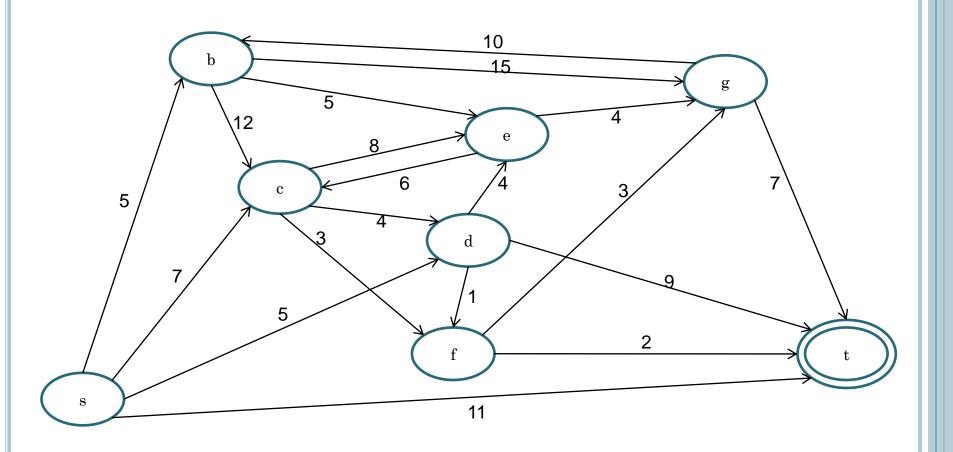
# UMETNA INTELIGENCA



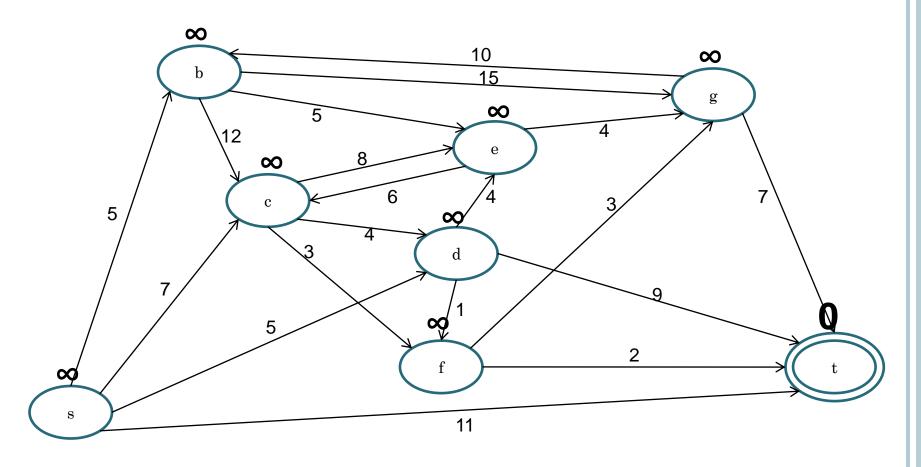
#### PRIMER - ADP (1/10)

Podan je graf na sliki. Poiščite pot z najmanjšo vsoto cen povezav od začetnega vozlišča  ${f s}$  do končnega vozlišča  ${f t}$ .

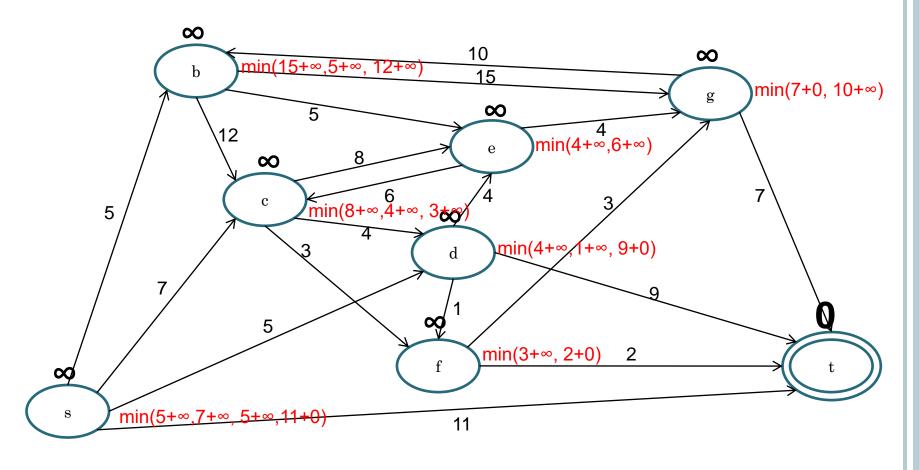


#### PRIMER - ADP (2/10)

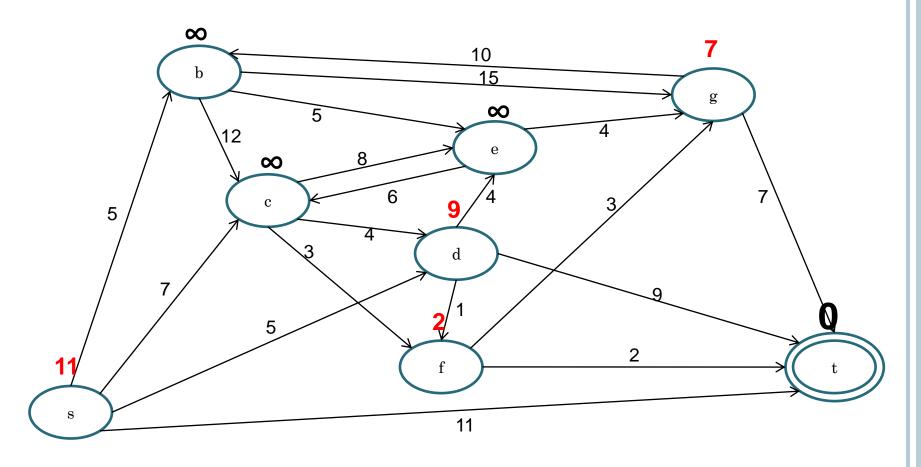
Inicializacija vrednosti h(i)...



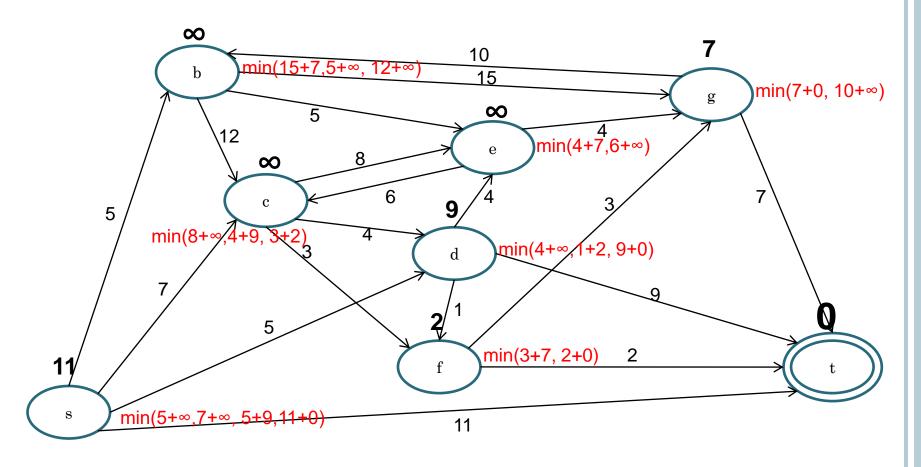
#### PRIMER - ADP (3/10)



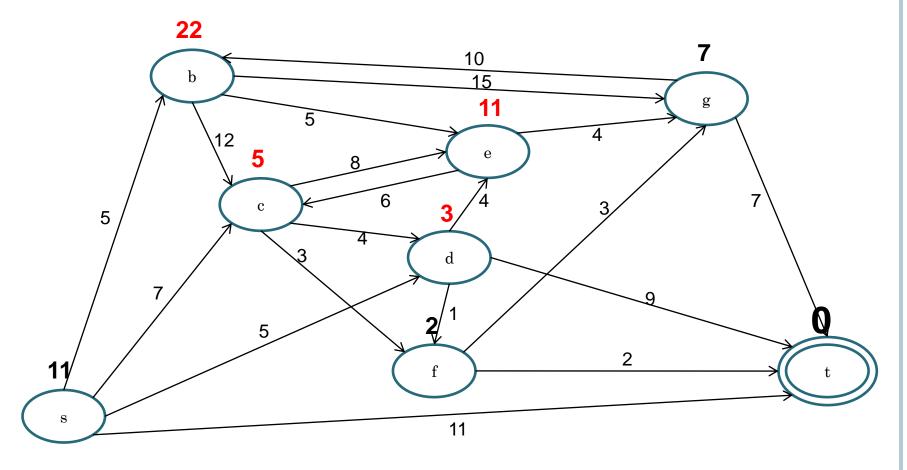
#### PRIMER - ADP (4/10)



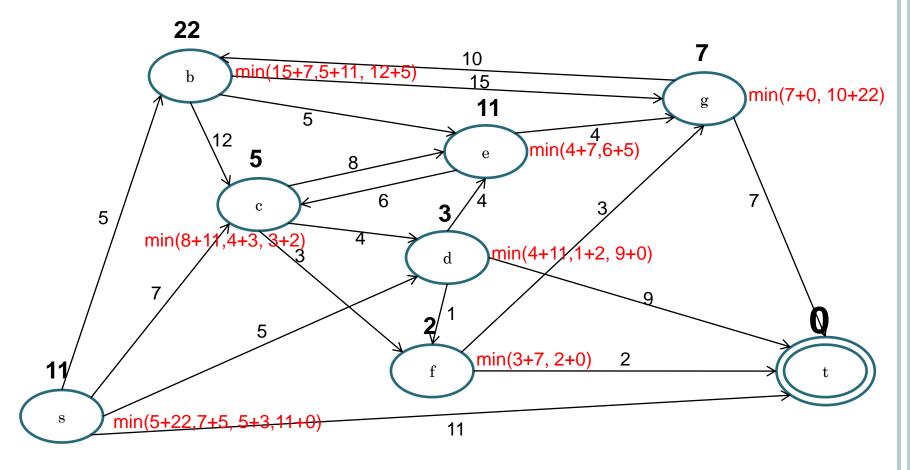
#### PRIMER - ADP (5/10)



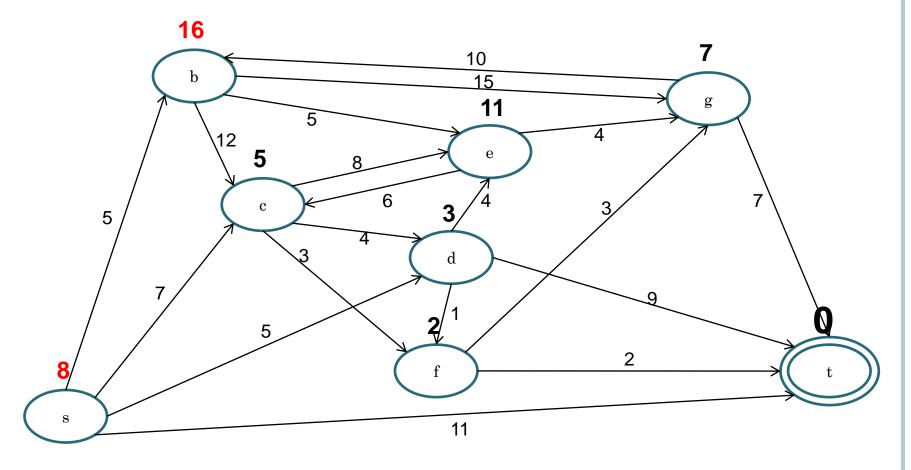
#### PRIMER - ADP (6/10)



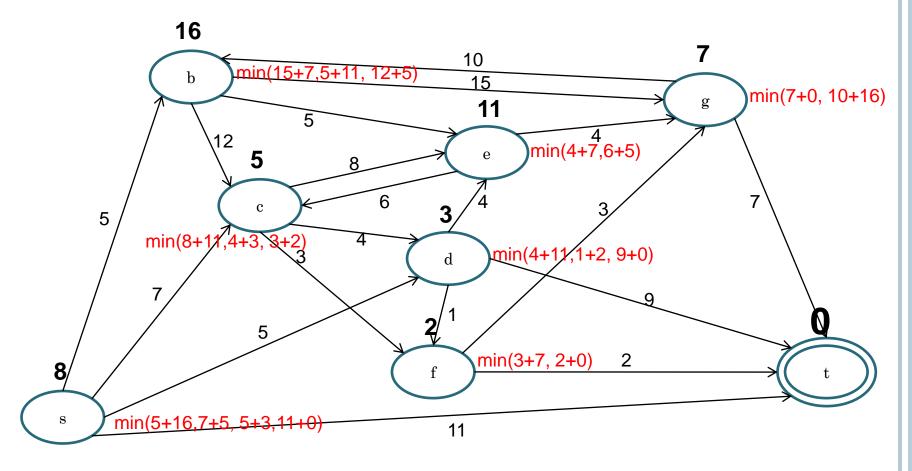
#### PRIMER - ADP (7/10)



#### PRIMER - ADP (8/10)

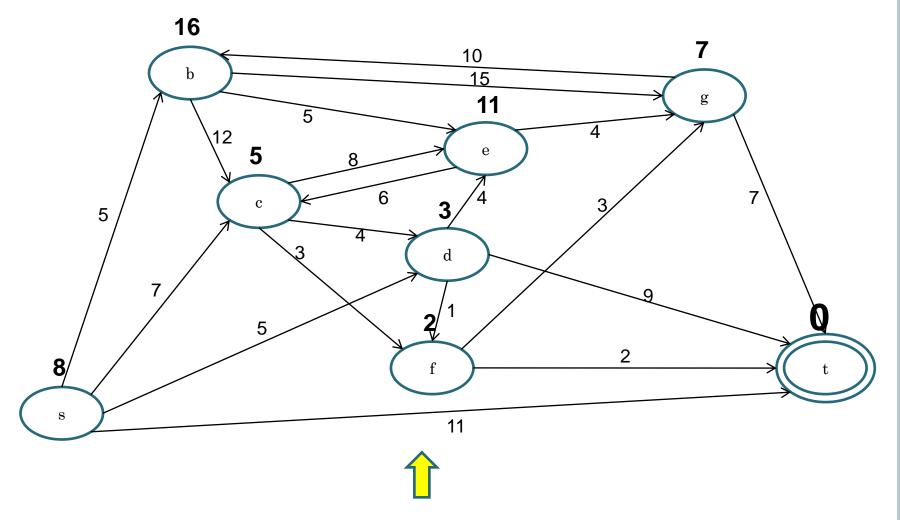


#### PRIMER - ADP (9/10)



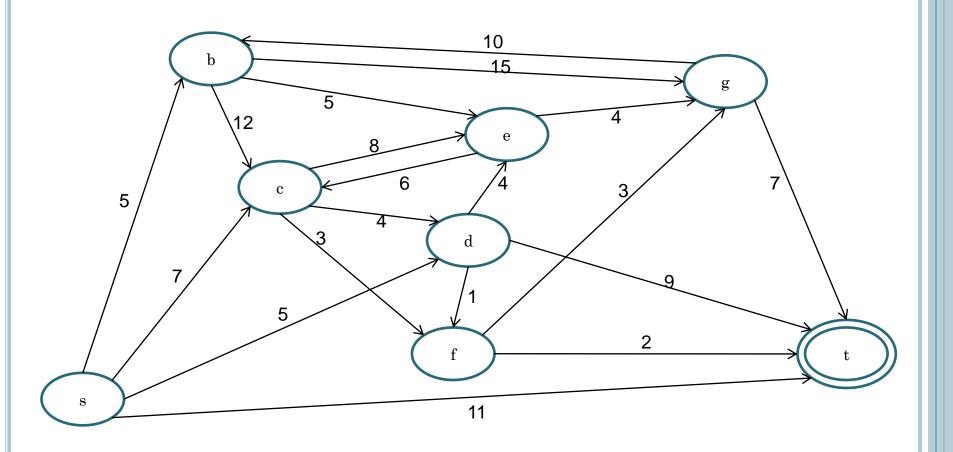
#### PRIMER - ADP (10/10)

Vrednosti h(i) so konvergirale k pravi vrednosti h\*(i).



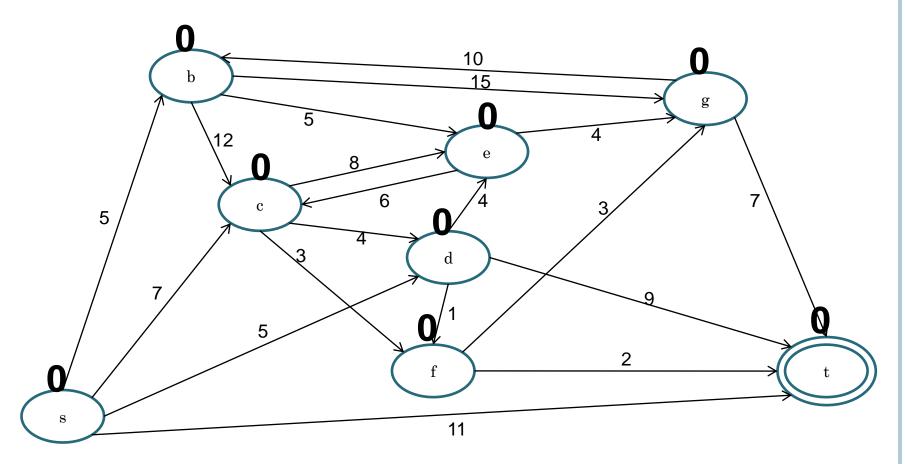
#### PRIMER – LRTA\* (1/22)

Podan je graf na sliki. Poiščite pot z najmanjšo vsoto cen povezav od začetnega vozlišča **s** do končnega vozlišča **t**.



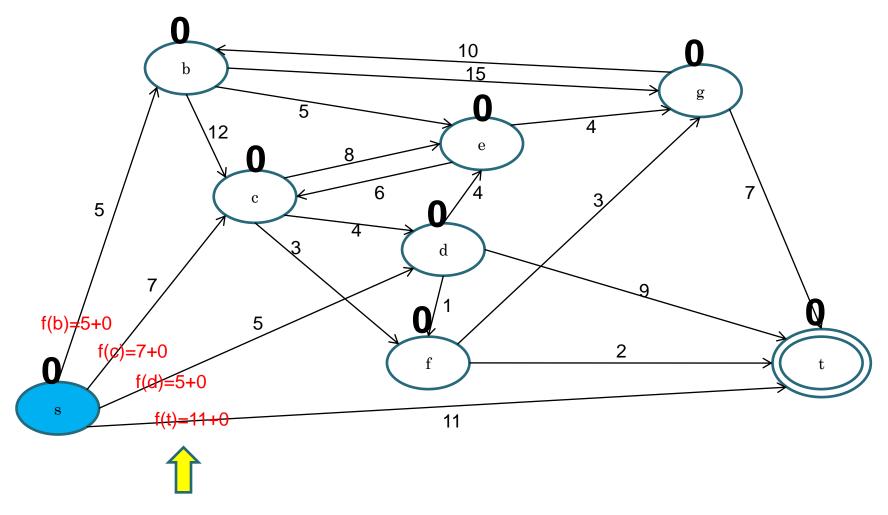
# PRIMER – LRTA\* (2/22)

Začetno stanje...



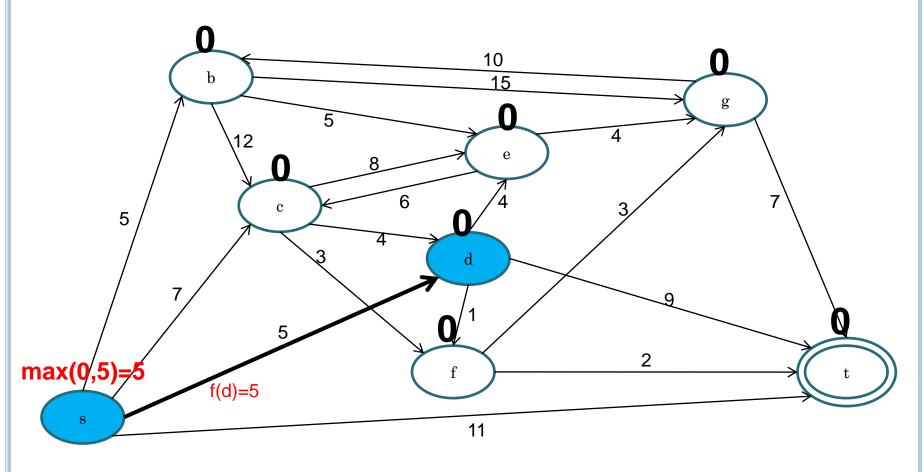
#### PRIMER – LRTA\* (3/22)

1. poskus...

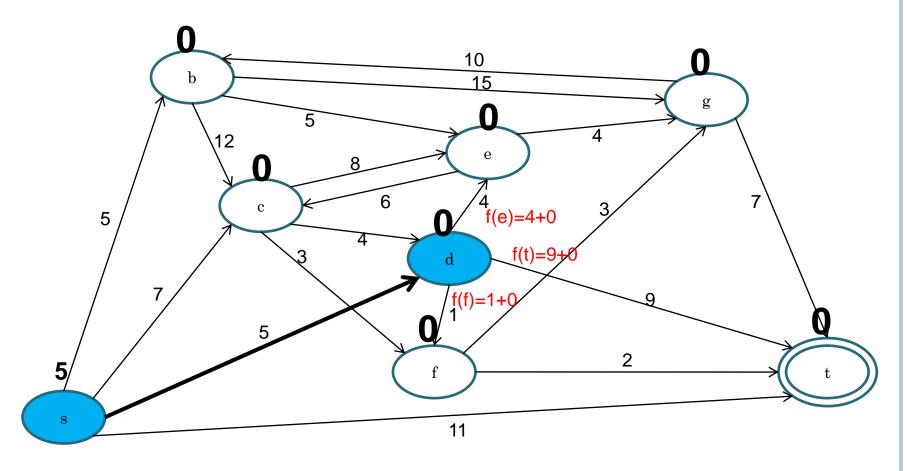


izberi minimalno ocenjeno vozlišče (med enakimi vozlišči izberi naključno)

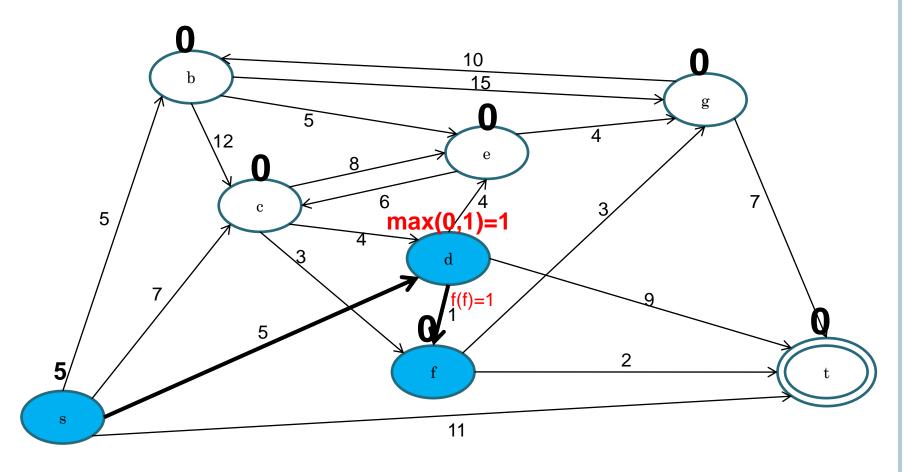
#### PRIMER – LRTA\* (4/22)



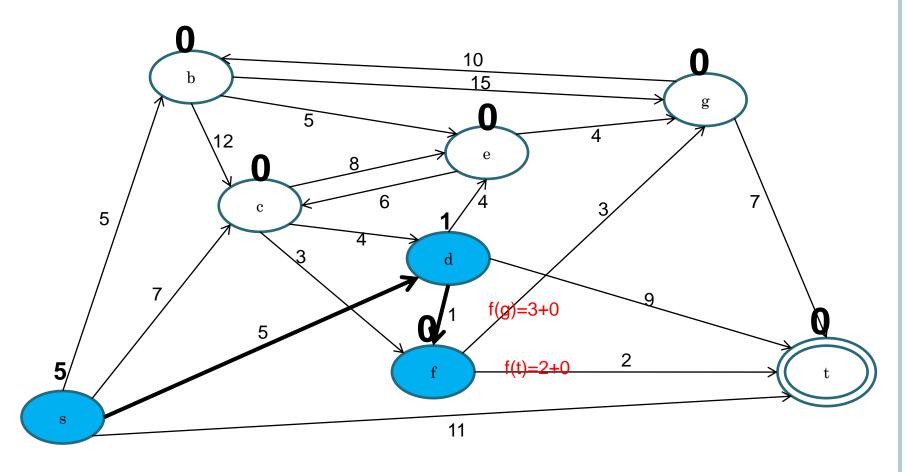
### PRIMER – LRTA\* (5/22)



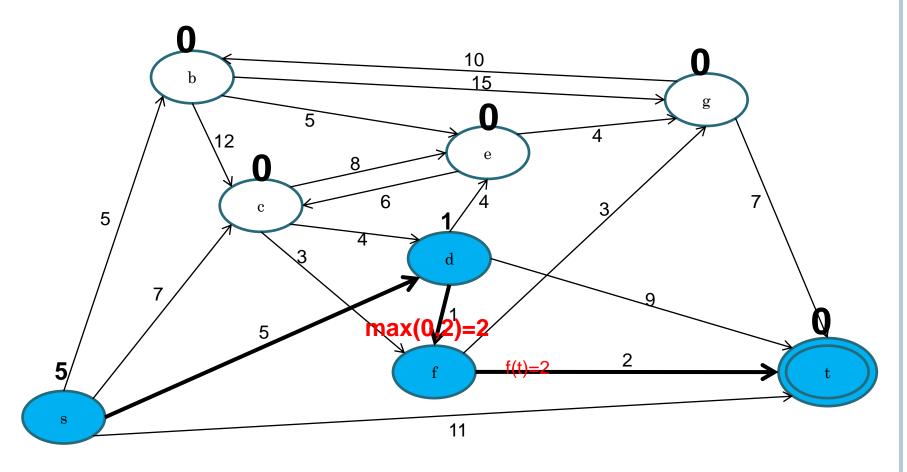
# PRIMER – LRTA\* (6/22)



# PRIMER – LRTA\* (7/22)

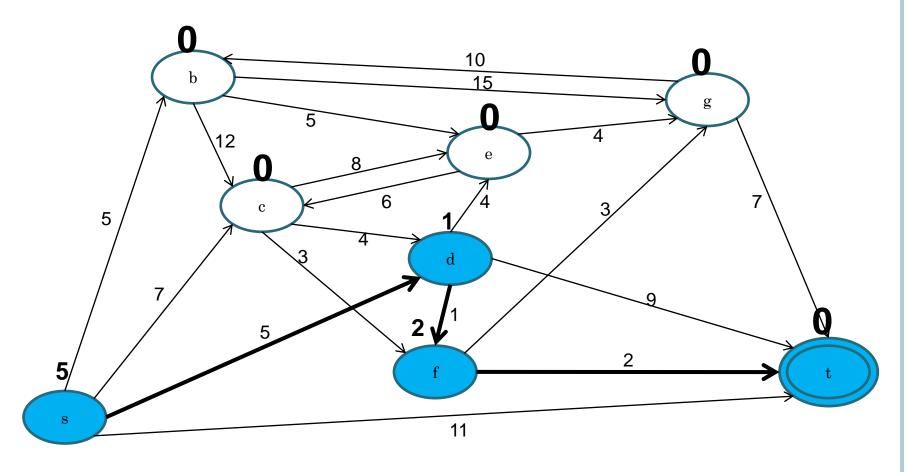


# PRIMER – LRTA\* (8/22)

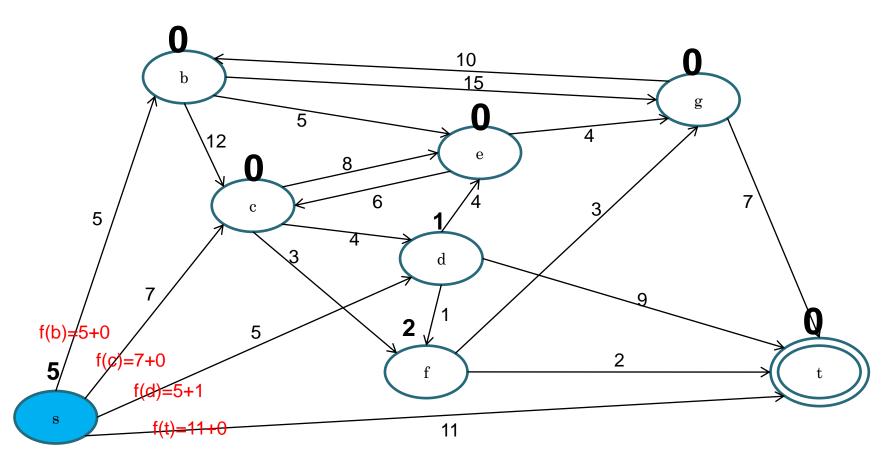


# PRIMER – LRTA\* (9/22)

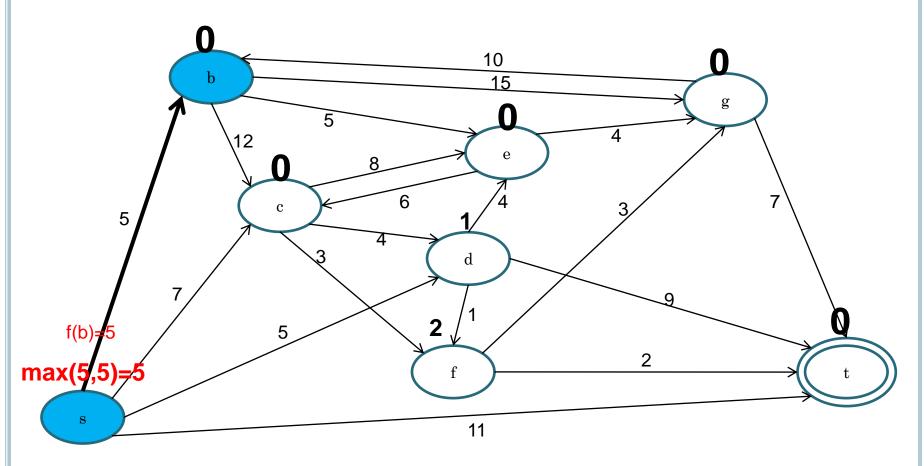
konec 1. poskusa.



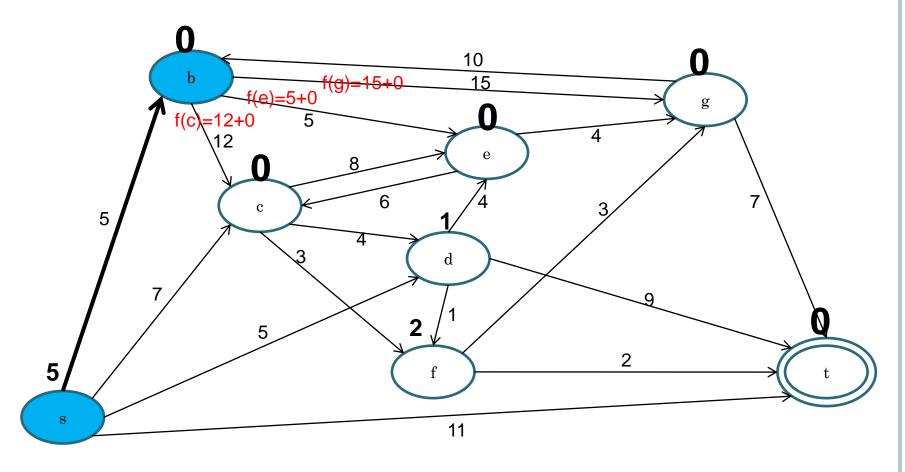
# PRIMER – LRTA\* (10/22)



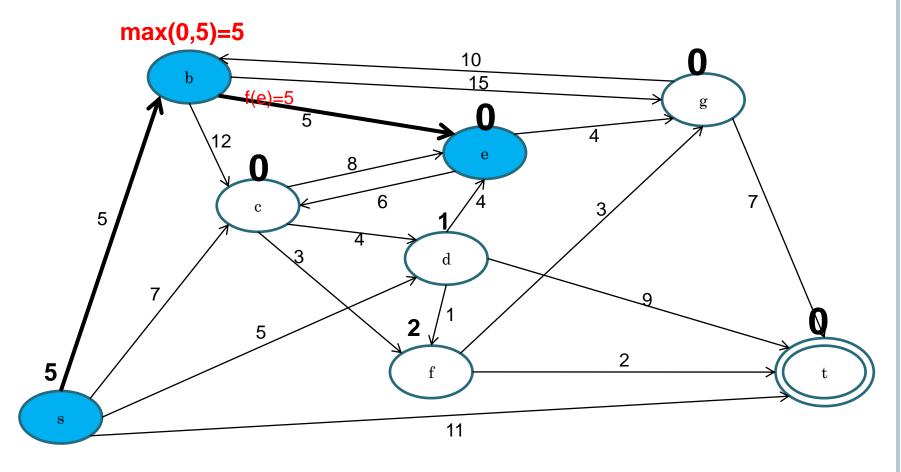
# PRIMER – LRTA\* (11/22)



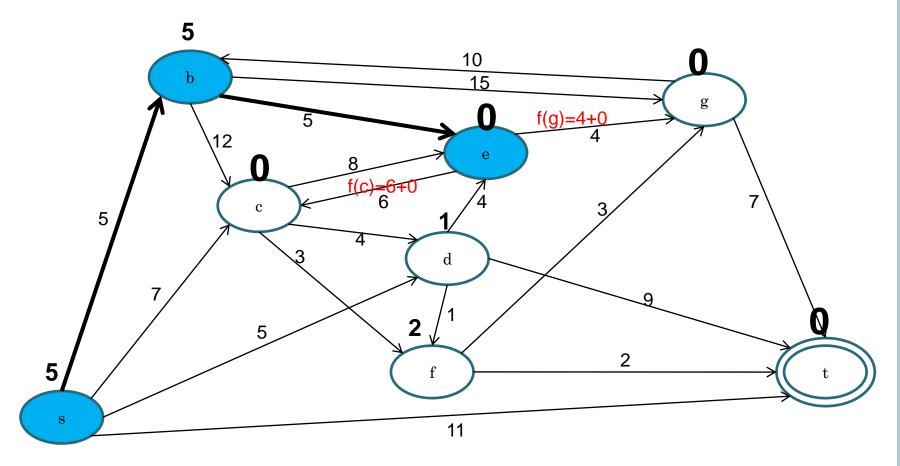
# PRIMER – LRTA\* (12/22)



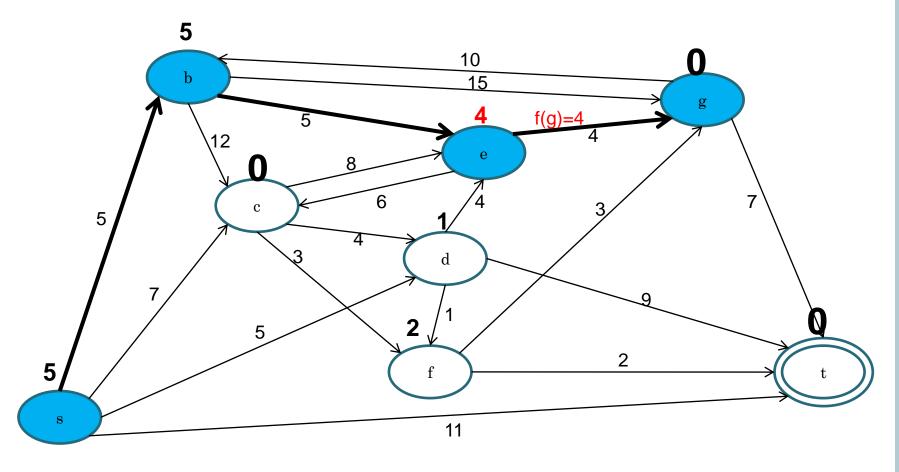
# PRIMER – LRTA\* (13/22)



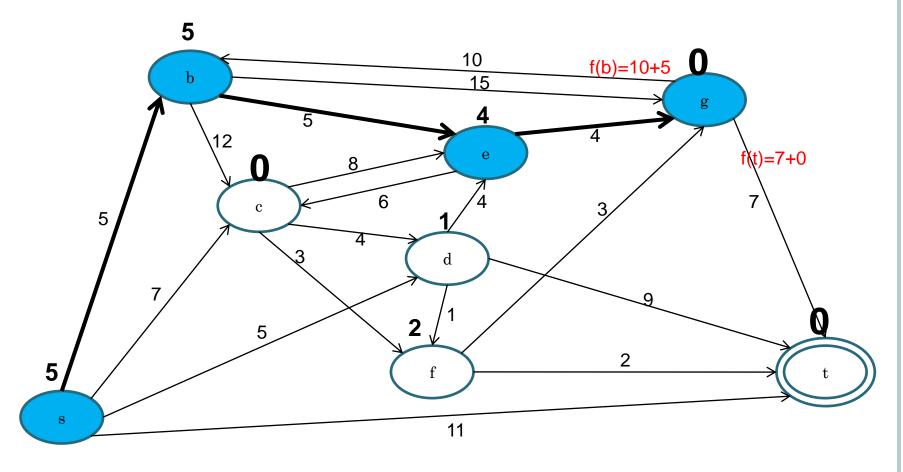
# PRIMER – LRTA\* (14/22)



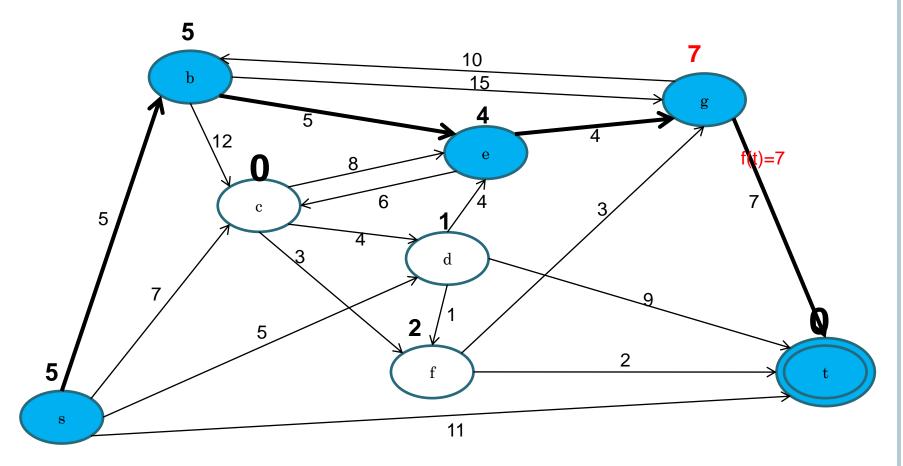
#### PRIMER – LRTA\* (15/22)



### PRIMER – LRTA\* (16/22)

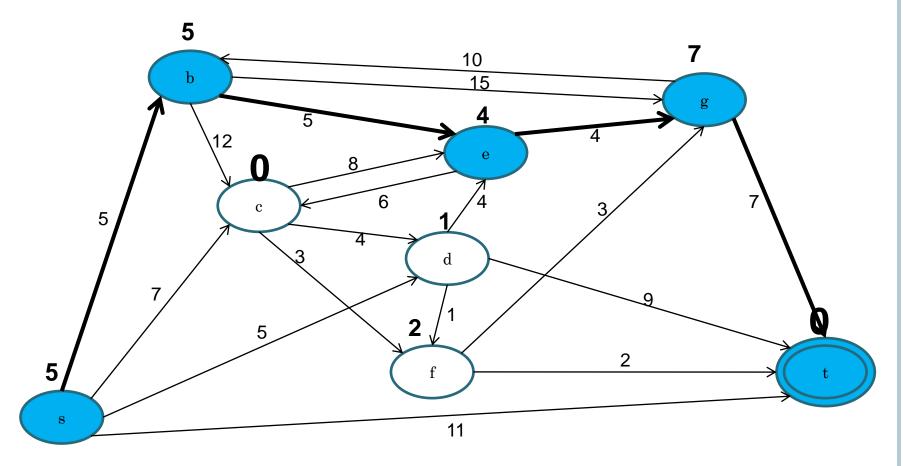


#### PRIMER – LRTA\* (17/22)



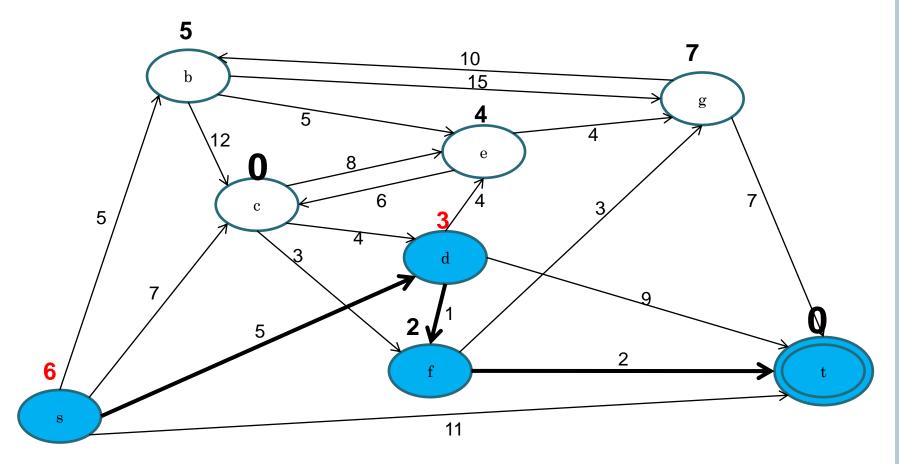
### PRIMER – LRTA\* (18/22)

Konec 2. poskusa.



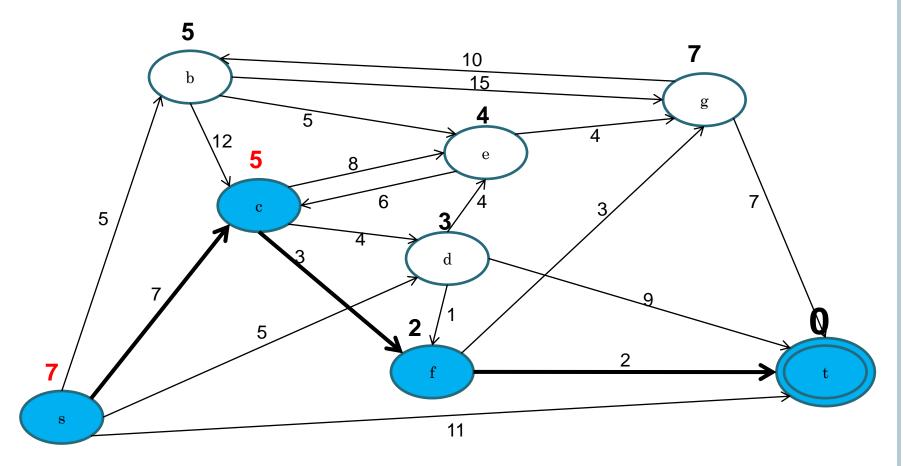
# PRIMER – LRTA\* (19/22)

Konec 3. poskusa.



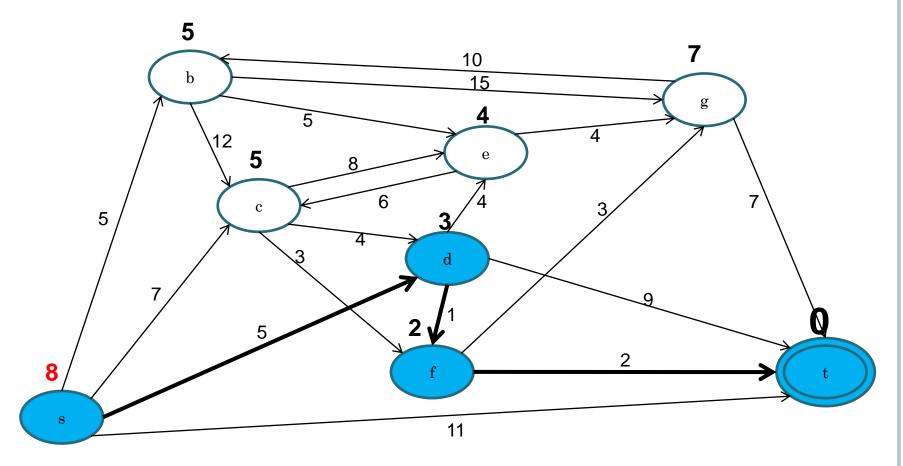
# PRIMER-LRTA\*~(20/22)

Konec 4. poskusa.



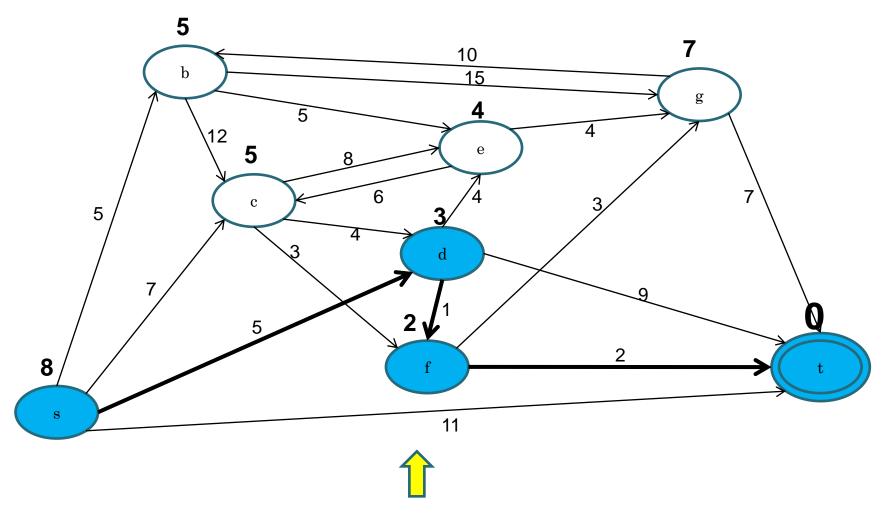
# PRIMER-LRTA\* (21/22)

Konec 5. poskusa.



### PRIMER – LRTA\* (22/22)

Konec 6. poskusa.



Konec postopka, ker se v dveh zaporednih izvajanjih pot agenta ne spremeni (vključno s hevrističnimi ocenami v vozliščih)