Markov Network Independencies

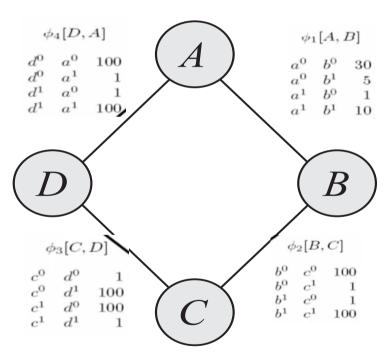
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Topics

- Markov Network Independencies
 - Basic Independencies
 - Independencies Revisited
 - From Distributions to Graphs

Markov network captures independencies of interactions

Misconception MN with factors



$$P(a,b,c,d) = \frac{1}{Z}\phi_1(a,b) \cdot \phi_2(b,c) \cdot \phi_3(c,d) \cdot \phi_4(d,a)$$

where

$$Z = \sum_{a,b,c,d} \phi_1(a,b) \cdot \phi_2(b,c) \cdot \phi_3(c,d) \cdot \phi_4(d,a)$$

As with BNs tight connection between factorization and independence properties:

P supports $(X \perp Y|Z)$ *iff* we can write distribution as $P(\chi) = \phi_1(X,Z) \phi_2(Y,Z)$

Proof: the first grouping yields a factor with $\{D, \{A, C\}\}$

The second grouping yields a factor with $\{B, \{A, C\}\}\$

Similarly we can infer $(A \perp C \mid B, D)$

Basic Independencies

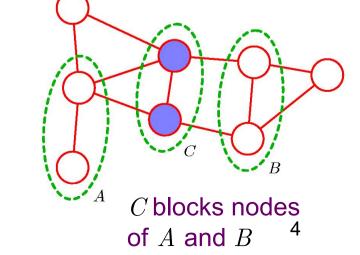
 As in Bayesian Networks, graph structure in a Markov network encodes a set of independence assumptions

 In a MN Probabilistic influence flows along the undirected paths in the graph and "blocked" if we condition on intervening

nodes

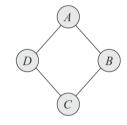
- i.e., we know their values

We state this formally, next



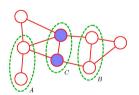
Active Path Definition

- Let $\mathcal H$ be a Markov network with nodes $\chi = \{X_1, ... X_n\}$,
- Let X_1 -...- X_k be a path in \mathcal{H}
- Let $Z \subseteq \chi$ be a set of observed variables
- A Path X_1 -...- X_k is <u>active</u> given Z if none of X_i is in Z
 - Ex 1:



If the observed set $Z=\{B\}$, path A-D-C is active

• Ex 2:

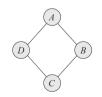


If the observed set $Z=\{C\}$, paths between nodes of $\{A\}$ and $\{B\}$ are inactive

 We can define separation in the graph when there is no active path, next

Separation and Global Independencies

- 1. Set of nodes Z <u>separates</u> sets X and Y denoted $\sup_{\mathcal{H}} (X; Y | Z)$ if there is no active path between any $X \in X$ and $Y \in Y$
 - Ex 1: $Z=\{B,D\}$ separates A and C
 - i.e., $\sup_{\mathcal{H}} (A; C \mid B, D)$ } or there is no active path between A and C
 - Ex 2: C separates A and B
- 2. Global independencies associated with ${\cal H}$ are
 - $I(\mathcal{H}) = \{ (X \perp Y | Z) : \operatorname{sep}_{\mathcal{H}}(X; Y | Z) \}$
 - Independencies in $I(\mathcal{H})$ guaranteed to hold for every distribution P over \mathcal{H}



 $I(\mathcal{H}) = \{ (A \perp C | B, D), (B \perp D | A, C) \}$

Definition of Separation Leads to a disadvantage

- With a superset of Z, separation still holds
 - If $sep_{\mathcal{H}}(X;Y|Z)$ then $sep_{\mathcal{H}}(X;Y|Z')$ for any $Z'\supset Z$
- If separation is taken as definition of independencies, we restrict ability to encode non-monotonic independence relations
 - Non-monotonic reasoning is quite useful
 - E.g., intercausal reasoning with BNs
 - Two diseases are independent, but dependent given some common symptom
 - Such independence properties cannot be expressed as a Markov network

Factorization and Independencies

- Can show connection between independence properties implied by a Markov structure and factorizing a distribution over the graph
- Analogous to Bayesian Networks
 - Let \mathcal{G} be a BN for a set of random variables χ and P be a distribution over χ .
 - If P factorizes according to \mathcal{G} , i.e.,product of CPDs, then \mathcal{G} is an I-map of P
 - i.e., independencies I(G) ⊊ I

Formalizing independencies in MNs and distributions

- Gibbs Distribution
 - A distribution P_{Φ} is a Gibbs distribution parameterized by a set of factors $\Phi = \{\phi_1(D_1),...,\phi_K(D_K)\}$
 - If defined as follows

$$P_{\Phi}(X_1,..X_n) = \frac{1}{Z}\tilde{P}(X_1,..X_n)$$

where

$$\tilde{P}(X_1,..X_n) = \prod_{i=1}^m \phi_i(D_i)$$

is an unnomalized measure and

$$Z = \sum_{X_1,...X_n} \tilde{P}(X_1,...X_n)$$
 is a normalizing constant

called the partition function

 D_i are sets of random variables

Soundness of Separation Criterion

- Theorem 1 (from factorization to independencies):
 - Let P be distributed over $\chi = \{X_1, ... X_n\}$ and \mathcal{H} a Markov structure over χ
 - If P is a Gibbs distribution that factorizes over \mathcal{H} , (i.e., every D_i in \mathcal{H} is a clique), then \mathcal{H} is an I-map for P (i.e., every independency in \mathcal{H} holds in P)
- Theorem 2: Hammersley-Clifford (other direction: from independencies to factorization)
 - if \mathcal{H} is an I-map for P then P factorizes over \mathcal{H}
 - Holds only for positive distributions (P > 0 for every assignment) 10

Positive Distribution

• A distribution P is said to be positive if for all events $\alpha \in S$ such that $\alpha \neq \emptyset$ we have

that $P(\alpha) > 0$

- Ex: A non-positive distribution
 - 16 possible values
 - Distribution *P*: 8 have value 1/8 rest are zero

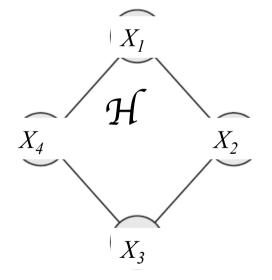
X_1	X_2	X_3	X_4	<i>P(</i> X)
0	0	0	0	1/8
1	0	0	0	1/8
1	1	0	0	1/8
1	1	1	0	1/8
0	0	0	1	1/8
0	0	1	1	1/8
0	1	1	1	1/8
1	1	1	1	1/8

Rest 8 probs are 0

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Non-positive distribution consistent with H

- Four binary random variables
- Global Independencies in graph H:
 - Consider $X_1 X_2 X_3 X_4 X_1$
 - implies $(X_1 \perp X_3 \mid X_2, X_4)$
- P also satisfies this
 - For the assignment $X_2=1, X_4=0$
 - $P(X_1=1|X_2=1,X_4=0)=1$
 - · Rest are zero
 - Thus X_1 is independent of X_3

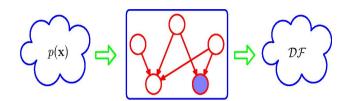


X_1	X_2	X_3	X_4	P(X)
0	0	0	0	1/8
1	0	0	0	1/8
1	1	0	0	1/8
1	1	1	0	1/8
0	0	0	1	1/8
0	0	1	1	1/8
0	1	1	1	1/8
1	1	1	1	1/8

Rest 8 probs are 0

- Global independencies hold $\Rightarrow \mathcal{H}$ is an I-map for P
- But P does not factorize according to \mathcal{H} (Proof by contradiction)¹²

Graphical Model as Filter



p(x) is allowed to pass through only if It satisfies independencies in graph This set is denoted DF or UF (for BN or MN)

- UI is set of distributions that are consistent with set of conditional independence statements read from the undirected graph using graph separation
- UF are set of distributions that can be expressed as factorization of the form

$$p(\mathbf{x}) = \frac{1}{Z} \prod_{C} \psi_{C}(\mathbf{x}_{C})$$

• Hammersley-Clifford theorem states that UI and UF are identical

Independencies in Bayesian Networks

- Bayesian networks have two types of independencies
 - Local independencies
 - Each node is independent of its non-descendants given it parents
 - Global independencies
 - Induced by d-separation
- These two sets of independencies are equivalent
 - One implies the other

Three Independencies of an MN

- 1. Pairwise Independencies (defined next slide)
 - Pairwise $I_p(\mathcal{H})$
- 2. Local independencies (defined shortly)
 - Markov Blanket $I_{\ell}(\mathcal{H})$
- 3. Global independency $I(\mathcal{H})$
 - Identify three sets of nodes A, B and C
 - To test conditional independence property

$$A \perp B \mid C$$

- Consider all possible paths from nodes in set ${\cal A}$ to nodes in set ${\cal B}$
 - If all such paths pass through one or more nodes in $C_{\!\!\!15}$ then path is blocked and independence holds

Pairwise Independency $I_p(\mathcal{H})$

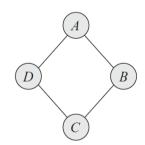
• If \mathcal{H} is a MN its pairwise independencies are

$$I_p(\mathcal{H}) = \{ (X \perp Y | \chi - \{X, Y\}) : X - Y \notin \mathcal{H} \}$$

Meaning: When X, Y are **not** directly connected i.e., $X - Y \notin \mathcal{H}$,

they are independent given all other variables

- Example:



$$I_p(\mathcal{H}) = \{ (A \perp C \mid B, D), (B \perp D \mid A, C) \}$$

Srihari Markov Blanket Independency $I(\mathcal{H})$

- Analogous to local independencies in Bayesian networks
 - We can block all influences by conditioning on its immediate neighbors
 - Node is conditionally independent of all nodes given its immediate neighbors
- For graph \mathcal{H} the Markov blanket of X in \mathcal{H} is the set of neighbors of X in $\mathcal H$
- Local independencies associated are

$$-I_{\ell}(\mathcal{H}) = \{ (X \perp \chi - \{X\} - MB_{\mathcal{H}}(X) | MB_{\mathcal{H}}(X)) : X \in \chi \}$$

Relationship between Markov properties

- Three independencies of network structure ${\cal H}$
- $I_p(\mathcal{H})$ is strictly weaker than $I_p(\mathcal{H})$ is strictly weaker than $I(\mathcal{H})$
- For positive distributions all three are equivalent

Separation in Markov Networks

- Markov network encodes a set of conditional independencies
- Probabilistic influence flows
 - in undirected paths
- Blocked if we condition on intervening nodes Separates sets A and B
 - Every path from any node in A to B passes through C
 - No explaining away
 - Testing for independence simpler than in directed graphs
 - Alternative view
 - Remove all nodes in set C together with all their connecting links
 - If no paths from A to B then conditional independence holds
- Markov blanket



 A node is conditionally independent of all other nodes conditioned only on its neighbors

Factorization Properties

- Factorization rule corresponds to conditional independence test
- Notion of locality needed
- Consider two nodes x_i and x_j not connected by a link
 - They are conditionally independent given all other nodes in graph
 - Because there is no direct path between them and
 - All other paths pass through nodes that are observed and hence those paths are blocked
 - Expressed as

$$p(x_i, x_j \mid \mathbf{x}_{\setminus \{i,j\}}) = p(x_i \mid \mathbf{x}_{\setminus \{i,j\}}) p(x_j \mid \mathbf{x}_{\setminus \{i,j\}})$$

- Where $X_{\setminus \{i,j\}}$ denotes set x of all variables with x_i and x_j removed
- For conditional independence to hold
 - factorization is such that x_i and x_j do not appear in the same factor
 - No path between them other than going through others
 - leads to graph concept of clique