

Principled inference from images, part II

In which we do a measurement.

Where did we leave off last time?

- What is a psf?
- How do I measure the brightness of a star?
- Tradeoffs between model and aperture photometry
- Using GalSim to create simulated images.

What will we do today?

- Discuss how and why to do model-fit photometry of galaxies
- Try to deal with some of the ‘normal’ complexity of measurement in images.
- Obtain some Legacy Surveys imaging data for stars and galaxies
- Perform a measurement.

Extended sources in images

$$g(\mathbf{u}) + s(\mathbf{u})$$

There is a source on the sky, \mathbf{g} . There is other light, \mathbf{s} , not associated with our source.

Extended sources in images

$$g(\mathbf{u}) + s(\mathbf{u})$$

$$\int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x})$$

This light is smeared out by the telescope psf, p .

Extended sources in images

$$g(\mathbf{u}) + s(\mathbf{u})$$

$$\int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x})$$

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x})$$

Light that falls on the detector is recorded by the pixels. Each pixel's area, Π , projects onto a different patch of sky.

Π is not necessarily regular, and it is not necessarily normalized to unity.

Extended sources in images

$$g(\mathbf{u}) + s(\mathbf{u})$$

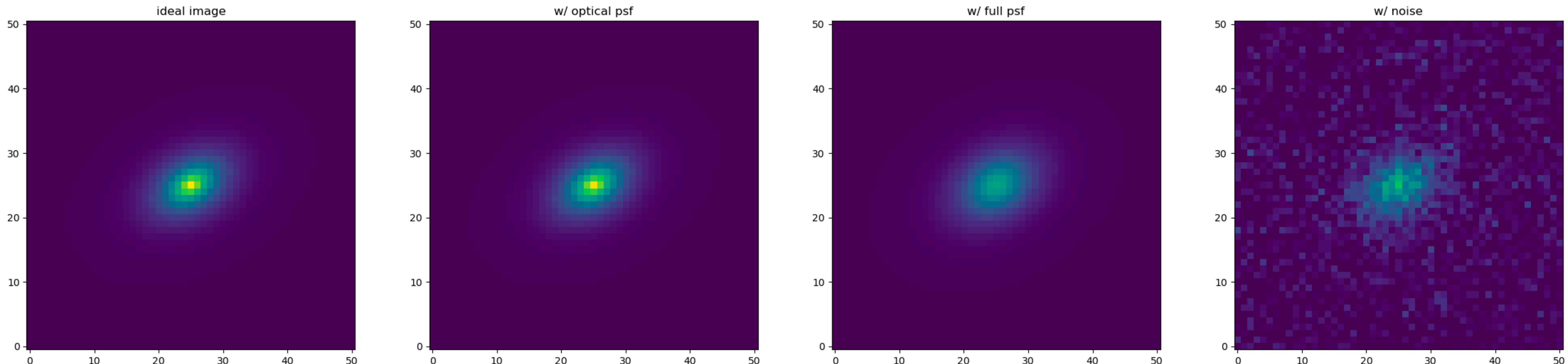
$$\int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x})$$

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x})$$

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x}) + A$$

The telescope and sensor can introduce additional non-astrophysical signals, A .

Extended sources in images



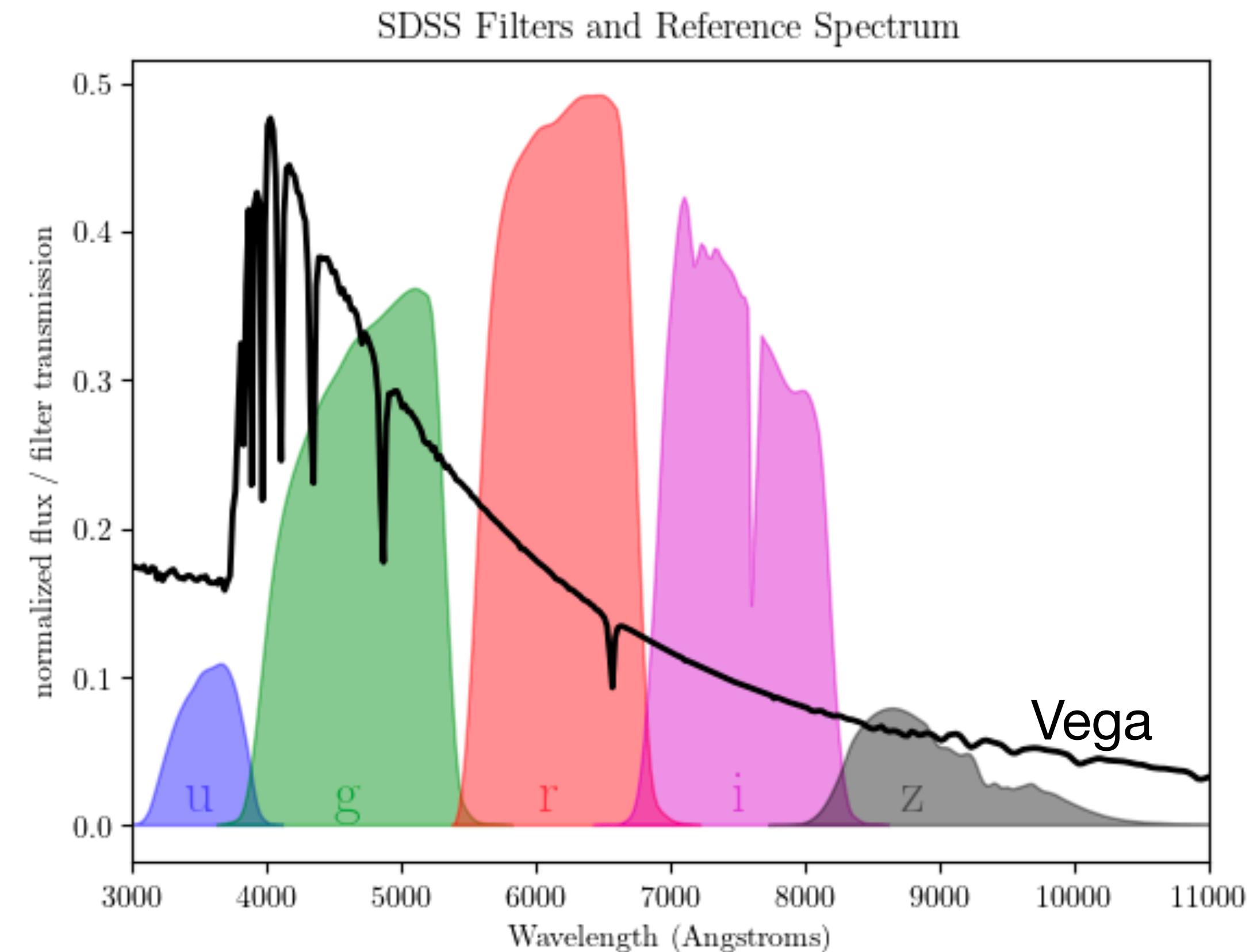
Interpreting the measured flux

$$g(\mathbf{u}) = \int dt \int d\lambda \frac{\lambda}{hc} I(\mathbf{u}, \lambda, t) r_{\text{atm}}(\mathbf{u}, \lambda, t) r_{\text{tel}}(\lambda, \mathbf{u}, t)$$

What we *actually* measure is the total number of photons integrated over our bandpass.

Typically, we compare the measured flux to a known reference spectrum.

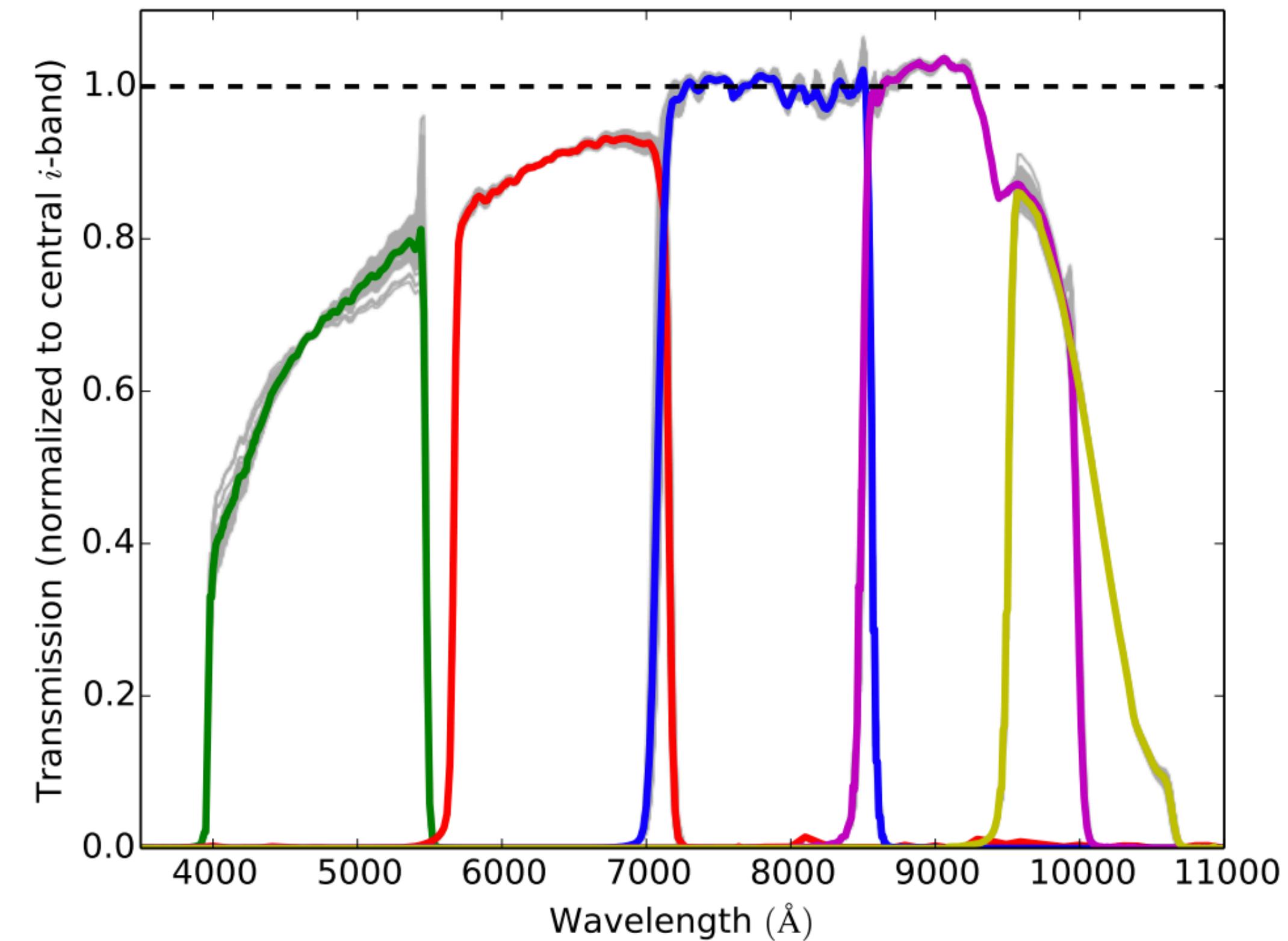
But we cannot interpret the result as a flux without assuming a spectrum for **g**.



Interpreting the measured flux

Why does the photometric calibration change?

- dust accumulates on the optical surfaces, and is cleaned off periodically.
- the mirror gradually loses reflectivity, and is re-aluminized from time to time
- the transparency of the atmosphere varies from night to night.
- the transparency of the filter varies with incidence angle of the light.

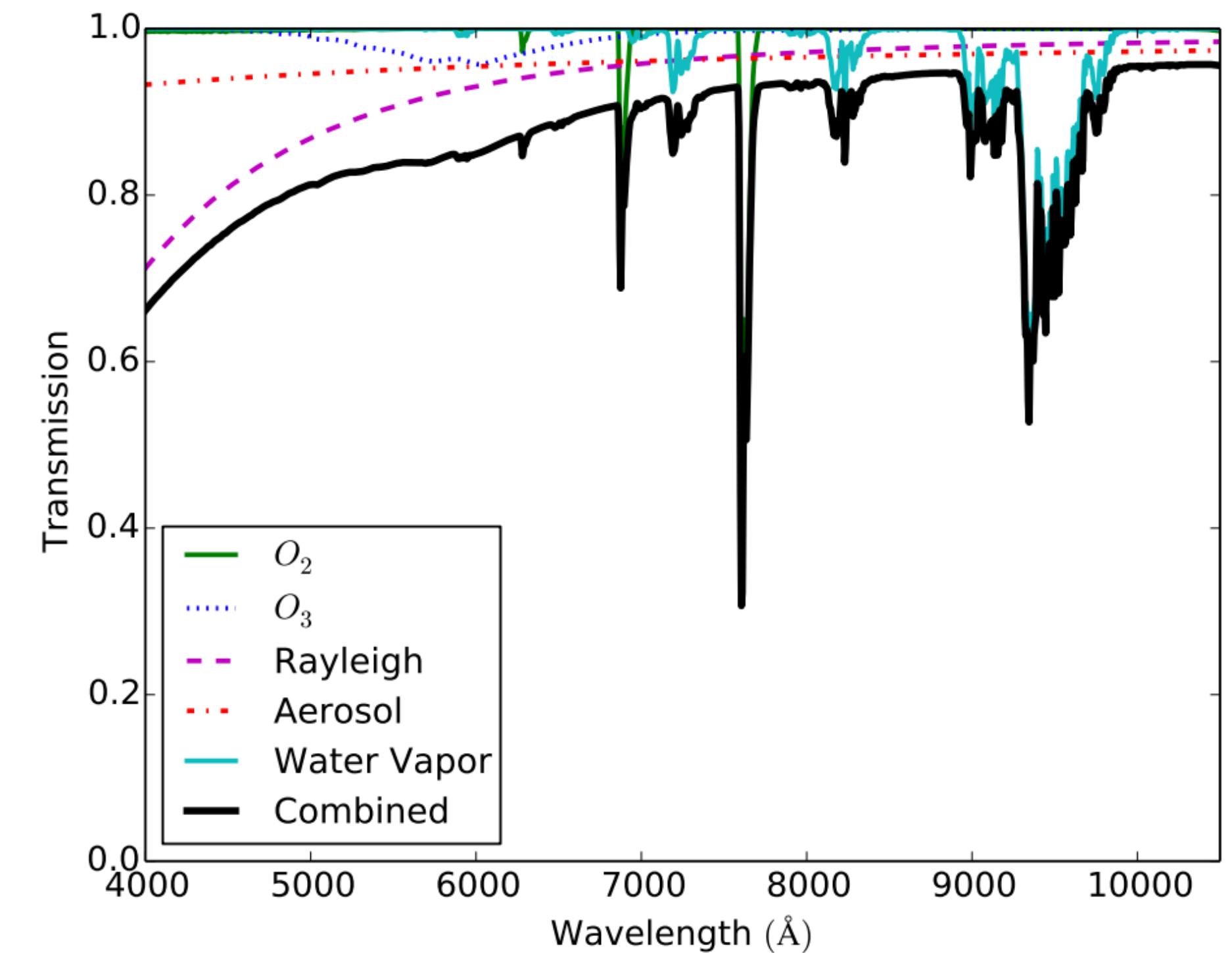


Variation in DECam passbands over the first three years of the Dark energy survey.

Interpreting the measured flux

Why does the photometric calibration change?

- dust accumulates on the optical surfaces, and is cleaned off periodically.
- the mirror gradually loses reflectivity, and is re-aluminized from time to time
- the transparency of the atmosphere varies from night to night.
- the transparency of the filter varies with incidence angle of the light.

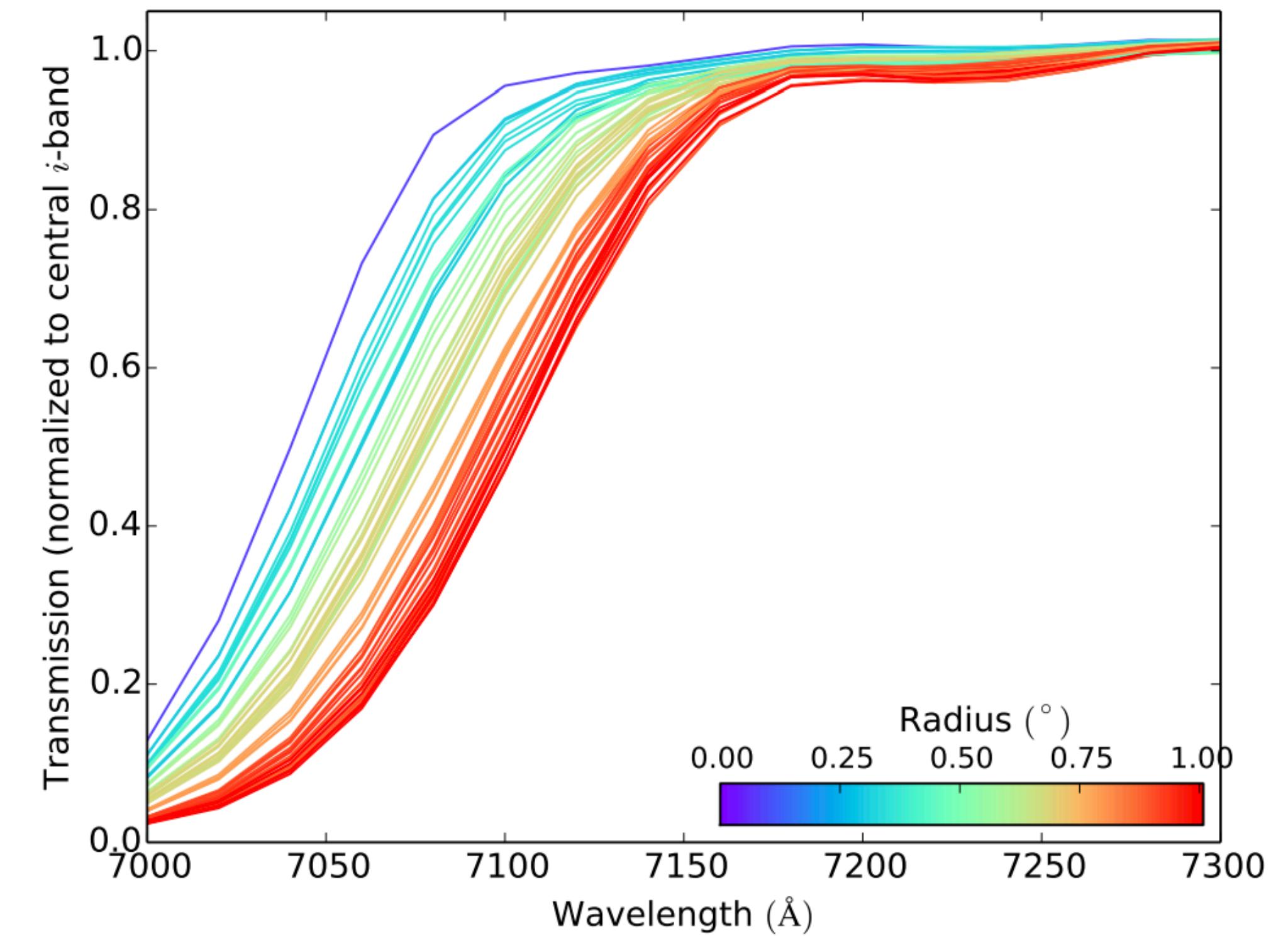


Components of atmospheric transparency.
These can vary independently over time.

Interpreting the measured flux

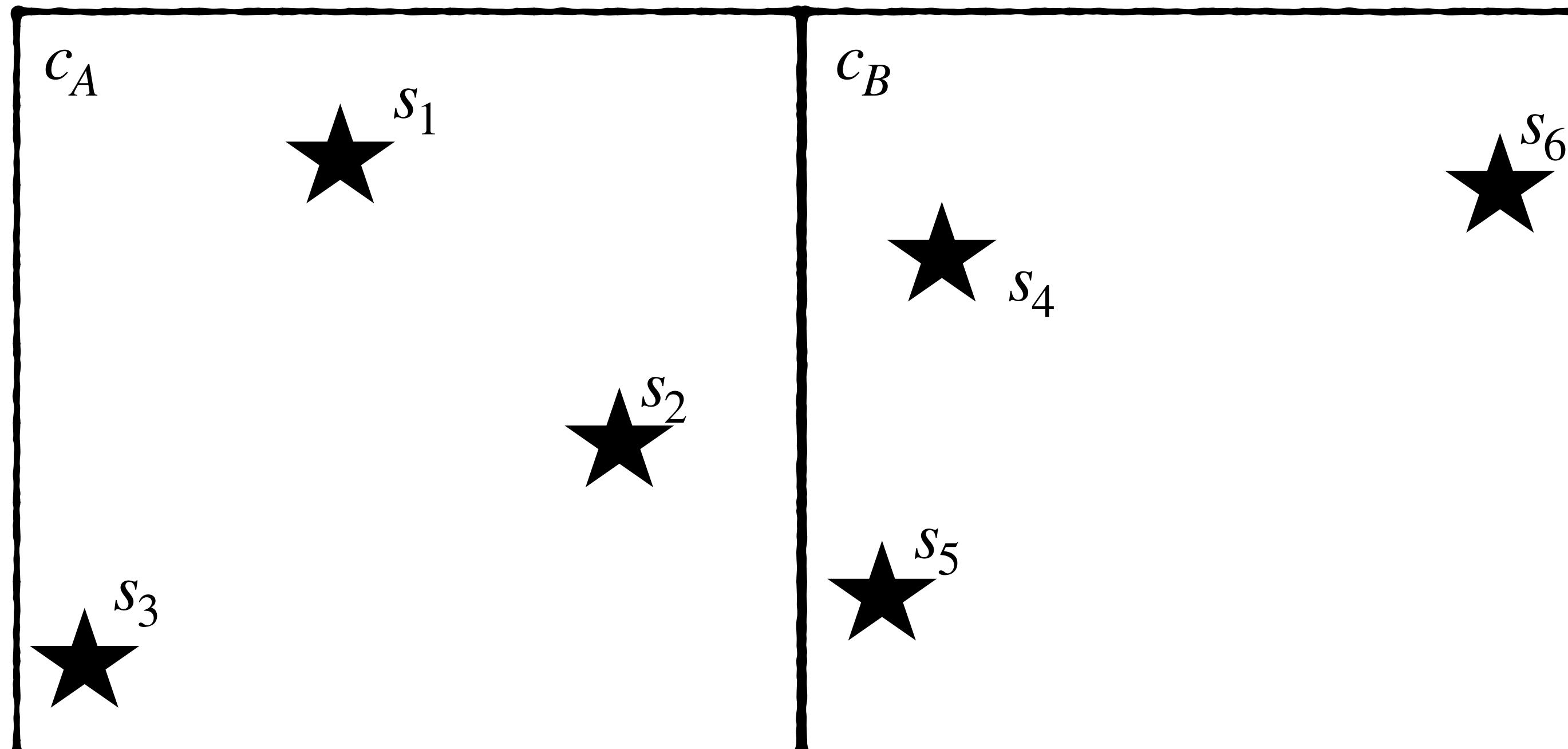
Why does the photometric calibration change?

- dust accumulates on the optical surfaces, and is cleaned off periodically.
- the mirror gradually loses reflectivity, and is re-aluminized from time to time
- the transparency of the atmosphere varies from night to night.
- the transparency of the filter varies with incidence angle of the light.



Variation in DECam i-band blue edge transmission over the field of view.

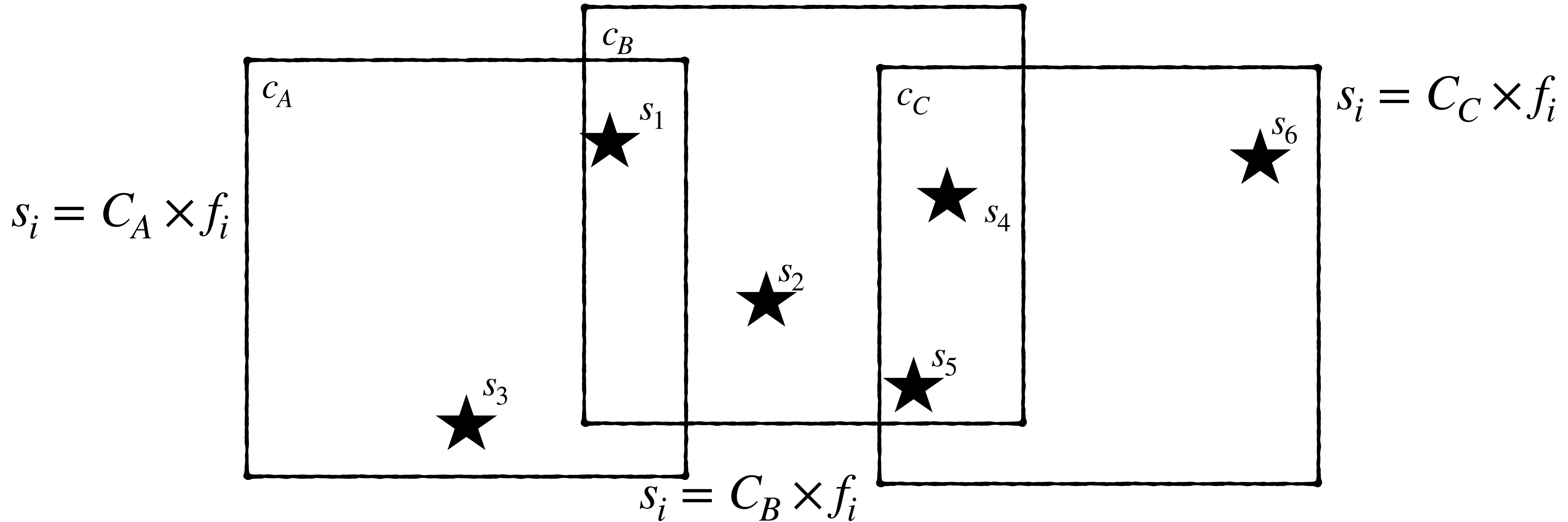
Self-consistency and ‘ubercalibration’



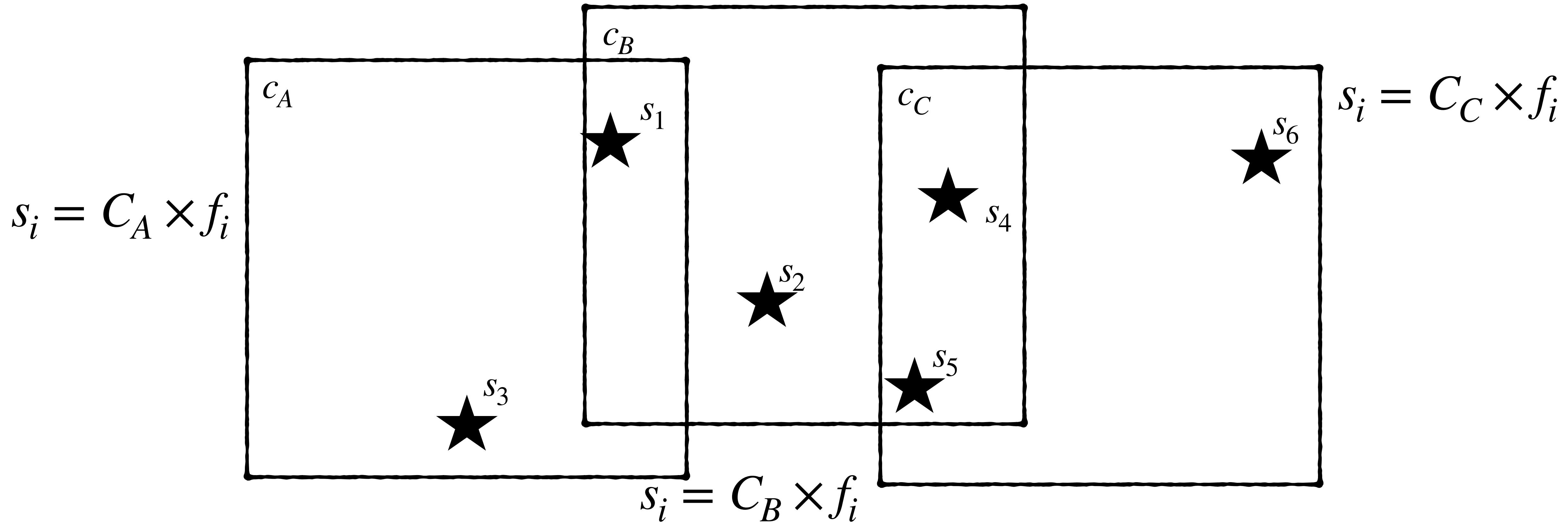
$$s_i = C_A \times f_i$$

$$s_i = C_B \times f_i$$

Self-consistency and ‘ubercalibration’



Self-consistency and ‘ubercalibration’



With overlap, we need more images, but with common measurements we can find the

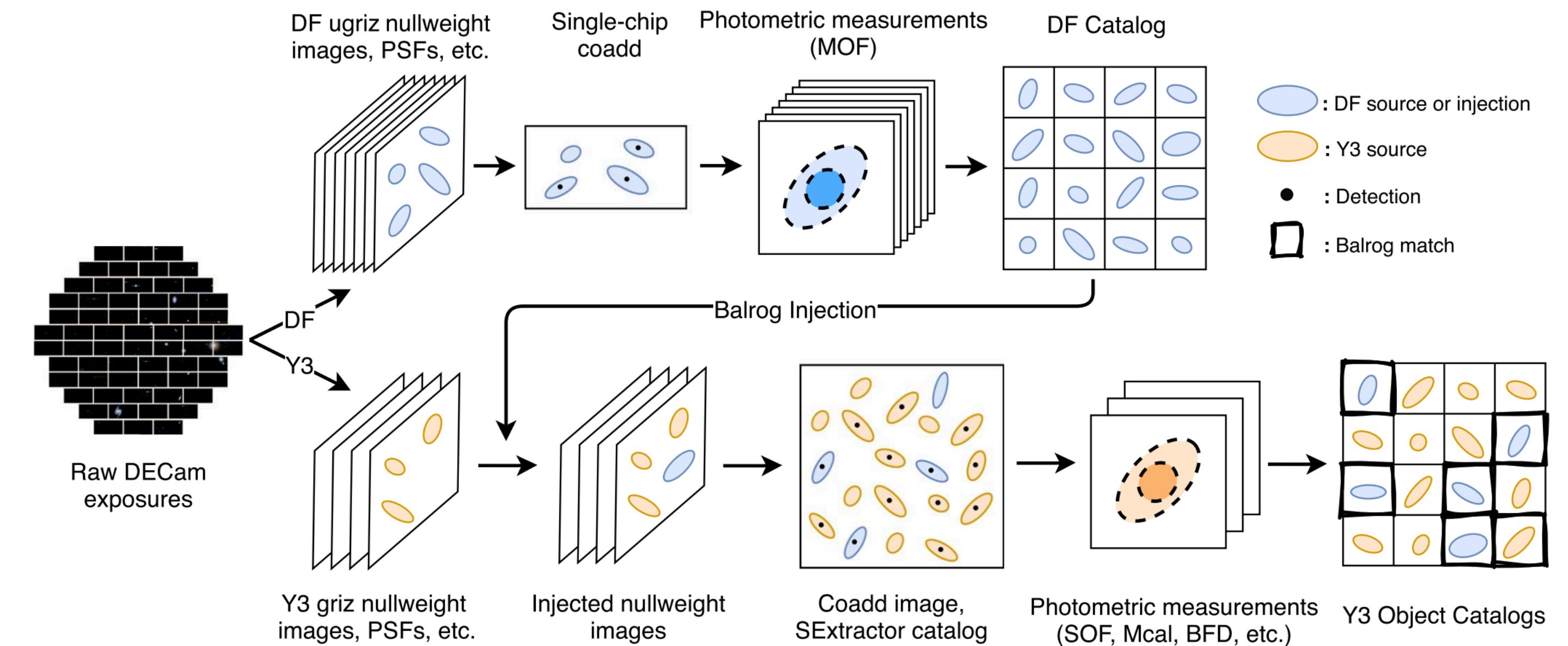
$$\text{ratios } \frac{C_A}{C_B} \text{ and } \frac{C_B}{C_C}.$$

Source injection

Measurement is very complicated.

It's actually extremely difficult to predict every possible systematic effect.

It's easier to just add known galaxies to the signal chain, and re-measure them afterwards.

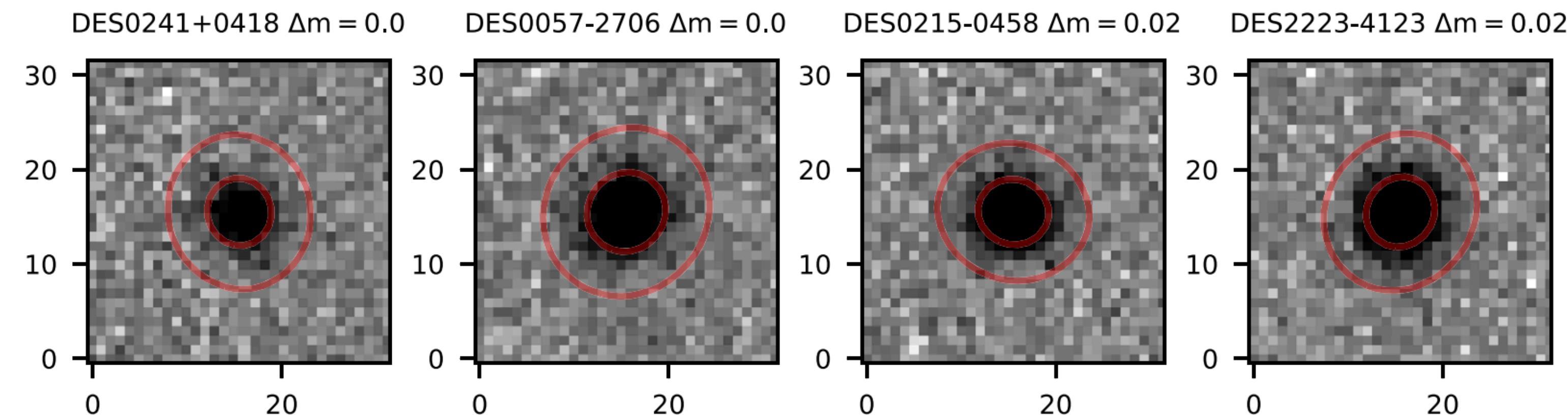
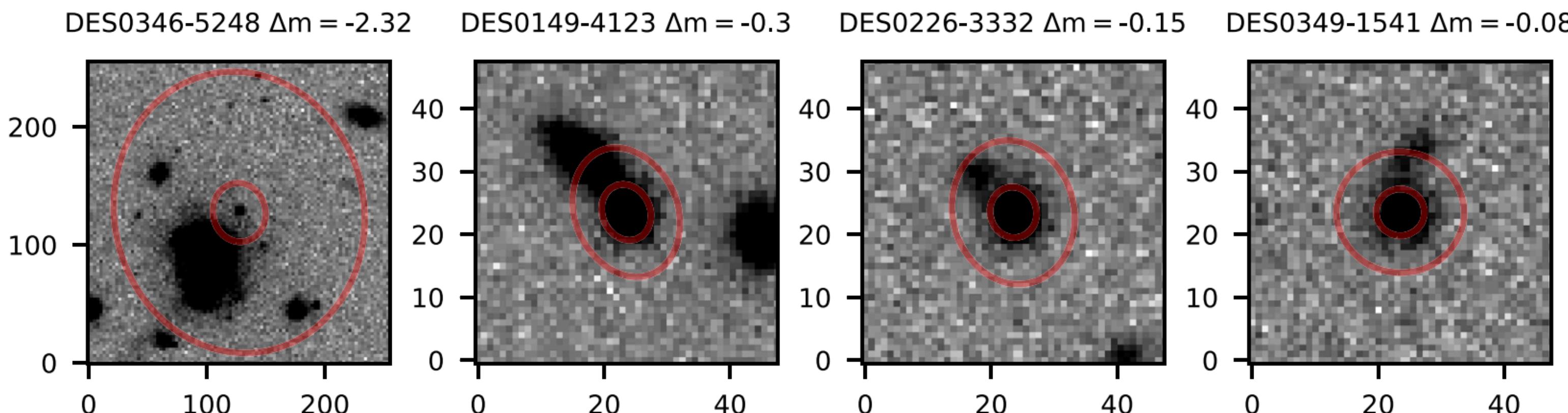


Source injection

Measurement is very complicated.

It's actually extremely difficult to predict every possible systematic effect.

It's easier to just add known galaxies to the signal chain, and re-measure them afterwards.

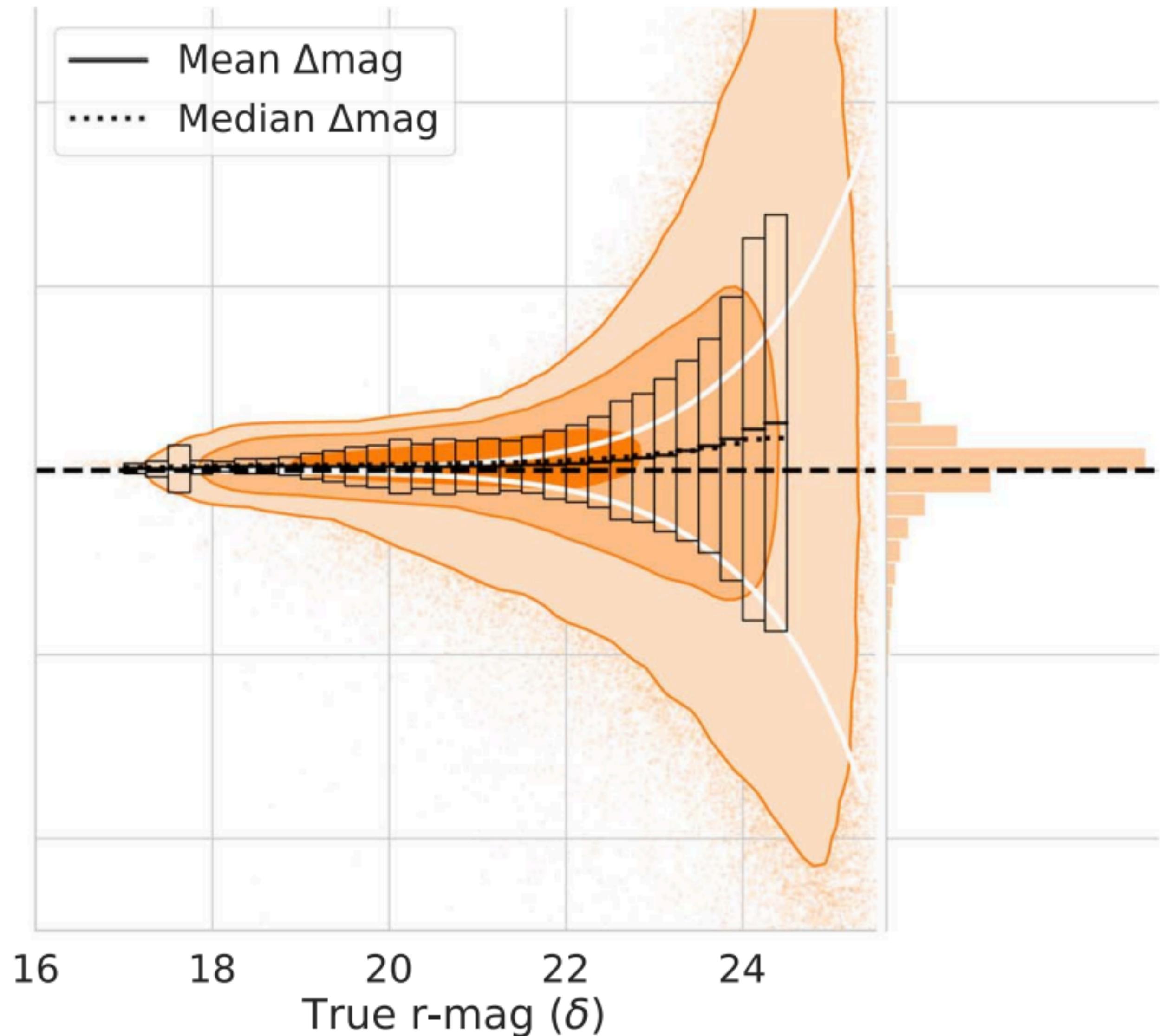


Source injection

Measurement is very complicated.

It's actually extremely difficult to predict every possible systematic effect.

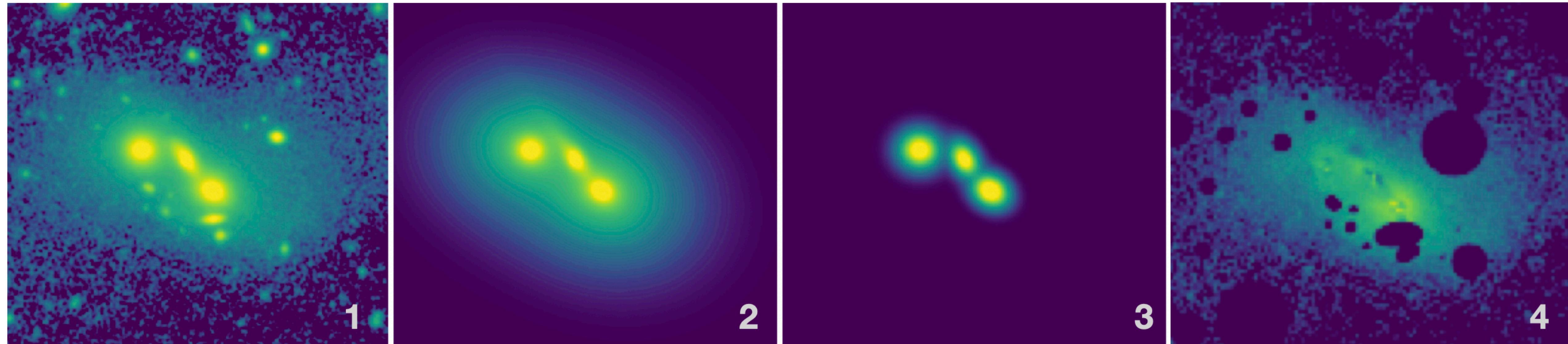
It's easier to just add known galaxies to the signal chain, and re-measure them afterwards.



Galaxy photometry with complications

Let's talk about the meaning of g and s.

$$g(\mathbf{u}) + s(u)$$

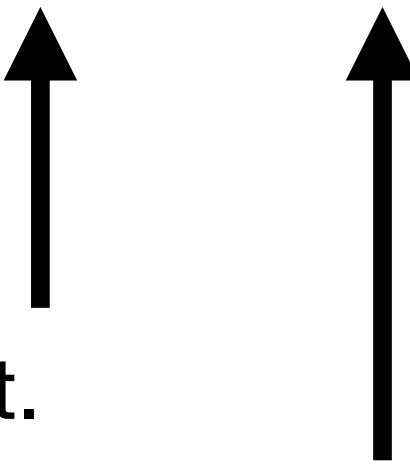


Subaru intra-group light, from Martínez-Lombilla et al. 2022

Decomposing the light into ‘source’ and ‘background’ or ‘interloper’ components is a modeling choice.

Constructing a model to fit to galaxies.

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x}) + A$$



The star or galaxy we care about.

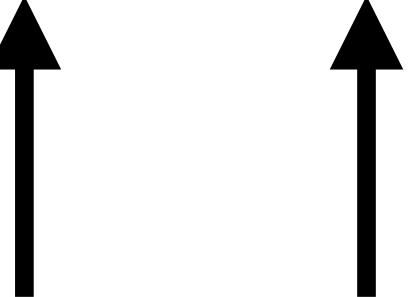
Other nearby galaxies.
Sky background
Diffuse extended light

Problem: We cannot simply construct T.

Solution:

- convert the question into a parameter estimation problem.
- add nuisance parameters to describe your model uncertainties.

Constructing a model to fit to galaxies.

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x}) + A$$


Since we don't have a 'template' for our target, we should build and fit a model.

General considerations:

- Model flexibility: can it actually fit any configuration of signal?
- Computational tractability: can we actually compute a model prediction?
- Degrees of freedom: can we actually constrain the model parameters?

Parameterized functional forms for galaxy light.

$$I_i = \int d^2\mathbf{x} \Pi(\mathbf{x} - \mathbf{x}_i) \int d^2\mathbf{u} (g(\mathbf{u}) + s(\mathbf{u})) p(\mathbf{u} - \mathbf{x}) + A$$

\uparrow

$$I = I_0 e^{-b_n \left[\left(\frac{r}{r_e} \right)^{\frac{1}{n}} - 1 \right]}$$

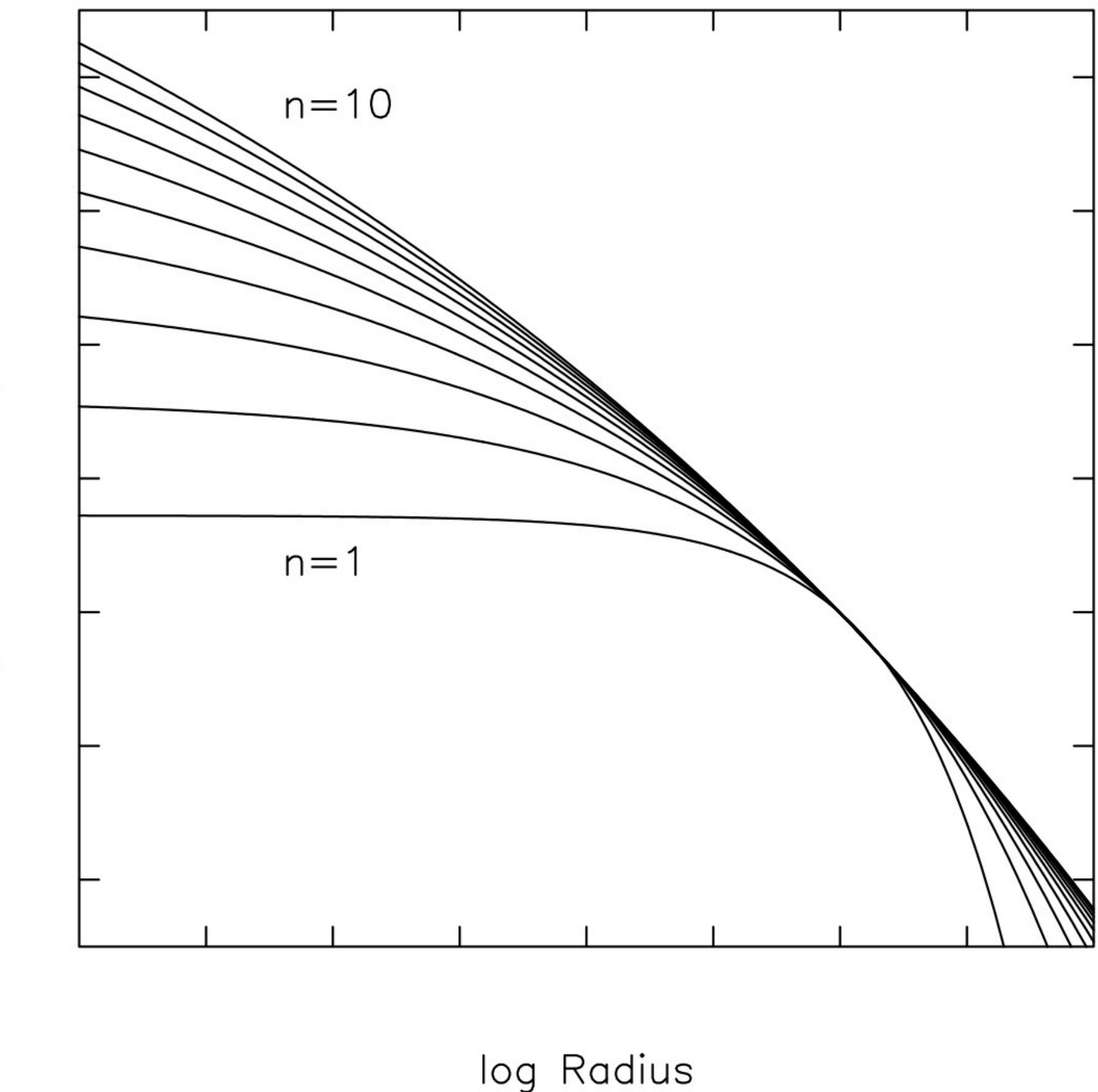
The Sérsic profile is a common parameterization for galaxy surface brightness.

n – index setting slope of profile

r_e – half-light radius

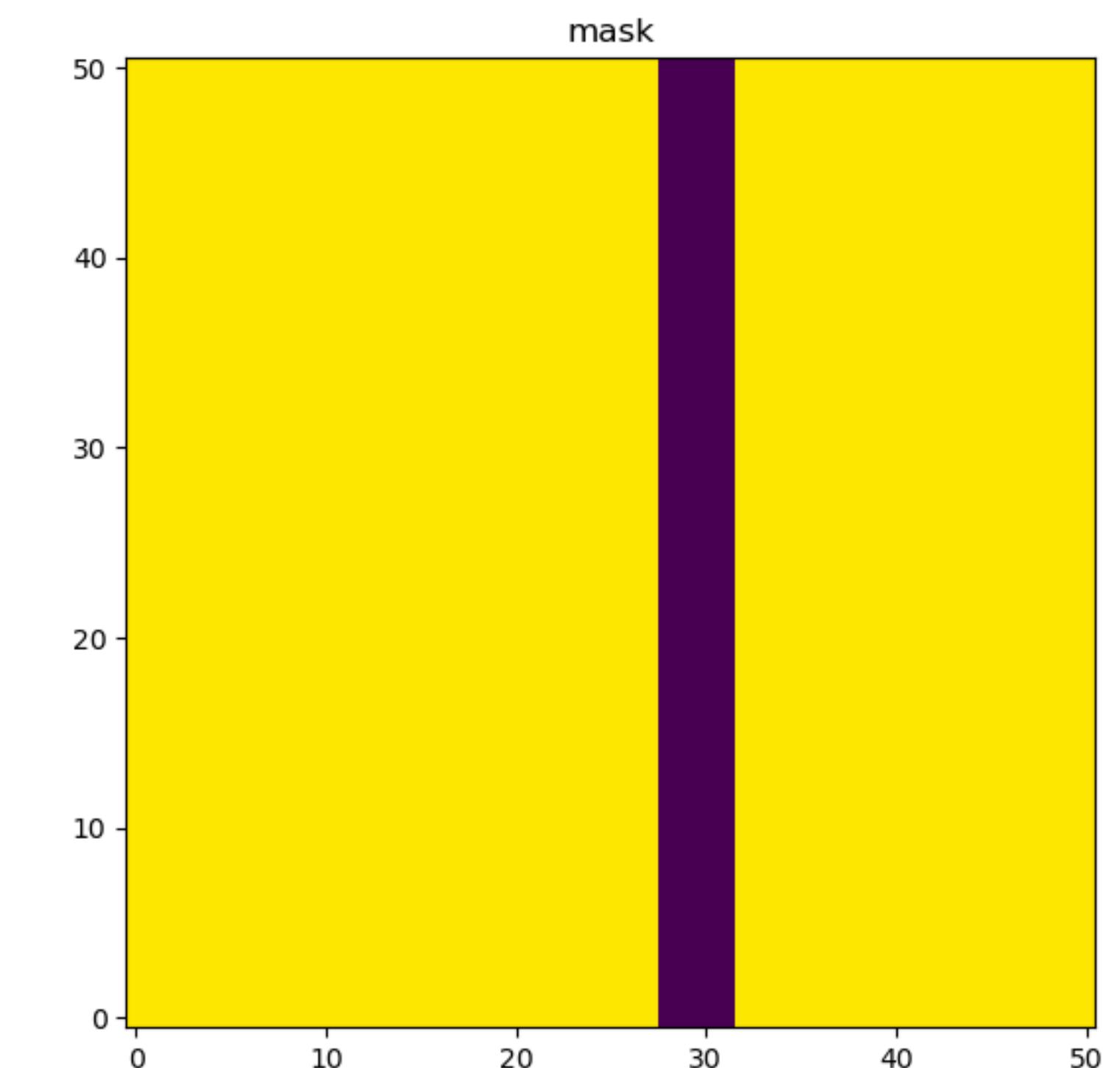
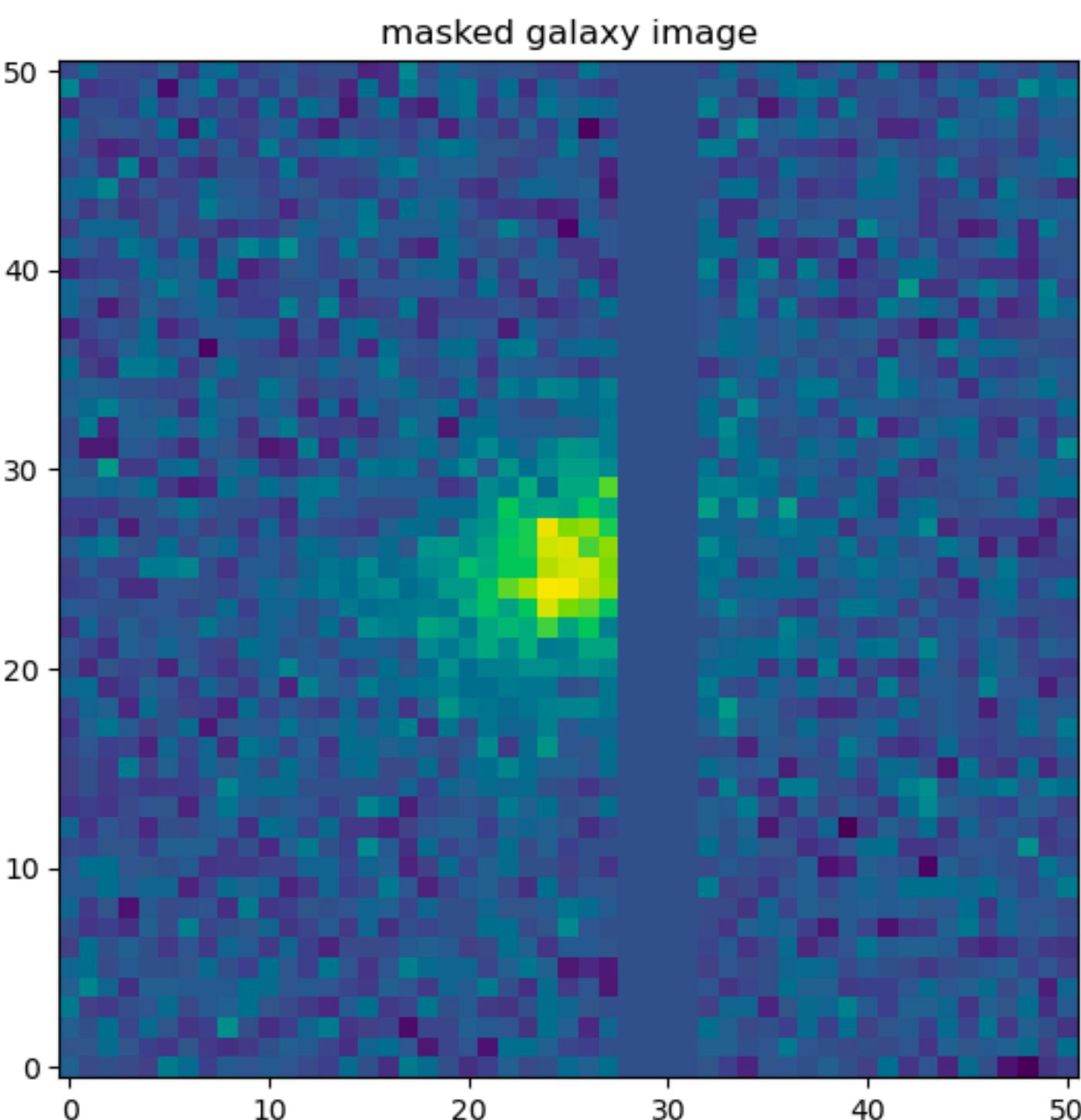
I_0 – Intensity at $r = r_e$

b_n is a function of n , roughly equal to $2n - \frac{1}{3}$



Things you can do once you can fit a model.

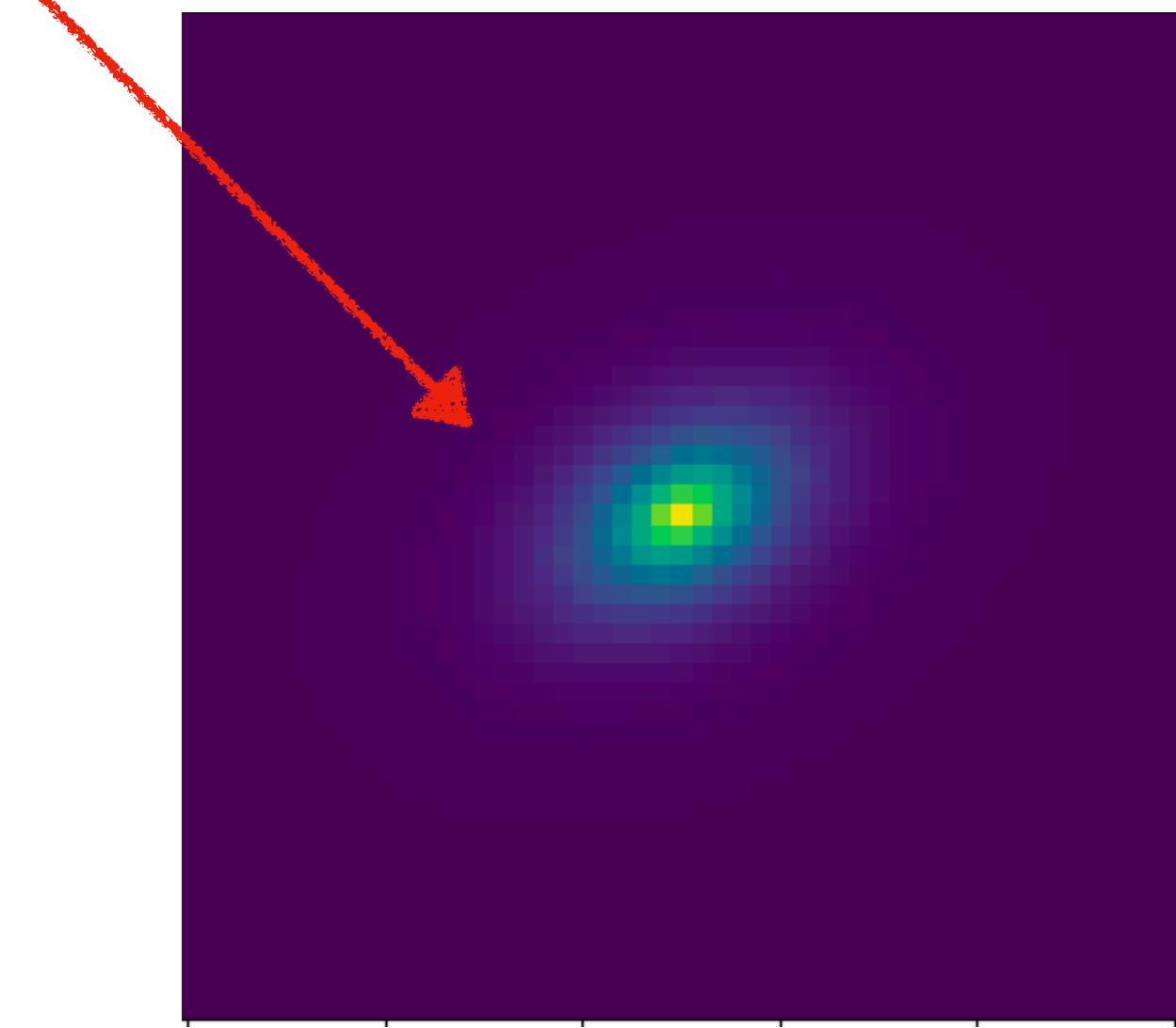
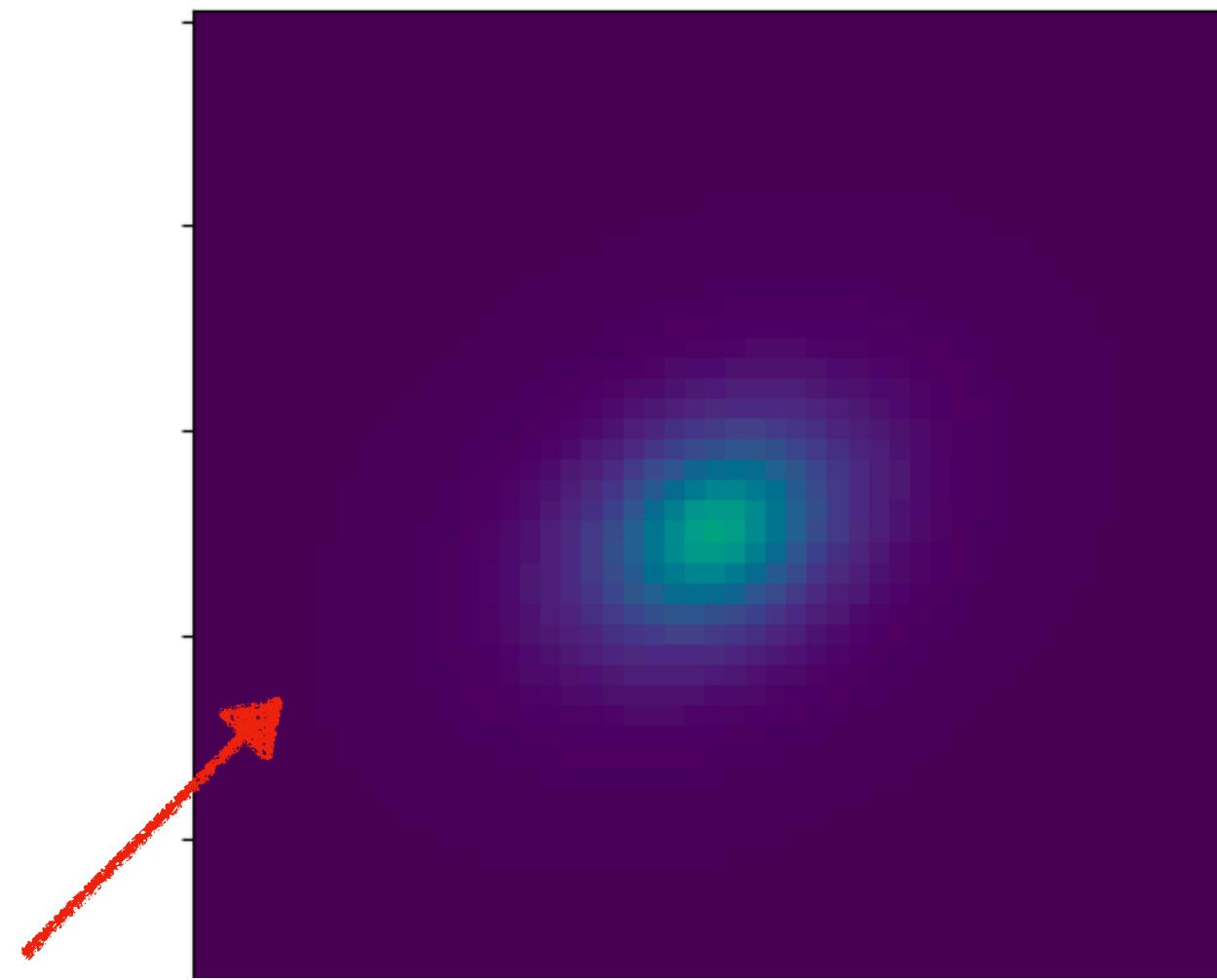
- Handle *masked* data



Things you can do once you can fit a model.

- Handle *masked* data
- Combine data with different PSFs

Same galaxy, different psf!



Things you can do once you can fit a model.

- Handle *masked* data
- Combine data with different PSFs
- deblend overlapping galaxies.



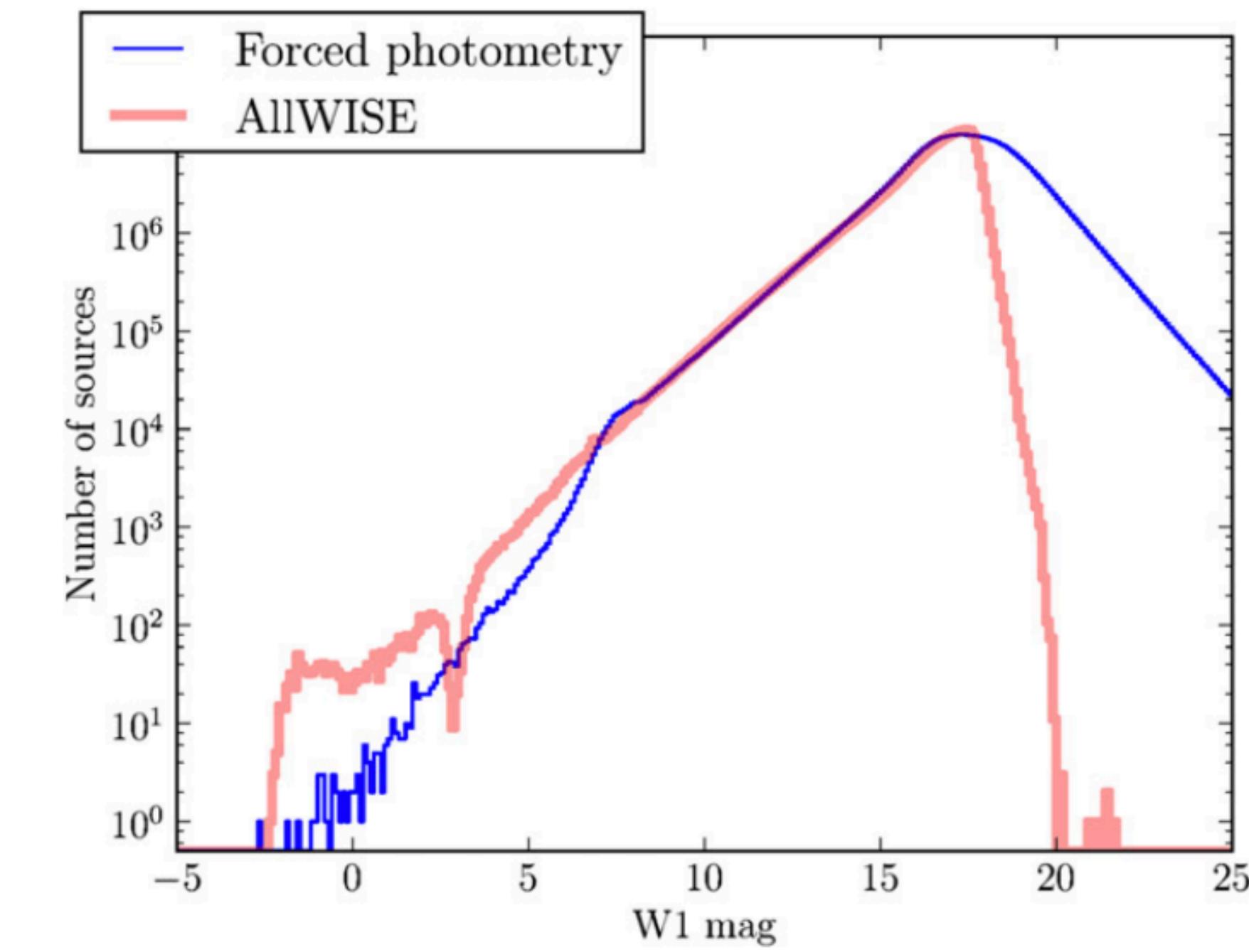
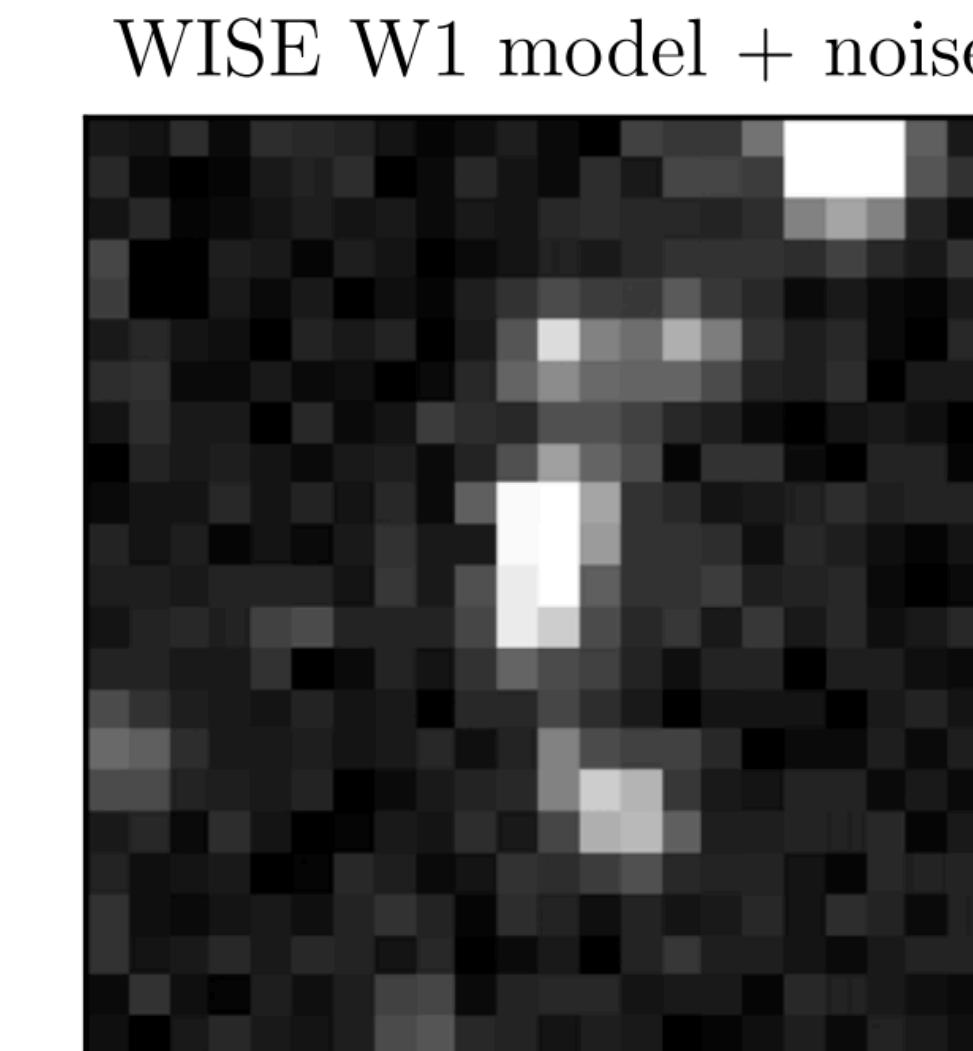
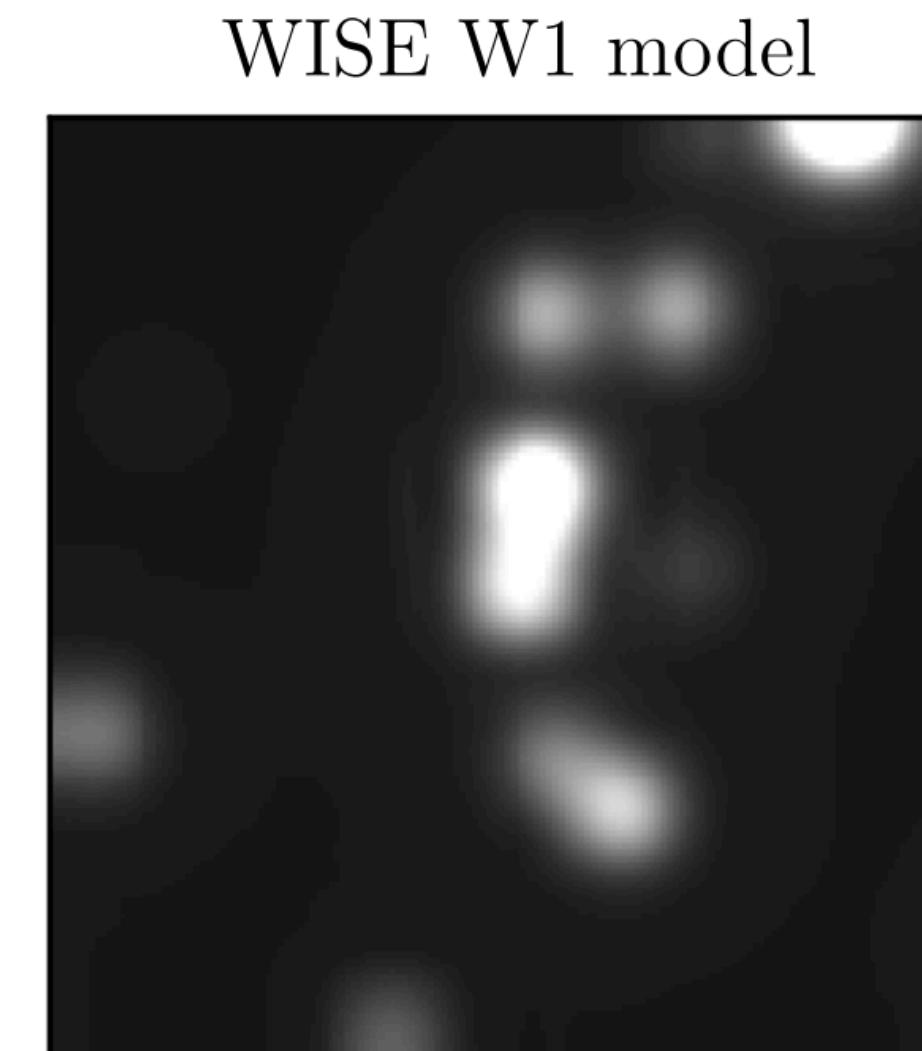
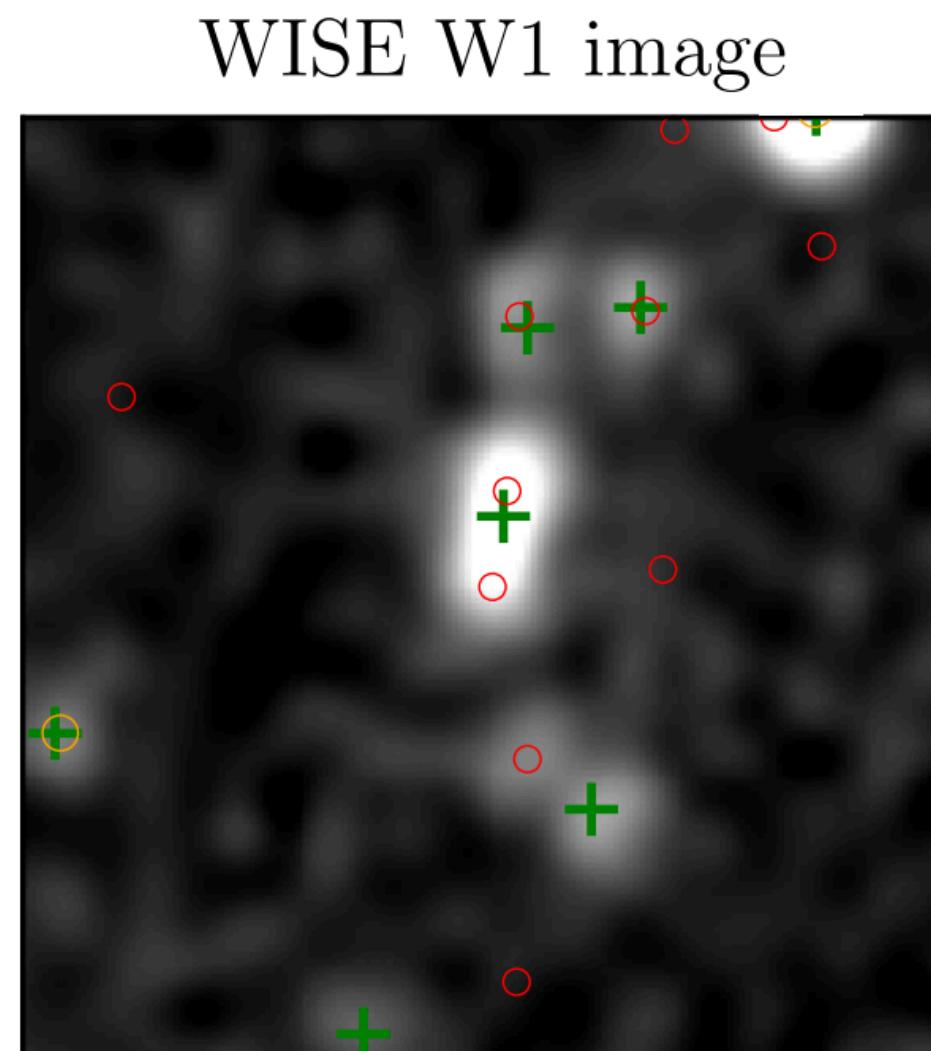
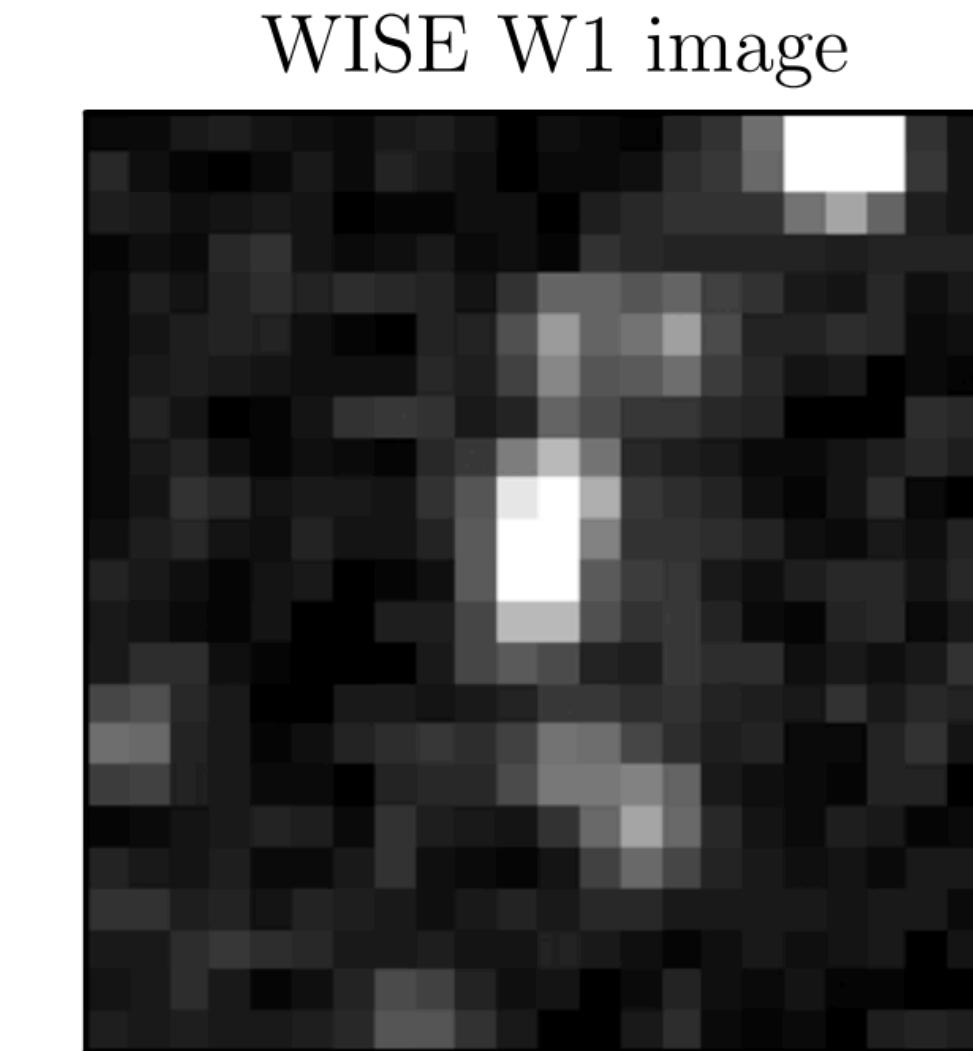
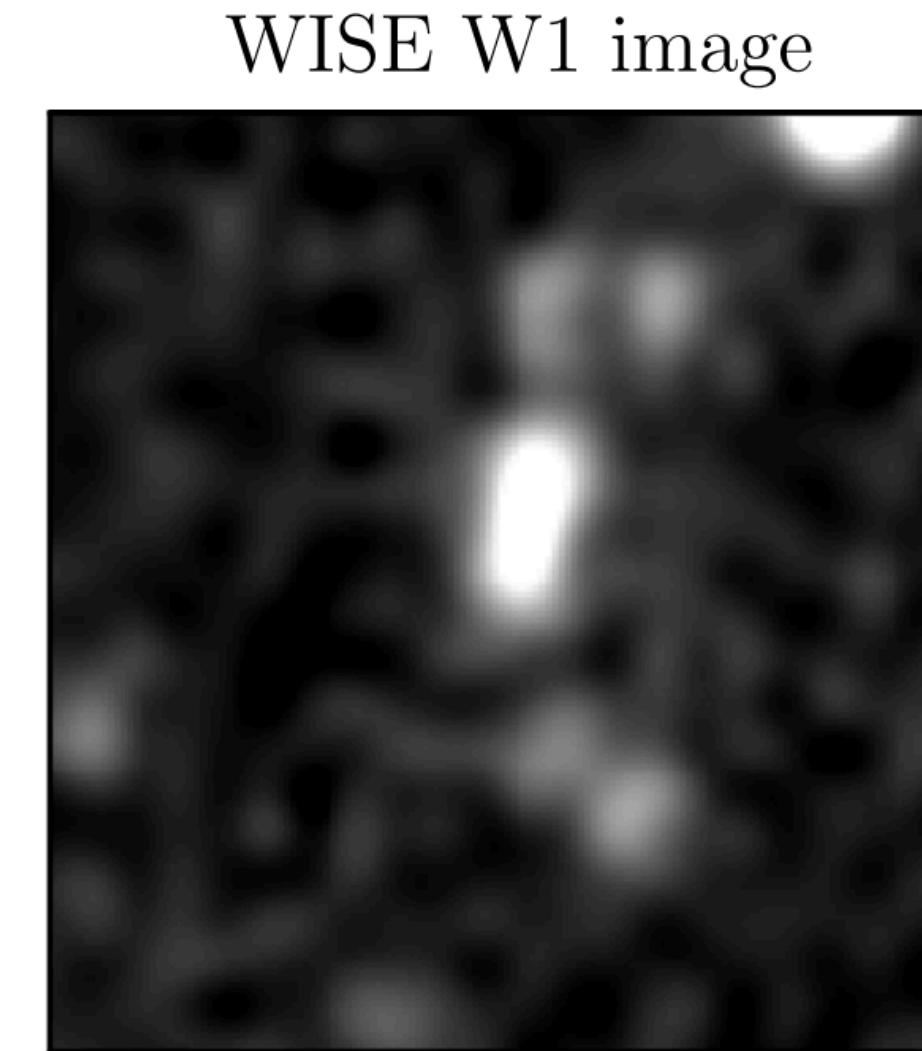
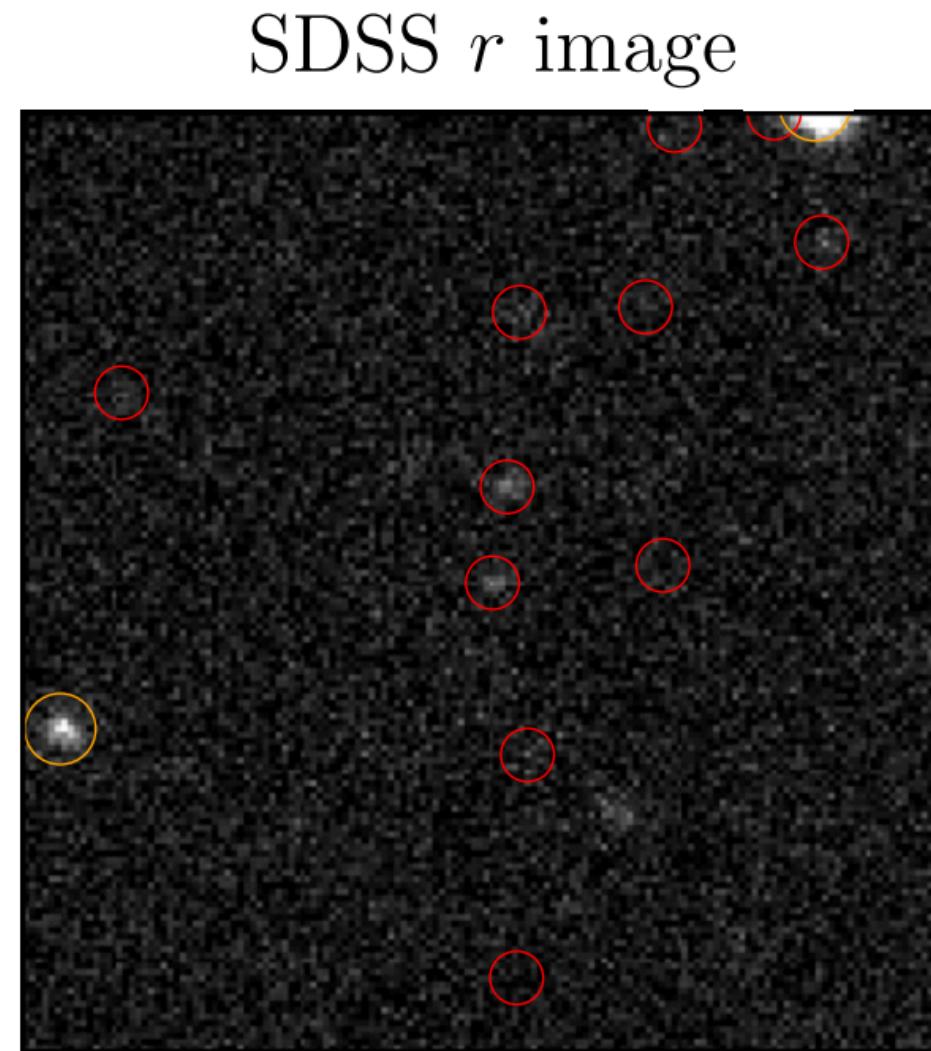
Things you can do once you can fit a model.

- Handle *masked* data
- Combine data with different PSFs
- deblend overlapping galaxies.
- Make measurements of galaxies you can't see (forced photometry)

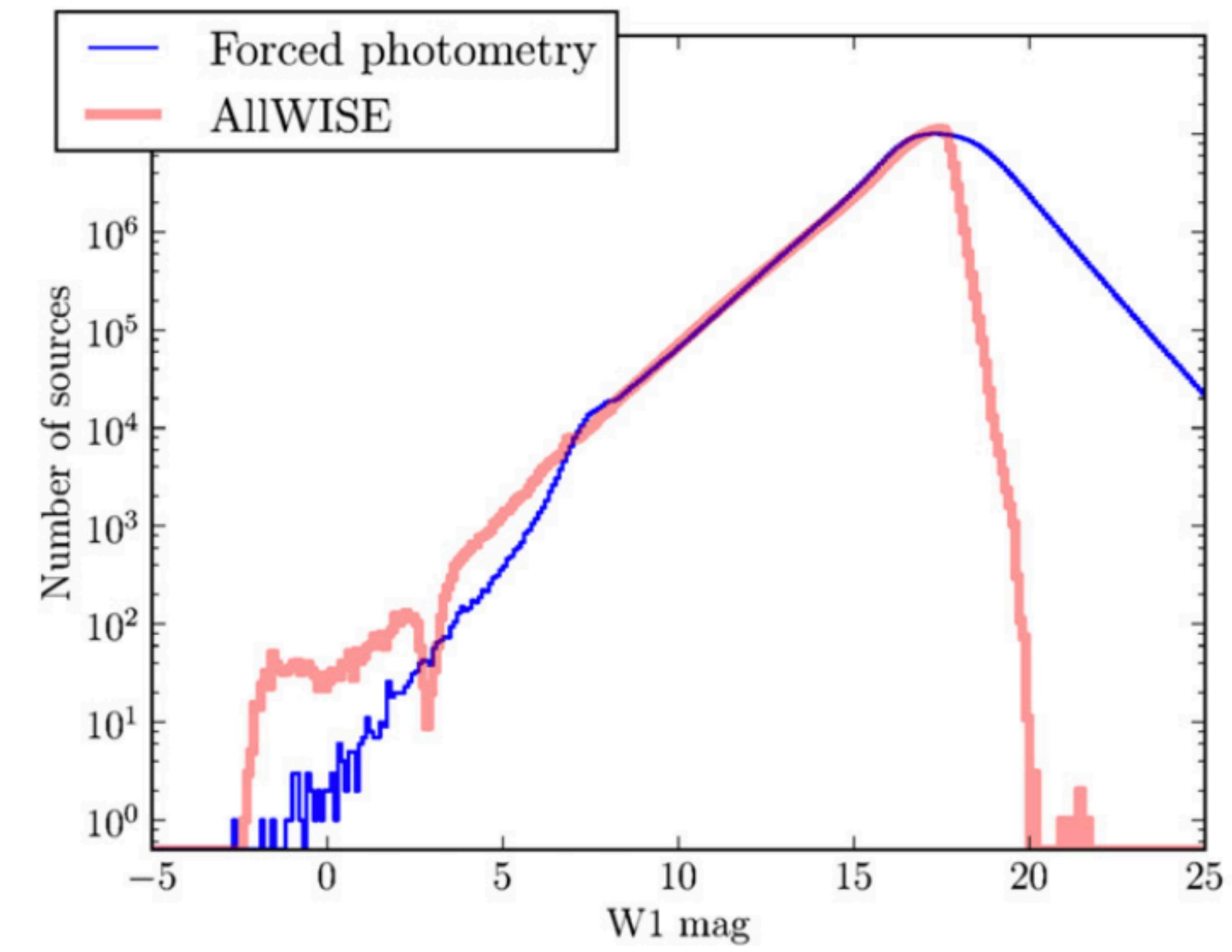
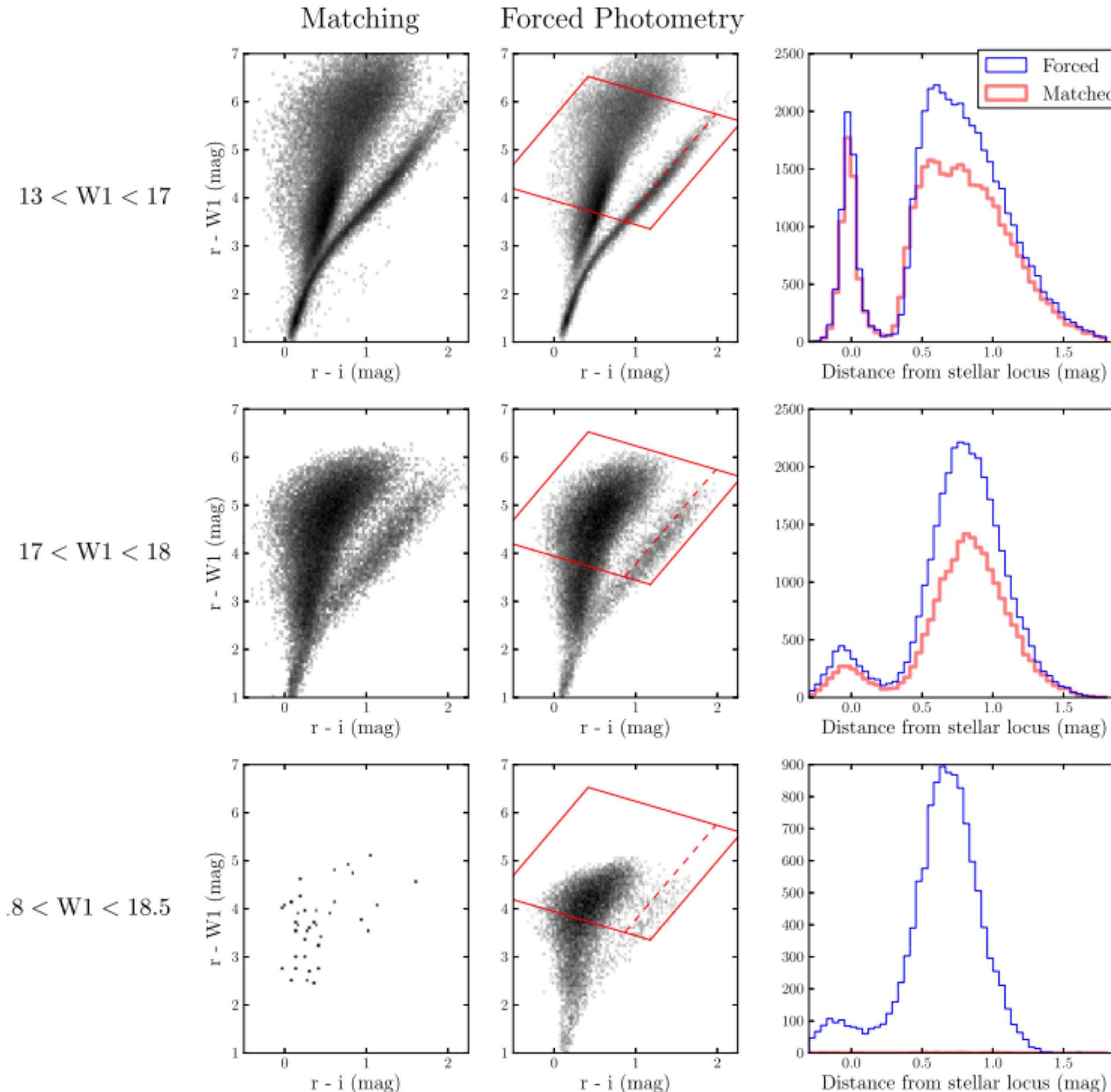
Things you can do once you can fit a model.

THE ASTRONOMICAL JOURNAL, 151:36 (12pp), 2016 February

LANG, HOGG, & SCHLEGEL

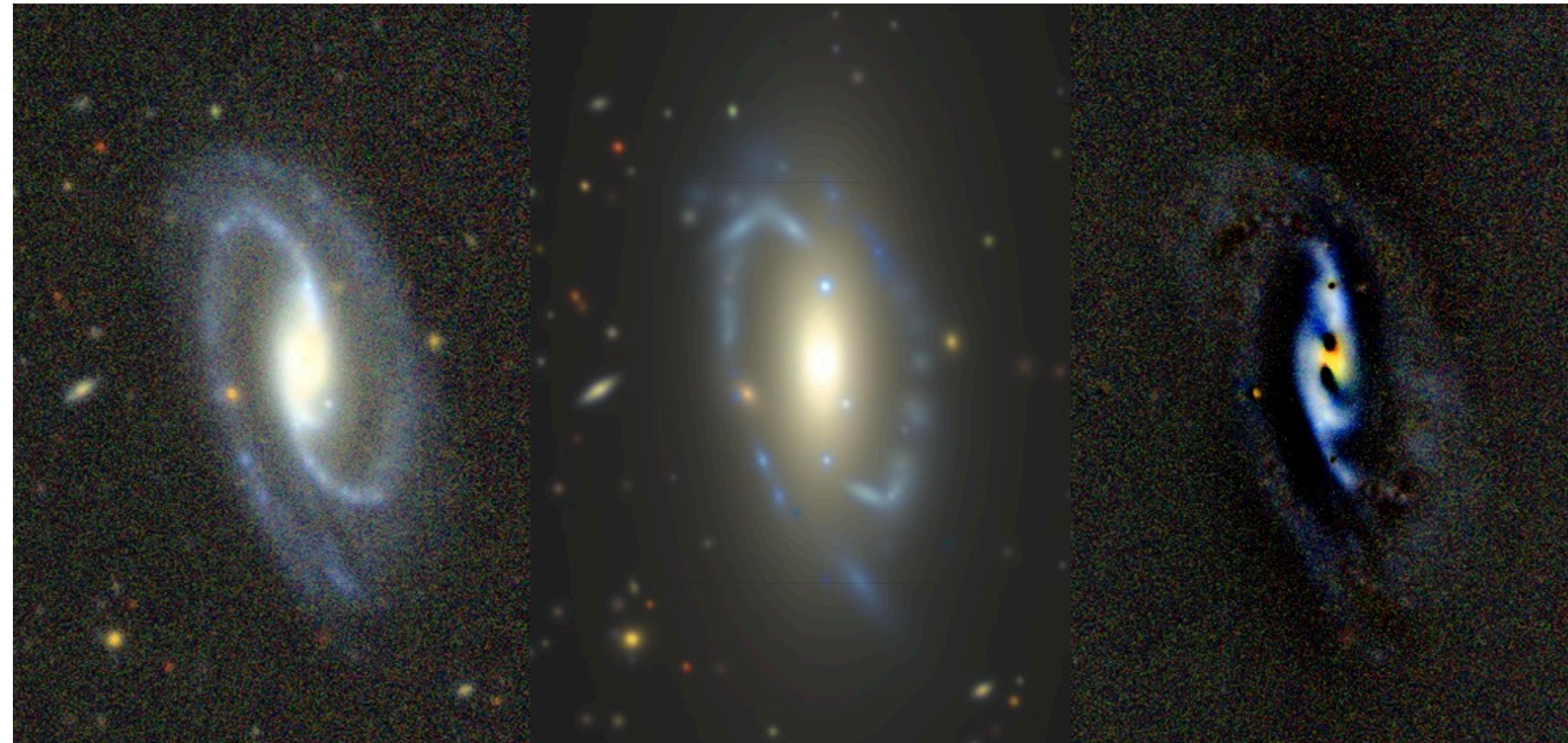


Things you can do once you can fit a model.



Things you can do once you can fit a model.

- Handle *masked* data
- Combine data with different PSFs
- deblend overlapping galaxies.
- Make measurements of galaxies you can't see (forced photometry)
- Interrogate the best-fit model



Exercise:

Open the *Simulated galaxy photometry.ipynb* notebook.

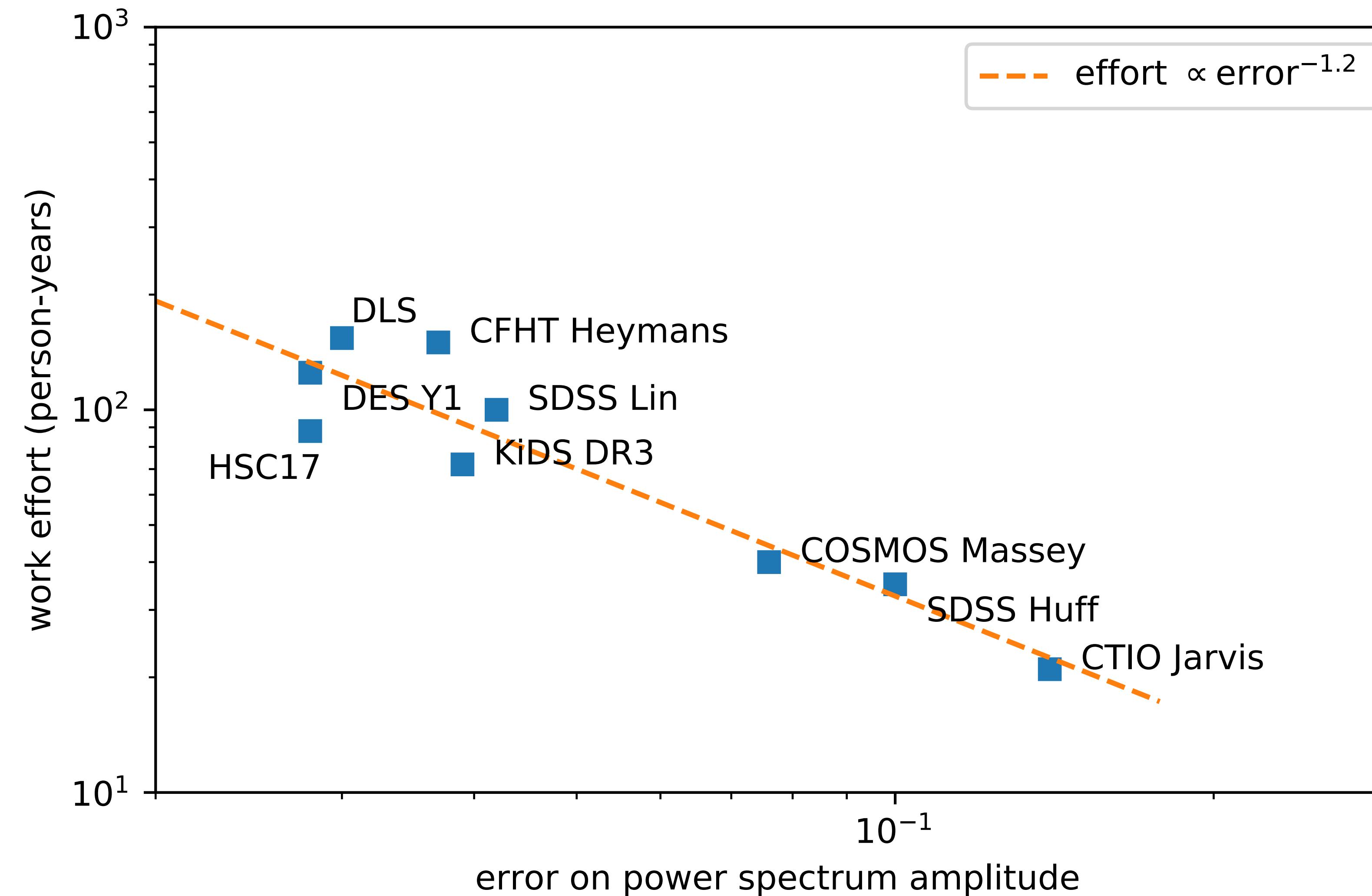
This will take us through the galaxy photometry model-fitting exercise.

Exercise:

Open the *Measurements with GalSim* notebook.

This will give you a measurement task on real data.

Larger context: precision science is hard!



Larger context: precision science is hard!

