

# Lecture 6: More on Connectivity

Shuai Li

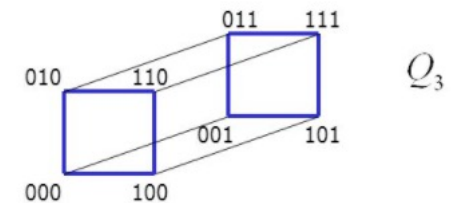
John Hopcroft Center, Shanghai Jiao Tong University

<https://shuaili8.github.io>

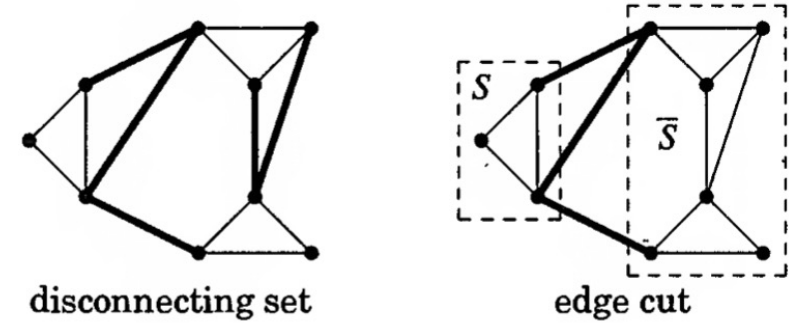
<https://shuaili8.github.io/Teaching/CS445/index.html>

# Vertex cut set and connectivity

- A proper subset  $S$  of vertices is a **vertex cut set** if the graph  $G - S$  is disconnected
- The **connectivity**,  $\kappa(G)$ , is the minimum size of a vertex set  $S$  of  $G$  such that  $G - S$  is disconnected or has only one vertex
  - The graph is  $k$ -connected if  $k \leq \kappa(G)$
- $\kappa(K^n) := n - 1$
- If  $G$  is disconnected,  $\kappa(G) = 0$ 
  - $\Rightarrow$  A graph is connected  $\Leftrightarrow \kappa(G) \geq 1$
- If  $G$  is connected, non-complete graph of order  $n$ , then
$$1 \leq \kappa(G) \leq n - 2$$
- For convention,  $\kappa(K_1) = 0$
- **Example** (4.1.3, W) For  $k$ -dimensional cube  $Q_k = \{0,1\}^k$ ,  $\kappa(Q_k) = k$



# Edge-connectivity



- A **disconnecting set** of edges is a set  $F \subseteq E(G)$  such that  $G - F$  has more than one component
  - A graph is  **$k$ -edge-connected** if every disconnecting set has at least  $k$  edges
  - The **edge-connectivity** of  $G$ , written  $\lambda(G)$ , is the minimum size of a disconnecting set
- Given  $S, T \subseteq V(G)$ , we write  $[S, T]$  for the set of edges having one endpoint in  $S$  and the other in  $T$ 
  - An **edge cut** is an edge set of the form  $[S, S^c]$  where  $S$  is a nonempty proper subset of  $V(G)$
- Every edge cut is a disconnecting set, but not vice versa
- **Remark** (4.1.8, W) Every minimal disconnecting set of edges is an edge cut

# Connectivity and edge-connectivity

- **Proposition** (1.4.2, D) If  $G$  is non-trivial, then  $\kappa(G) \leq \lambda(G) \leq \delta(G)$
- If  $\delta(G) \geq n - 2$ , then  $\kappa(G) = \delta(G)$
- **Theorem** (4.1.11, W) If  $G$  is a 3-regular graph, then  $\kappa(G) = \lambda(G)$

# Properties of edge cut

- When  $\lambda(G) < \delta(G)$ , a minimum edge cut cannot isolate a vertex
- Similarly for (any) edge cut

- **Proposition** (4.1.12, W) If  $S$  is a set of vertices in a graph  $G$ , then

$$|[S, S^c]| = \sum_{v \in S} d(v) - 2e(G[S])$$

- **Corollary** (4.1.13, W) If  $G$  is a simple graph and  $|[S, S^c]| < \delta(G)$ , then  $|S| > \delta(G)$ 
  - $|S|$  must be much larger than a single vertex

# Blocks

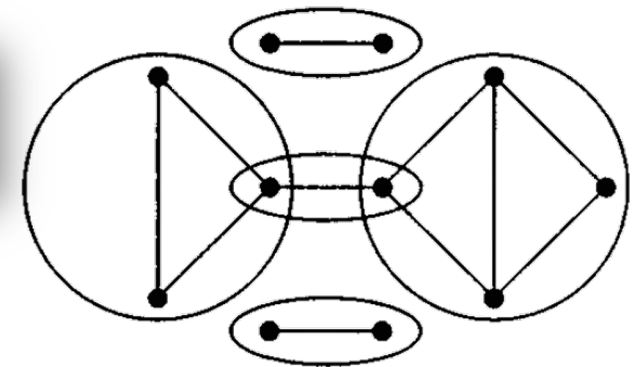
- A **block** of a graph  $G$  is a maximal connected subgraph of  $G$  that has no cut-vertex. If  $G$  itself is connected and has no cut-vertex, then  $G$  is a block

**Proposition** (1.2.14, W)

An edge  $e$  is a bridge  $\Leftrightarrow e$  lies on no cycle of  $G$

• Or equivalently, an edge  $e$  is not a bridge  $\Leftrightarrow e$  lies on a cycle of  $G$

- Example
- An edge of a cycle cannot itself be a block
  - An edge is block  $\Leftrightarrow$  it is a bridge
  - The blocks of a tree are its edges
- If a block has more than two vertices, then it is 2-connected
  - The blocks of a loopless graph are its isolated vertices, bridges, and its maximal 2-connected subgraphs

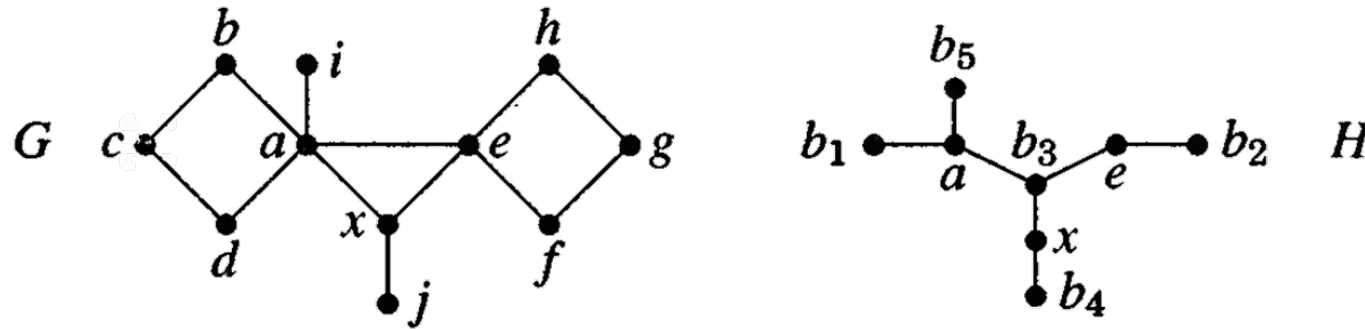


# Intersection of two blocks

- **Proposition** (4.1.19, W) Two blocks in a graph share at most one vertex
  - When two blocks share a vertex, it must be a cut-vertex
- Every edge is a subgraph with no cut-vertex and hence is in a block. Thus blocks in a graph decompose the edge set

# Block-cutpoint graph

- The **block-cutpoint graph** of a graph  $G$  is a bipartite graph  $H$  in which one partite set consists of the cut-vertices of  $G$ , and the other has a vertex  $b_i$  for each block  $B_i$  of  $G$ . We include  $vb_i$  as an edge of  $H \iff v \in B_i$ .

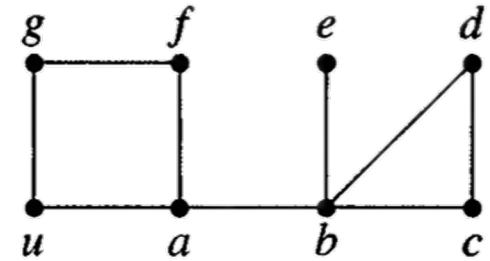


- (Ex34, S4.1, W) When  $G$  is connected, its block-cutpoint graph is a tree



# Depth-first search (DFS)

- Depth-first search

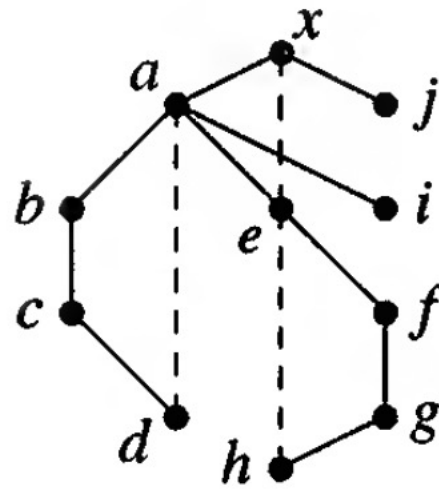
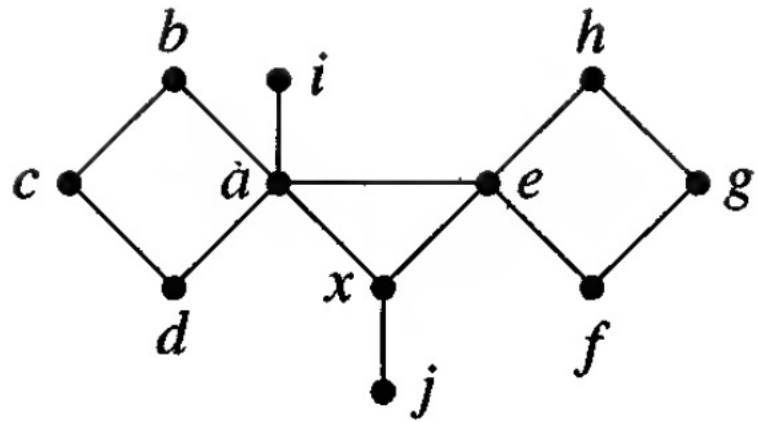
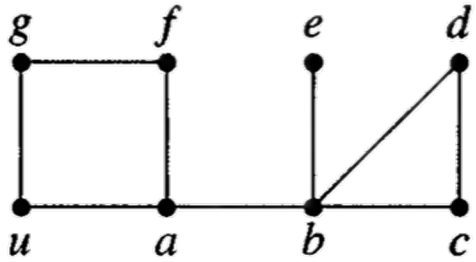


- **Lemma** (4.1.22, W) If  $T$  is a spanning tree of a connected graph grown by DFS from  $u$ , then every edge of  $G$  not in  $T$  consists of two vertices  $v, w$  such that  $v$  lies on the  $u, w$ -path in  $T$

# Finding blocks by DFS

- **Input:** A connected graph  $G$
- **Idea:** Build a DFS tree  $T$  of  $G$ , discarding portions of  $T$  as blocks are identified. Maintain one vertex called ACTIVE
- **Initialization:** Pick a root  $x \in V(H)$ ; make  $x$  ACTIVE; set  $T = \{x\}$
- **Iteration:** Let  $v$  denote the current active vertex
  - If  $v$  has an unexplored incident edge  $vw$ , then
    - If  $w \notin V(T)$ , then add  $vw$  to  $T$ , mark  $vw$  explored, make  $w$  ACTIVE
    - If  $w \in V(T)$ , then  $w$  is an ancestor of  $v$ ; mark  $vw$  explored
  - If  $v$  has no more unexplored incident edges, then
    - If  $v \neq x$  and  $w$  is a parent of  $v$ , make  $w$  ACTIVE. If no vertex in the current subtree  $T'$  rooted at  $v$  has an explored edge to an ancestor above  $w$ , then  $V(T') \cup \{w\}$  is the vertex set of a block; record this information and delete  $V(T')$
    - if  $v = x$ , terminate

# Example



# Strong orientation

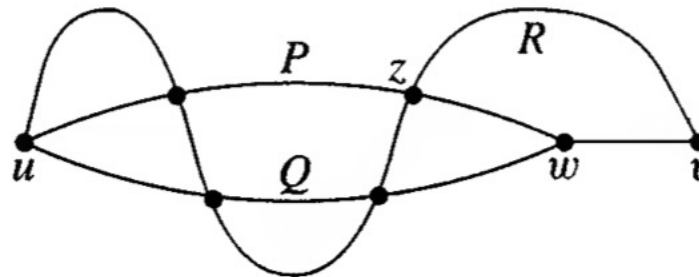
- **Theorem** (2.5, L) Let  $G$  be a finite connected graph without bridges. Then  $G$  admits a strong orientation, i.e. an orientation that is a strongly connected digraph
  - A directed graph is strongly connected if for every pair of vertices  $(v, w)$ , there is a directed path from  $v$  to  $w$

• The blocks of a loopless graph are its isolated vertices, bridges, and its maximal 2-connected subgraphs

# 2-Connected Graphs

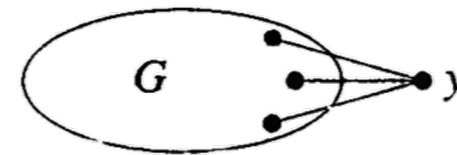
# 2-connected graphs

- Two paths from  $u$  to  $v$  are **internally disjoint** if they have no common internal vertex
- **Theorem** (4.2.2, W; Whitney 1932)  
A graph  $G$  having at least three vertices is 2-connected  $\Leftrightarrow$  for each pair  $u, v \in V(G)$  there exist internally disjoint  $u, v$ -paths in  $G$

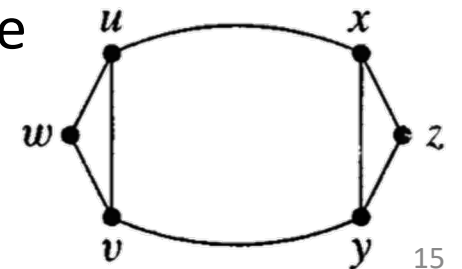


# Equivalent definitions for 2-connected graphs

- **Lemma** (4.2.3, W; Expansion Lemma) If  $G$  is a  $k$ -connected graph, and  $G'$  is obtained from  $G$  by adding a new vertex  $y$  with at least  $k$  neighbors in  $G$ , then  $G'$  is  $k$ -connected

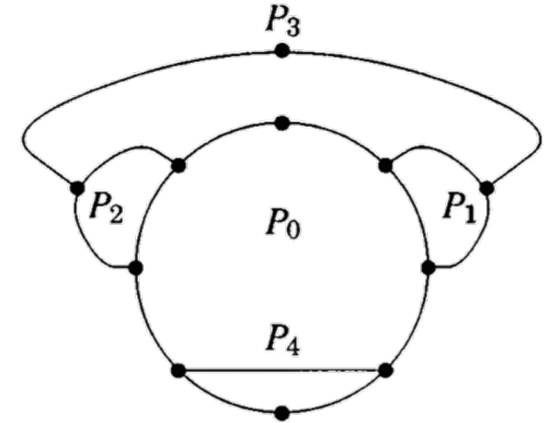


- **Theorem** (4.2.4, W) For a graph  $G$  with at least three vertices, TFAE
  - $G$  is connected and has no cut-vertex
  - For all  $x, y \in V(G)$ , there are internally disjoint  $x, y$ -paths
  - For all  $x, y \in V(G)$ , there is a cycle through  $x$  and  $y$
  - $\delta(G) \geq 1$  and every pair of edges in  $G$  lies on a common cycle



# Ear decomposition

- An **ear** of a graph  $G$  is a maximal **path** whose internal vertices have degree 2 in  $G$
- An **ear decomposition** of  $G$  is a decomposition  $P_0, \dots, P_k$  such that  $P_0$  is a cycle and  $P_i$  for  $i \geq 1$  is an ear of  $P_0 \cup \dots \cup P_i$
- **Theorem** (4.2.8, W)  
A graph is 2-connected  $\iff$  it has an ear decomposition.  
Furthermore, every cycle in a 2-connected graph is the initial cycle in some ear decomposition
- **Corollary** (4.2.6, W) If  $G$  is 2-connected, then the graph  $G'$  obtained by **subdividing** an edge of  $G$  is 2-connected



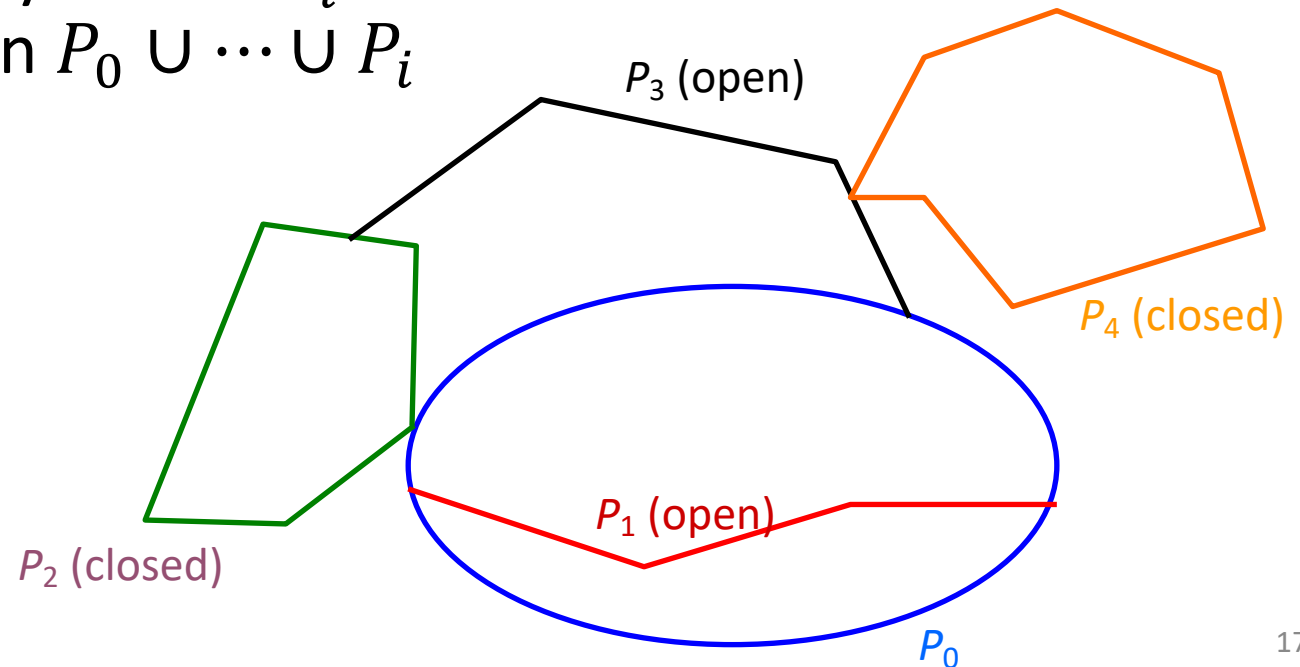
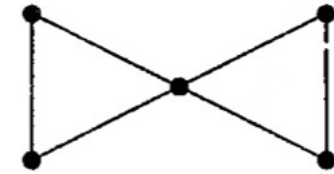
(Ex14, S1.1.2, H)  $\kappa(G) \geq 2$  implies  $G$  has at least one cycle





# Closed-ear

- A **closed ear** of a graph  $G$  is a **cycle**  $C$  such that all vertices of  $C$  except one have degree 2 in  $G$
- A **closed-ear decomposition** of  $G$  is a decomposition  $P_0, \dots, P_k$  such that  $P_0$  is a cycle and  $P_i$  for  $i \geq 1$  is an (open) ear or a closed ear in  $P_0 \cup \dots \cup P_i$



# Closed-ear decomposition

- **Theorem** (4.2.10, W)

A graph is 2-edge-connected  $\Leftrightarrow$  it has a closed-ear decomposition.  
Every cycle in a 2-edge-connected graph is the initial cycle in some such decomposition

**Proposition** (1.2.14, W)

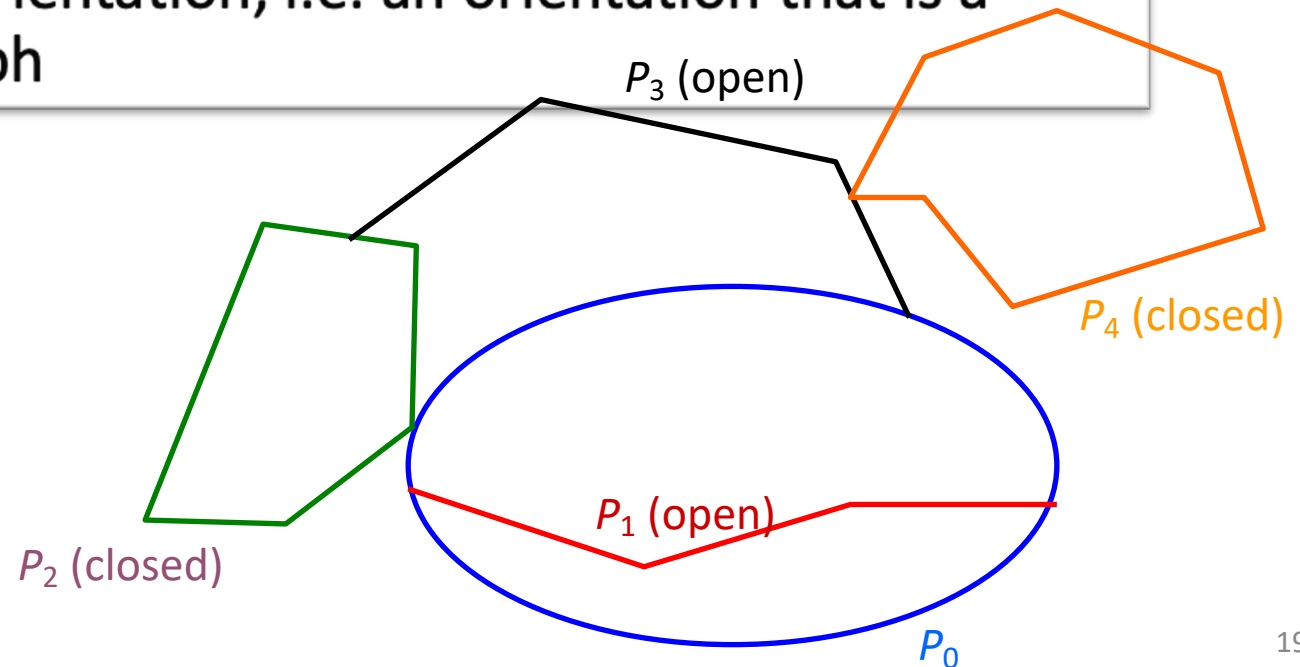
An edge  $e$  is a bridge  $\Leftrightarrow e$  lies on no cycle of  $G$

- Or equivalently, an edge  $e$  is not a bridge  $\Leftrightarrow e$  lies on a cycle of  $G$

# Strong orientation (Revisited)

- **Theorem** (4.2.14, W; Robbins 1939) A graph has a strong orientation  $\Leftrightarrow$  it is 2-edge-connected

**Theorem** (2.5, L) Let  $G$  be a finite connected graph without bridges. Then  $G$  admits a strong orientation, i.e. an orientation that is a strongly connected digraph



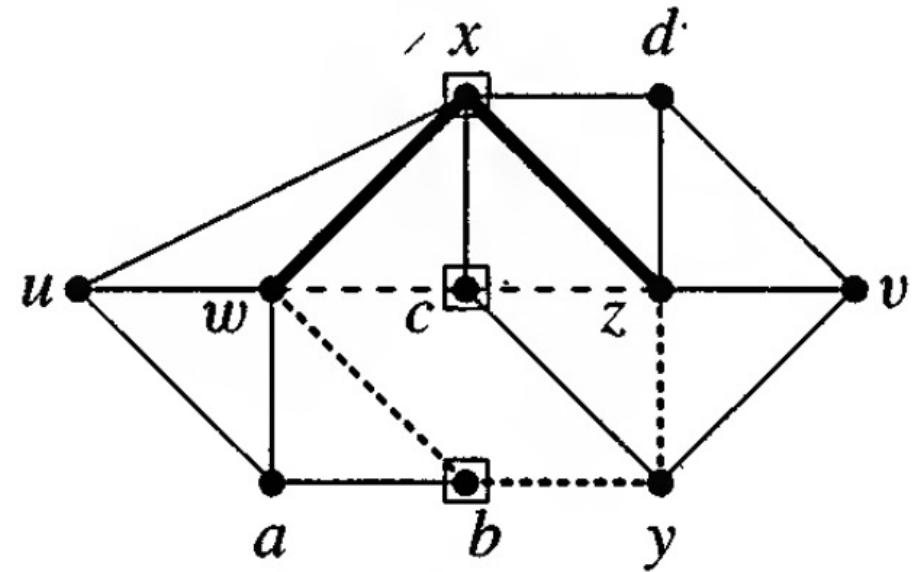
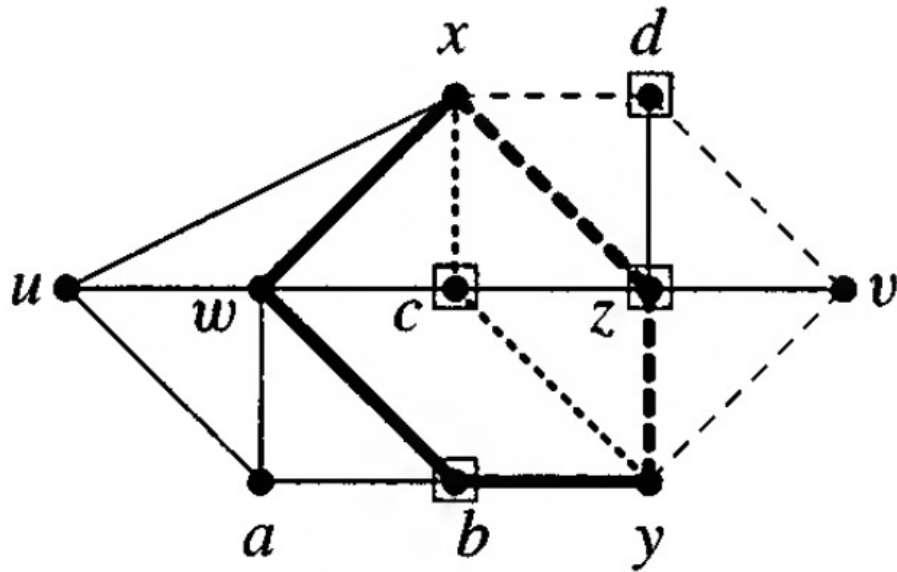
# k-Connected and k-Edge- Connected graphs

# $x, y$ -cut

- Given  $x, y \in V(G)$ , a set  $S \subseteq V(G) - \{x, y\}$  is an  $x, y$ -separator or  **$x, y$ -cut** if  $G - S$  has no  $x, y$ -path
  - Let  **$\kappa(x, y)$**  be the minimum size of an  $x, y$ -cut
  - Let  **$\lambda(x, y)$**  be the maximum size of a set of pairwise internally disjoint  $x, y$ -paths
  - $\kappa(x, y) \geq \lambda(x, y)$
- For  $X, Y \subseteq V(G)$ , an  **$X, Y$ -path** is a path having first vertex in  $X$ , last vertex in  $Y$ , and no other vertex in  $X \cup Y$

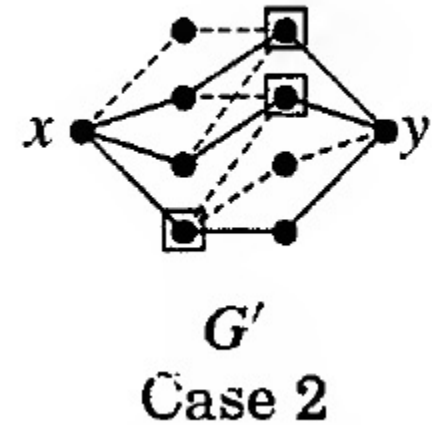
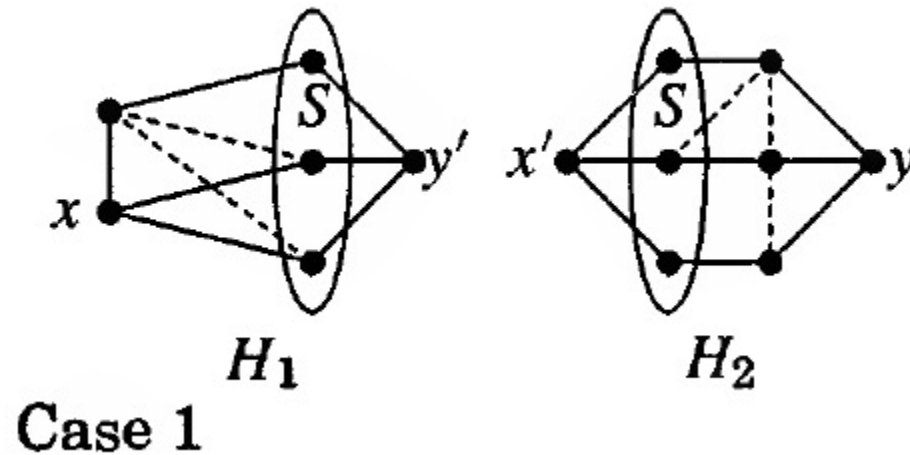
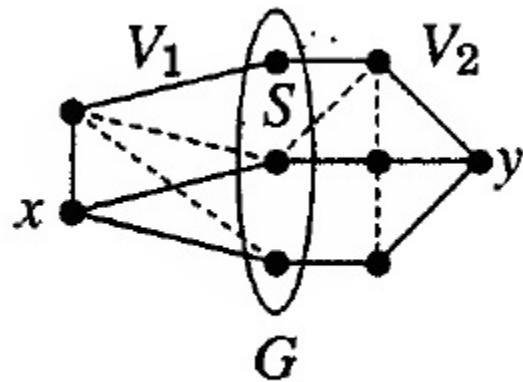
# Example (4.2.16, W)

- $S = \{b, c, z, d\}$
- $\kappa(x, y) = \lambda(x, y) = 4$
- $\kappa(w, z) = \lambda(w, z) = 3$



# Menger's Theorem

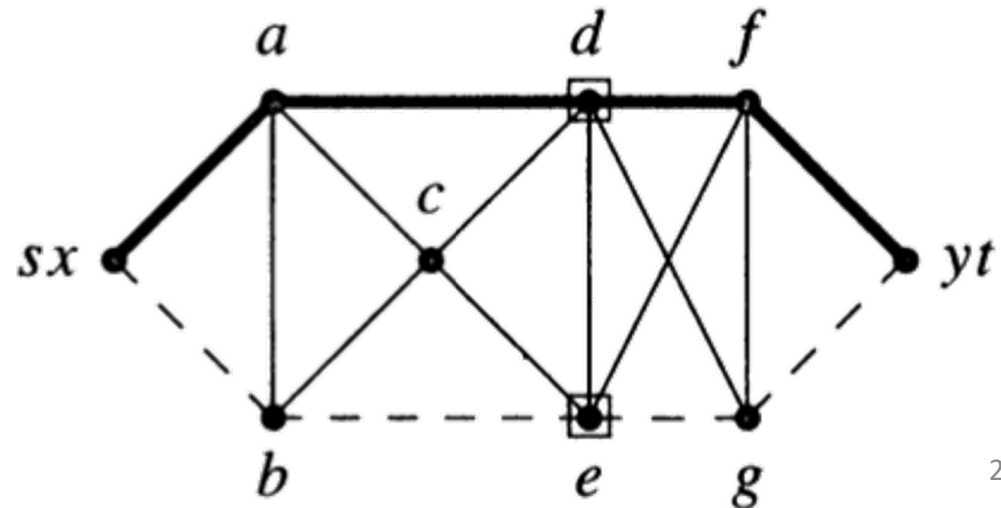
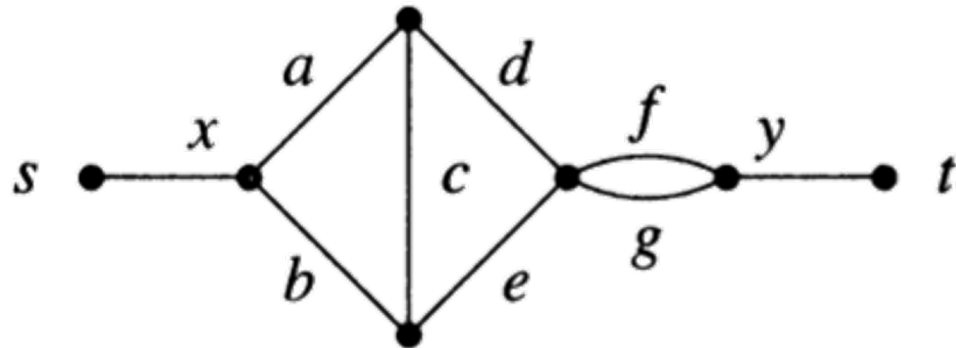
- **Theorem** (4.2.17, W; Menger, 1927) If  $x, y$  are vertices of a graph  $G$  and  $xy \notin E(G)$ , then  $\kappa(x, y) = \lambda(x, y)$



**Theorem** (3.1.16, W; 1.53, H; 2.1.1, D; König 1931; Egeváry 1931)  
 Let  $G$  be a bipartite graph. The **maximum** size of a matching in  $G$  is equal to the **minimum** size of a vertex cover of its edges

# Edge version

- **Theorem** (4.2.19, W) If  $x$  and  $y$  are distinct vertices of a graph or digraph  $G$ , then the minimum size  $\kappa'(x, y)$  of an  $x, y$ -disconnecting set of edges equals the maximum number  $\lambda'(x, y)$  of pairwise edge-disjoint  $x, y$ -paths
- The **line graph**  $L(G)$  of a graph  $G$  is the graph whose vertices are the edges of  $G$  with  $ef \in E(L(G))$  when  $e = uv$  and  $f = vw$  in  $G$



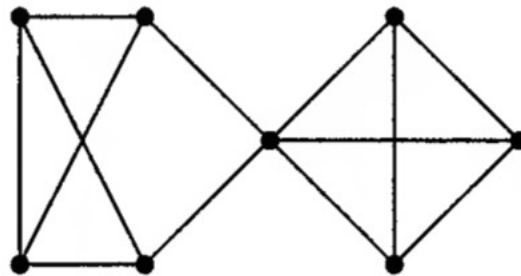


# Back to connectivity

- **Theorem** (4.2.21, W)

$$\kappa(G) = \min_{x \neq y \in V(G)} \lambda(x, y), \quad \lambda(G) = \min_{x \neq y \in V(G)} \lambda'(x, y)$$

- **Lemma** (4.2.20, W) Deletion of an edge reduces connectivity by at most 1



# Application of Menger's Theorem

# CSDR

- Let  $\mathbf{A} = A_1, \dots, A_m$  and  $\mathbf{B} = B_1, \dots, B_m$  be two family of sets. A **common system of distinct representatives (CSDR)** is a set of  $m$  elements that is both an system of distinct representatives (SDR) for  $\mathbf{A}$  and an SDR for  $\mathbf{B}$

- Given some family of sets  $X$ , a **system of distinct representatives** for the sets in  $X$  is a 'representative' collection of distinct elements from the sets of  $X$

$$S_1 = \{2, 8\},$$

$$S_2 = \{8\},$$

$$S_3 = \{5, 7\},$$

$$S_4 = \{2, 4, 8\},$$

$$S_5 = \{2, 4\}.$$

The family  $X_1 = \{S_1, S_2, S_3, S_4\}$  does have an SDR, namely  $\{2, 8, 7, 4\}$ . The family  $X_2 = \{S_1, S_2, S_4, S_5\}$  does not have an SDR.

- Theorem(1.52, H)** Let  $S_1, S_2, \dots, S_k$  be a collection of finite, nonempty sets. This collection has SDR  $\Leftrightarrow$  for every  $t \in [k]$ , the union of any  $t$  of these sets contains at least  $t$  elements

# Equivalent condition for CSDR

- **Theorem** (4.2.25, W; Ford-Fulkerson 1958) Families  $\mathbf{A} = \{A_1, \dots, A_m\}$  and  $\mathbf{B} = \{B_1, \dots, B_m\}$  have a common system of distinct representatives (CSDR)  $\Leftrightarrow$

$$\left| \left( \bigcup_{i \in I} A_i \right) \cap \left( \bigcup_{j \in J} B_j \right) \right| \geq |I| + |J| - m$$

for every pair  $I, J \subseteq [m]$

# Summary

- Disconnecting edge set

**Shuai Li**

<https://shuaili8.github.io>

# Questions?