



## Motivation

Meta learning (learning to learn) algorithms facilitate few-shot learning

Model-agnostic meta learning (MAML) [1]

- Meta-learning phase: learn from tasks  $T_1 \dots T_n$
- Target learning phase: few shot learning on  $T_{n+1}$

**The good:**

- Model-agnostic: no requirement for the network structure
- Very little labeled data needed at the target phase

**The bad:**

- A lot of labeled data needed at the meta-learning phase
- Tasks  $T_1 \dots T_n$  need to be drawn from the same distribution as the target – we need good knowledge of the target domain

## Keep the general flow of MAML but use unlabeled data for

Algorithm 1: Unsupervised Meta-learning with Tasks constructed by Random sampling and Augmentation (UMTRA)

```

require:  $N$ : class-count,  $N_{MGP}$ : meta-batch size,  $N_U$ : no. of updates
require:  $\mathcal{U} = \{x_1, \dots, x_N\}$ : unlabeled dataset
require:  $\alpha, \beta$ : step size hyperparameters
require:  $A$ : augmentation function
randomly initialize  $\theta$ ;
while not done do
  for  $i$  in  $1 \dots N_{MGP}$  do
    Sample  $N$  data points  $x_1, \dots, x_N$  from  $\mathcal{U}$ ;
     $T_i \leftarrow \{x_1, \dots, x_N\}$ ;
  end
  foreach  $T_i$  do
    Generate training set  $D_i = \{(x_1, 1), \dots, (x_N, N)\}$ ;
     $\theta_i^* = \theta$ ;
    for  $j$  in  $1 \dots N_U$  do
      Evaluate  $\nabla_{\theta_i^*} \mathcal{L}_{T_i}(f_{\theta_i^*})$ ;
      Compute adapted parameters with gradient descent:  $\theta_i^* = \theta_i^* - \alpha \nabla_{\theta_i^*} \mathcal{L}_{T_i}(f_{\theta_i^*})$ ;
    end
    Generate validation set for the meta-update  $D_i^* = \{(A(x_1), 1), \dots, (A(x_N), N)\}$ 
  end
  Update  $\theta \leftarrow \theta - \beta \nabla_{\theta} \sum_{i=1}^N \mathcal{L}_{T_i}(f_{\theta})$  using each  $D_i^*$ ;
end

```

## Unsupervised Meta-learning with Tasks constructed by Random sampling and

Start with an unlabeled data set  $D$  of samples

- We assume a large number of classes  $C$  present, but we don't know the class of each sample

Generate synthetic one shot training tasks  $T_1 \dots T_n$

- Random selection of samples with artificial labels
- The large number of classes ensures high likelihood that classes are different

Create validation data by augmentation  $x_v = A(x)$

- Augmentation type varies by domain, the objective is to maintain class membership of the augmented data

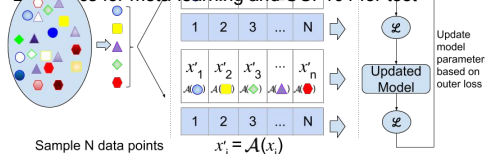


- On video: use frame selection to create augmented video

■ C3D architecture

■ Sample a sequence of length 16 from each video

■ Metrics for meta-learning and UCF101 for test

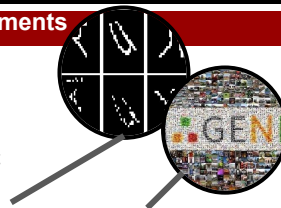


## Experiments

Few shot learning benchmarks:

outperforms other unsupervised algorithms and alternates for best with CACTUS-MAML [2].

Massive reduction of required labeled data: 25000 to 25 for Omniglot (5.5) for 95.43% vs 98.83 vs MAML.



Algorithm (N, K)	Clustering	Omniglot				Mini-Imagenet			
		(5,1)	(5,5)	(20,1)	(20,5)	(5,1)	(5,5)	(5,20)	(5,50)
<i>Training from scratch</i>									
$k_{nn}$ -nearest neighbors	BiGAN	49.55	68.06	27.37	46.70	25.56	31.10	37.31	43.60
linear classifier	BiGAN	48.28	68.72	27.80	45.82	27.08	33.91	44.00	50.41
MLP with dropout	BiGAN	40.54	62.56	19.92	40.71	22.91	29.06	40.06	48.36
cluster matching	BiGAN	43.96	58.62	21.54	31.06	24.63	29.49	33.89	36.13
CACTUS-MAML	BiGAN	58.18	78.66	35.56	58.62	36.24	51.28	61.33	66.91
CACTUS-ProtoNets	BiGAN	54.74	71.69	33.40	50.62	36.62	50.16	59.56	63.27
$k_{nn}$ -nearest neighbors	ACAI/DC	57.46	81.16	39.73	66.38	28.90	42.25	56.44	63.90
linear classifier	ACAI/DC	61.08	81.82	43.20	66.33	29.44	39.79	56.19	65.28
MLP with dropout	ACAI/DC	51.95	77.20	30.65	58.62	29.03	39.67	52.71	60.95
cluster matching	ACAI/DC	54.94	71.09	32.19	45.93	22.20	23.50	24.97	26.87
CACTUS-MAML	ACAI/DC	68.84	87.78	48.09	73.36	39.90	53.97	63.84	69.64
CACTUS-ProtoNets	ACAI/DC	68.12	83.58	47.75	66.27	39.18	53.36	61.54	63.55
UMTRA (ours)	N/A	<b>83.80</b>	<b>95.43</b>	<b>74.25</b>	<b>92.12</b>	<b>39.93</b>	<b>50.73</b>	<b>61.11</b>	<b>67.15</b>
MAML (Supervised)	N/A	94.46	98.83	84.60	96.29	46.81	62.13	71.03	75.54
ProtoNets (Supervised)	N/A	98.35	99.58	95.31	98.81	46.56	62.29	70.05	72.04

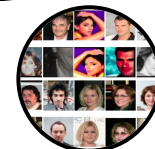
Works on video classification as well:

Test on all samples of each class by looking at just one example for train



Algorithm	Test Accuracy / F1-Score
<i>Training from scratch</i>	29.30 / 20.48
Pre-trained on Kinetics	45.51 / 42.49
UMTRA on unlabeled Kinetics (ours)	<b>60.33 / 58.47</b>
Supervised MAML on Kinetics	71.08 / 69.44

Algorithm (N, K)	(5, 1)	(5, 5)	(5, 10)
<i>Training from scratch</i>	26.86	39.65	50.61
UMTRA	<b>33.43</b>	<b>50.19</b>	<b>58.84</b>



## References:

[1] C. Finn, P. Abbeel, and S. Levine. "Model-agnostic meta-learning for fast adaptation of deep networks." In Proc. of the 34th Int'l Conf. on Machine Learning (ICML-2017), pp. 1126-1135, 2017.

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