Instruction Name	Command#	Command Data	Command Type	Reply Data
Convert To Ascii*	124	Baud Rate	Command	Baud Rate
Echo Data	55	Data	Command	Data
Error	255	n/a	Reply	Error Code
<u>Home</u>	1	Ignored	Command	Final position (in this case 0)
Limit Active	9	n/a	Reply	Final Position
Load Event Instructio n*	30	Key Event	Command	Key Event
Manual Move	11	n/a	Reply	Final Position
Manual Move Tracking	10	n/a	Reply	Tracking Position
Move Absolute	20	Absolute Position	Command	Final Position
Move At Constant Speed	22	Speed	Command	Speed
Move Index	78	Index Number	Command	Final Position
Move Relative	21	Relative Position	Command	Final Position
Move To Stored Position	18	Address	Command	Final Position
Move Tracking	8	n/a	Reply	Tracking Position
Read All Digital Inputs	69	Ignored	Command	Pin States
Read All Digital Outputs	72	Ignored	Command	Pin States
Read Analog Input	76	Pin Number	Command	Voltage

Read				
<u>Digital</u>	68	Pin Number	Command	Pin State
<u>Input</u>				
Read				
<u>Digital</u>	71	Pin Number	Command	Pin State
Output				
Read		Register		
Register	5	Address	Command	Data
Renumbe				
<u>r*</u>	2	Ignored	Command	Device ID
Reset	0	Ignored	Command	None
Restore				
Settings*	36	Peripheral ID	Command	Peripheral ID
Return				
Analog			Decid Oak	
	75	Ignored	Read-Only Setting	Pin Count
Input Count				
Count				
Return				
Analog	77	Ignored	Read-Only Setting	Pin Count
Output			Setting	
Count				
Return				
Calibrated			Read-Only	Calibrated
Encoder	83	Ignored	Setting	Encoder
Count				Count
Count				
Return			D 101	0 17 11
<u>Calibratio</u>	85	Ignored	Read-Only Setting	Calibration Error
<u>n Error</u>			Jetting	LIIOI
Return				
<u>Calibratio</u>	84	Ignored	Read-Only Setting	Calibration Type
n Type			Setting	Type
Return				
Current	60	Ignored	Read-Only	Position
Position			Setting	
Return			Read-Only	
Device ID	50	Ignored	Setting	Device ID
Return				
Digital			Pood Only	
Input	67	Ignored	Read-Only Setting	Pin Count
			Ĵ	
Count				
Return Digital				
<u>Digital</u>	70	Ignored	Read-Only Setting	Pin Count
<u>Output</u>			Jetting	
Count				

Return Encoder	82	Ignored	Read-Only	Encoder
Count		ignorea	Setting	Count
Return				
Event				
	31	Key Event	Command	n/a
Instructio				
<u>n</u>				
Return	50		Read-Only	Build
<u>Firmware</u>	56	Ignored	Setting	Number
Build				
Return_			Read-Only	
<u>Firmware</u>	51	Ignored	Setting	Version
<u>Version</u>				
<u>Return</u>				
<u>Power</u>	52	Ignored	Read-Only	Voltage
<u>Supply</u>		3	Setting	, and g
<u>Voltage</u>				
<u>Return</u>			Danid Only	Carial
<u>Serial</u>	63	Ignored	Read-Only Setting	Serial Number
<u>Number</u>			J	
Return	53	Setting	Command	Setting
<u>Setting</u>	ეა 	Number	Command	Value
Return	- ·		Read-Only	. .
<u>Status</u>	54	Ignored	Setting	Status
Return				
Stored	17	Address	Command	Stored
Position				Position
Set				
Accelerati	113	Acceleration	Setting	Acceleration
on Only*				
Set				
Accelerati	43	Acceleration	Setting	Acceleration
on*		333333337		
<u> </u>				
Set Active	25	Axis	Setting	Axis
Axis*		, (Alo	Johns	, talo
Set Active	6	Register	Setting	Register
Register		Address	Setting	Address
Cot Alica				
Set Alias	48	Alias Number	Setting	Alias Number
Number*		. 10111001		. Tarribor
Set Auto-		Auto-Home		Auto-Home
<u>Home</u>	105	Disabled	Setting	Disabled
<u>Disabled</u>		Mode		Mode
Mode*				

Set Auto-				
<u>Reply</u>	101	Auto-Reply	Sotting	Auto-Reply
Disabled	101	Mode	Setting	Mode
Mode*				
Set Axis				
Device	26	Device	Setting	Device
Number*		Number		Number
Set Axis				
Inversion	27	Invert Status	Setting	Invert Status
*		oit Giaide	Journal of the state of the sta	Grando
Cot Avic				
Set Axis	20	Profile	Catting	Profile
<u>Velocity</u>	28	Number	Setting	Number
Profile*				
Set Axis		Maximum		Maximum
<u>Velocity</u>	29	Velocity	Setting	Velocity
Scale*				
<u>Set Baud</u>	122	Baud Rate	Setting	Baud Rate
Rate*	122	Bada Nato	Cotting	Bada Rate
Cat Classed				
Set Closed	440	Closed-Loop	0 - 11'	Closed-Loop
<u>Loop</u>	118	Mode	Setting	Mode
Mode*				
Set				
Current	45	New Position	Setting	New Position
Position				
Set Cycle				
Distance	80	Distance	Setting	Distance
Set				
Decelerati	114	Deceleration	Setting	Deceleration
		Decocioration	Cotting	Becomeration
on Only*				
Set_				
<u>Device</u>	121	Direction	Setting	Direction
Direction *				
<u>Set</u>				
<u>Device</u>	40	Mode	Setting	Mode
Mode*				
Set Filter	81	Filter Holder	Setting	Filter Holder
<u>Holder ID</u>		ID	Journal	ID
Set Hold	39	Value	Sotting	Value
Current*	Ja	value	Setting	value
Set Home				0,11
Offset*	47	Offset	Setting	Offset
Set Home				
Sensor	104	Home	Setting	Home
Type*	104	Sensor Type	Cetting	Sensor Type
<u> </u>				

Set Home	41	Speed	Setting	Speed
Speed*			-	
Set Home	103	Home Status	Setting	Home Status
<u>Status</u>				
Set Index	79	Distance	Setting	Distance
<u>Distance</u>				
Set_				
Joystick	33	Calibration Mode	Setting	Calibration Mode
Calibratio		Mode		IVIOGE
n Mode				
Set Knob				
<u>Direction</u>	108	Direction	Setting	Direction
*				
Set Knob		Knob		Knob
<u>Disabled</u>	107	Disabled Mode	Setting	Disabled Mode
Mode*		Mode		ivioue
Set Knob	110	Jog Size	Setting	Jog Size
Jog Size*		009 0.20	John 19	009 0.20
Set Knob		Movement		Movement
Movemen	109	Mode	Setting	Mode
t Mode*				
Set Knob		\		\/-I!
<u>Velocity</u>	112	Velocity Profile	Setting	Velocity Profile
Profile*		. 101110		
Set Knob				
<u>Velocity</u>	111	Velocity Scale	Setting	Velocity Scale
Scale*		Scale		Scale
<u>Set</u>				
Manual				
Move	440	Tracking	Cattin a	Tracking
Tracking	116	Mode	Setting	Mode
Disabled				
Mode*				
C-+				
<u>Set</u>				
Maximum	44	Range	Setting	Range
Position*				
Cot				
<u>Set</u>	400	Message ID	0.445	Message ID
Message	102	Mode	Setting	Mode
ID Mode*				
Cot				
Set_				
Microstep	37	Microsteps	Setting	Microsteps
Resolutio n*				
<u>n*</u>				

		_		
<u>Set</u>		Minimum		Minimum
Minimum	106	Position	Setting	Position
Position*				
Set Move		Tracking		Tracking
<u>Tracking</u>	115	Mode	Setting	Mode
Mode*				
Set Move		Tracking		Tracking
<u>Tracking</u>	117	Period	Setting	Period
Period*				
Set Park	65	Park State	Setting	Position
State*		L dik Oldio	Cotting	Collion
<u>Set</u>				
Peripheral	66	Peripheral ID	Setting	Peripheral ID
ID*				
<u>Set</u>				
<u>Peripheral</u>	86	Peripheral Serial	Setting	Peripheral Serial
<u>Serial</u>	00	Number	Setting	Number
Number*				
Set				
	123	Protocol	Setting	Protocol
Protocol*				
<u>Set</u>				
Running	38	Value	Setting	Value
Current*				
Set Slip				
Tracking	119	Tracking Period	Setting	Tracking Period
Period*		renou		renou
Set Stall				
Timeout*	120	Timeout	Setting	Timeout
Set Target	42	Speed	Setting	Speed
Speed*				
Slip				Tracking
Tracking	12	n/a	Reply	Position
Stop	23	Ignored	Command	Final Position
Store				OSIGOTI
Current	16	Address	Command	Address
Position*				
Unexpect				
ed	13	n/a	Reply	Final
<u>Position</u>		. ", "	Соргу	Position
Write All	74	Din Ctatas	Commond	Din Ctates
<u>Digital</u>	74	Pin States	Command	Pin States
<u>Outputs</u>				

Write Digital Output	73	See Description		Same as Command Data
Write Register	7	Data	Command	Data