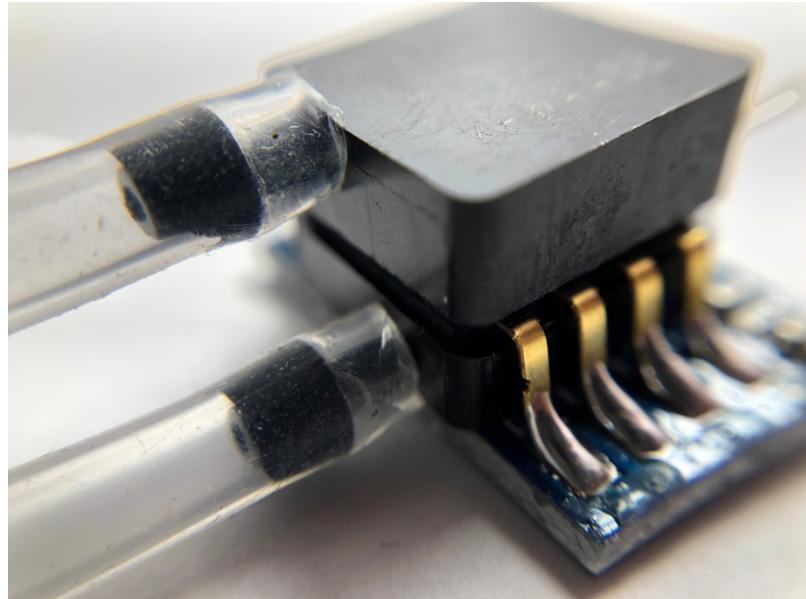
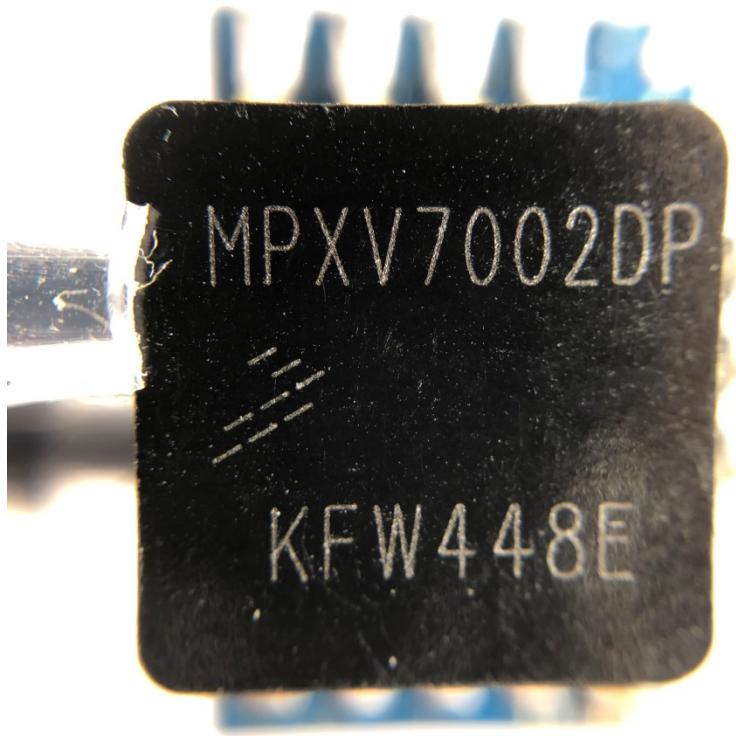
$$v_a = \sqrt{\frac{2gh(\rho_b - \rho_a)}{\rho_a}}$$

Pitot Tube Example



Velocity:

$$v_a = \sqrt{\frac{2(P_a - P_{static})}{\rho_a}}$$



Pitot Tube Example

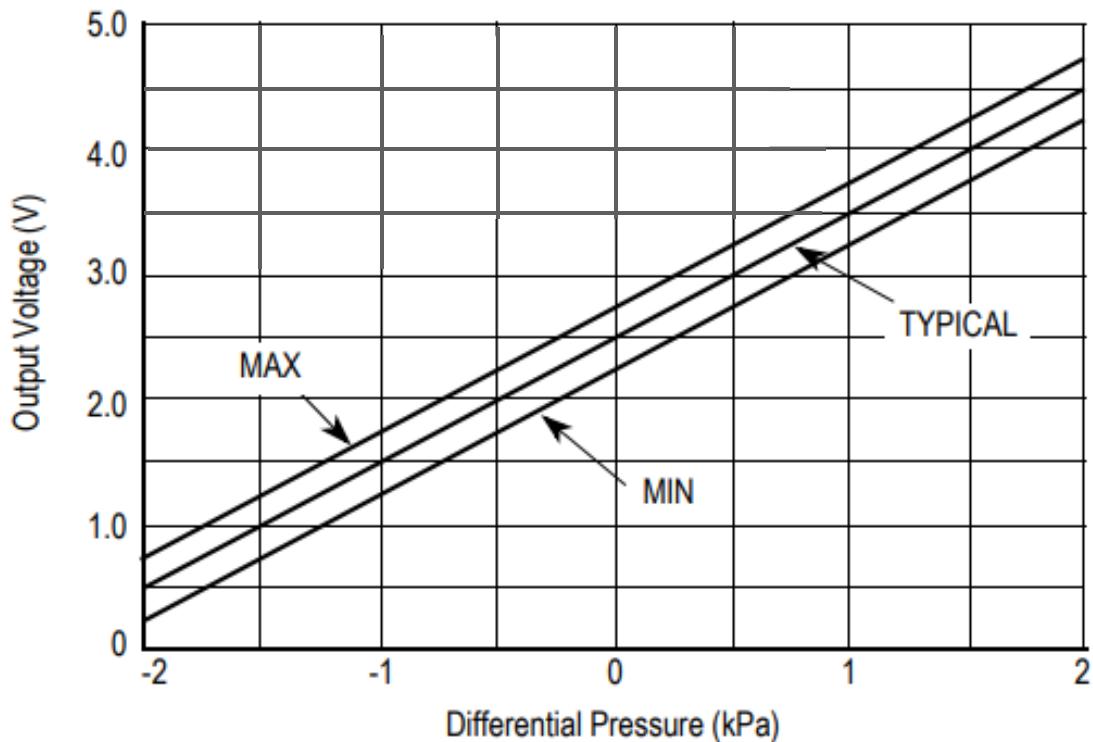


Figure 4. Output versus Pressure Differential

Velocity:

$$v_a = \sqrt{\frac{2(P_a - P_{static})}{\rho_a}}$$

Create a relationship between differential pressure and voltage output

Pitot Tube Example

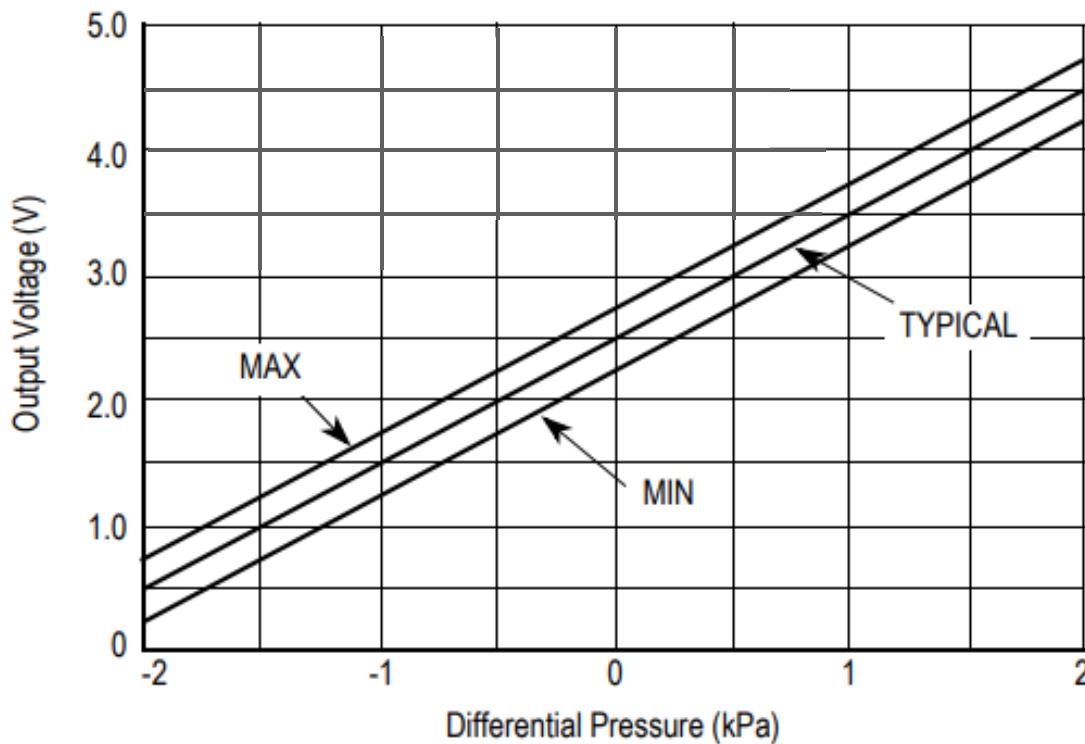


Figure 4. Output versus Pressure Differential

$$y = mx + b$$

$$y = 2.5, \quad x = 0$$

$$y = 0.5, \quad x = -2$$

Pitot Tube Example

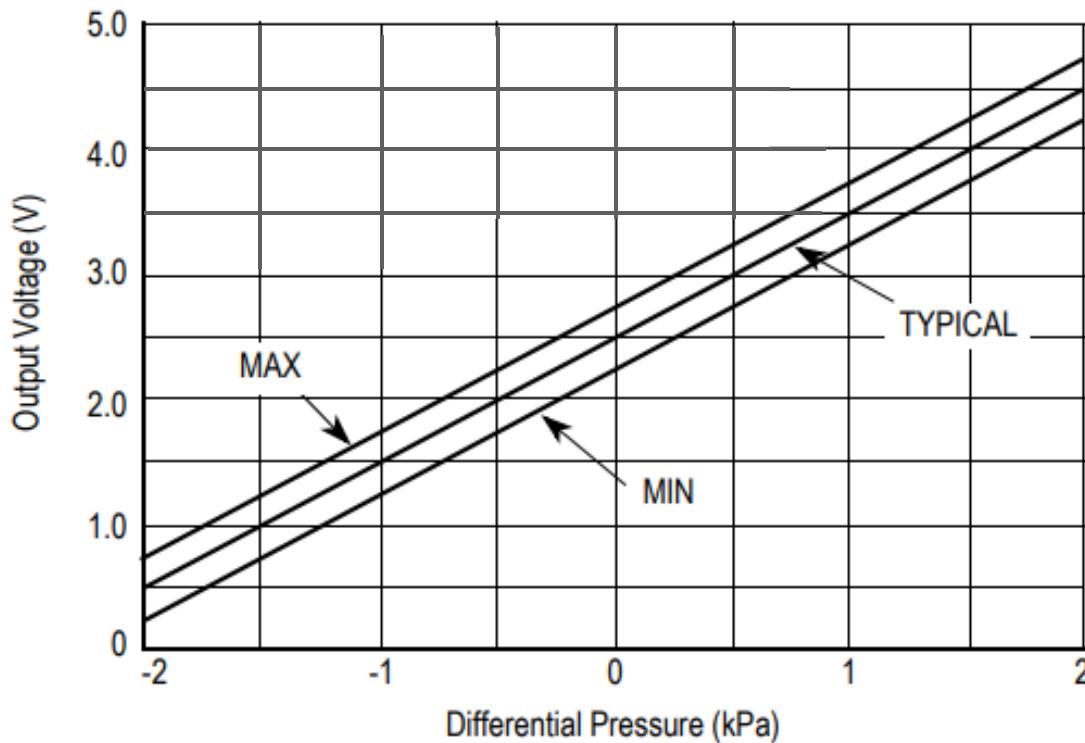


Figure 4. Output versus Pressure Differential

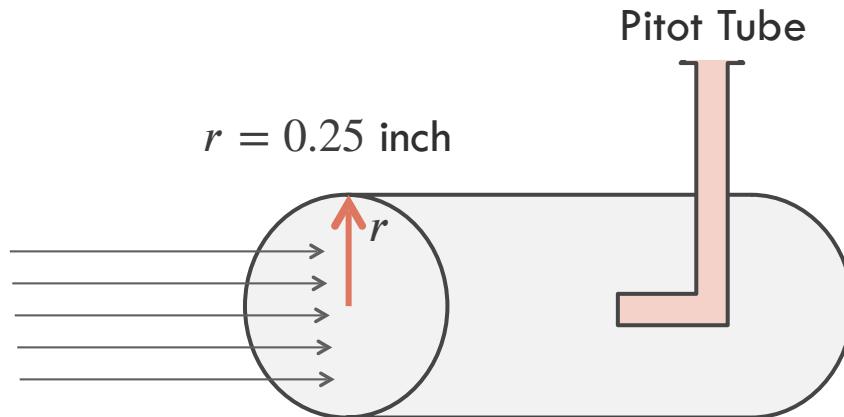
$$y = x + 2.5$$

$$V_{out} = \Delta P + 2.5$$

$$1000\Delta P = V_{out} - 2.5$$

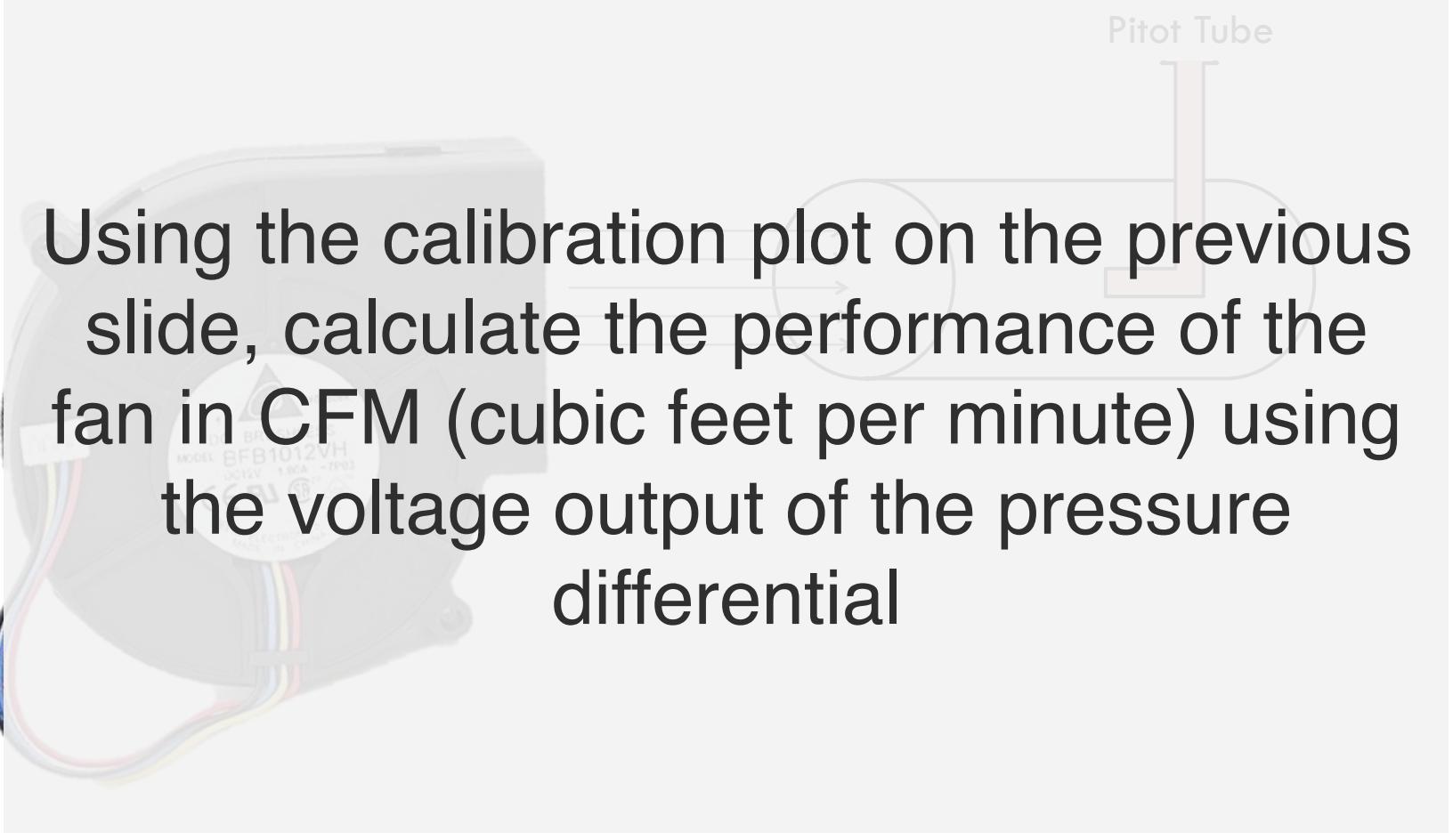
$$v_a = \sqrt{\frac{2000(V_{out} - 2.5)}{\rho_a}}$$

Pitot Tube Example



Pitot tube is measuring voltage difference between static port and velocity inlet port

Pitot Tube Example



Using the calibration plot on the previous slide, calculate the performance of the fan in CFM (cubic feet per minute) using the voltage output of the pressure differential

Arduino Bit Conversion

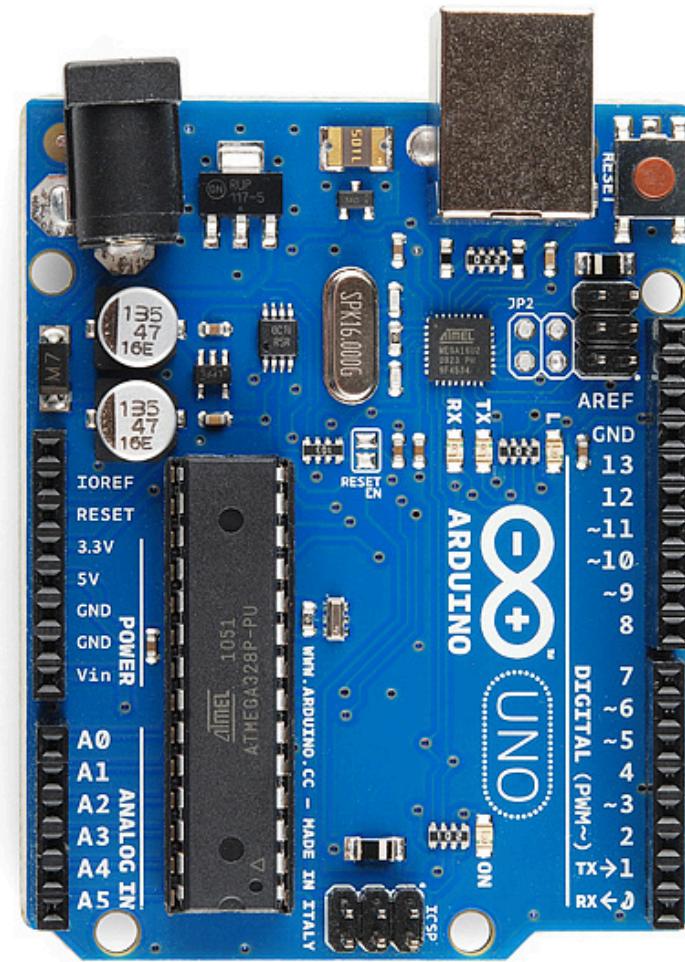
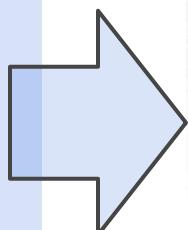
- Readings are 10-bits
- Voltage range of ADC is 0-5V

Arduino Board

ADC Resolution = 10-bit

Measurement Range = 0V-5V

$$Q = \frac{5V}{2^{10}} = 4.9\text{mV/bit}$$



Pitot Tube Example

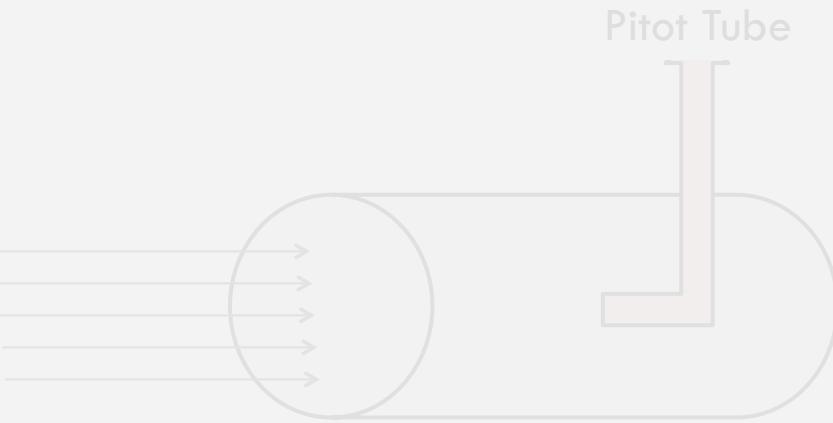
$$Q = \text{CFM} \cdot \frac{\text{ft}^3}{\text{min}} \cdot \frac{\text{min}}{60\text{sec}} \cdot \frac{\text{m}^3}{3.28^3 \cdot \text{ft}^3}$$

Pitot Tube

$Q \equiv$ volumetric flow rate = vA

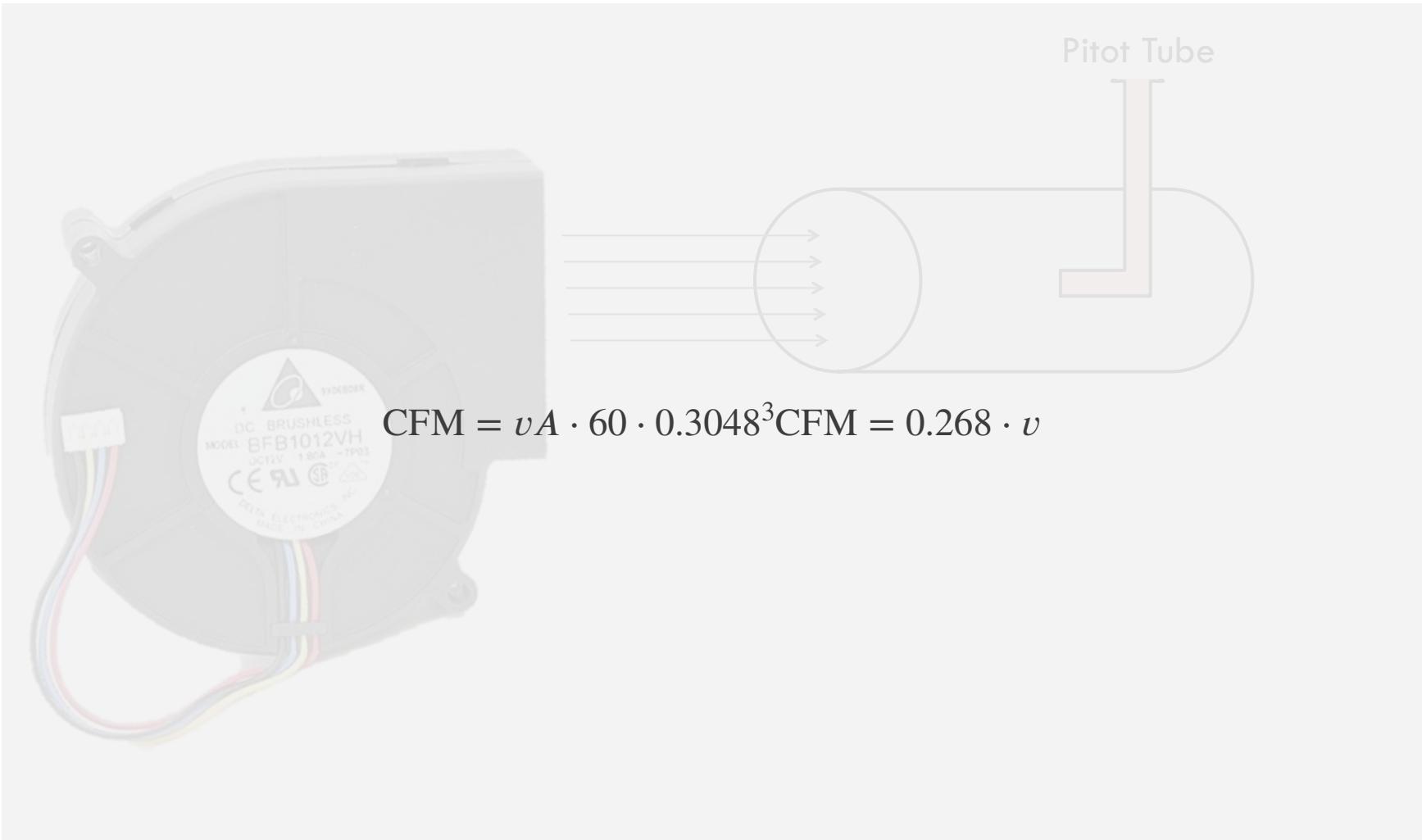
$A \equiv$ pipe area $v \equiv$ mean flow velocity

Pitot Tube Example

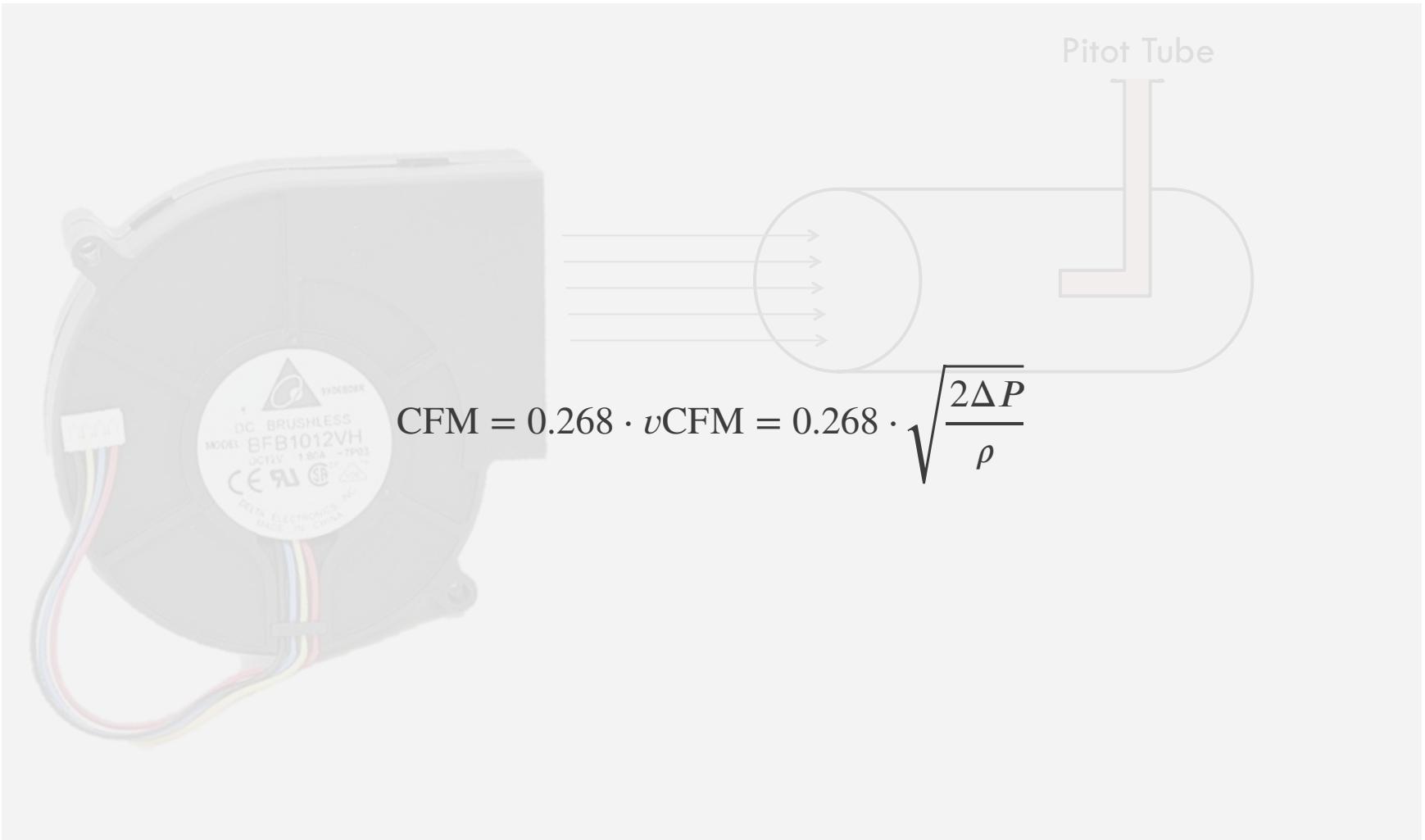


$$\text{CFM} = vA \cdot 60 \cdot 3.28^3$$
$$\text{CFM} = 2117.25\pi r^2 \cdot vr = 0.25 \text{ in.} \cdot 1 \text{ in.} = 0.0254 \text{ m}$$
$$r = 0.00635 \text{ m}$$

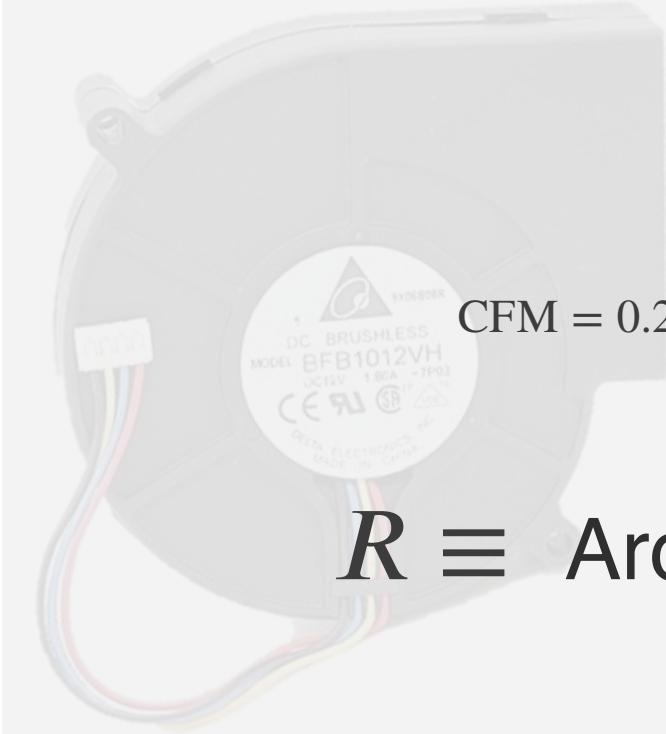
Pitot Tube Example



Pitot Tube Example



Pitot Tube Example

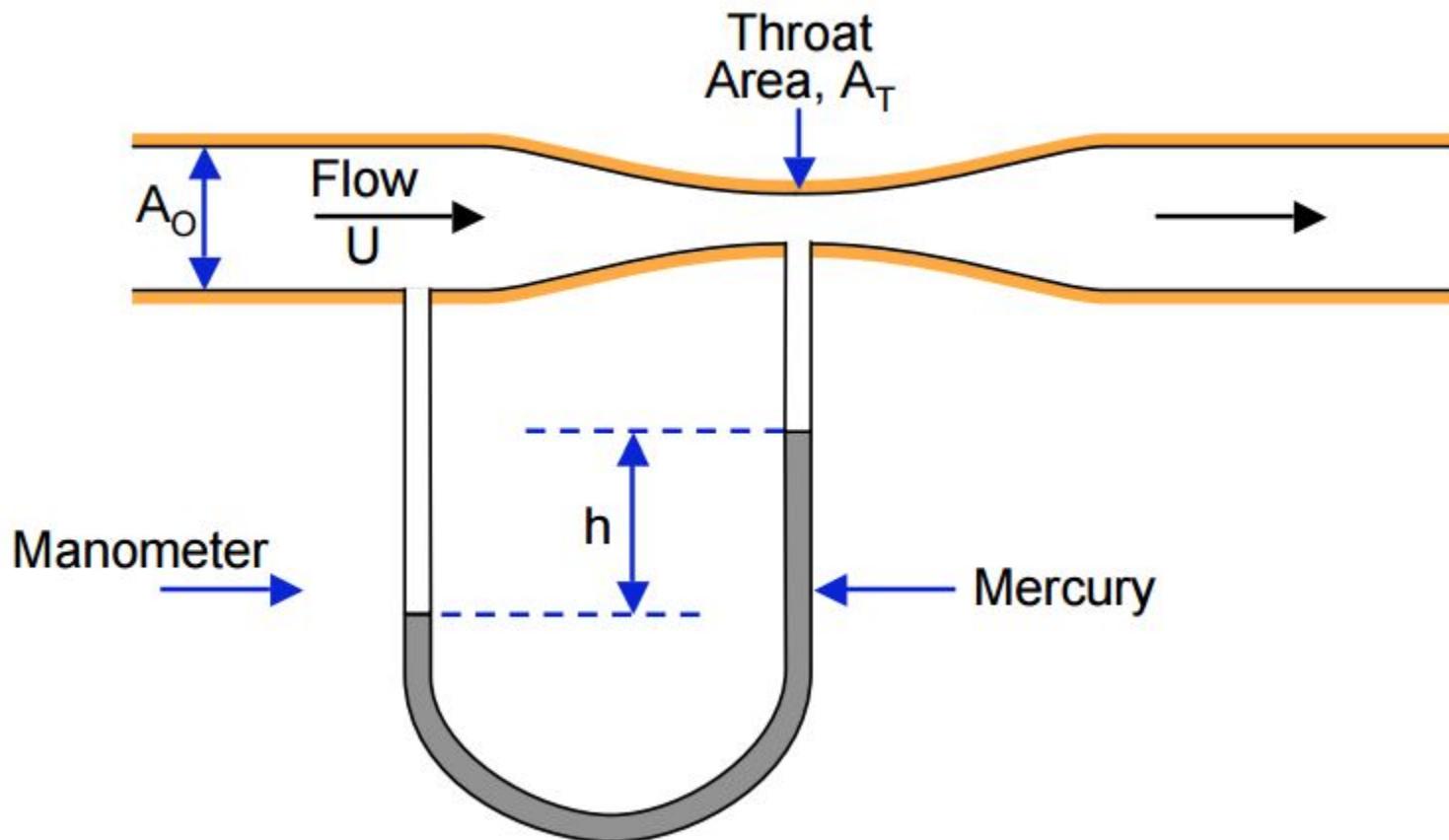


A photograph of a DC brushless fan is positioned on the left side of the slide. The fan's label is visible, showing "DC BRUSHLESS MODEL BFB1012VH 12V 1.00A -TP03 CE UL CB". To the right of the fan is a schematic diagram of a pitot tube. The diagram shows a horizontal pipe with a T-shaped pitot tube inserted into it. Air is shown flowing from left to right through the pipe. The formula for calculating CFM is displayed above the pitot tube diagram.

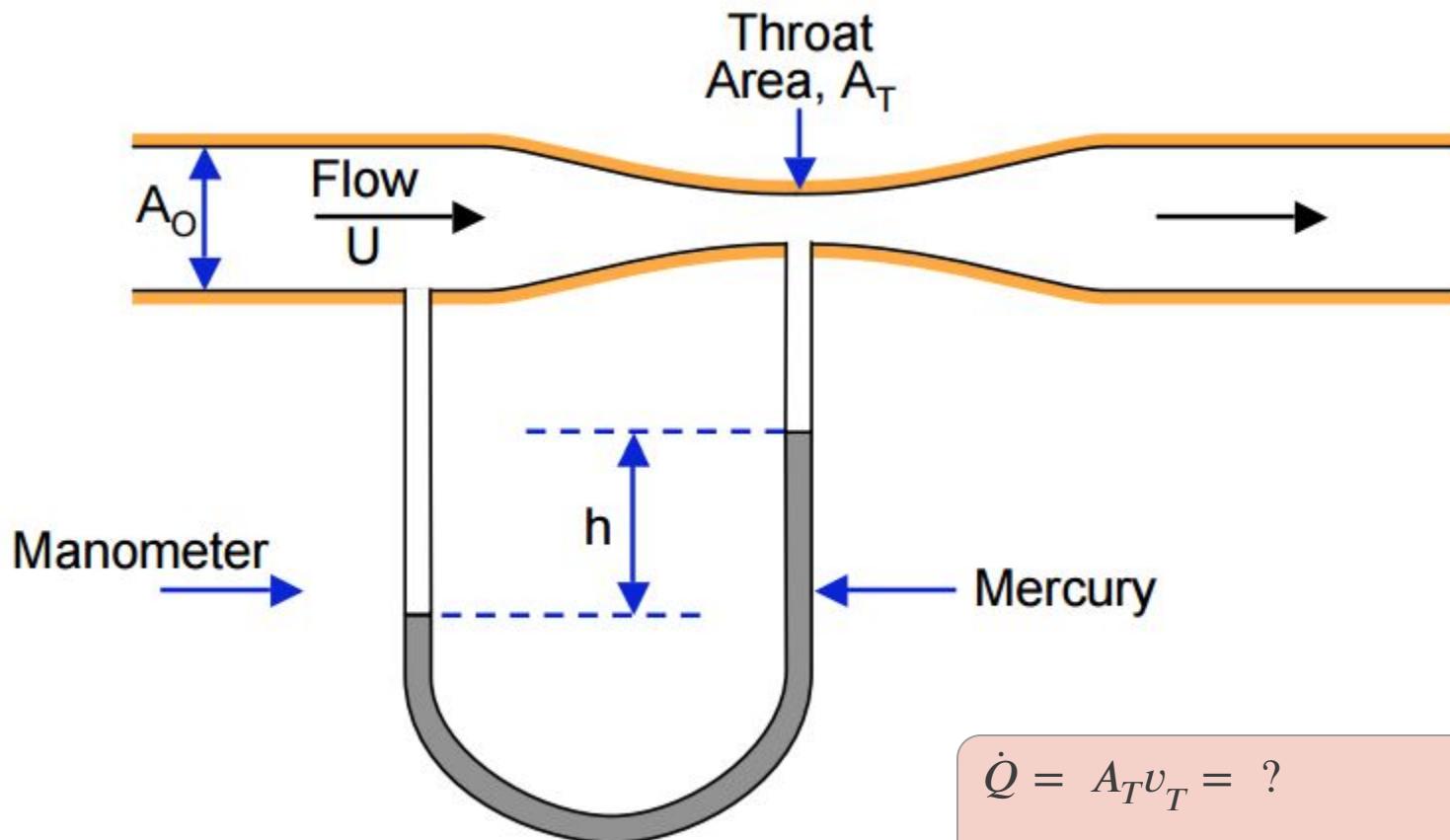
$$\text{CFM} = 0.268 \cdot v$$
$$\text{CFM} = 0.268 \cdot \sqrt{\frac{2000 \left(\left(\frac{5.0 \cdot R}{1023.0} \right) - 2.5 \right)}{\rho_a}}$$

$R \equiv$ Arduino 10-bit reading

Venturi Meter

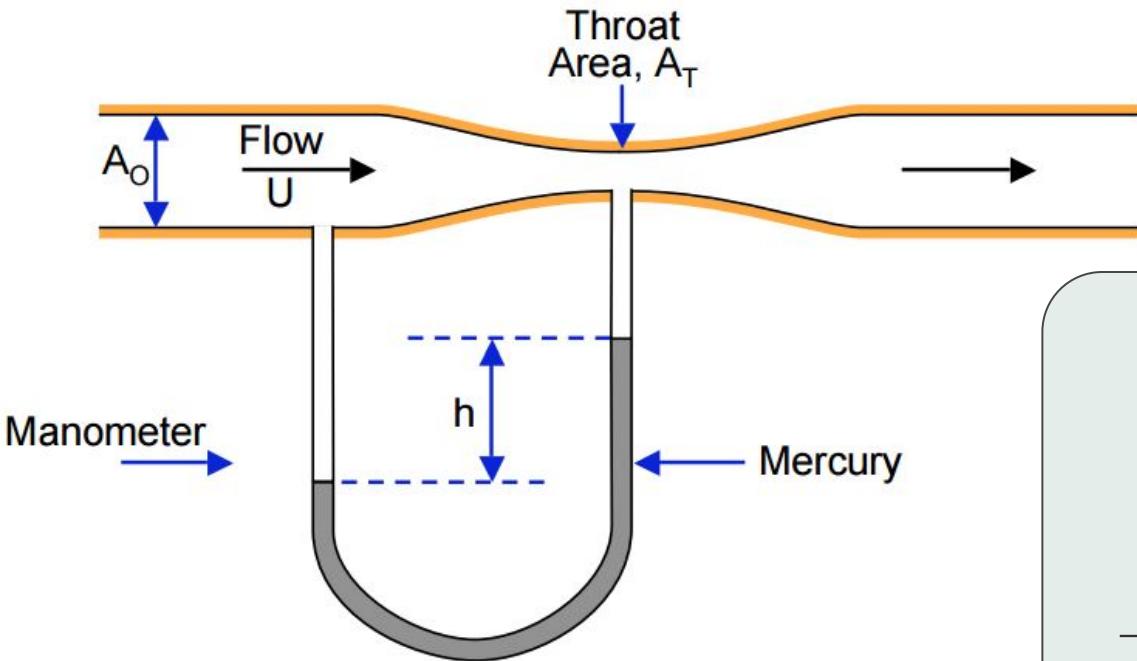


Venturi Meter



$$\dot{Q} = A_T v_T = ?$$

Venturi Meter

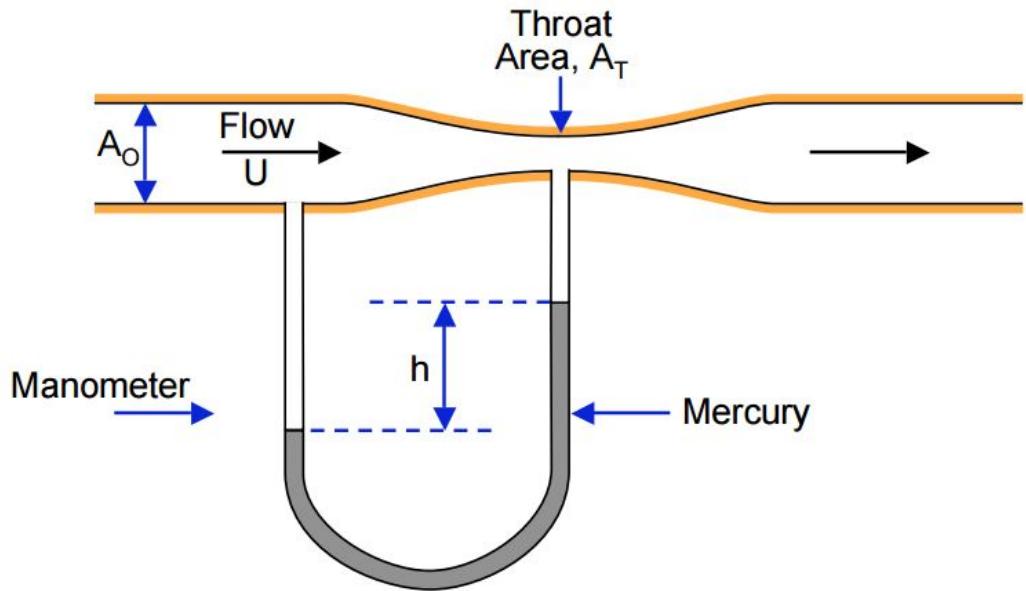


Bernoulli's equation

$$\begin{aligned} P_{0,tot} + \frac{1}{2}\rho_0 v_0^2 + \rho_0 g h_0 \\ = P_{T,tot} + \frac{1}{2}\rho_T v_T^2 + \rho_T g h_T \end{aligned}$$

Conservation equation:

$$A_0 v_0 = A_T v_T$$



Bernoulli's equation

$$P_{0,tot} + \frac{1}{2}\rho_0 v_0^2 + \rho_0 g h_0 = P_{T,tot} + \frac{1}{2}\rho_T v_T^2 + \rho_T g h_T$$

Conservation equation:

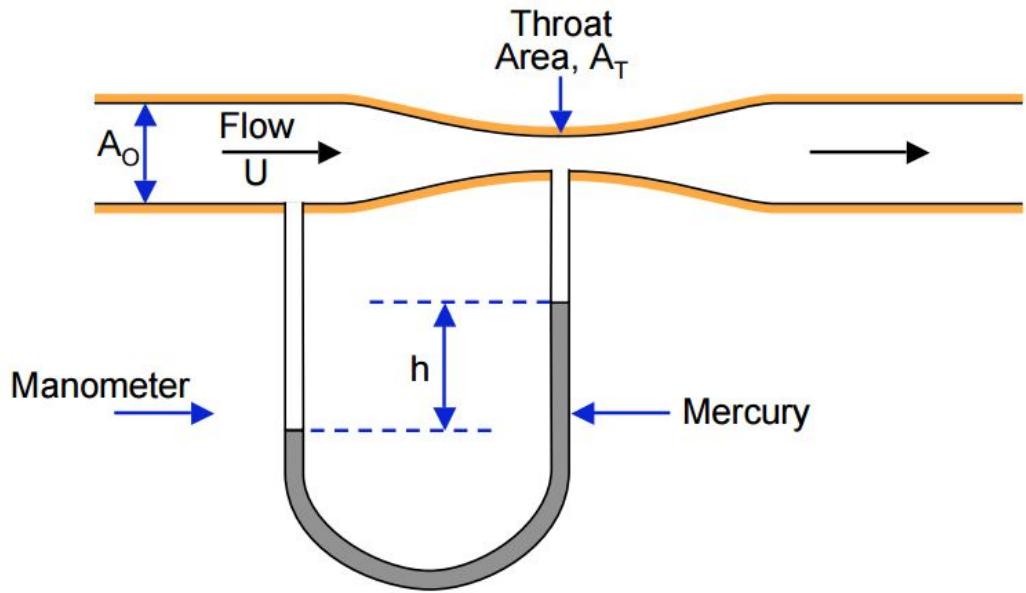
$$A_0 v_0 = A_T v_T$$

$$P_{0,tot} + \frac{1}{2}\rho_0 v_0^2 = P_{T,tot} + \frac{1}{2}\rho_0 v_T^2$$

$$P_0 - P_T = \frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 v_0^2$$

$$P_0 - P_T = gh(\rho_m - \rho_0)$$

$$\frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 v_0^2 = gh(\rho_m - \rho_0)$$



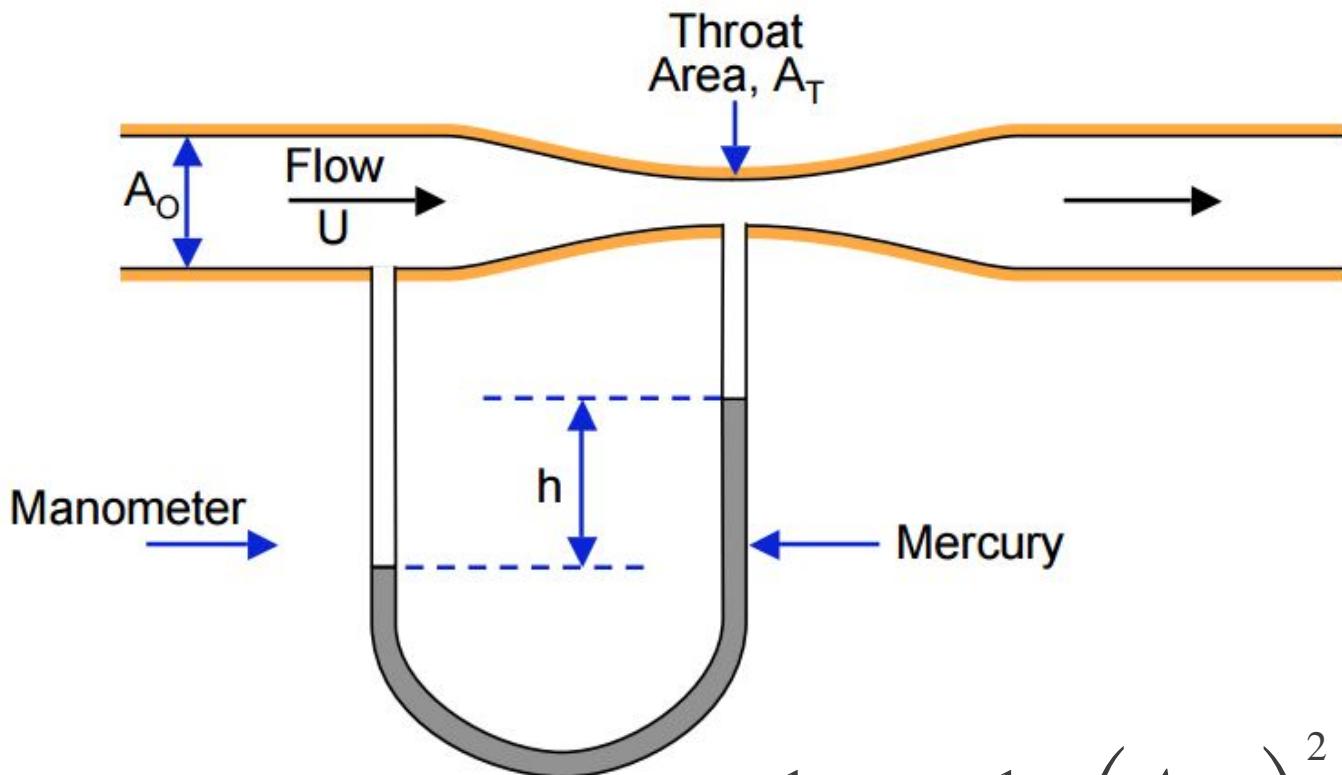
Bernoulli's equation

$$P_{0,tot} + \frac{1}{2}\rho_0 v_0^2 + \rho_0 g h_0 = P_{T,tot} + \frac{1}{2}\rho_T v_T^2 + \rho_T g h_T$$

Conservation equation:

$$A_0 v_0 = A_T v_T$$

$$\left. \begin{aligned} P_{0,tot} + \frac{1}{2}\rho_0 v_0^2 &= P_{T,tot} + \frac{1}{2}\rho_0 v_T^2 \\ P_0 - P_T &= \frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 v_0^2 \\ P_0 - P_T &= gh(\rho_m - \rho_0) \\ \frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 v_0^2 &= gh(\rho_m - \rho_0) \end{aligned} \right\} \quad \frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 \left(\frac{A_T}{A_0} v_T \right)^2 = gh(\rho_m - \rho_0)$$



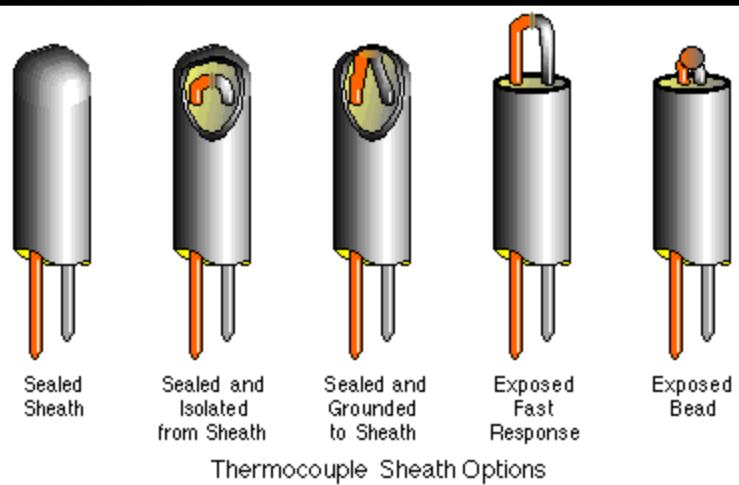
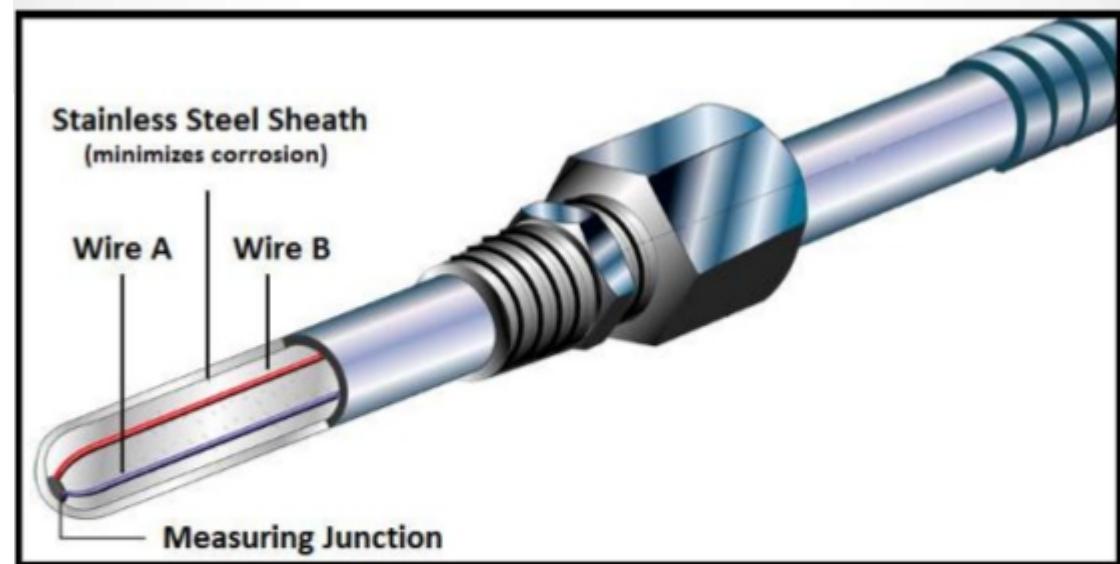
$$\frac{1}{2}\rho_0 v_T^2 - \frac{1}{2}\rho_0 \left(\frac{A_T}{A_0} v_T \right)^2 = gh(\rho_m - \rho_0)$$

$$\dot{Q} = A_T v_T = A_T \sqrt{\frac{2gh(\rho_m - \rho_0)}{\rho_0 \left(1 - \left(\frac{A_T}{A_0} \right)^2 \right)}}$$

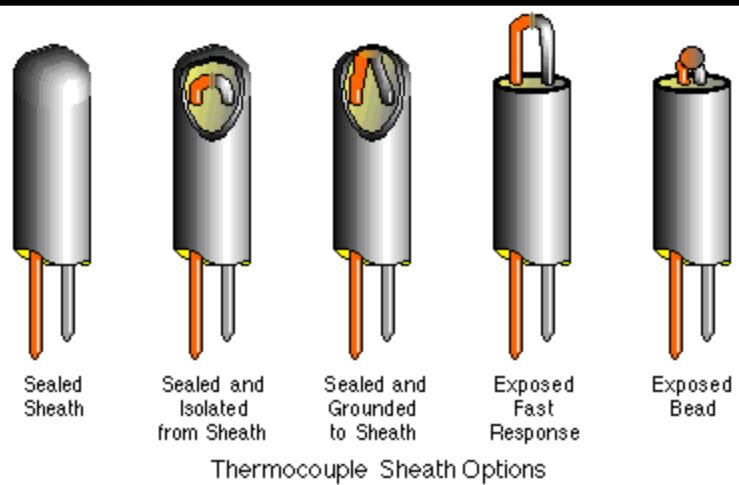
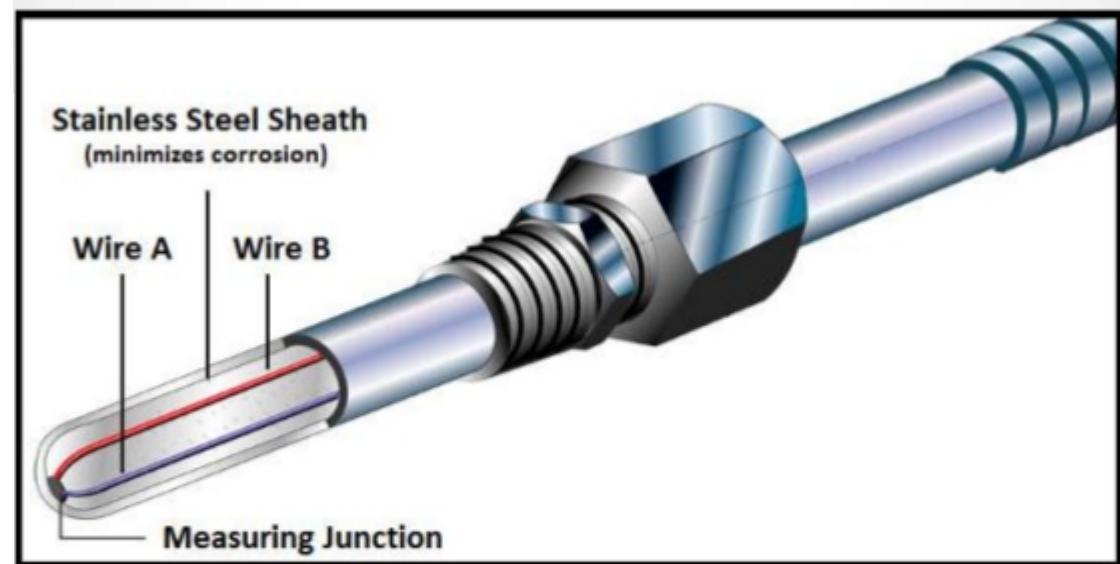
$$v_T^2 \left(1 - \left(\frac{A_T}{A_0} \right)^2 \right) = \frac{2gh(\rho_m - \rho_0)}{\rho_0}$$

$$v_T = \sqrt{\frac{2gh(\rho_m - \rho_0)}{\left(1 - \left(\frac{A_T}{A_0} \right)^2 \right)}}$$

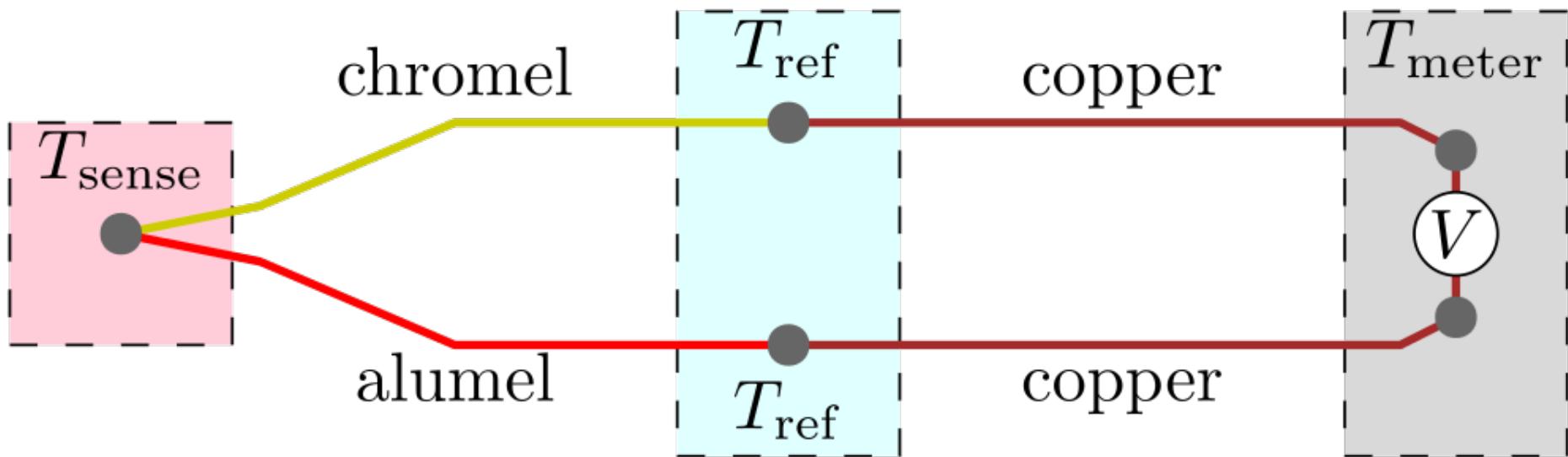
Thermocouples



Thermocouples

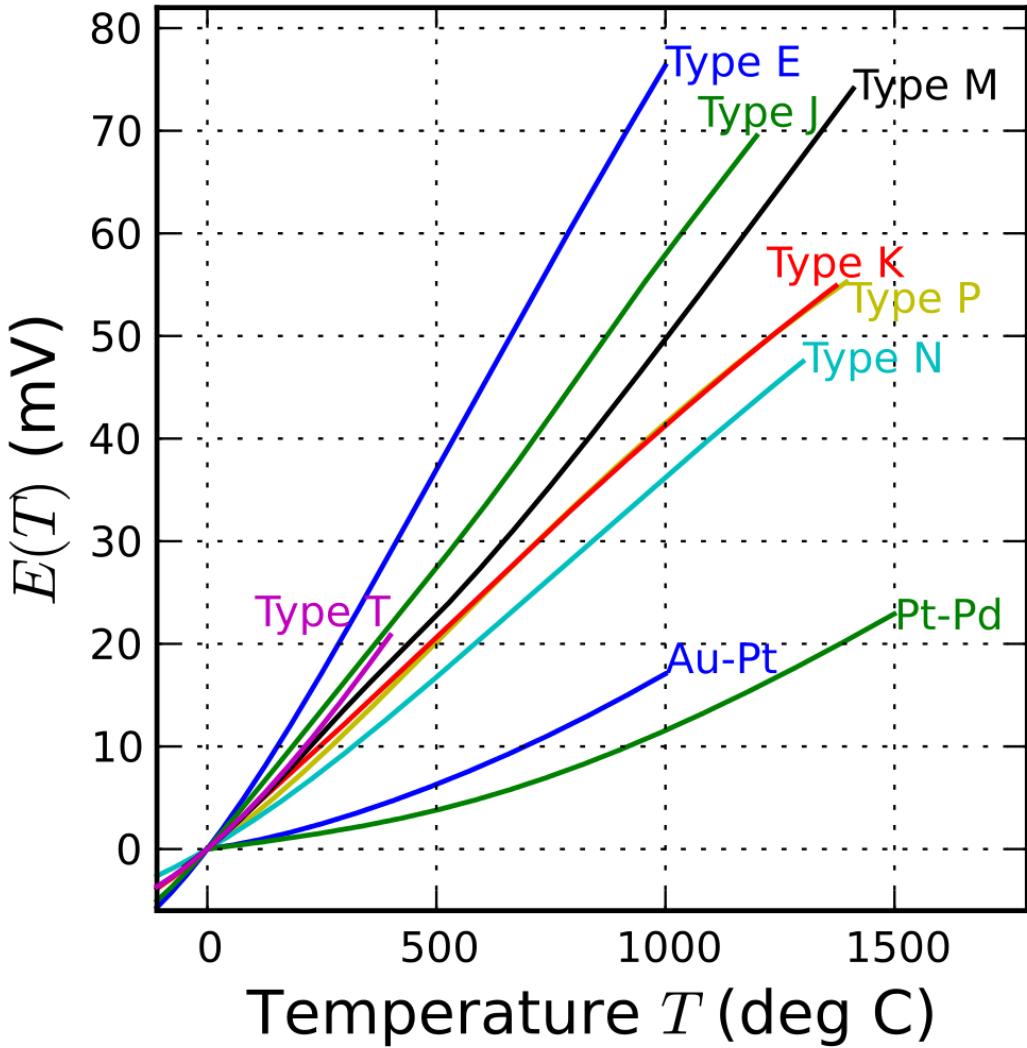


Thermocouples



Temperature → Voltage

Thermocouples



$$V = E(T_{sense}) - E(T_{ref})$$

$$E(T_{sense}) = V + E(T_{ref})$$

Measured
Reference junction
sensor



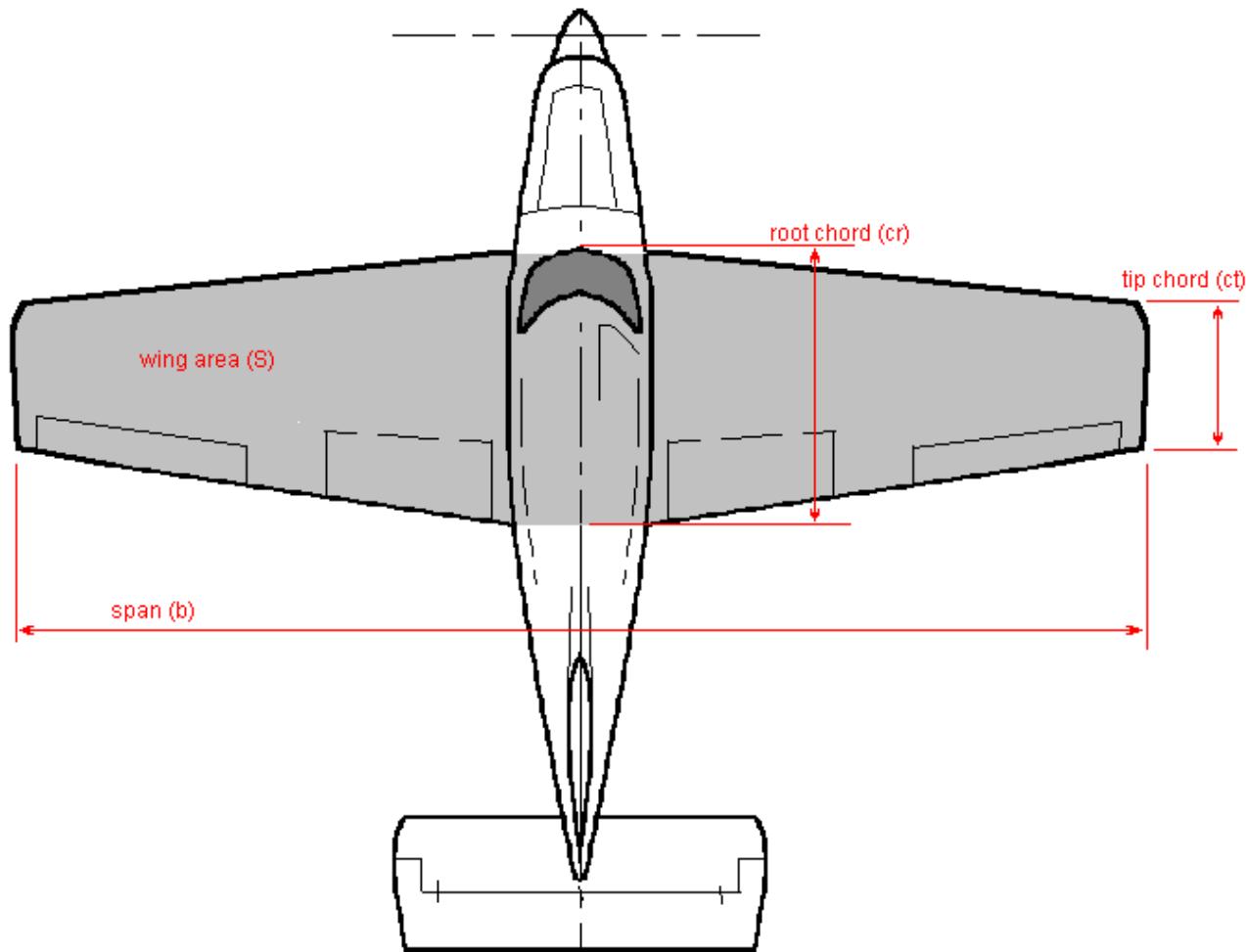
Engineering Refreshers

Engineering Refreshers

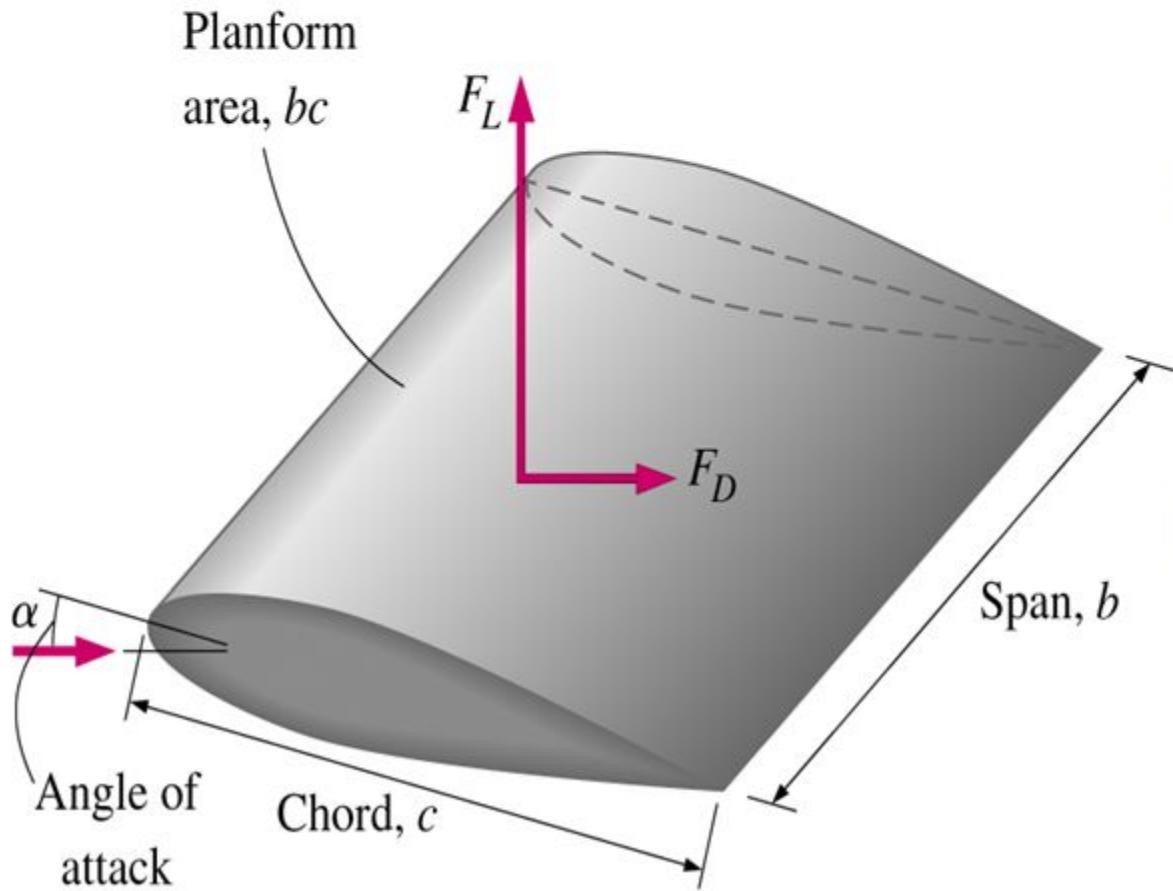
Laboratory Experiments

1. Wind Tunnel - aerodynamics
2. Viscous Pipe Flow – fluid dynamics
3. Heat Exchanger – heat transfer
4. Cross-Section Fin – heat transfer
5. Pelton Wheel – hydrodynamics,
physics

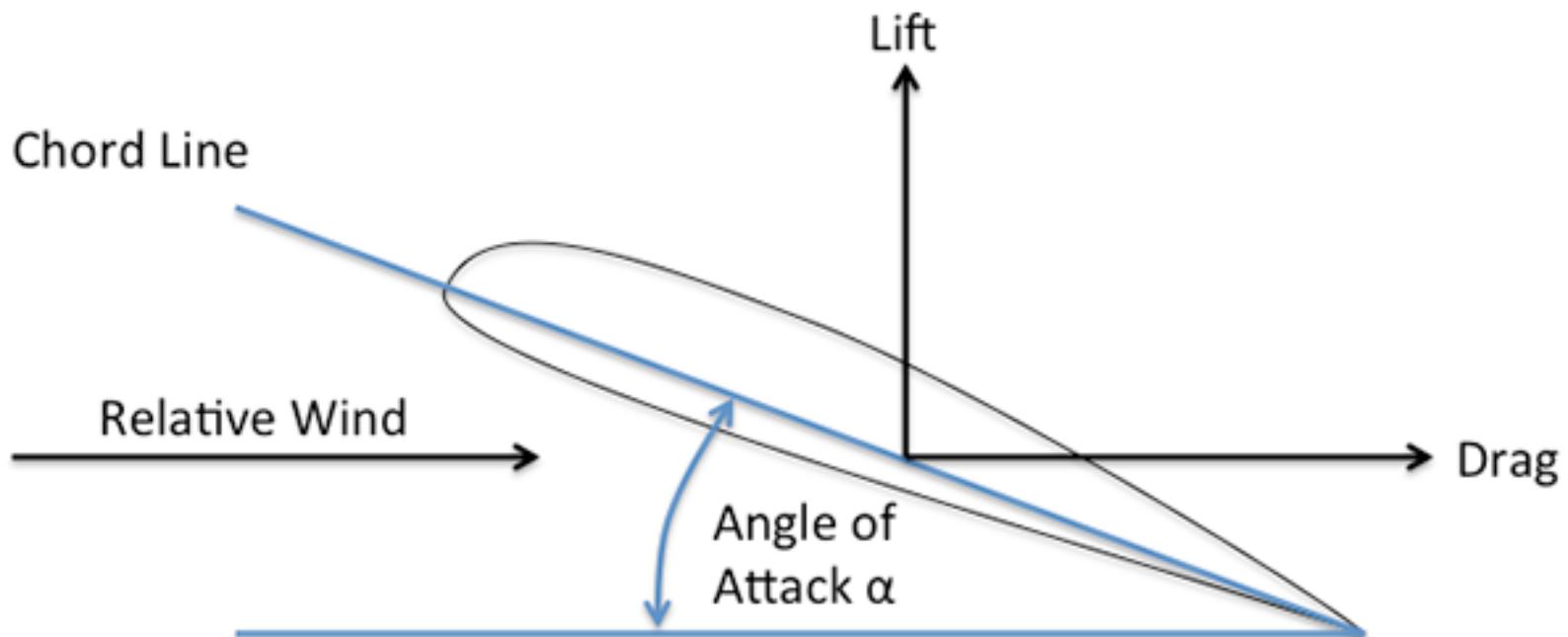
Aerodynamics



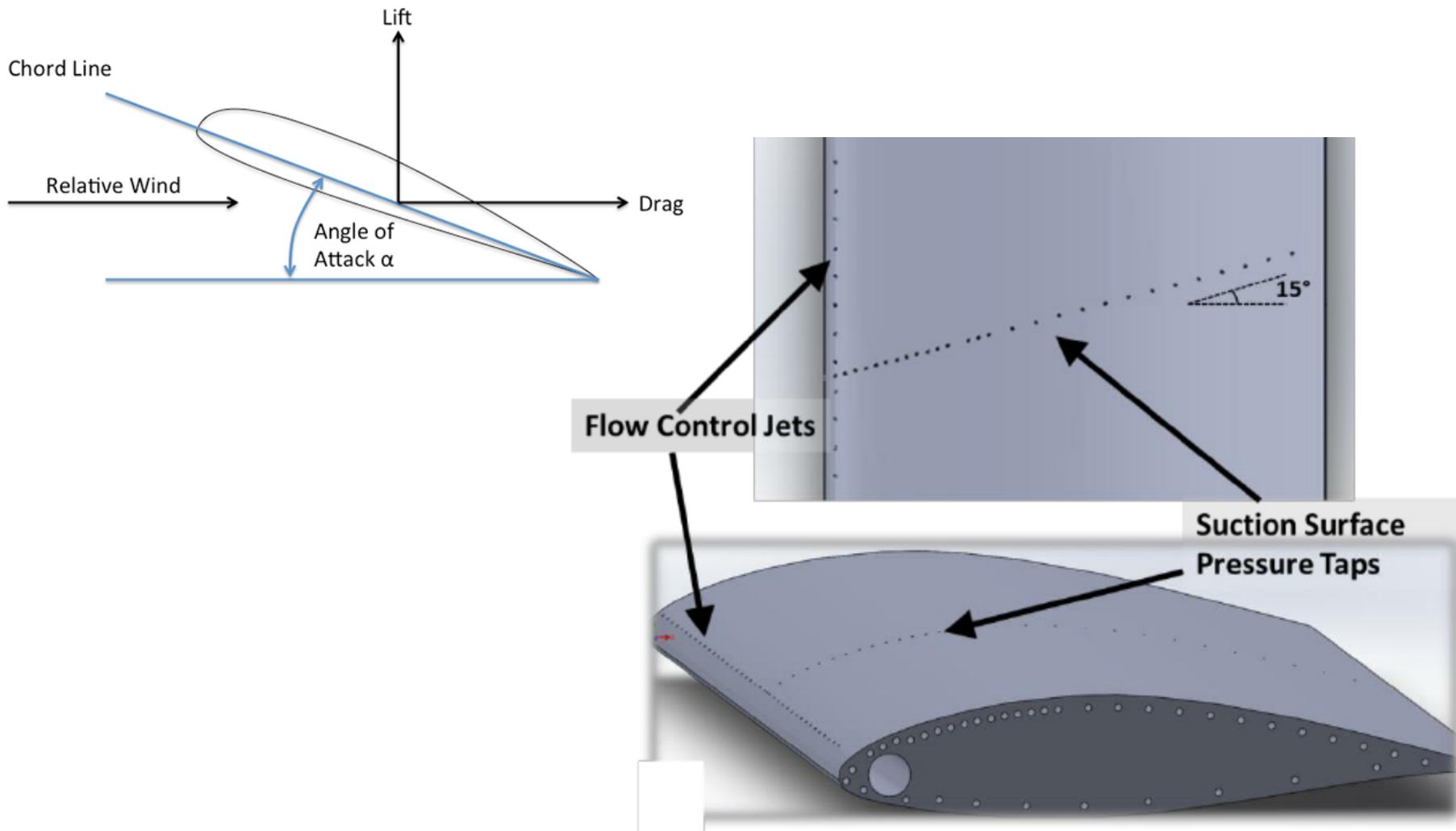
Aerodynamics



Aerodynamics



Aerodynamics



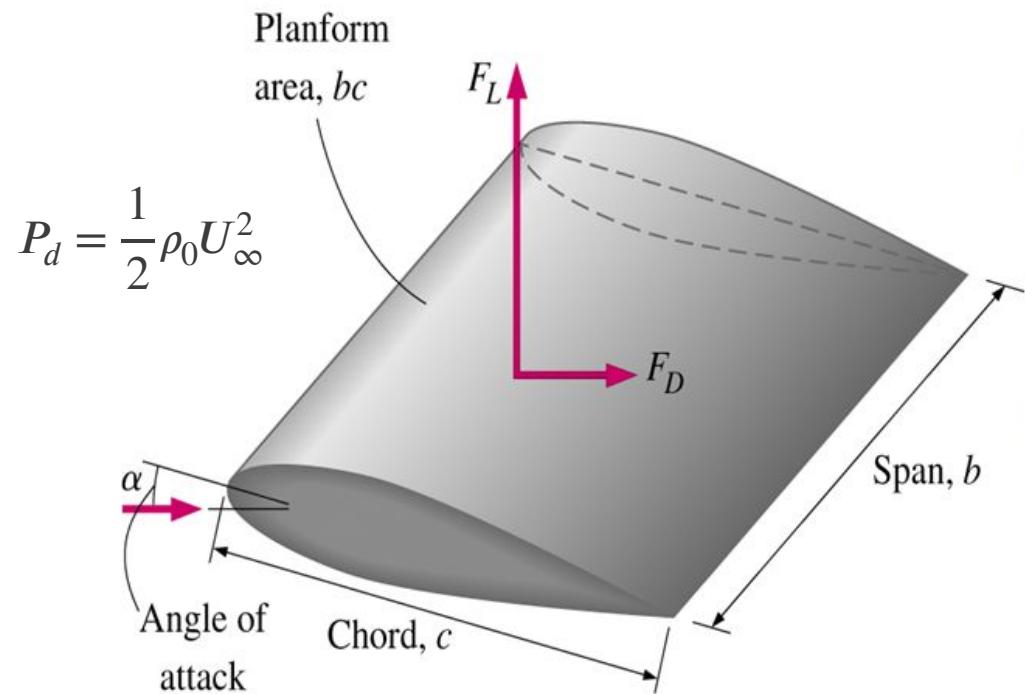
Aerodynamics

Performance of an Airfoil

$$C_L = \frac{L}{P_d S}$$

$$C_D = \frac{D}{P_d S}$$

$$C_P = \frac{P - P_\infty}{P_d S}$$

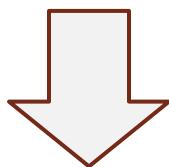


Aerodynamics

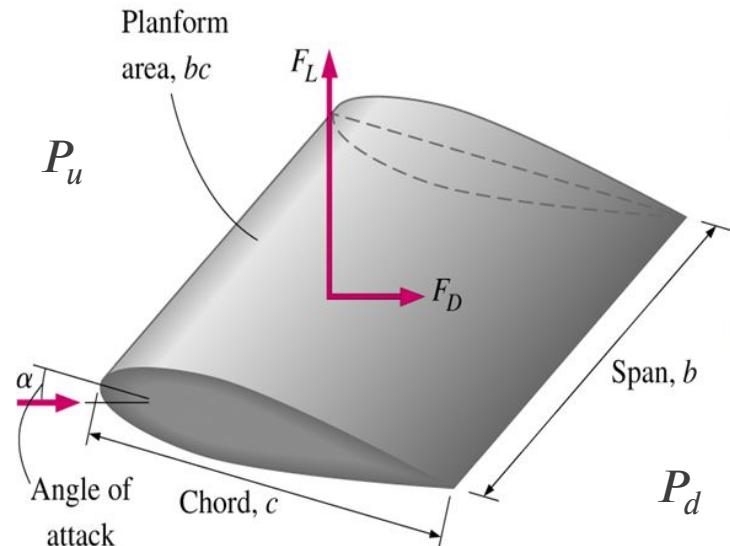
MATLAB's Trapz Function

Momentum deficit:

$$D' = \int_a^b (P_u + \rho u_0^2) dy - \int_c^d (P_d + \rho u^2) dy$$

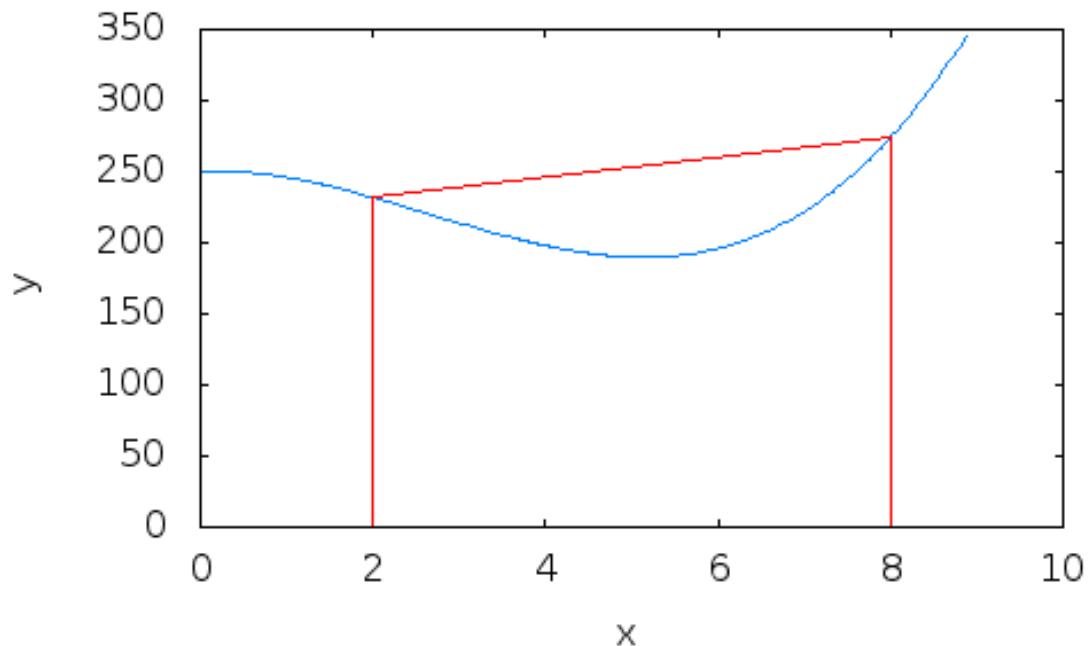


$$\int_m^n f(x) dx = \sum_{k=1}^N \frac{f(x_{k-1}) + f(x_k)}{2} \Delta x_k$$

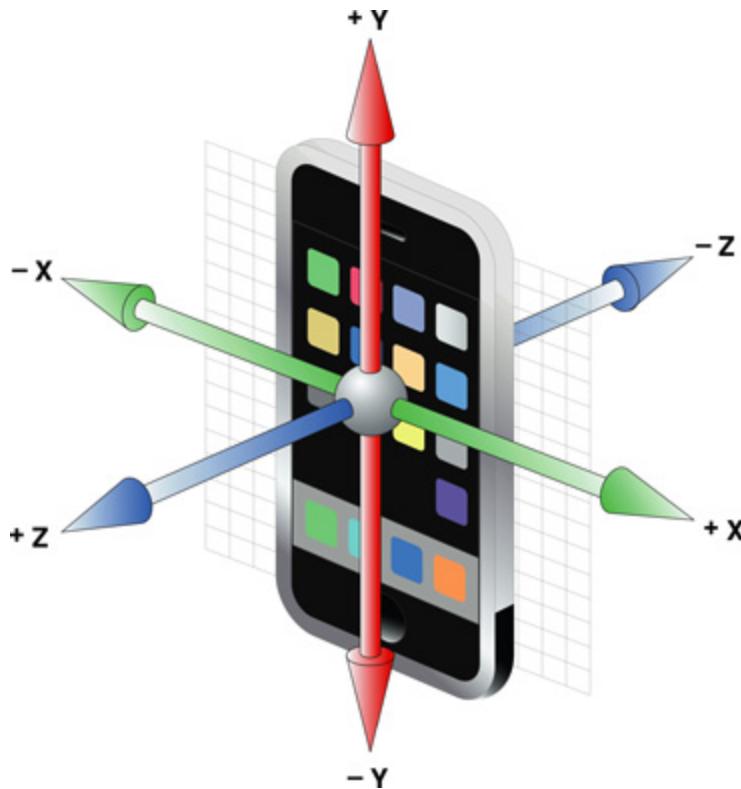


MATLAB Trapz

$$\int_m^n f(x) dx = \sum_{k=1}^N \frac{f(x_{k-1}) + f(x_k)}{2} \Delta x_k$$



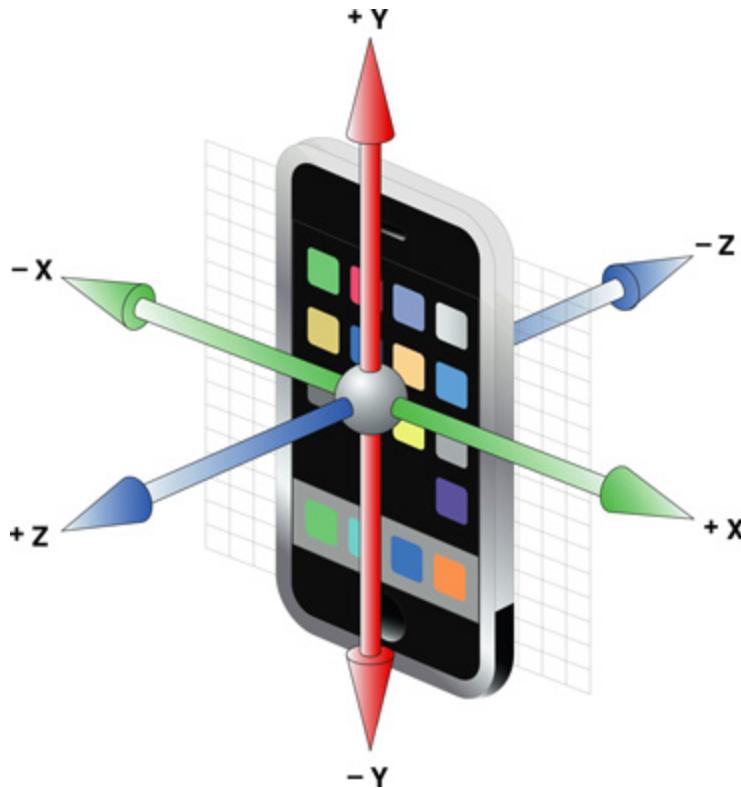
MATLAB Trapz - Example



$$\int_m^n f(x) dx = \sum_{k=1}^N \frac{f(x_{k-1}) + f(x_k)}{2} \Delta x_k$$

$$\int_m^n f(x) dx = \text{cumtrapz}(\text{data})$$

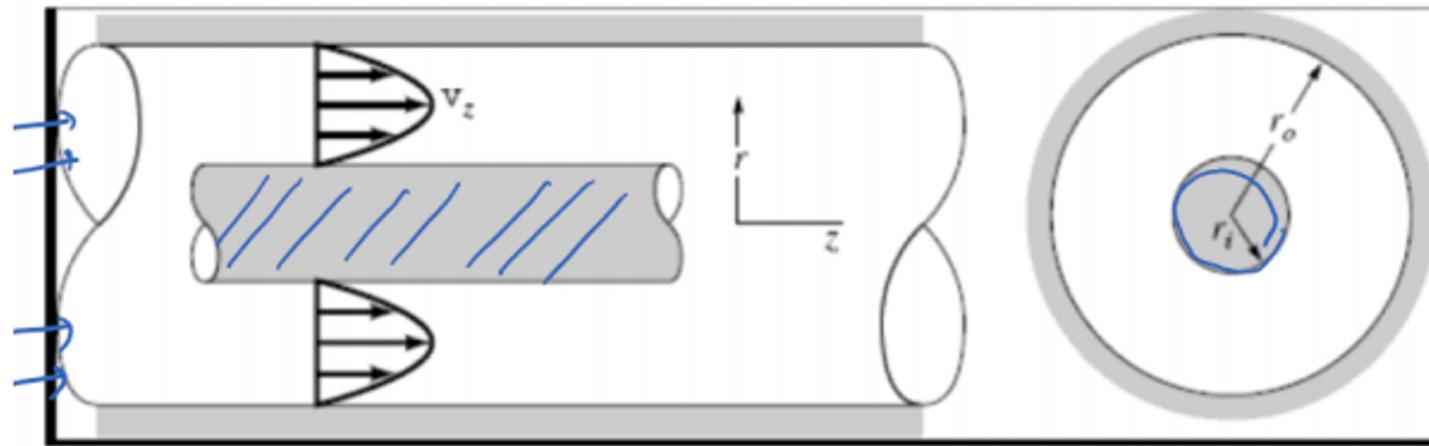
MATLAB Trapz - Example



$$a = \frac{dv}{dt} \rightarrow v = \frac{dx}{dt}$$

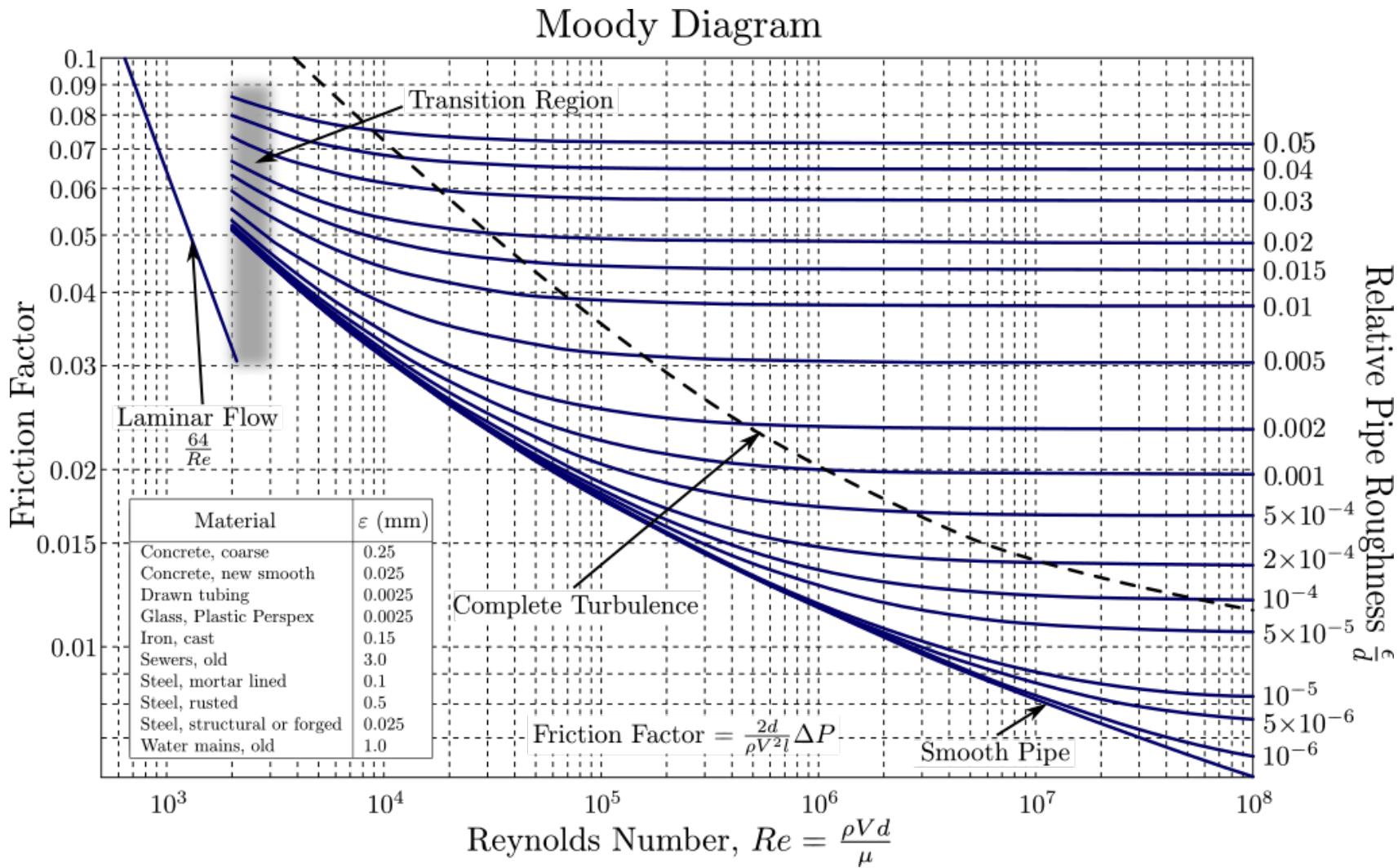
$$\int_m^n f(x) dx = \text{cumtrapz}(\text{data})$$

Pipe Flow



$$\frac{u(r)}{u_{max}} = \left(1 - \frac{r^2}{R^2} \right)$$

Pipe Flow - Losses



Pipe Flow Experiment

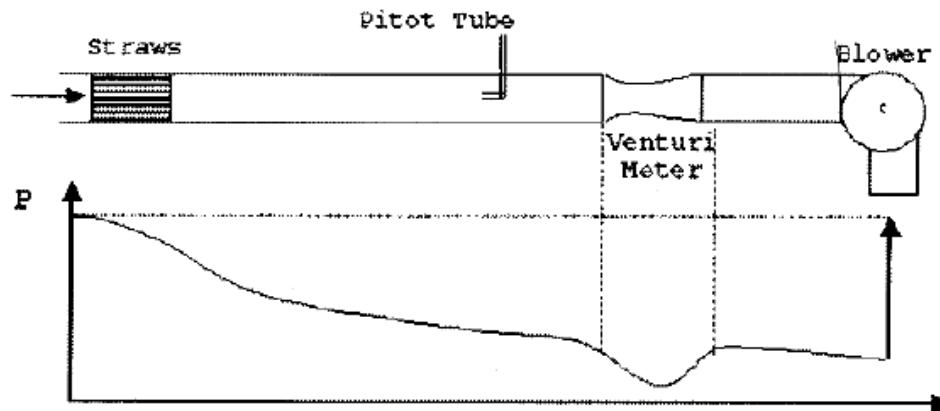
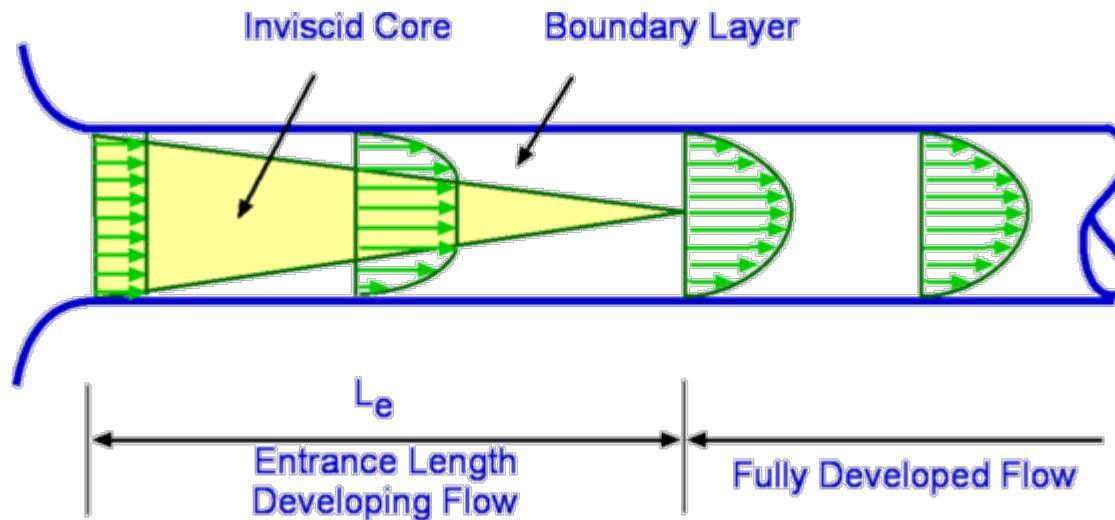


Figure 6.4. Experimental apparatus and pressure diagram



Pipe Flow Experiment

Re will be the most important information here, along with location of local velocity measurement.

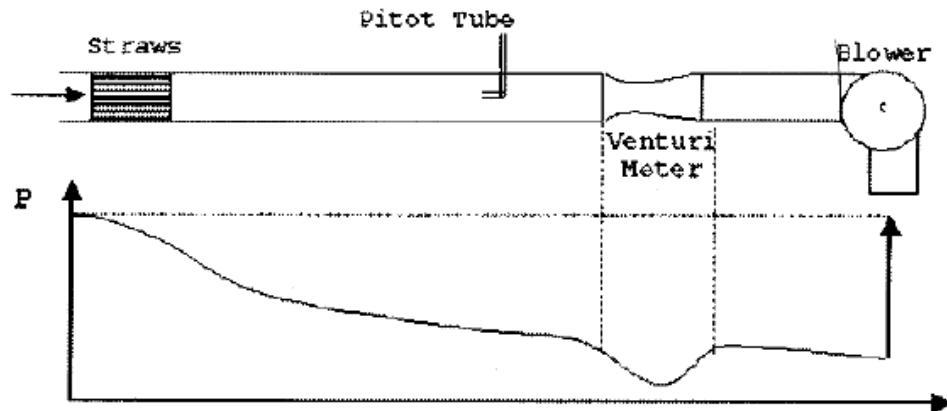
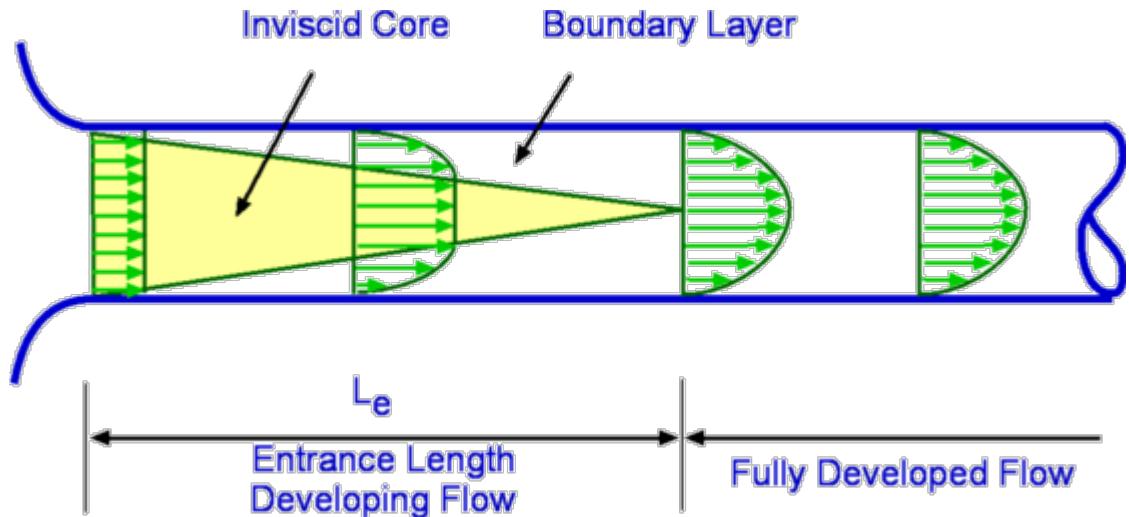


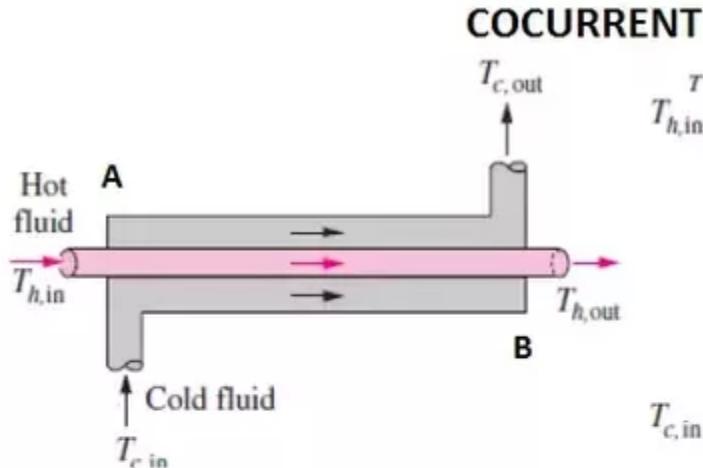
Figure 6.4. Experimental apparatus and pressure diagram

Friction factor (laminar):

$$f = \frac{64}{Re}$$



Heat Transfer – Heat Exchangers

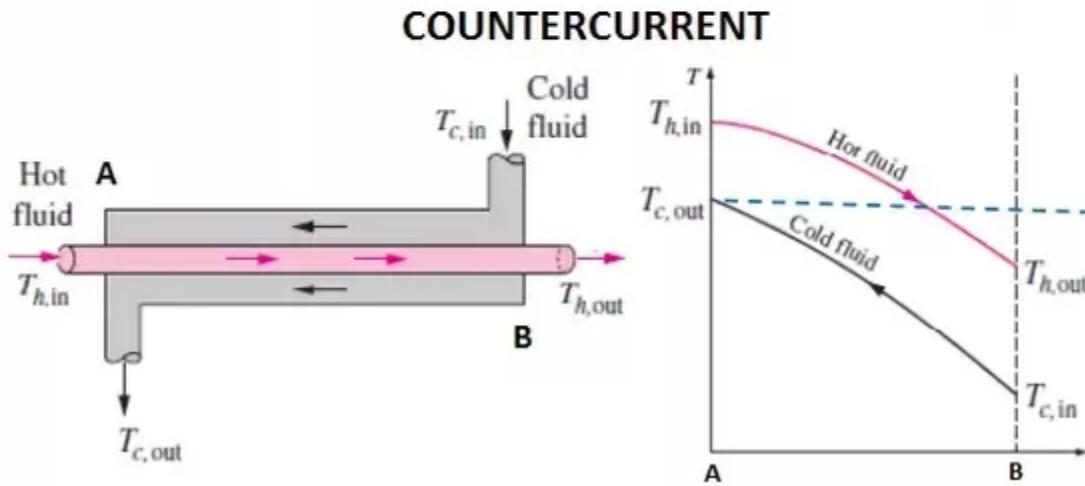


$$\dot{q} = hA(\Delta T)$$

$$\dot{q}_h = \dot{m}_h c_{p,h} (T_{h,i} - T_{h,o})$$

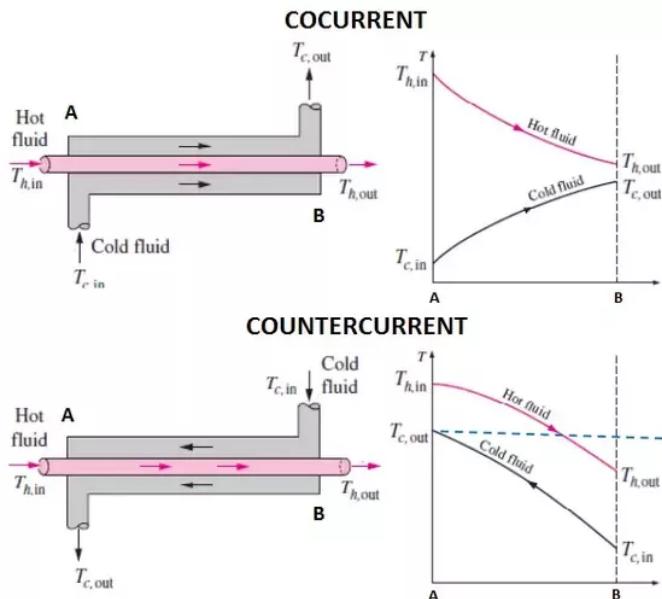
$$\dot{q}_c = \dot{m}_c c_{p,c} (T_{c,i} - T_{c,o})$$

No losses $\rightarrow \dot{q} = \dot{q}_h = \dot{q}_c$



Heat Transfer – Heat Exchangers

Methods for Calculating \dot{q}

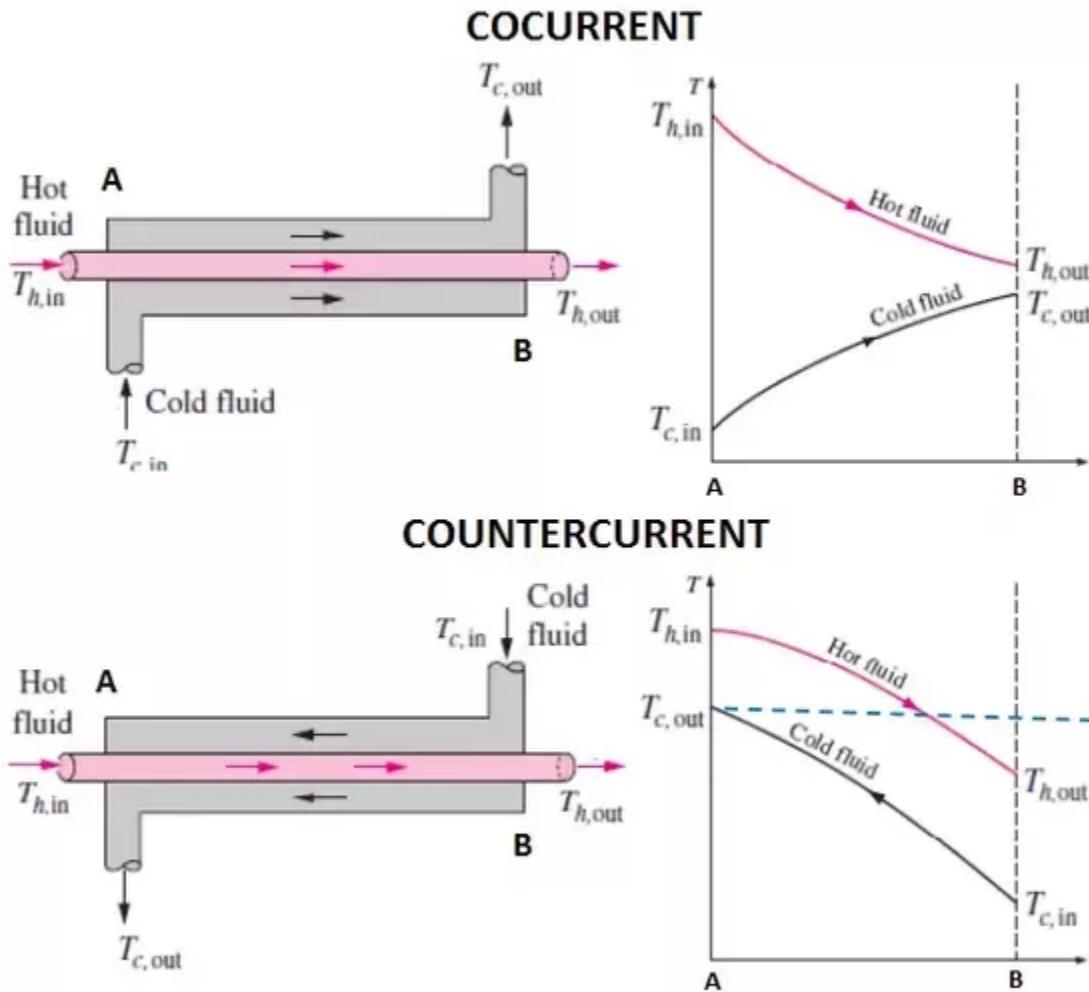


$$\dot{q} = hA(\Delta T_{lm})$$

$\Delta T_{lm} \equiv$ logarithmic mean
temperature difference (LMTD)

$$\Delta T_{lm} = LMTD = \frac{\Delta T_A - \Delta T_B}{\ln \frac{\Delta T_A}{\Delta T_B}}$$

Heat Transfer – Heat Exchangers

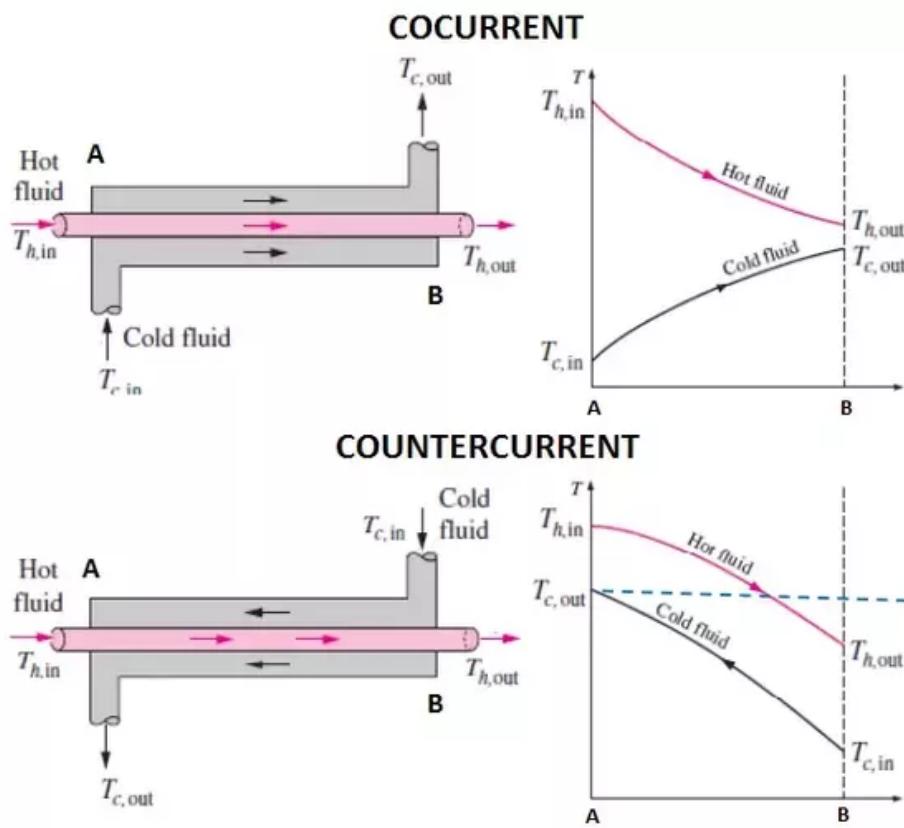


$$\Delta T_{lm} = \frac{\Delta T_A - \Delta T_B}{\ln \frac{\Delta T_A}{\Delta T_B}}$$

What is ΔT_{lm} for parallel?

What is ΔT_{lm} for counter?

Heat Transfer – Heat Exchangers

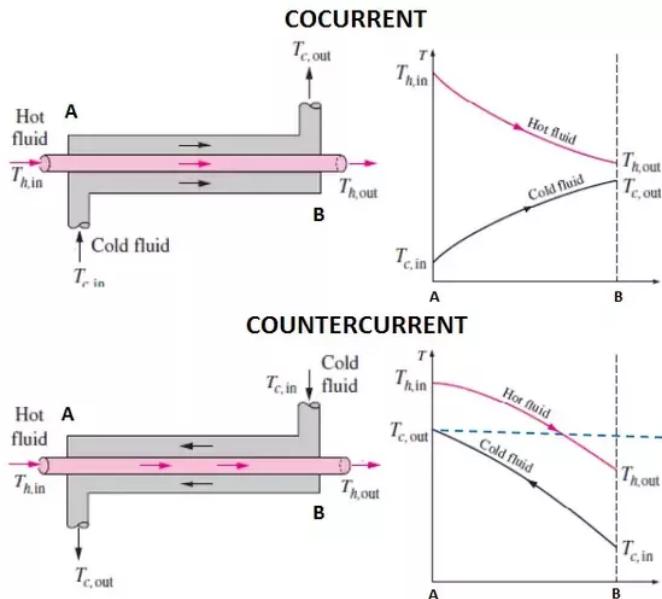


$$\Delta T_{lm} = \frac{\Delta T_A - \Delta T_B}{\ln \frac{\Delta T_A}{\Delta T_B}}$$

$$\Delta T_{lm} = \frac{(T_{h,i} - T_{c,i}) - (T_{h,o} - T_{c,o})}{\ln(T_{h,i} - T_{c,i}) - \ln(T_{h,o} - T_{c,o})}$$

$$\Delta T_{lm} = \frac{(T_{h,i} - T_{c,o}) - (T_{h,o} - T_{c,i})}{\ln(T_{h,i} - T_{c,o}) - \ln(T_{h,o} - T_{c,i})}$$

Heat Transfer – Heat Exchangers

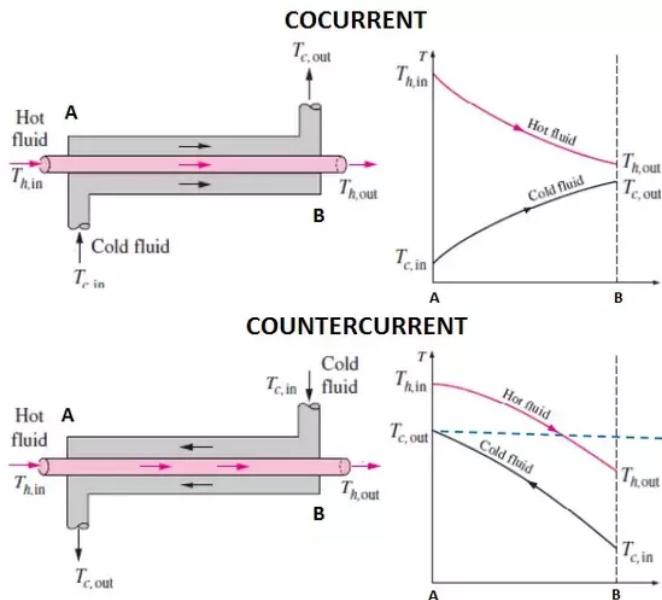


Method for Calculating \dot{q}

$$\dot{q} = hA \cdot LMTD = hA \frac{\Delta T_A - \Delta T_B}{\ln \frac{\Delta T_A}{\Delta T_B}}$$

Heat Transfer – Heat Exchangers

Efficiency is also important:



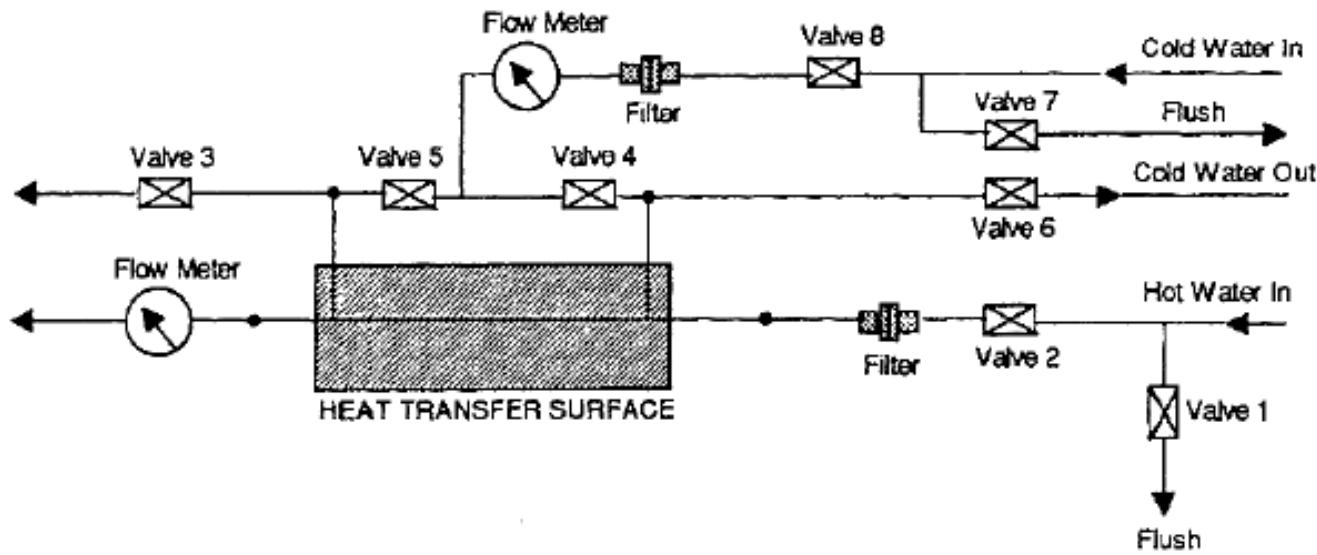
$$\epsilon = \frac{\dot{q}}{\dot{q}_{max}}$$

$$\dot{q}_{max} = C_{min}(T_{h,i} - T_{c,i})$$

where C_{min} is the minimum between:

$$m_c c_{p,c} \text{ or } m_h c_{p,h}$$

Heat Transfer – Heat Exchangers



• = THERMOCOUPLES

Figure 7.2. *Heat exchanger experimental setup.*

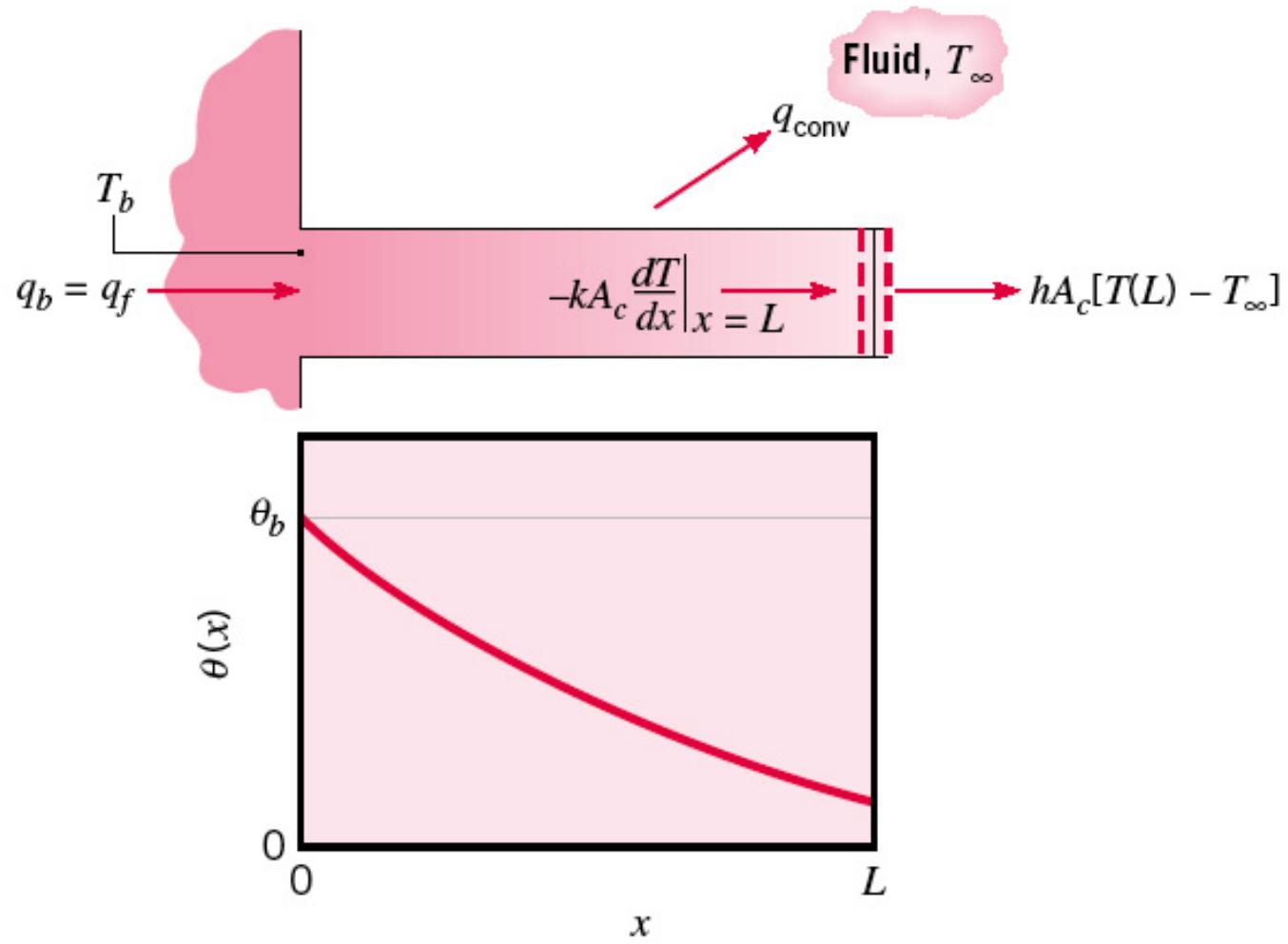
Heat Transfer – Heat Exchangers



It will be important to take note of the flow rate in order to calculate Reynold's number and determine heat transfer coefficients

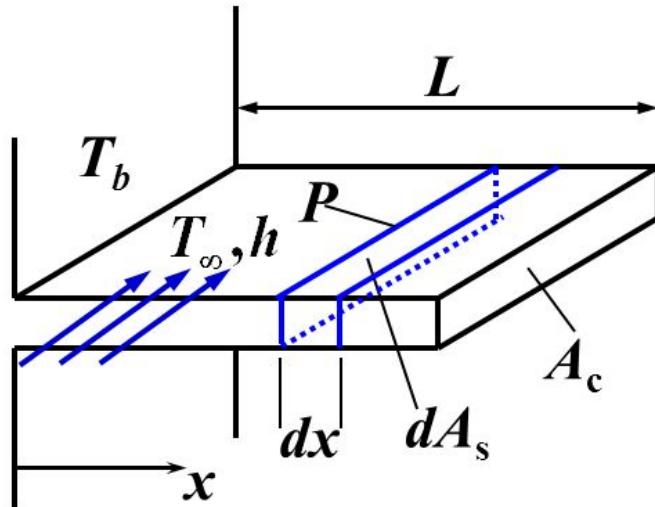
Figure 7.2. Heat exchanger experimental setup.

Heat Transfer - Fins



Heat Transfer - Fins

Fins of Uniform Cross-Sectional Area



P : fin perimeter

$A_c(x) = \text{constant}$,
and $dA_s = Pdx$

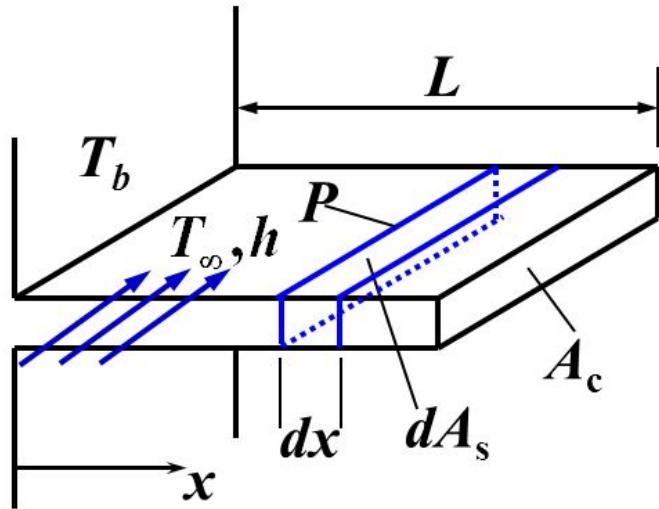
$$\frac{d}{dx} \left[A_c(x) \frac{dT}{dx} \right] - \frac{h}{k} \frac{dA_s}{dx} [T(x) - T_\infty] = 0$$

$$\frac{d^2 T}{dx^2} - \frac{hP}{kA_c} [T(x) - T_\infty] = 0$$

Steady state

Heat Transfer - Fins

Fins of Uniform Cross-Sectional Area



P : fin perimeter

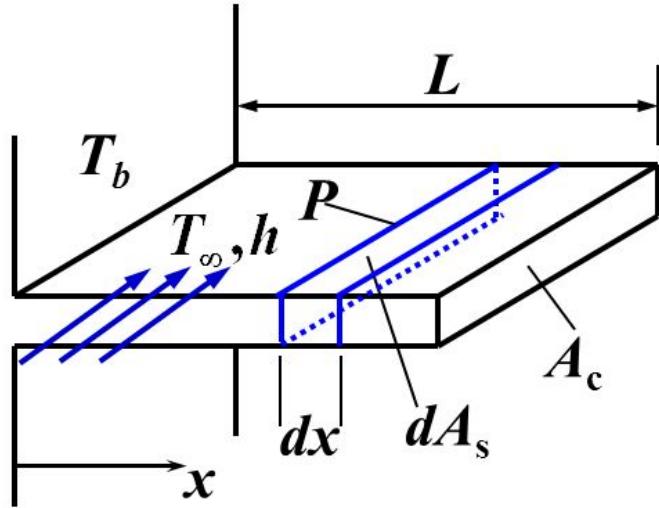
$A_c(x) = \text{constant}$,
and $dA_s = Pdx$

$$\frac{\partial^2 T(x, t)}{\partial x^2} - \frac{hC}{kA} [T(x, t) - T_\infty] = \frac{\frac{1}{\alpha} \partial T(x, t)}{\partial t}$$

Transient

Heat Transfer - Fins

Fins of Uniform Cross-Sectional Area

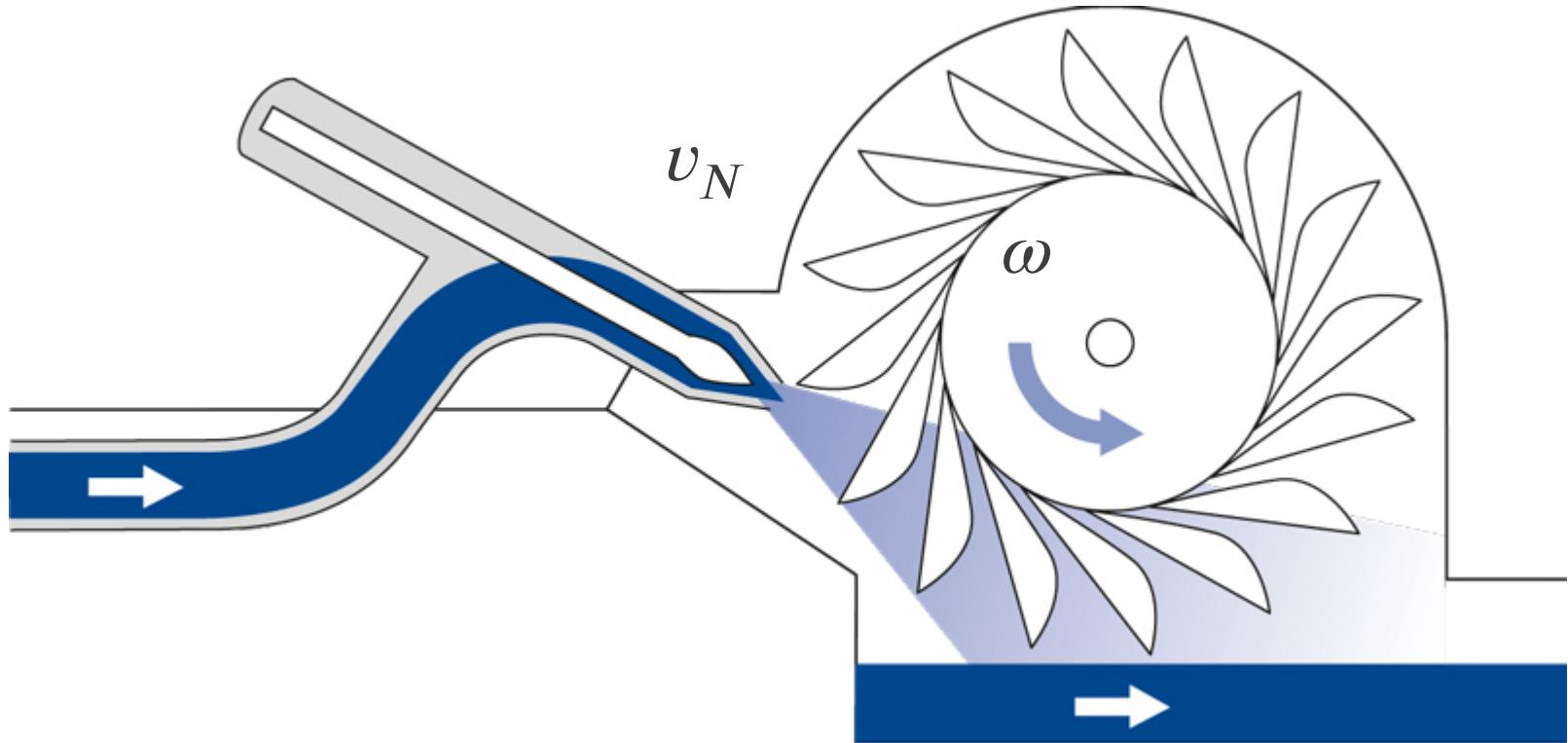


P : fin perimeter

$A_c(x) = \text{constant}$,
and $dA_s = Pdx$

$$T(x, t) = T_{amb} + \frac{q''_o}{k} \left\{ \left[\frac{e^{m(x-2L)} + e^{-mx}}{m(1-e^{-2mL})} \right] - 2e^{-m^2\alpha t} \left[\frac{1}{2m^2L} + L \sum_{n=1}^{\infty} \frac{\cos\left(\frac{n\pi}{L}x\right) e^{-\frac{n^2\pi^2}{L^2}\alpha t}}{m^2L^2+n^2\pi^2} \right] \right\}$$

Hydrodynamics



Hydrodynamics

Velocity relative to moving buckets

$$V_r = v_N - \omega r$$

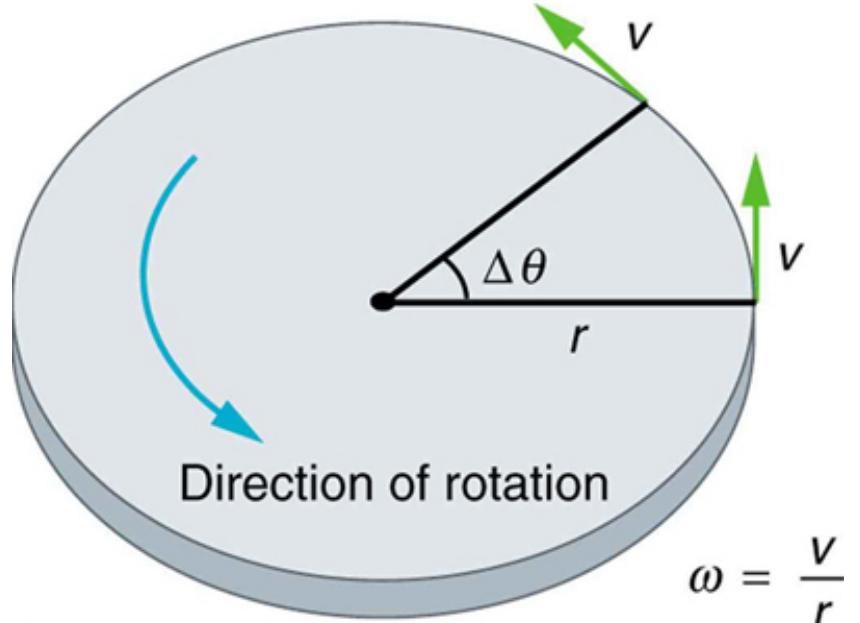
Friction factor k_1 :

$$V_{r,losses} = k_1(v_N - \omega r)$$

Angular dependence:

$$\Delta V_r = V_r + V_{r,losses} \cos \theta = (v_N - \omega r) + k_1(v_N - \omega r) \cos \theta$$

$$\Delta V_r = (v_N - \omega r)(1 + k_1 \cos \theta)$$



$$\omega = \frac{v}{r}$$

Hydrodynamics

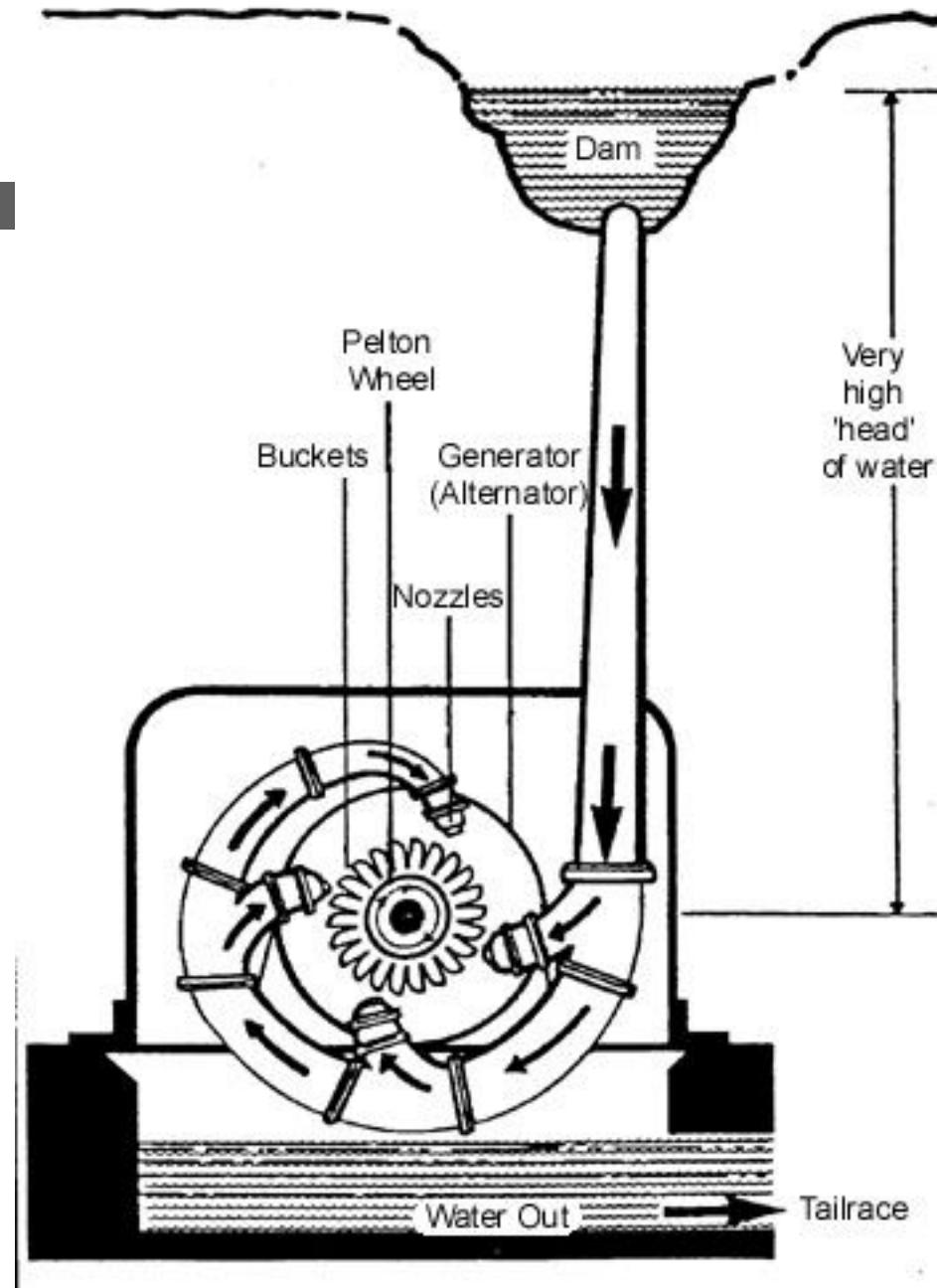
Nozzle Flow

$$\frac{1}{2} \rho v_N^2 + \rho gh = 0$$

$$v_N = \sqrt{2gh}$$

Assuming loss:

$$v_N = C_v \sqrt{2gh}$$



Hydrodynamics

Power Output

$$P = \frac{\text{work}}{\text{time}} = \frac{dW}{dt} = \frac{d}{dt}(F \cdot r)$$

$$P = F \cdot v$$

$$F = ?$$



Hydrodynamics

Power Output

$$P = \frac{\text{work}}{\text{time}} = \frac{dW}{dt} = \frac{d}{dt}(F \cdot r)$$

$$P = F \cdot v$$

$$F = ma = m \frac{dv}{dt} = \frac{m\Delta V}{\Delta t}$$

$$m = \dot{m}\Delta t = v_N A \rho \Delta t$$

$$F = \rho A v_N \Delta V$$

$$P = \rho A v_N \Delta V \omega r$$



Hydrodynamics

Power Output

$$P = \rho A v_N \Delta V \omega r$$

$$P = \omega r \rho A v_N (v_N - \omega r) (1 + k_1 \cos \theta)$$

$$P = \omega r \rho A C_v \sqrt{2gh} (C_v \sqrt{2gh} - \omega r) (1 + k_1 \cos \theta)$$

What is P_{max} and when is it reached? Try:

$$P = v_r \rho A v_N (v_N - v_r) (1 + c)$$

Hydrodynamics

What is P_{max} and when is it reached? Try:

$$P = v_r \rho A v_N (v_N - v_r)(1 + c)$$

$$\frac{\partial P}{\partial t} = 0$$

$$P = \rho A (1 + c) (v_r v_N^2 - v_r^2 v_N)$$

$$\frac{\partial P}{\partial v_r} = \frac{\partial (\rho A (1 + c) (v_r v_N^2 - v_r^2 v_N))}{\partial v_r} = 0$$

Hydrodynamics

$$\frac{\partial P}{\partial v_r} = \frac{\partial (\rho A(1+c)(v_r v_N^2 - v_r^2 v_N))}{\partial v_r} = 0$$

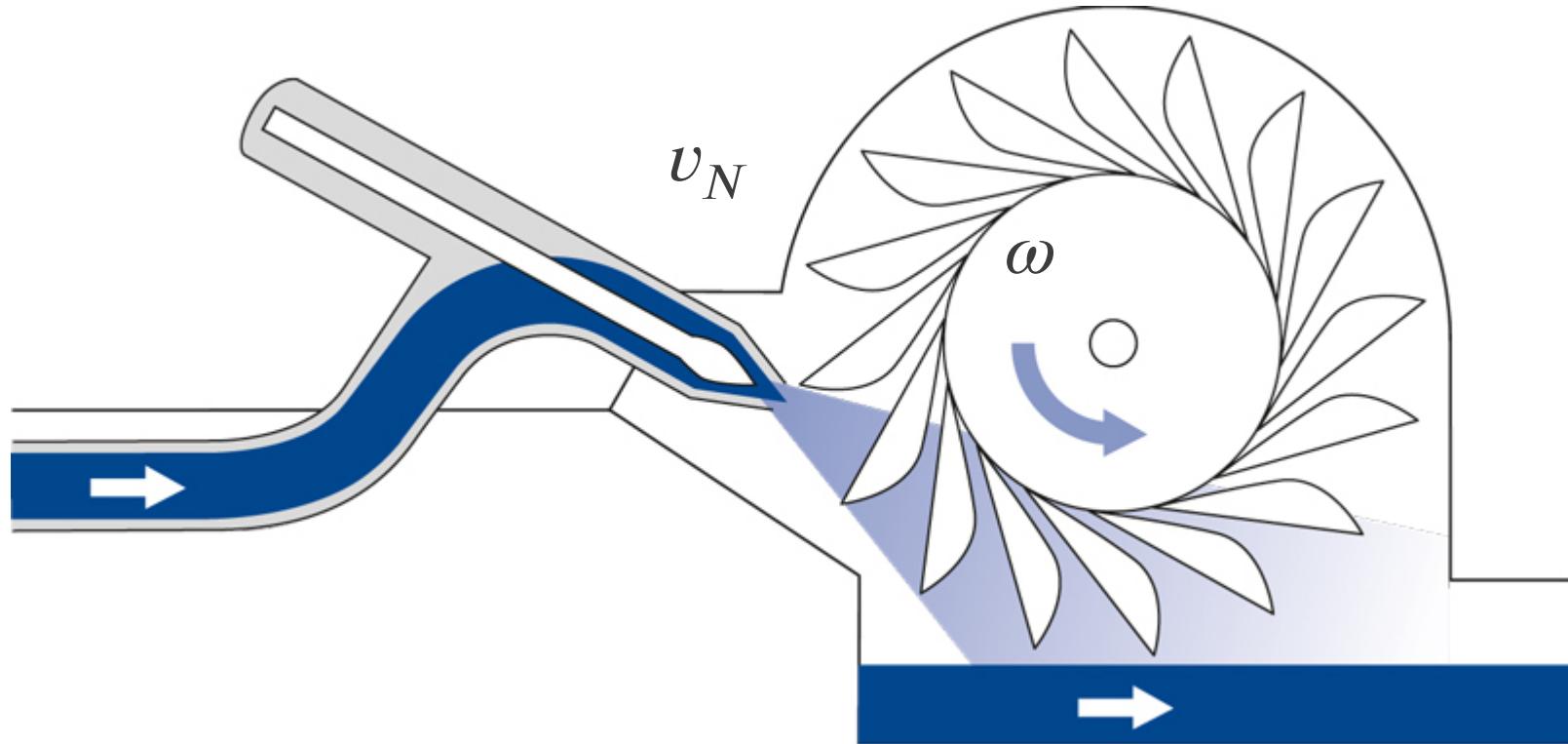
$$v_N^2 - 2v_r v_N = 0$$

$$v_r = \frac{v_N}{2}$$

$$P_{max} = \rho A(1+c) \left(\frac{v_N}{2} v_N^2 - \left(\frac{v_N}{2} \right)^2 v_N \right)$$

$$P_{max} = \frac{\rho A(1+c)v_N^3}{4} = \frac{\rho A}{2} v_N^3$$

Hydrodynamics



Next Week Labs Start

Prepare for lab by reviewing respective material

Group Laboratory Assignments

	Lab for the Week				
Lab Group	Week 1	Week 2	Week 3	Week 4	Week 5
1	Wind Tunnel	Pipe	Heat X	X-Fin	Pelton
2	Pelton	Wind Tunnel	Pipe	Heat X	X-Fin
3	X-Fin	Pelton	Wind Tunnel	Pipe	Heat X
4	Heat X	X-Fin	Pelton	Wind Tunnel	Pipe
5	Pipe	Heat X	X-Fin	Pelton	Wind Tunnel

Bibliography

- <https://faraday.physics.utoronto.ca/PVB/Harrison/Manometer/Manometer.html>
- <http://chemineering.blogspot.com/2014/03/pressure-calculation-in-u-tube-and.html>
- https://it.wikipedia.org/wiki/Tubo_manometrico
- <https://automationforum.in/t/how-pitot-tube-is-used-in-flow-measurement/2759>
- <http://www.msubbu.in/ln/fm/Unit-III/PitotTube.htm>
- https://upload.wikimedia.org/wikipedia/commons/thumb/a/af/Pitot_tube_types.svg/724px-Pitot_tube_types.svg.png
- <https://www.chegg.com/homework-help/questions-and-answers/following-device-known-venturi-meter-used-measure-flow-rate-water-pipe-cross-sectional-area-q19133644>
- <http://hyperpost.blogspot.com/2018/01/sensor-suhu-thermocouple.html>
- <http://www.capgo.com/Resources/Temperature/Thermocouple/Thermocouple.html>
- <https://en.wikipedia.org/wiki/Thermocouple>
- http://code7700.com/aero_angle_of_attack.htm
- https://www.researchgate.net/publication/321315585_Aircrafts_winglets_analysis_in_CFD
- <https://slideplayer.com/slide/7467548/>
- <https://slideplayer.com/slide/8672376/26/images/7/Fins+of+Uniform+Cross-Sectional+Area.jpg>
- <http://clipground.com/images/pelton-turbine-clipart-13.jpg>
- https://www.researchgate.net/publication/263075013_Large_Low-Frequency_Oscillations_Initiated_by_Sub-Optimal_Flow_Control_on_a_Post-Stall_Airfoil/figures?lo=1

Bibliography (cont.)

- <https://www.chegg.com/homework-help/questions-and-answers/consider-viscous-steady-laminar-fully-developed-incompressible-flow-annular-pipe-use-navie-q16625561>
- <https://qph.fs.quoracdn.net/main-qimg-c5ecb7bba26ac88639072505d7c44b97>
- https://www.wiley.com/college/incropera/0471457280/image_gallery/ch03/pages/03_17.html