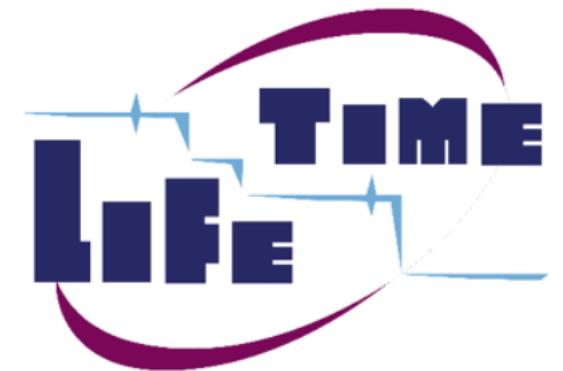


# Deep Learning Methods for Survival Analysis

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# Outline

- Part 1 – Deep Learning for Survival Predictions
  - Neural networks for right-censored survival data with **time-independent** or **time-dependent** covariates  
*Case Study 1: Prediction of Progression of AMD (Age-related Macular Degeneration)*
  - Neural networks for interval-censored (and left truncated) survival data  
*Case Study 2: Prediction of Development of AD (Alzheimer's Disease)*

## Outline

- Part 2 – Deep Learning for Causal Survival Analysis
  - CATE (conditional average treatment effect) for survival outcomes
  - Deep learning approaches for estimating CATE with survival outcomes
  - Case Study 3: *Individualized Treatment Effects of AREDS formula in delaying Progression to late-AMD*

# Acknowledgement



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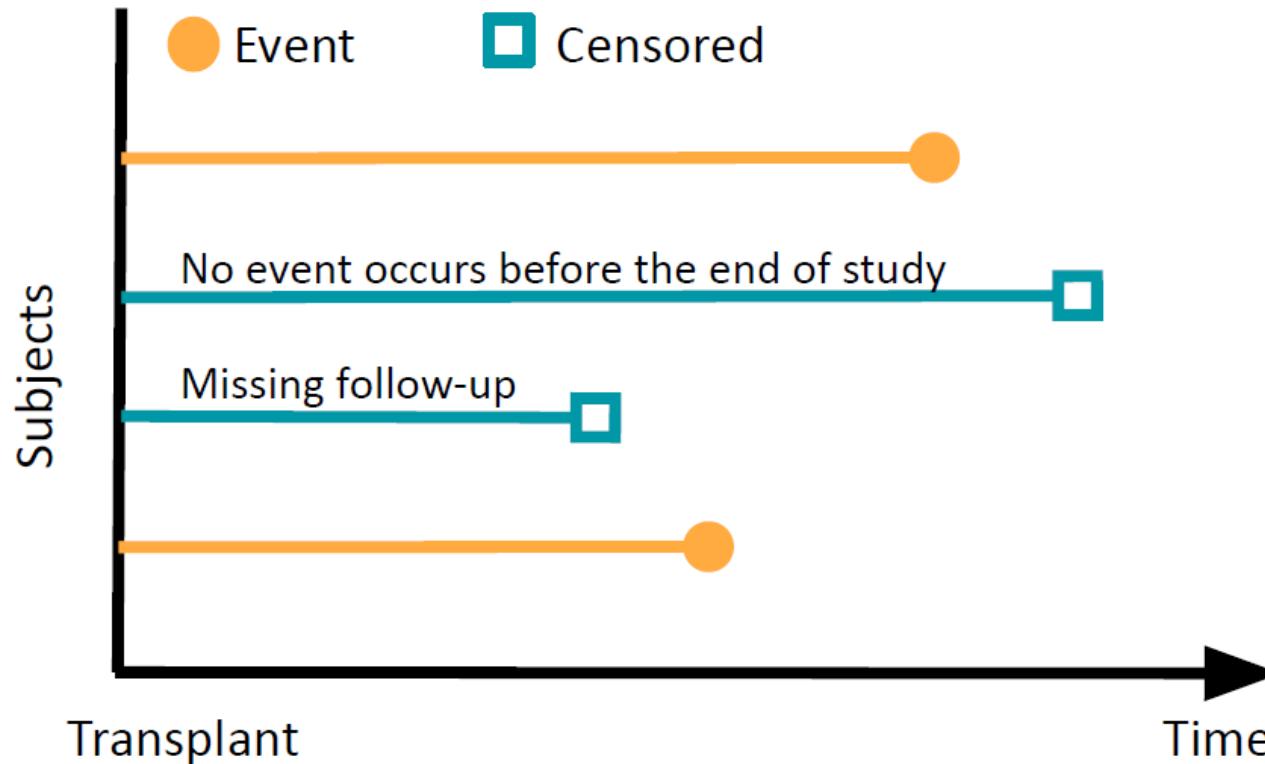


Yue (Luna) Wei

# Part I: Deep Learning for Survival Predictions

## 1.1 Neural networks for right-censored survival data

# Survival Data



**Goal:** Covariates  $X$  ← Association → Outcome: Time to Event  $T$

Censoring: the events of interest are not observed.

Right-censored data:  $Y = \min\{T, C\}$ ,  $\Delta = 1(T \leq C)$ ,  $X$

## Survival Prediction (with time-independent covariates)

$$\Pr(T > t | X)$$

## Dynamic Survival Prediction (with time-dependent covariates)

For  $t > s$        $\Pr(T > t | \{X(u), 0 \leq u \leq s\}, T > s)$

# Useful Functions in Survival Analysis

$$\Pr(T > t | X = x) = S(t | X = x) = \exp(-\Lambda(t | x)) = \exp\left(-\int_0^t \lambda(u | x) du\right)$$

Survival function:  $S(t | X = x)$

Hazard function:  $\lambda(t | X = x)$

Cumulative hazard function:  $\Lambda(t | X = x)$

## CoxPH: Cox Proportional Hazards Model

$$\Pr(T > t | X = x) = \exp(-\Lambda(t|x)) = \exp\left(-\int_0^t \boxed{\lambda(u|x)} du\right)$$
$$= \exp\left(-\int_0^t \boxed{\lambda_0(u) \exp(\beta x)} du\right)$$

Proportional Hazards Assumption:  $\lambda(u|x) = \lambda_0(u) \exp(\beta x)$

# Partial Likelihood for CoxPH Model

$$\Pr(T > t | X = x) = \exp\left(- \int_0^t \lambda_0(u) \exp(\beta x) du\right)$$

Right-censored data:  $Y = \min\{T, C\}$ ,  $\Delta = 1(T \leq C)$ ,  $X$

$\beta$  can be optimized by minimizing the  $l(\beta) = -\log pL(Y, \Delta, X)$

$$l(\beta) := -\frac{1}{n} \sum_{i:\Delta_i=1} [\beta x_i - \log \sum_{j \in R(Y_i)} \exp(\beta x_j)]$$

## Survival Probability Prediction under CoxPH

$$\Pr(T > t | X = x) = \exp\left(-\int_0^t \lambda_0(u) \exp(\beta x) du\right) = \exp(-\Lambda_0(t) \exp(\beta x))$$

After solving  $\hat{\beta}$  by minimizing  $l(\beta)$ , we also obtain

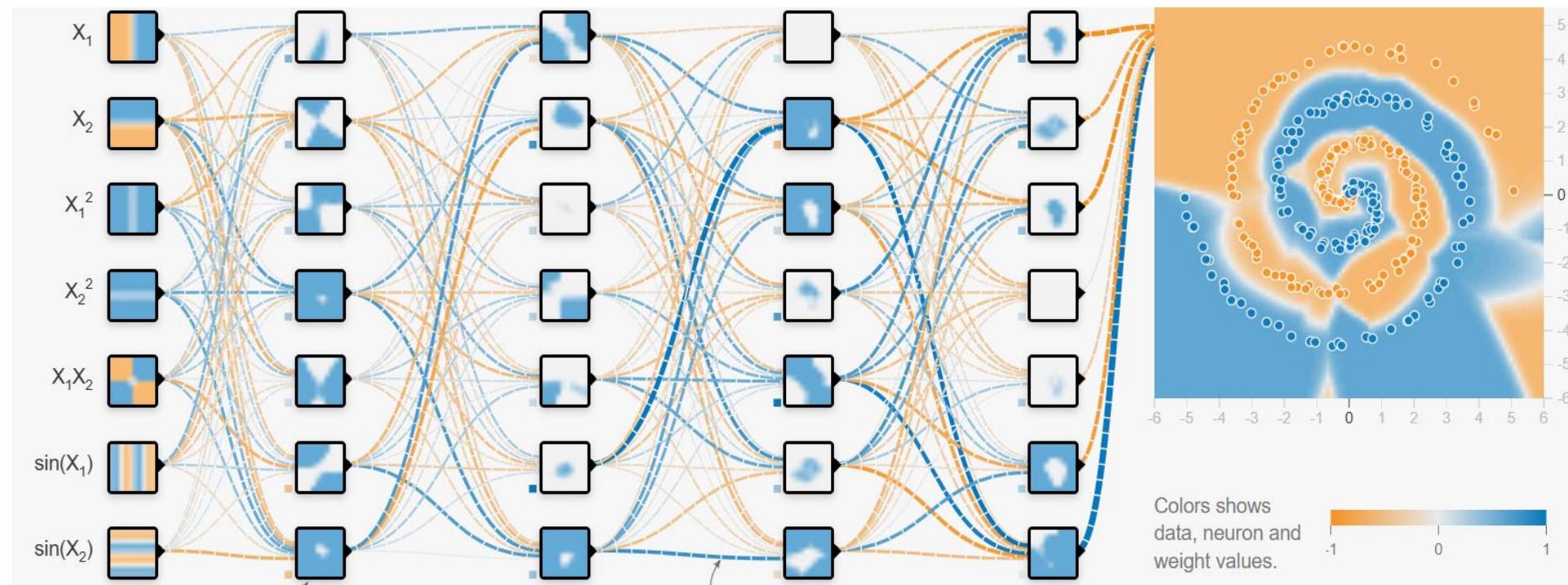
$$\hat{\Lambda}_0(\cdot) = \hat{\Lambda}_0(\cdot | \hat{\beta})$$

Then

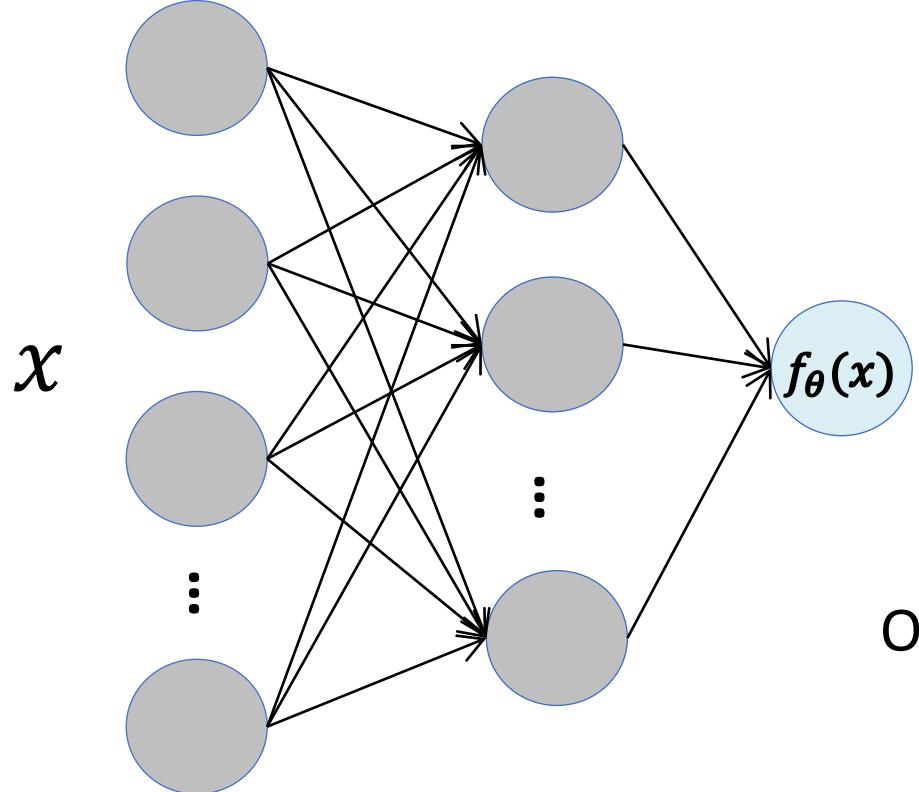
$$\hat{\Pr}(T > t | X = x) = \exp(-\hat{\Lambda}_0(t) \exp(\hat{\beta} x))$$

# Deep Learning

- Neural-network-based machine learning method.
- A neural network with multiple hidden layers is called a “deep” network, hence the name “deep learning” (LeCun et al. 2015).
- A deep/wide neural network can theoretically approximate any continuous function (Cybenko 1989).



# A simple Neural Network (NN) (for continuous Y)



- Observed data:  $(\mathbf{x}, y)$
- Input nodes: of NN:  $\mathbf{x}$
- Output node of NN:  $f_{\theta}(\mathbf{x})$
- Parameters to be optimized:  $\theta$

Optimize  $\theta$  by minimizing a loss function  $L(\theta)$

$$L(\theta) = (f_{\theta}(\mathbf{x}) - y)^2$$

# Optimization Algorithms for Training NN

- Gradient Descent (GD): computes the gradient of the loss function with respect to the model parameters using the **entire** training dataset in each iteration.
  - Stable training
- Stochastic Gradient Descent (SGD): computes the gradient using a **small subset** of examples in each iteration.
  - Memory efficient
  - Introduces **noise** that can help escape local minima or saddle points.

# Evaluation Metrics

- C-index

$$\frac{\sum_{i,j} \Delta_i I(T_i < T_j) I(\hat{T}_i < \hat{T}_j)}{\sum_{i,j} \Delta_i I(T_i < T_j)}$$

- Mean Square Error (MSE): (Only for simulation when true survival function  $S_0$  is known)

$$\frac{1}{n} \sum_i \frac{1}{T_i} \int_0^{T_i} \{S_0(u|X_i) - \hat{S}(u|X_i)\}^2 du$$

- Integrated Brier Score (IBS) score:

$$\frac{1}{n} \sum_i \frac{1}{T_i} \int_0^{T_i} \{I(u < T_i) - \hat{S}(u|X_i)\}^2 du$$

# Deep Learning Models for Survival Data

## Continuous-Time Models:

- CoxPH+NN

Method	Description	Example
CoxTime	Cox-Time is a relative risk model that extends Cox regression beyond the proportional hazards [1].	<a href="#">notebook</a>
CoxCC	Cox-CC is a proportional version of the Cox-Time model [1].	<a href="#">notebook</a>
CoxPH (DeepSurv)	CoxPH is a Cox proportional hazards model also referred to as DeepSurv [2]. [Katzman, J. 2018]	<a href="#">notebook</a>
PCHazard	The Piecewise Constant Hazard (PC-Hazard) model [12] assumes that the continuous-time hazard function is constant in predefined intervals. It is similar to the Piecewise Exponential Models [11] and PEANN [14], but with a softplus activation instead of the exponential function.	<a href="#">notebook</a>

- SODEN [Tang, W. 2022]: Survival ODE+NN
- SuMo-net [Rindt, D. 2022]: Monotone NN

# Deep Learning Models for Survival Data

## Discrete-Time Models:

Method	Description	Example
LogisticHazard (Nnet-survival)	The Logistic-Hazard method parametrize the discrete hazards and optimize the survival likelihood [12] [7]. It is also called Partial Logistic Regression [13] and Nnet-survival [8].	<a href="#">notebook</a>
PMF	The PMF method parametrize the probability mass function (PMF) and optimize the survival likelihood [12]. It is the foundation of methods such as DeepHit and MTLR.	<a href="#">notebook</a>
DeepHit, DeepHitSingle	DeepHit is a PMF method with a loss for improved ranking that can handle competing risks [3].	<a href="#">single</a> <a href="#">competing</a>
MTLR (N-MTLR)	The (Neural) Multi-Task Logistic Regression is a PMF methods proposed by [9] and [10].	<a href="#">notebook</a>
BCESurv	A method representing a set of binary classifiers that remove individuals as they are censored [15]. The loss is the binary cross entropy of the survival estimates at a set of discrete times, with targets that are indicators of surviving each time.	<a href="#">bs_example</a>

DeepHit [Lee, C. 2018]

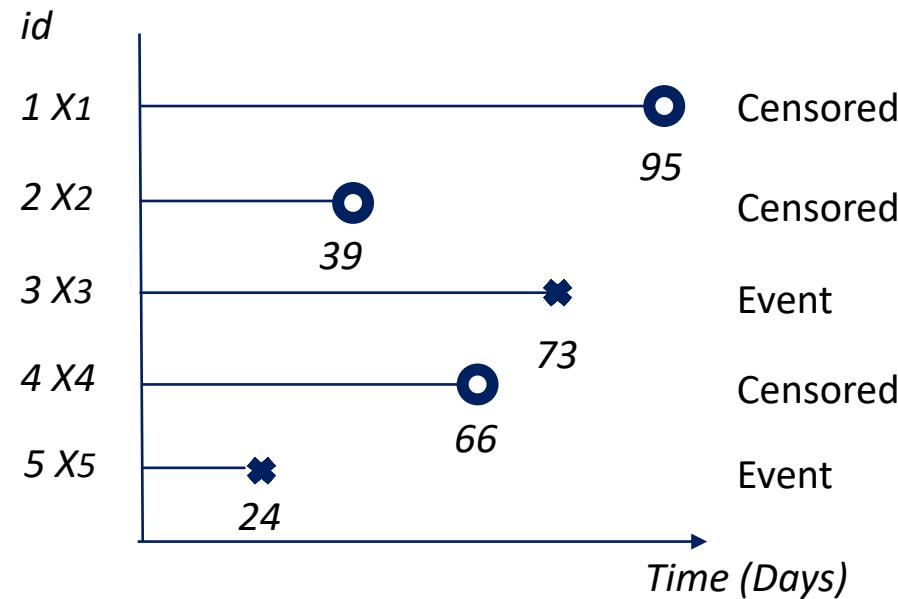
Dr. Haavard Kvamme: <https://github.com/havakv/pycox>

The screenshot shows the GitHub page for the `pycox` package. At the top is the GitHub logo. Below it is the `pycox` logo, which consists of the word "pycox" in a bold, lowercase sans-serif font with a horizontal line above it that ends in a circle at the letter "o".  
  
The page title is "Time-to-event prediction with PyTorch".  
  
Below the title are several badge links:

- Python package passing
- pypi v0.3.0
- conda-forge v0.3.0
- python missing
- License BSD 2-Clause

  
A navigation bar below the badges includes links to "Get Started", "Methods", "Evaluation Criteria", "Datasets", "Installation", and "References".  
  
The main text on the page describes `pycox` as a Python package for survival analysis and time-to-event prediction using PyTorch, built on the `torchtuples` package. It mentions an R version available at `survivalmodels`. The text also notes the inclusion of various survival models, evaluation metrics, and preprocessing tools.  
  
A small note at the bottom right of the page says "Generated by Sphinx-Gallery".

# Data Format for Continuous-time Models:

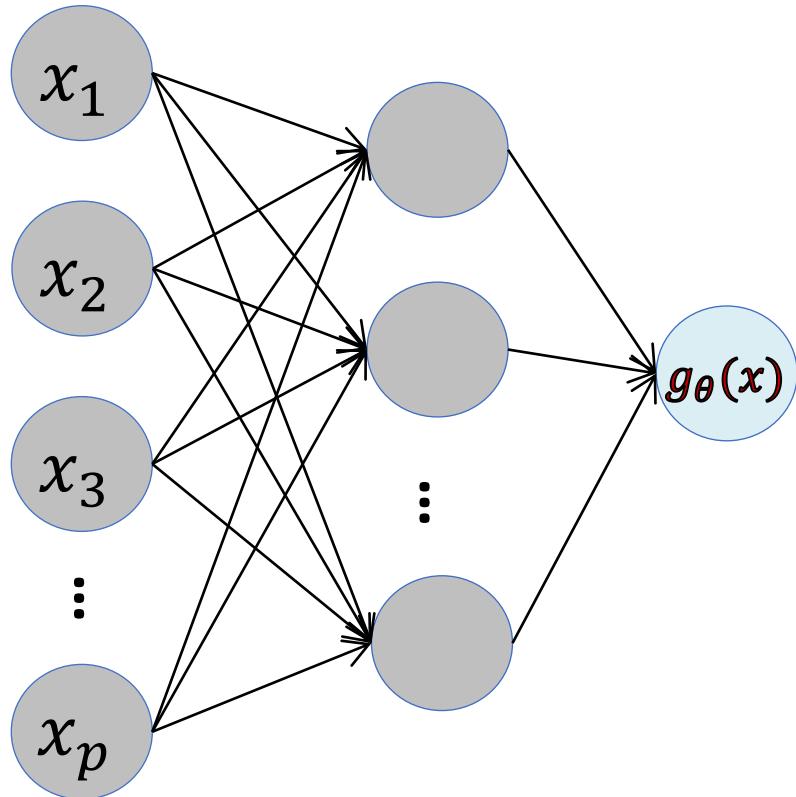


Subject	Time	Event	X
1	95	0	...
2	39	0	...
3	73	1	...
4	66	0	...
5	24	1	...
...	...	...	...

# DeepSurv: CoxPH + NN

$$\Pr(T > t | X = x) = \exp \left( - \int_0^t \lambda_0(u) \exp(g_\theta(x)) du \right)$$

Risk Score



- Observed data:  $(Y, \Delta, X)$
- Input nodes of NN:  $x$
- Output node of NN:  $g_\theta(x)$
- Parameters to be optimized:  $\theta$

$$l(\theta) := -\frac{1}{n_E} \sum_{i: \Delta_i=1} \left[ g_\theta(x_i) - \log \sum_{j \in R(Y_i)} \exp(g_\theta(x_j)) \right]$$

$$\widehat{\Pr}(T > t | X = x) = \exp \left( -\widehat{\Lambda}_0(t | g_{\widehat{\theta}}) \exp(g_{\widehat{\theta}}(x)) \right)$$

## DeepSurv: Theoretical Guarantee

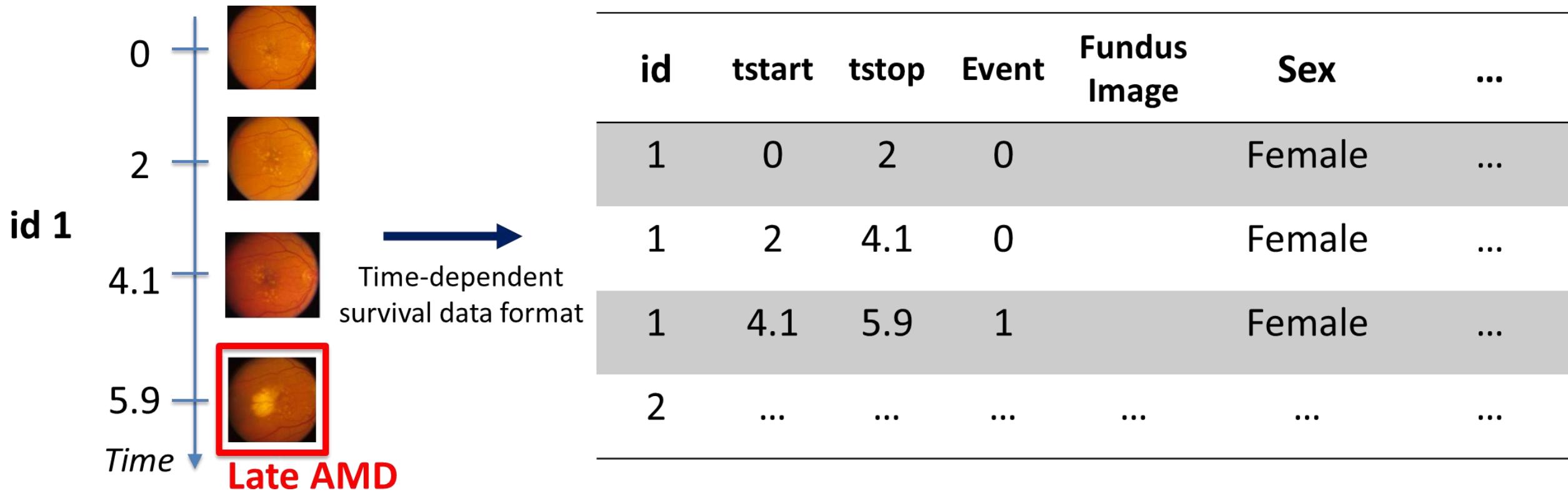
$$\Pr(T > t | X = x) = \exp\left(- \int_0^t \lambda_0(u) \exp(g_{\theta}(x)) du\right)$$

Risk Score

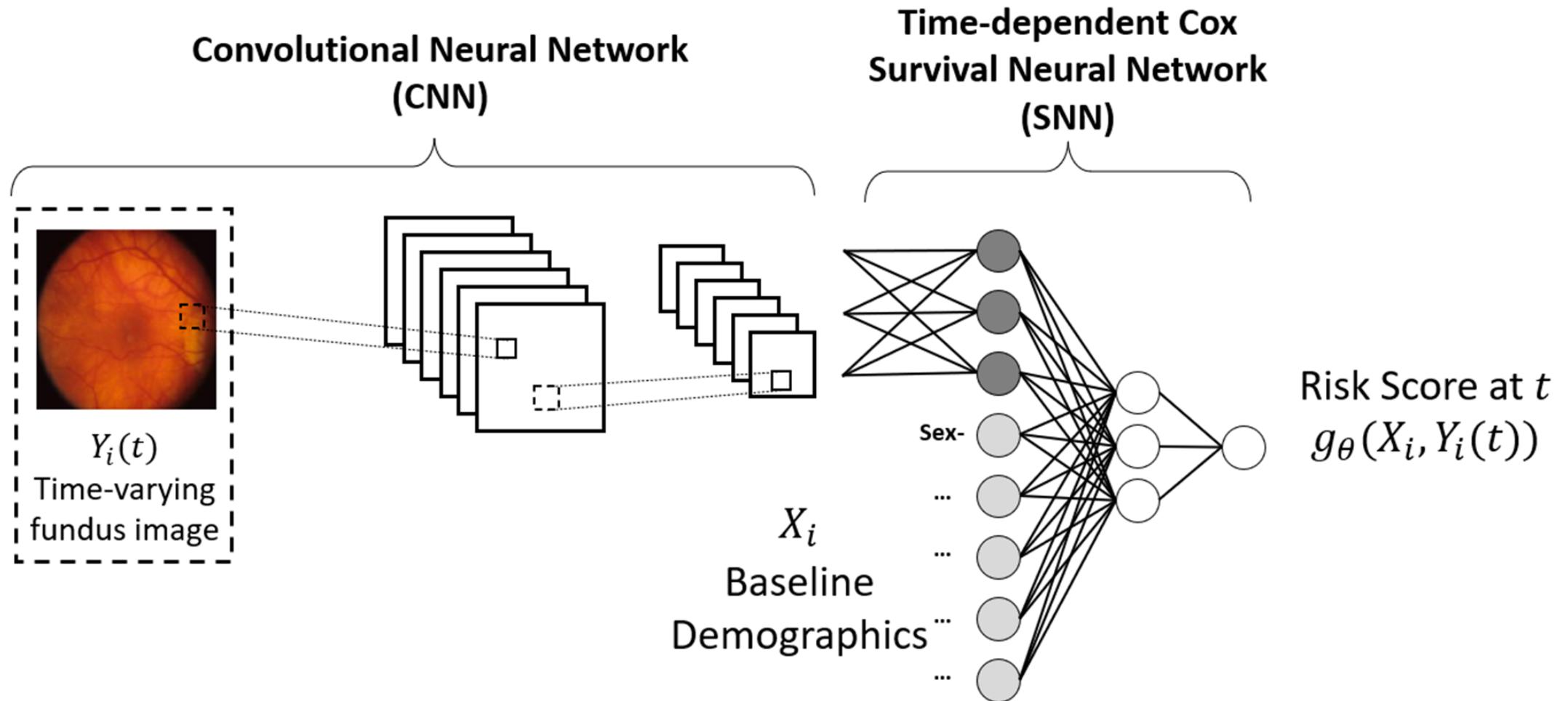
[Zhong, Q. 2022] established the statistical foundations for DeepSurv

[Zeng, L. 2025+] established the statistical properties and offered practical guidelines when using mini-batch estimator via SGD to solve DeepSurv

# tdCoxSNN: Time-dependent Cox Survival Neural Network

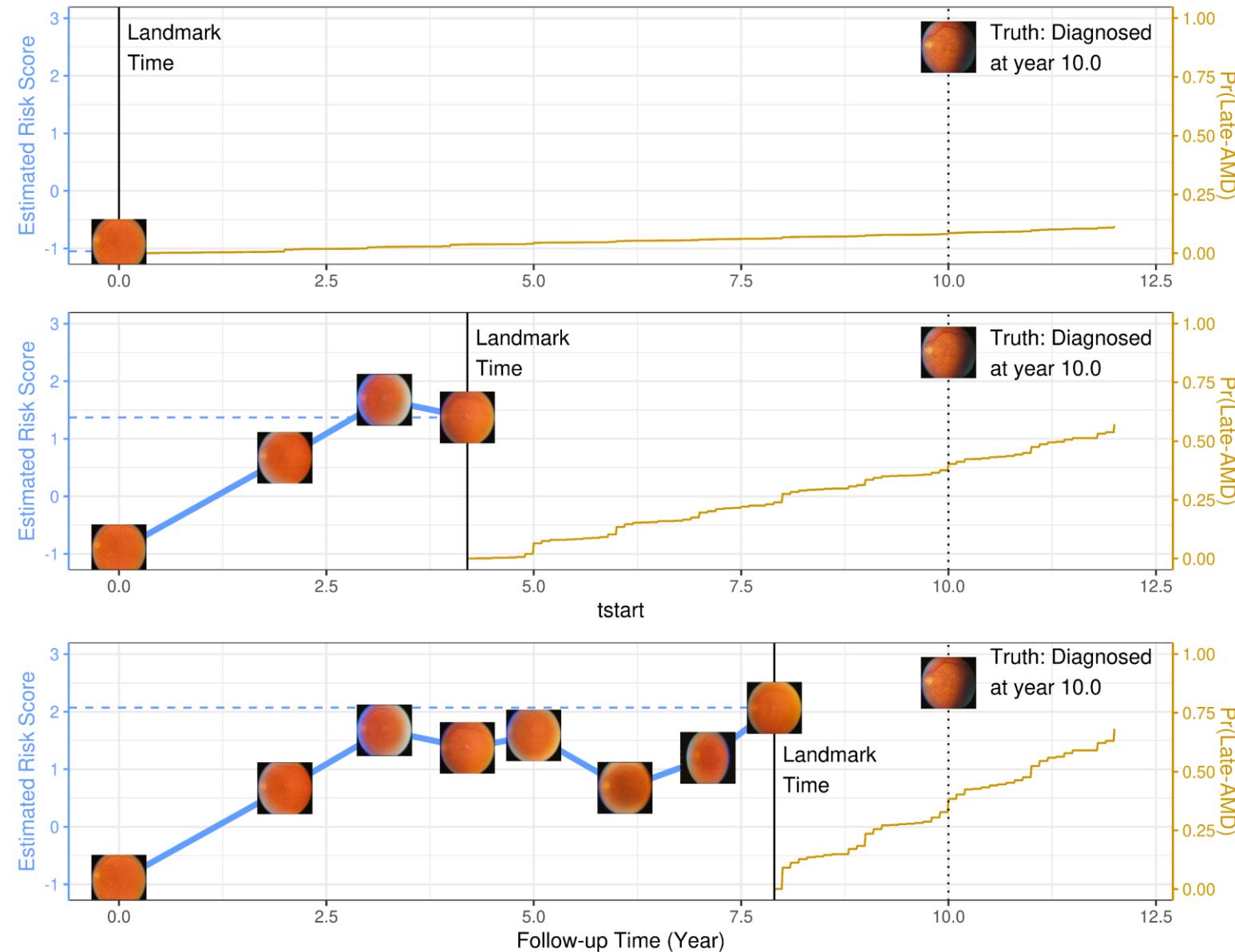


# tdCoxSNN



The PyTorch, Tensorflow, and R-Tensorflow version can be found at <https://github.com/langzeng/tdCoxSNN>.

# Dynamic Prediction with Longitudinal Fundus Images



Relax the Proportional Hazards assumption:

SuMo-net:

$$\Pr(T > t | X = x) = \exp(-\Lambda(t, x))$$

Directly model the cumulative hazard function through Monotone-NN

SODEN:

$$\Pr(T > t | X = x) = \exp\left(-\int_0^t \lambda(u, x) du\right)$$

Directly model the hazard function through NN with positive output

Fit the NN by maximizing the full likelihood:  $\max \sum_i \Delta_i \log[\lambda(Y_i | X_i)] - \Lambda(Y_i | X_i)$

# Survival ODE

$\Lambda(t|X_i)$  is the solution of the following Ordinary Differential Equation (ODE):

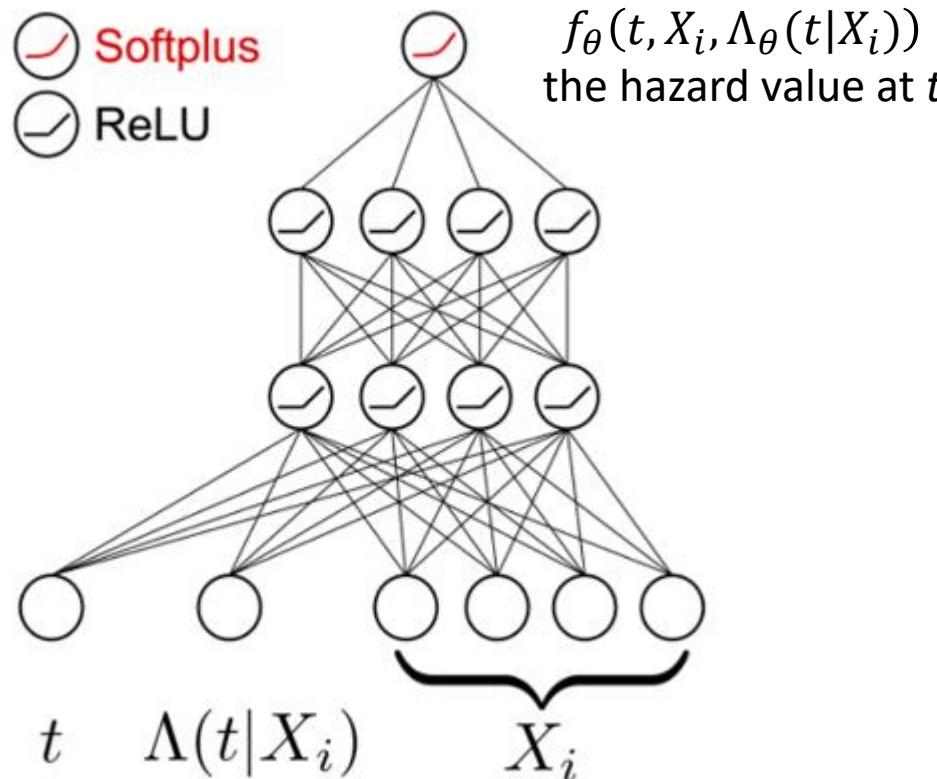
$$\begin{cases} \frac{d\Lambda(t|X_i)}{dt} = \lambda(t|X_i) \\ \Lambda(0|X_i) = 0 \end{cases}$$

- Obtain  $\Lambda(Y_i|X_i)$  through numerical approximation.
- Note that ODE constraints are for every individual.

# SODEN: Survival ODE+NN

Model  $\lambda(t|X_i)$  through a neural network  $f_\theta(t, X_i, \Lambda_\theta(t|X_i))$

$$\begin{cases} \frac{d\Lambda_\theta(t|X_i)}{dt} = f_\theta(t, X_i, \Lambda_\theta(t|X_i)) \\ \Lambda_\theta(0|X_i) = 0 \end{cases}$$



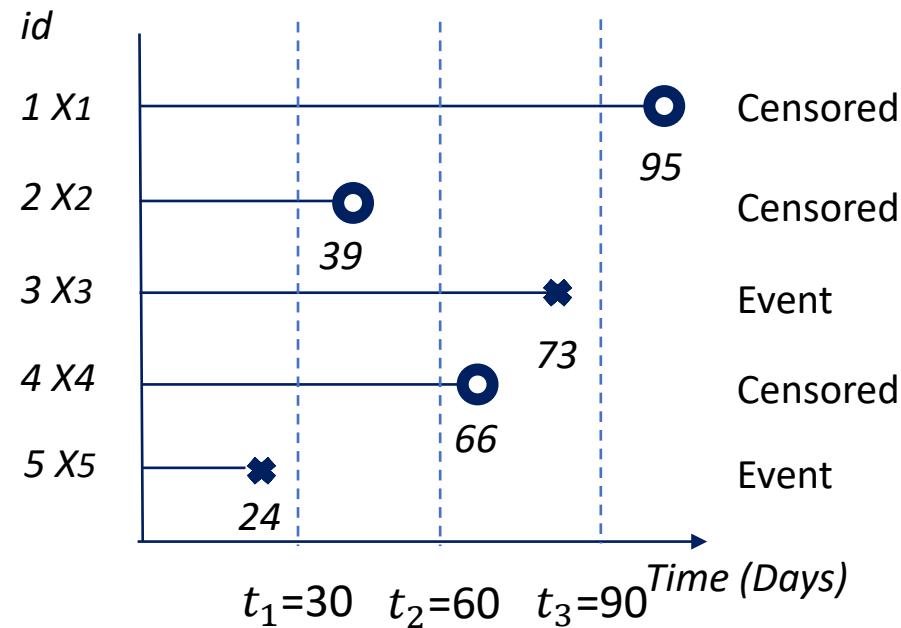
- Observed data:  $(Y, \Delta, X)$
- Input nodes of NN:  $t, X, \Lambda_\theta$
- Output node of NN:  $\lambda$  at  $t$
- Parameters to be optimized:  $\theta$

# Gradient-Based Optimization Algorithms for SODEN

- Loss function:  $l(\theta) = \sum_i \left\{ -\Delta_i \log \left[ \frac{d\Lambda_\theta(t|X_i)}{dt} \Big|_{t=Y_i} \right] + \Lambda_\theta(Y_i|X_i) \right\}$
- Training procedure:
  - Step 1: Given current parameter  $\theta$ , compute  $\Lambda_\theta(Y_i|X_i)$  and its gradient w.r.t. to  $\theta$  by solving\*
$$\begin{cases} \frac{d\Lambda_\theta(t|X_i)}{dt} = f_\theta(t, X_i, \Lambda_\theta(t|X_i)) \\ \Lambda_\theta(0|X_i) = 0 \end{cases}$$
  - Step 2: Update the parameter  $\theta$  using the quantities calculated in step 1.
- Prediction:  $\widehat{\Pr}(T > t|X = x) = \exp(-\widehat{\Lambda}_\theta(t|X_i))$

\*The ODE is solved using package “*torchdiffeq*”

# Data Format for Discrete-time Models:



Subject	Time	Event	$x$
1	90	0	...
2	30	0	...
3	90	1	...
4	60	0	...
5	30	1	...
...	...	...	...

# DeepHit: Discrete-time Survival Model + NN

$$t^* \in \{0, t_1, t_2, \dots, t_m\}$$

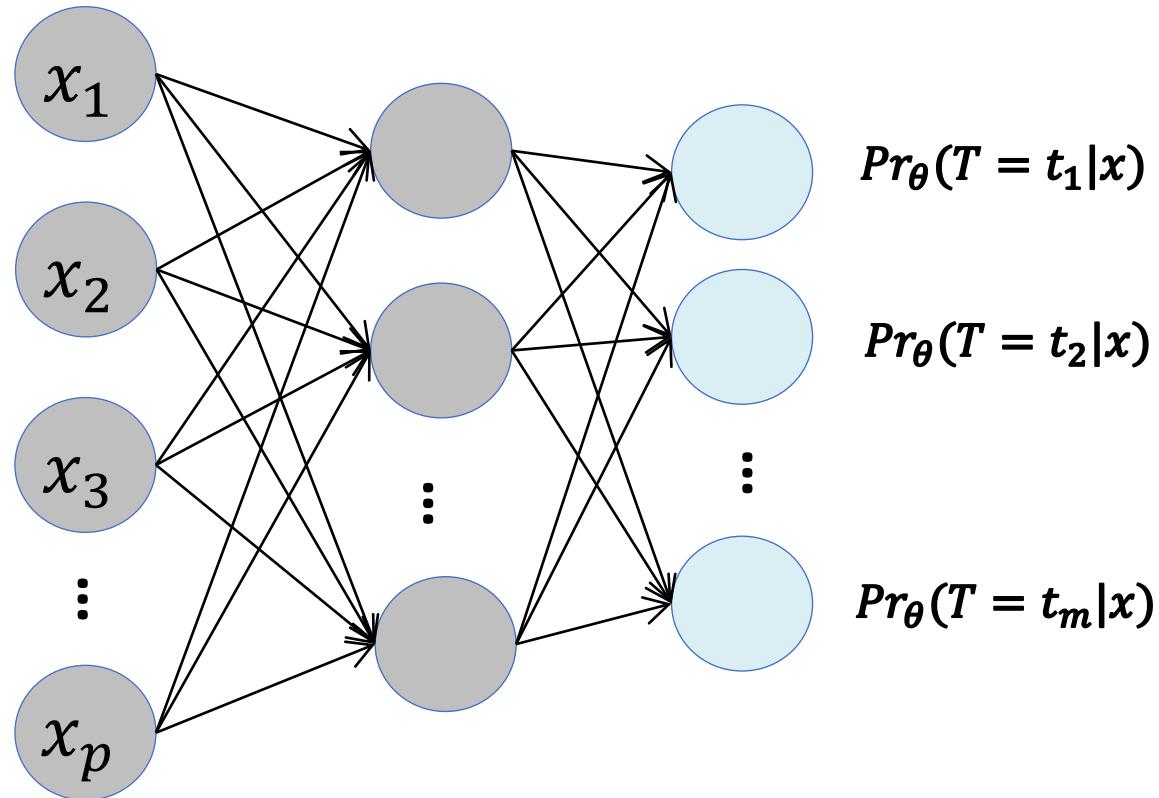
$$\Pr(T > t^* | X) = 1 - \Pr(T \leq t^* | X) = 1 - \sum_{s=t_1}^{t^*} \Pr(T = s | X)$$

Discretize the time:

- $m$ : number of time points
- Discretization strategy

$$\Pr(\textcolor{red}{T_d} = t_j | X) := \Pr(t_{j-1} < \textcolor{red}{T_c} \leq t_j | X)$$

# DeepHit: Discrete-time Survival Model + NN



- Observed data:  $(Y, \Delta, X)$
- Input nodes of NN:  $x$
- Output nodes of NN:  
 $(Pr_{\theta}(t_1|x), \dots, Pr_{\theta}(t_m|x))$
- Parameters to be optimized:  $\theta$

# DeepHit: Loss Function

$$l(\theta) = L_1 + \alpha L_2$$

$L_1 : -\log Likelihood(Y, \Delta, X)$

$$= - \sum \{ I(\Delta_i = 1) \log[\Pr_{\theta}(T = Y_i | X_i)] + I(\Delta_i = 0) \log[\Pr_{\theta}(T > Y_i | X_i)] \}$$

$L_2 : Pairwise\ discordance\ (Ordering\ Error)$

$$= \sum_{\text{all pairs } (i,j)} I(\Delta_i = 1, Y_i < Y_j) \exp\left(-\frac{\Pr_{\theta}(T \leq Y_i | X_i) - \Pr_{\theta}(T \leq Y_j | X_j)}{\sigma}\right)$$

A patient who died at time  $T$  should have higher risk at time  $T$  than a patient who survived longer than  $T$ .

# Example with Codes

Primary Biliary Cirrhosis (PBC) disease

Dataset: “pbc2” (Mayo Clinic)

Consists of 312 subjects

Outcome of interest: time-to-liver transplant

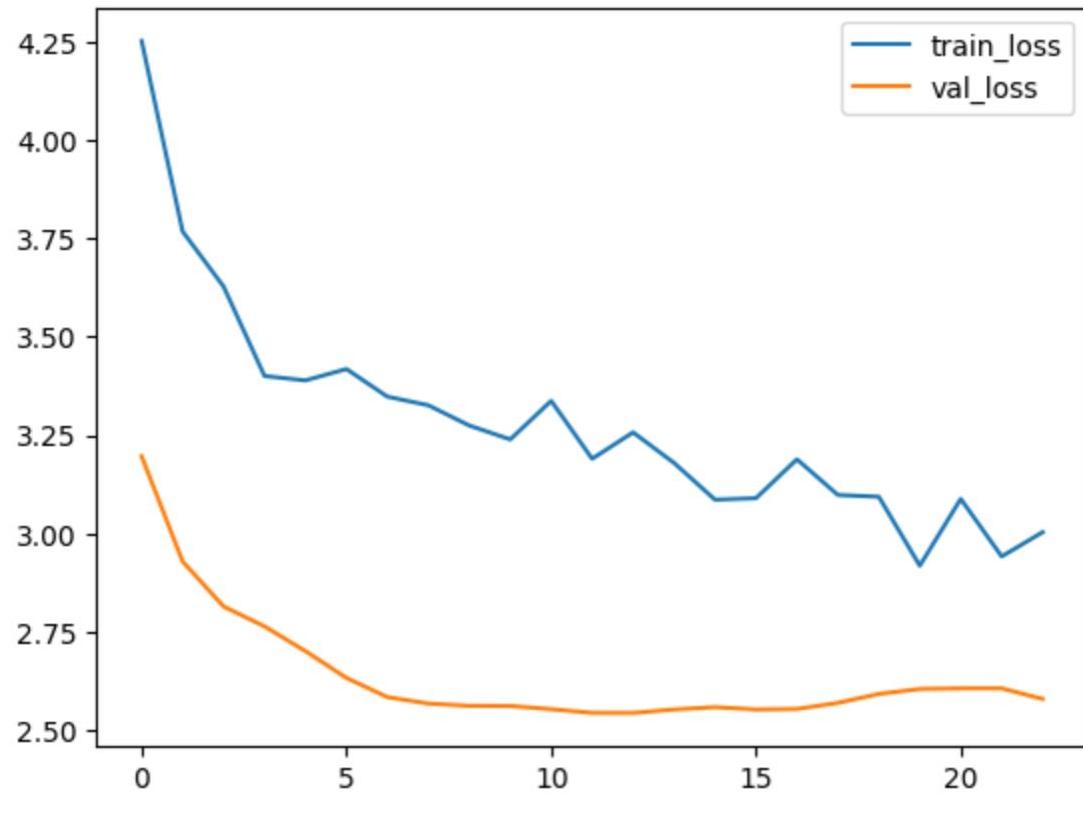
Predictors:

- 12 lab variables (7 continuous lab tests, e.g., albumin; 5 categorical, e.g., liver enlargement)
- 3 other variables (sex, age at start-of-study, and treatment indicator)

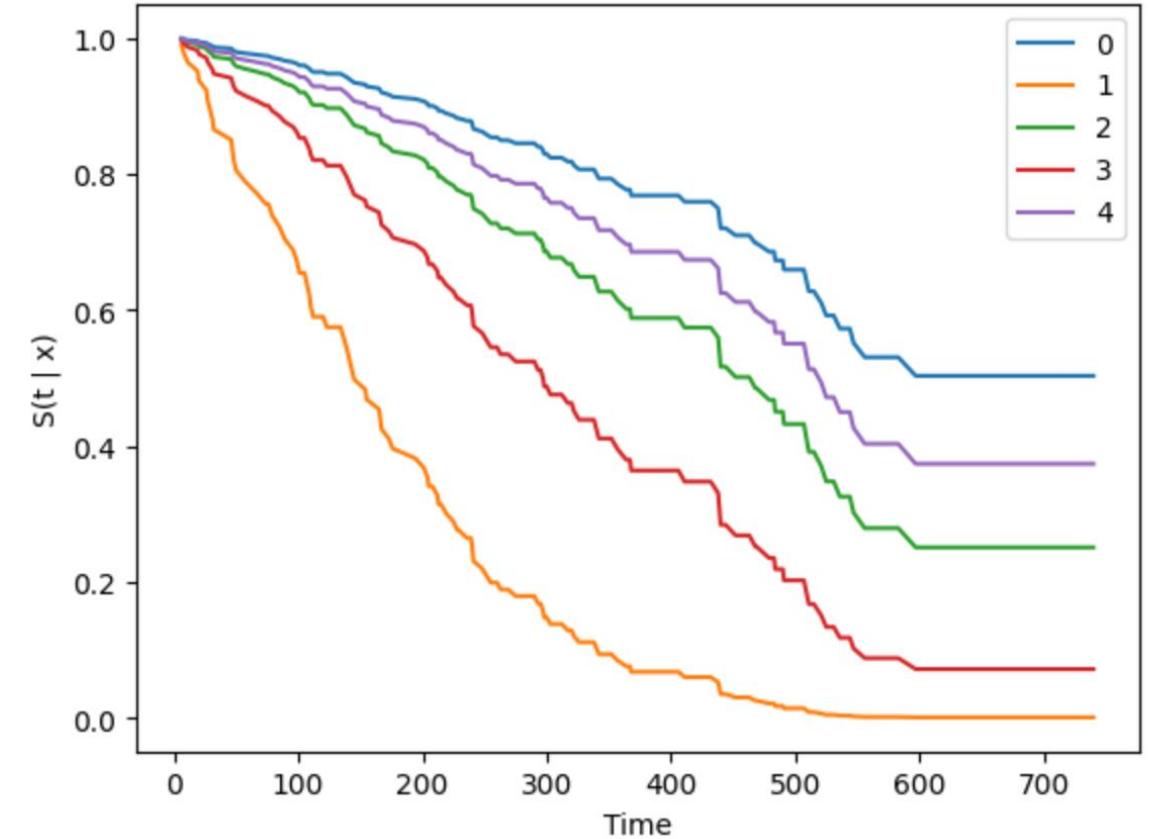
*“DeepSurv\_DeepHit\_PBC.ipynb”*

# DeepSurv Result

Training



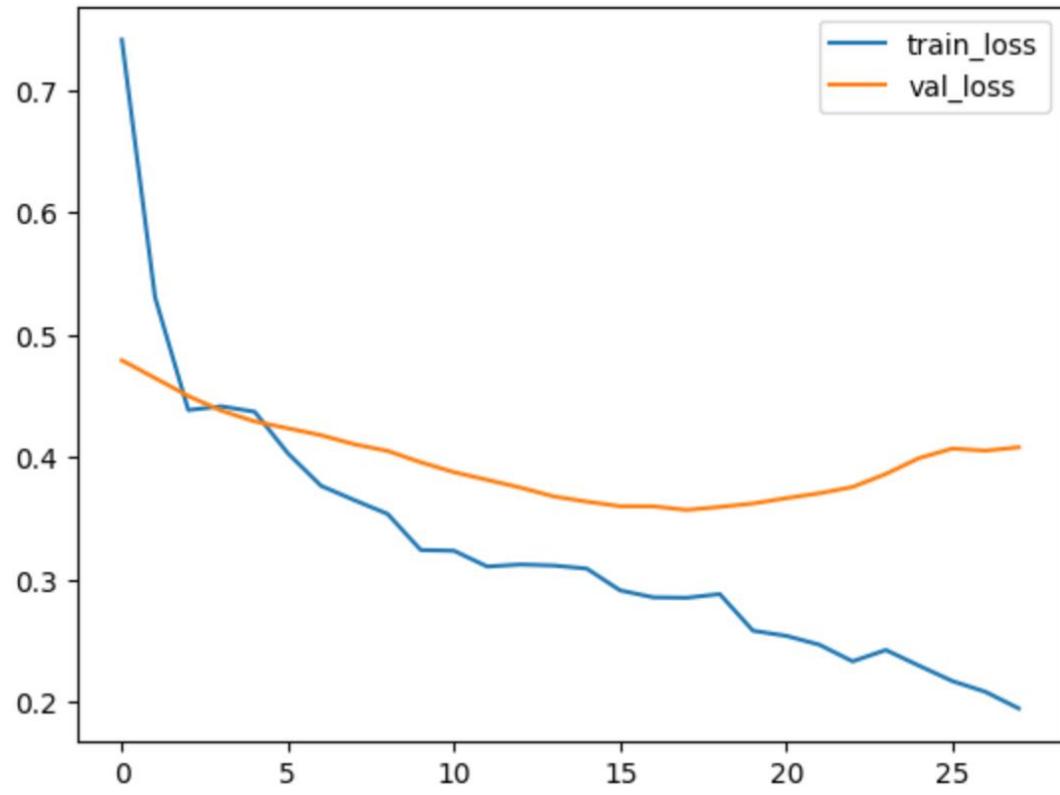
Prediction



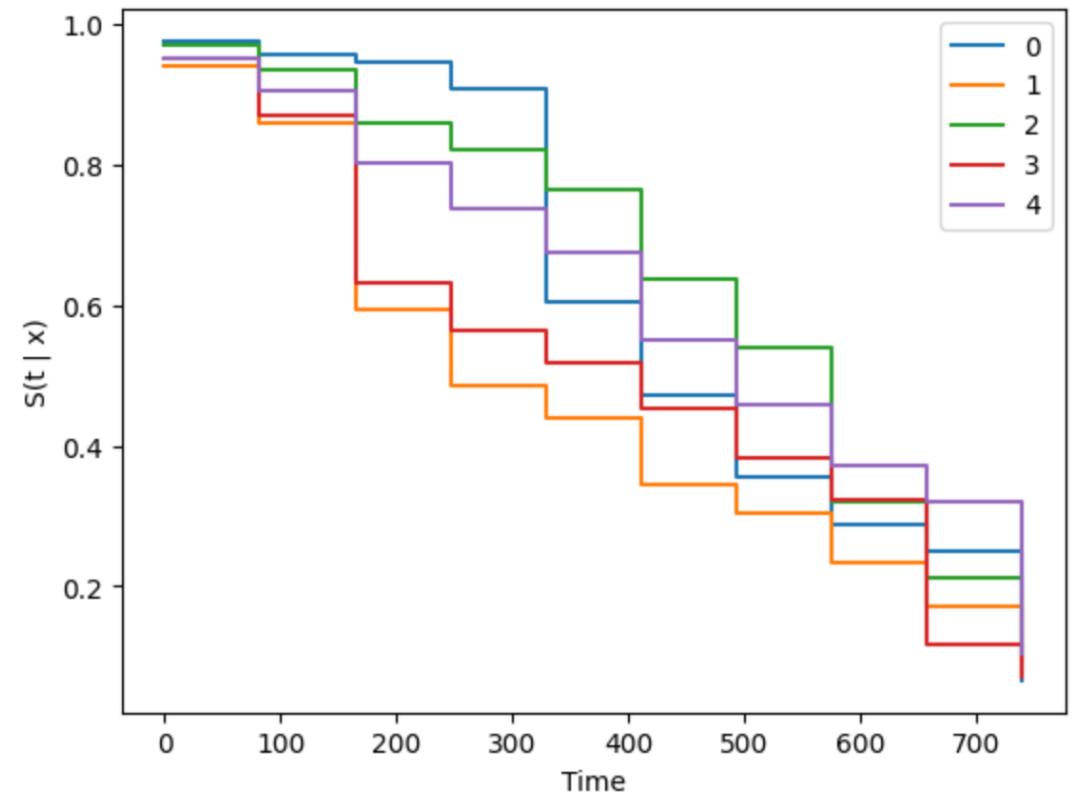
C-index (on test data) = 0.87; IBS (on test data) = 0.10

# DeepHit Result

Training



Prediction



C-index (on test data) = 0.79; IBS (on test data) = 0.17

# Part I

*Case Study 1: Prediction of Progression of AMD (Age-related Macular Degeneration)*

# Age-related Macular Degeneration (AMD)



HEALTHY EYE CONDITION



EARLY AMD



LATE AMD

- AMD, a prognostic chronic disease, is a leading cause of vision loss in the developed world.
- The late phase (late-AMD) is associated with severe visual loss.
- Predicting the progression of AMD provides the best chance of preserving the vision.

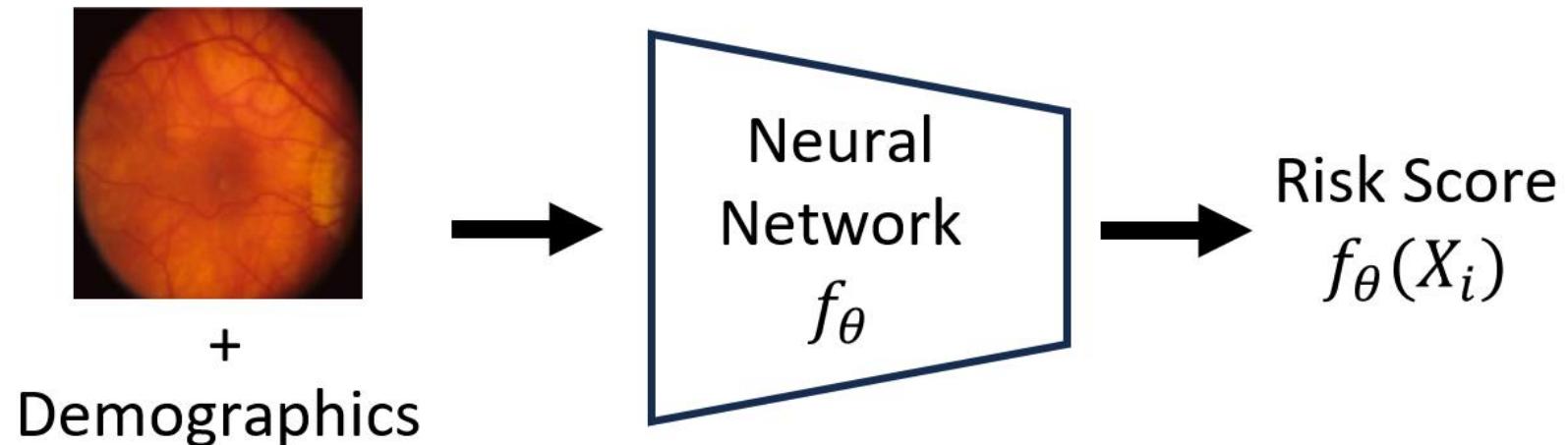
**Outcome:** Time-to-late-AMD

**Target:** Predict AMD progression with fundus images

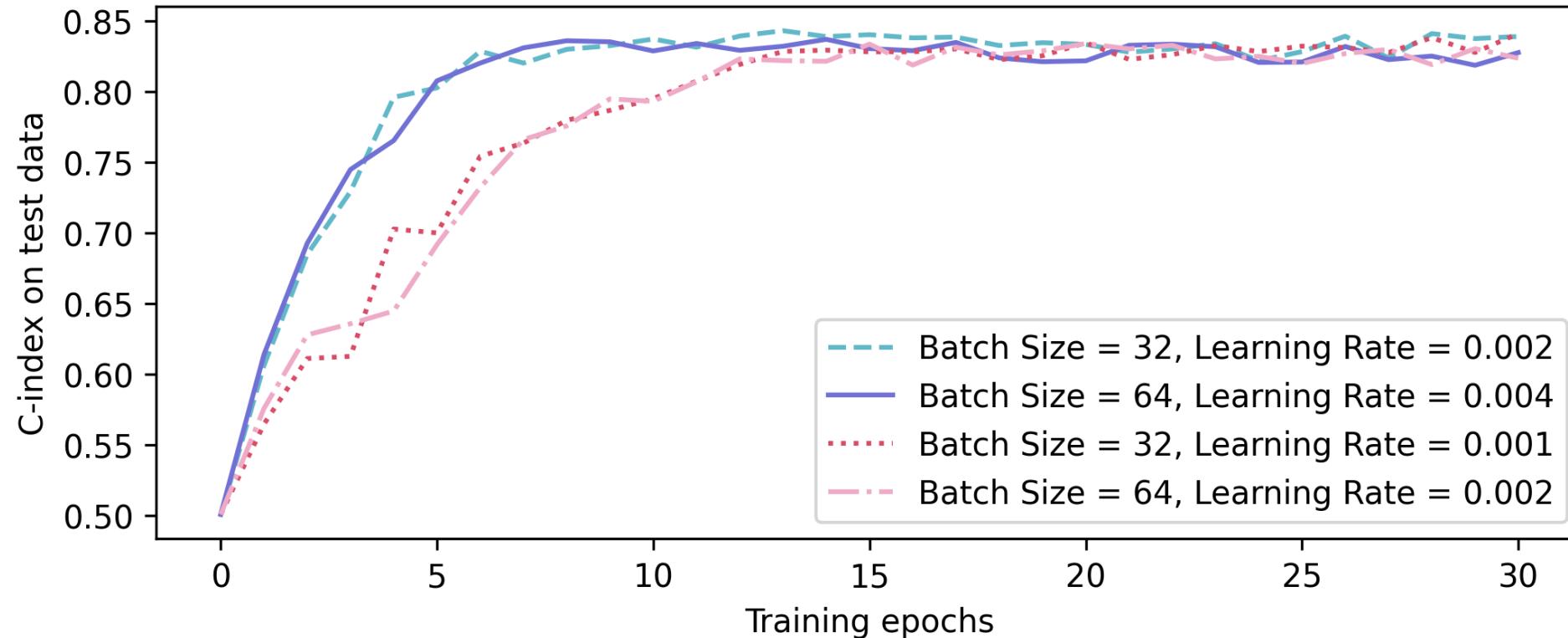
# Survival Prediction with High-dimensional Covariates

- Medical Image Predictor: fundus images ( $3 \times 224 \times 224$ )
- Outcome of interest: Time-to-late-AMD

Cox Neural Network:  $\lambda(t|X) = \lambda_0(t) \exp\{f_\theta(X)\}$

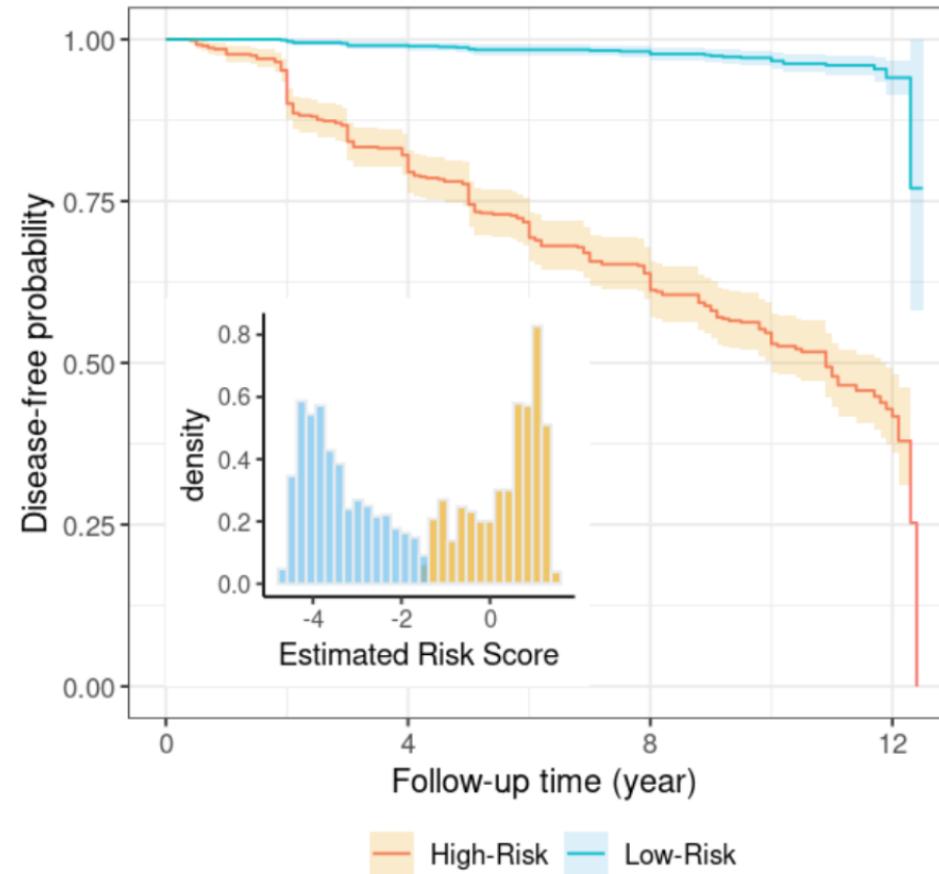


# Training of NN

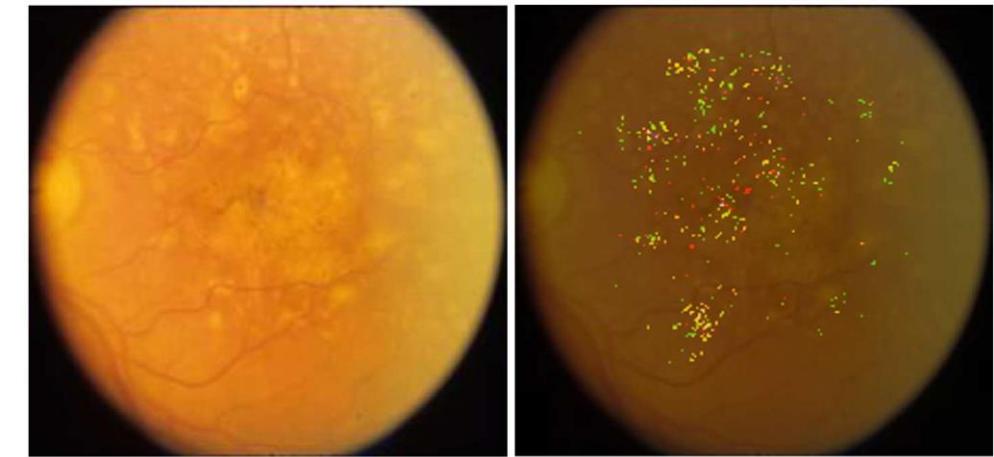


- A final model was fitted through hyper-parameter tuning with C-index 0.85 on a hold-out test data.

# Subgroup Identification and Saliency Map



		High-Risk	
		At Risk	Events
At Risk	607	465	271
Events	0	122	211
		Low-Risk	
At Risk	975	925	723
Events	0	10	20



# Prediction Risk Subgroup Characteristics

Table 2: Characteristics of high-risk and low-risk groups in test data

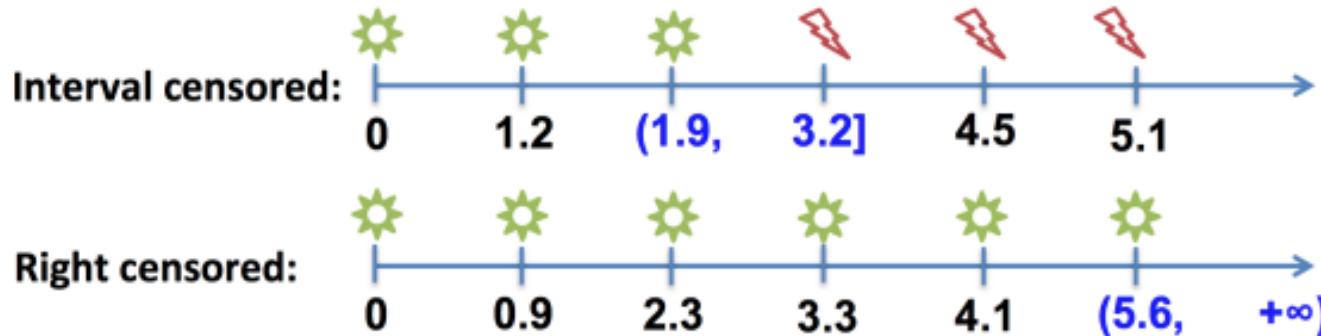
<b>Eye-level variables</b>	High-Risk (N = 607)	Low-Risk (N = 975)	p-value
Baseline manually extracted image features			
Maximum Drusen Size (mean $\pm$ s.d.)	3.83 $\pm$ 1.18	2.41 $\pm$ 1.02	<0.001
Pigmentary Abnormalities (N, %)	161 (26.5)	64 (6.6)	<0.001
Soft Drusen (N, %)	502 (82.7)	308 (31.6)	<0.001
Calcified Drusen (N, %)	18 (3.0)	0 (0)	<0.001
Reticular Drusen (N, %)	21 (3.5)	2 (0.2)	<0.001
Drusen area (mean $\pm$ s.d.)	4.39 $\pm$ 2.25	1.36 $\pm$ 1.36	<0.001
Increased Pigment (N, %)	311 (51.2)	108 (11.1)	<0.001
<b>Subject-level variable</b>	High-Risk	Low-Risk	p-value
Exclude subjects with two eye of disparate risk	(N = 283)	(N = 440)	
Baseline age, year (mean $\pm$ s.d.)	70.5 $\pm$ 5.6	68.4 $\pm$ 4.4	<0.001
Female (N, %)	150 (53.0)	261 (59.3)	0.110
Educational level at least highschool (N, %)	167 (59.0)	305 (69.3)	0.006
Baseline smoking status (N, %)			0.516
Never smoked	114 (40.3)	196 (44.5)	
Former smoker	146 (51.6)	209 (47.5)	
Current smoker	23 (8.1)	35 (8.0)	

\* Two-sample t-test for continuous features, Pearson's Chi-squared test for categorical features

# Part I

## 1.2 Neural networks for interval-censored survival data

# Interval-Censored Data



Observed data:  $D_i = (L_i, R_i; X_i)$   
 $L_i < T_i \leq R_i$ ; when  $R_i = \infty$ , right censoring

Likelihood:  $\Pr(L_i < T_i \leq R_i) = S(L_i | X_i) - S(R_i | X_i)$

# Modeling $S(t|X)$

Semiparametric transformation model:

$$S(t|X) = \exp(-\textcolor{red}{G}\{\exp(X^T \beta)\} \Lambda(t))$$

$G(\cdot)$  is an increasing transformation function

- $G(x) = x$ : proportional hazards (PH) model
- $G(x) = \log(1 + x)$ : proportional odds (PO) model
- In practice, transformation can be assumed unknown and get ‘estimated’ by the data

$\Lambda(\cdot)$  is an unspecified function

- Can be estimated through a sieve maximum likelihood estimation approach

# Sieve Estimation

- Build a sieve space using Bernstein polynomials
- Approximate  $\Lambda(\cdot)$  by a sieve estimator  $\Lambda_n(\cdot)$

$$\Lambda_n(t) = \sum_{k=0}^{m_n} \phi_k B_k(t, m_n, c, u),$$

- Obtain sieve MLEs  $(\hat{\beta}_n, \hat{\Lambda}_n)$

# Loss Function

- The loss function (based on the full log-likelihood):  $-l(\theta, \Lambda; X) + \lambda \|\theta\|_1$

$$l(\theta, \Lambda; X) = \frac{1}{n} \sum_{\{i=1\}}^n \log[\exp\{-\Lambda(L_i) e^{g(X_i; \theta)}\} - \exp\{-\Lambda(R_i) e^{g(X_i; \theta)}\}]$$

- The goal is to estimate  $\Lambda(\cdot)$  and  $g(\cdot; \theta)$  through neural networks.

# BPNet-IC: two sub NNs

- For the estimation of  $g(X_i; \theta)$ , use a standard feed-forward neural network
- For the estimation of  $(\Lambda(L_i), \Lambda(R_i))$ , use the neural network constructed by Bernstein polynomials (**BPNet**)

$$\Lambda_n(t) = f^{out} \left( \sum_{k=0}^{m_n} w_k f_k(t) \right) = \sum_{k=0}^{m_n} w_k f_k(t) = \sum_{k=0}^{m_n} w_k B_k(t, m_n, c, u),$$

- $t$ : input nodes
- one hidden layer with  $(m_n + 1)$  nodes with  $f_k = B_k(t, m_n, c, u)$  as hidden node activation function
- Simultaneously solve the two NNs using one loss function

# ODE-NN-IC

- The previous method of BPNet-IC depends on the PH assumption
- Relax PH by directly modeling  $\Lambda(t|X)$
- Full log-likelihood:

$$\sum_{\{i=1\}}^n \log[\exp\{-\Lambda(L_i|X_i)\} - \exp\{-\Lambda(R_i|X_i)\}]$$

# ODE-NN-IC: ODE+NN

$$\lambda(t|X_i) = f_\theta(t, X_i, \Lambda(t|X_i))$$

- The NN takes  $\Lambda(t|X_i)$  as its input
- Note the relationship:  $\Lambda(t|X_i)$  is the solution of the following ODE:

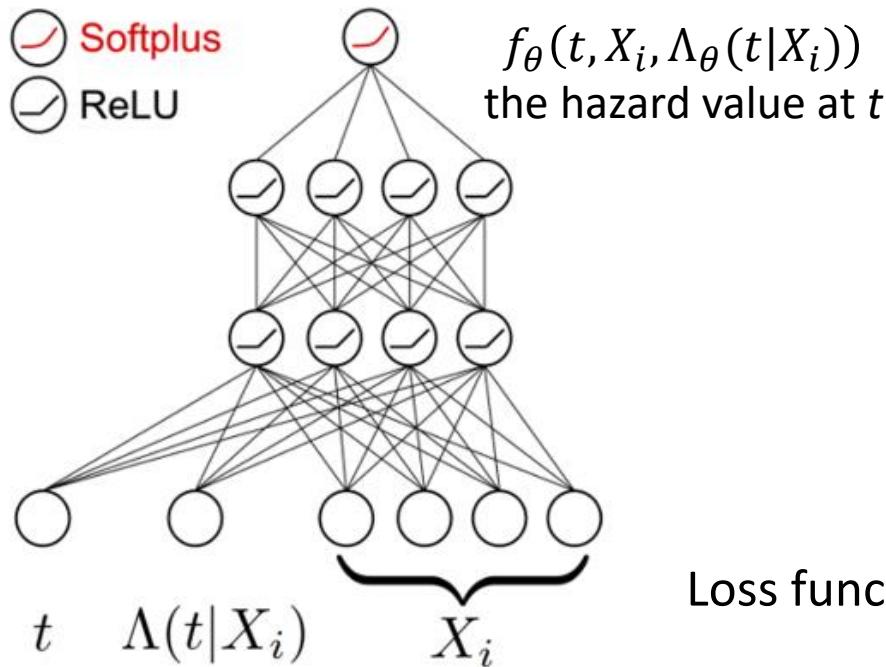
$$\begin{cases} \frac{d}{dt} \Lambda(t|X_i, \theta) = f_\theta(t, X_i, \Lambda(t|X_i)) \\ \Lambda(0|X_i, \theta) = 0 \end{cases}$$

- Iteratively solve the ODE, get both  $\Lambda(t|X_i)$  and  $\lambda(t|X_i)$ , and fit the neural network

# ODE-NN-IC: NN part

- The full log-likelihood in IC without PH:

$$\sum_{\{i=1\}}^n \log[\exp\{-\Lambda_\theta(L_i|X_i)\} - \exp\{-\Lambda_\theta(R_i|X_i)\}]$$



Model  $\lambda(t|X_i)$  through NN

- Observed data:  $(L, R, X)$
- Input nodes of NN:  $x, t, \Lambda(t|X_i)$
- Output node of NN:  $\lambda_\theta(x)$
- Parameters to be optimized:  $\theta$

Loss function:  $-\sum_i \log[\exp\{-\Lambda(L_i|X_i)\} - \exp\{-\Lambda(R_i|X_i)\}] + \alpha \|\theta\|_1$

# Example with Codes – ODE-NN-IC

Simulated IC dataset with 20 covariates

Dataset: “ODE\_NN\_IC\_Simu\_trainData” (training) and “ODE\_NN\_IC\_SimuTestData” (test set)

Consists of 1000 subjects in both training set and test set

Predictors:

- 4 continuous, 4 binary, 12 multinomial
- **Non-PH** for one binary variable; **nonlinear** effects for selected continuous covariates

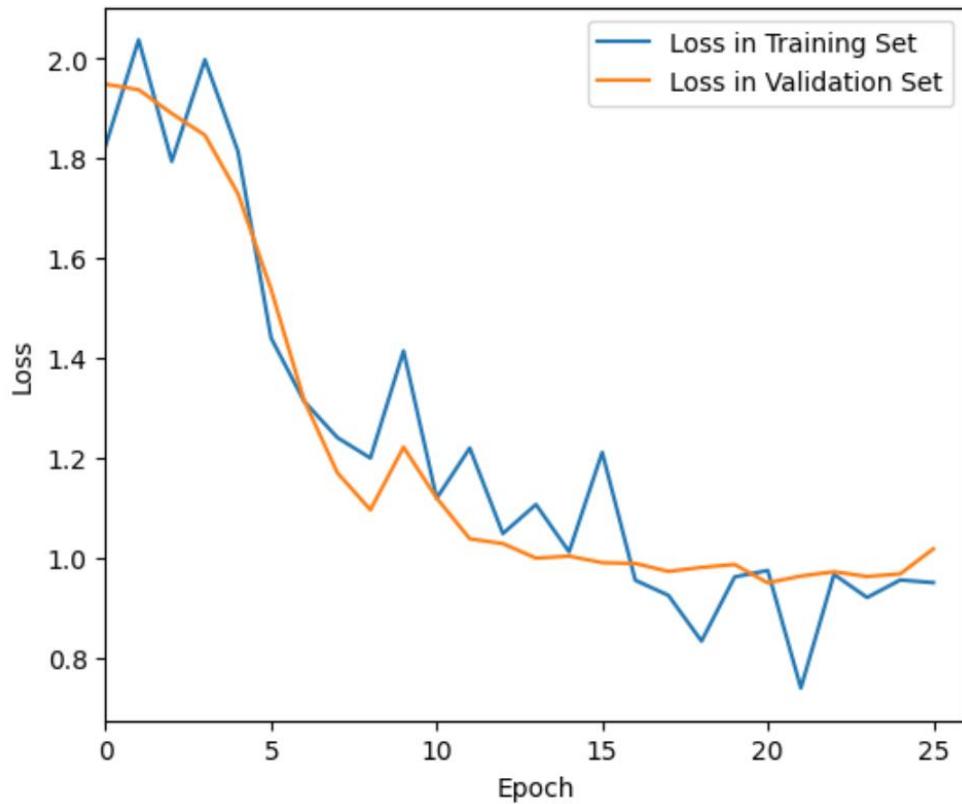
Outcome of interest: event time generate from following:

$$S(t|X_i) = \left[ e^{-0.01t^{10}} I(X_{i5} = 0) + e^{-0.01t^5} I(X_{i5} = 1) \right]^{\exp(\sum_j \beta_j X_{ij} + X_{i1}^2 + X_{i2}^2 + X_{i3} X_{i4})}$$

“ODE\_NN\_IC\_Simu.ipynb”

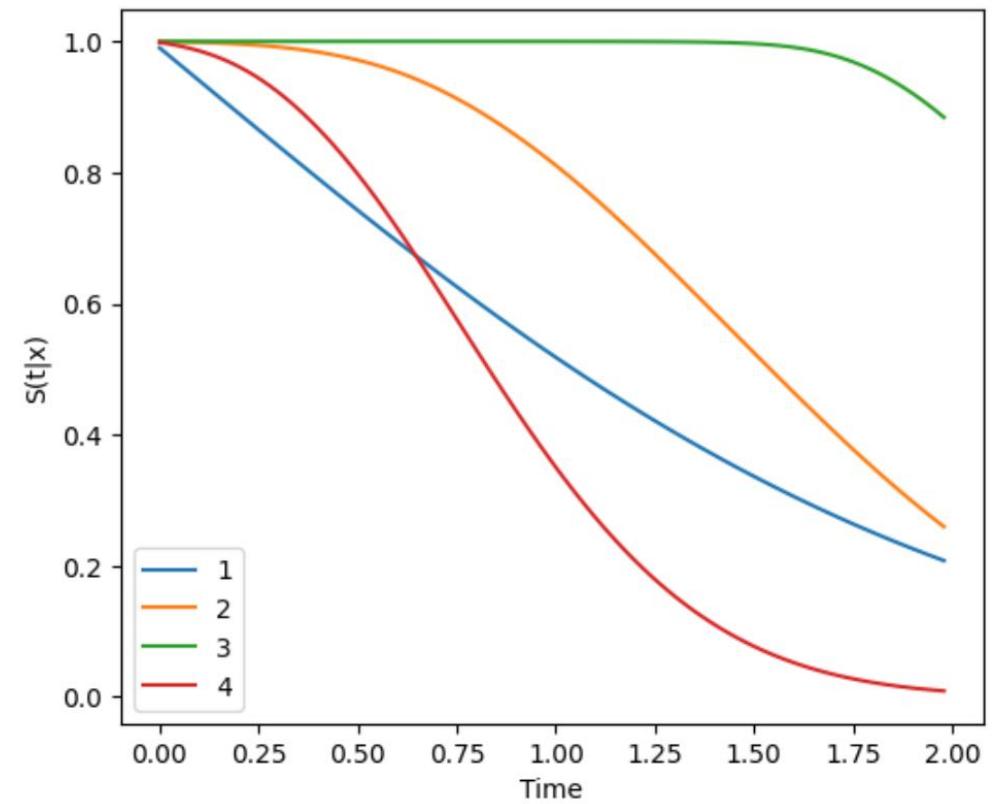
# ODE-NN-IC Result

Training



MSE (on test data) = 0.033

Prediction



# Part I

## *Case study 2: Prediction of Development of AD (Alzheimer's Disease)*

Tao Sun, Ying Ding. Neural network on interval-censored data with application to the prediction of Alzheimer's disease. (2022). *Biometrics*. doi: 10.1111/biom.13734. PMID: 35960189

# Alzheimer's Disease Neuroimaging Initiative (ADNI)

- Estimated heritability of AD is up to 79%
- Desirable to make **early** predictions for AD using genetic data
- ADNI: longitudinal study for AD since 2004
  - investigating clinical, imaging, and genetic biomarkers for AD
  - four consecutive phases (ADNI1, ADNIGO, ADNI2, ADNI3)
  - 2,300 individuals recruited with CN, MCI, or AD
- Analysis plan
  - 1,740 Caucasian individuals with genetic data
  - event of interest: **time-to-AD**
  - start time: age 55
  - AD rarely occurs before 55; ADNI recruited subjects with age  $\geq 55$

# ADNI Data

- Attribute 1: time-to-AD is subject to **general interval censoring**
  - interval-censoring if progressed to AD during study
  - right-censoring if free of AD at the last assessment
  - left-censoring if enrolled with AD
- Attribute 2: time-to-AD is subject to **left truncation** in ADNIGO
  - subjects with AD are not recruited in ADNIG
- Attribute 3: **high-dimensional** GWAS data
  - 7.7 million SNPs

# Joint Likelihood

Likelihood function for all ADNI phases

C: conditional      F: full (unconditional)

$$L_n(\beta, \Lambda | D_1, D_2) = L_{n_1}^C(\beta, \Lambda | D_1) \times L_{n_2}^F(\beta, \Lambda | D_2),$$

where

$$L_{n_1}^C(\beta, \Lambda | D_1) = \prod_{i=1}^{n_1} \frac{\exp[-G\{\exp(\tilde{Z}_i^T \beta)\Lambda(\tilde{L}_i)\}] - \exp[-G\{\exp(\tilde{Z}_i^T \beta)\Lambda(\tilde{R}_i)\}]}{\exp[-G\{\exp(\tilde{Z}_i^T \beta)\Lambda(\tilde{A}_i)\}]},$$

A<sub>i</sub>: truncation time

$$L_{n_2}^F(\beta, \Lambda | D_2) = \prod_{i=1}^{n_2} (\exp[-G\{\exp(Z_i^T \beta)\Lambda(L_i)\}] - \exp[-G\{\exp(Z_i^T \beta)\Lambda(R_i)\}]).$$

# Analysis of ADNI Data

- ▶ Randomly split ADNI into Data1 and Data2 by a ratio 3:1
  - ▶ Data1 for GWAS, training, and internal validation
  - ▶ Data2 for external validation

Table: Characteristics of the complete ADNI data, Data1, and Data2.

	Complete (n=1740)	Data1 (n=1305)	Data2 (n=435)
Age			
Mean(SD)	73.5 (7.1)	73.4 (7.2)	74.0 (6.9)
Median (range)	73.5 (55.0-91.4)	73.5 (55.0-91.4)	73.5 (55.0-90.3)
Gender (n, %)			
Female	780 (44.8%)	587 (45.0%)	193 (44.4%)
Male	960 (55.2%)	718 (55.0%)	242 (55.6%)
Education			
Mean(SD)	16.1 (2.8)	16.1 (2.8)	15.9 (2.7)
Median (range)	16 (4-20)	16 (4-20)	16 (7-20)
APOE (n, %)			
0 allele	941 (54.1%)	697 (53.4%)	244 (56.1%)
1 allele	637 (36.6%)	487 (37.3%)	150 (34.5%)
2 alleles	162 (9.3%)	121 (9.3%)	41 (9.4%)
Censoring types (n, %)			
Left-censored	300 (17.2%)	222 (17.0%)	78 (17.9%)
Interval-censored	342 (19.7%)	257 (19.7%)	85 (19.6%)
Right-censored	1098 (63.1%)	826 (63.3%)	272 (62.5%)
Study (n, %)			
ADNI1	703 (40.4%)	537 (41.2%)	166 (38.2%)
ADNIGO	114 (6.5%)	84 (6.4%)	30 (6.9%)
ADNI2	619 (35.6%)	462 (35.4%)	157 (36.1%)
ADNI3	304 (17.5%)	222 (17.0%)	82 (18.8%)
Follow-up years			
Mean(SD)	3.1 (3.2)	3.1 (3.2)	3.0 (3.3)
Median (range)	2.0 (0.0-15.0)	2.0 (0.0-14.7)	2.0 (0.0-15.0)

# GWAS Findings on Time-to-AD

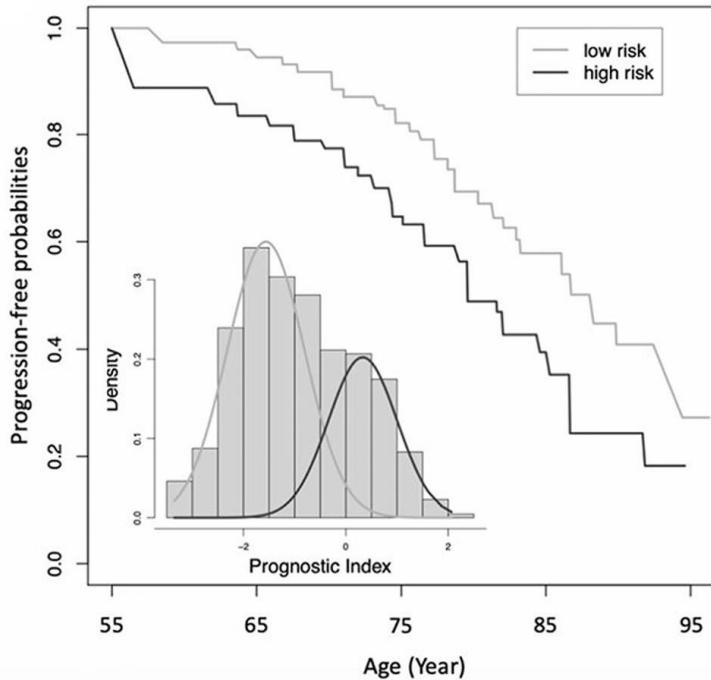
- Perform two sets of genome-wide score tests w/ wt APOE
  - PVRL2–TOMM40–APOE–APOC1 (chr19) and CHRNA4 (chr20) reach the significance level ( $p < 5 \times 10^{-8}$ )
  - Novel discovery: CDKN2AIP (chr4) by both GWAS ( $p < 1 \times 10^{-5}$ )
- Representative SNPs as predictors: 71, 371, and 623 SNPs at the p-value thresholds of  $1 \times 10^{-5}$ ,  $1 \times 10^{-4}$ , and  $2 \times 10^{-4}$

# Prediction Performance Comparisons

Scenario	SNPs	APOE	IcenReg	BPNet-NN	ODE-NN-IC
IBS Score					
1	71	0.085 (0.011)	0.068 (0.016)	0.065 (0.002)	0.061 (0.004)
2	371	0.085 (0.011)	0.064 (0.018)	0.053 (0.006)	0.060 (0.002)
3	623	0.085 (0.011)	-	0.050 (0.006)	0.068 (0.007)
$p_{out}$					
1	71	0.41 (0.04)	0.32 (0.04)	0.33 (0.04)	0.35 (0.03)
2	371	0.41 (0.04)	0.44 (0.04)	0.30 (0.05)	0.32 (0.04)
3	623	0.41 (0.04)	-	0.32 (0.04)	0.32 (0.02)

# Subgroup Identification

- Low- and high-risk subgroups by BPnet-NN
  - Gaussian Mixture modeling on  $\hat{g}(Z_i; \hat{\theta})$



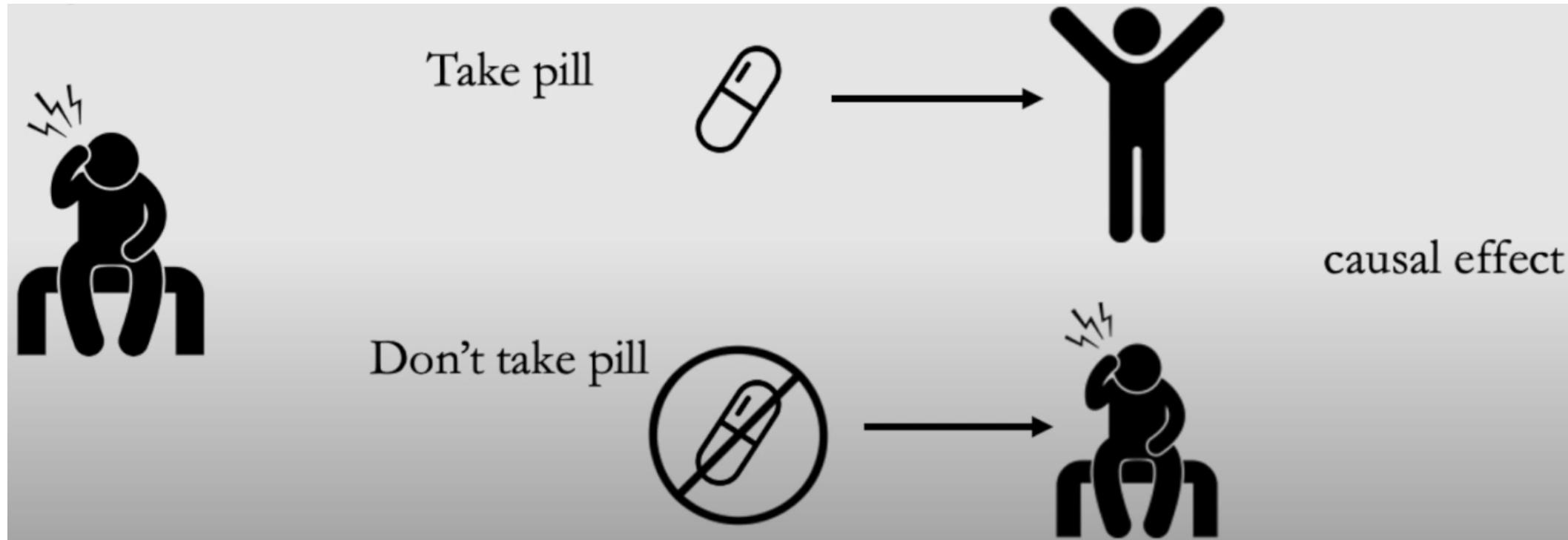
- Helpful for early prevention and clinical management

# Part II: Deep Learning for Causal Survival Analysis

2.1 CATE (conditional average treatment effect) for survival outcomes

# Causal Inference

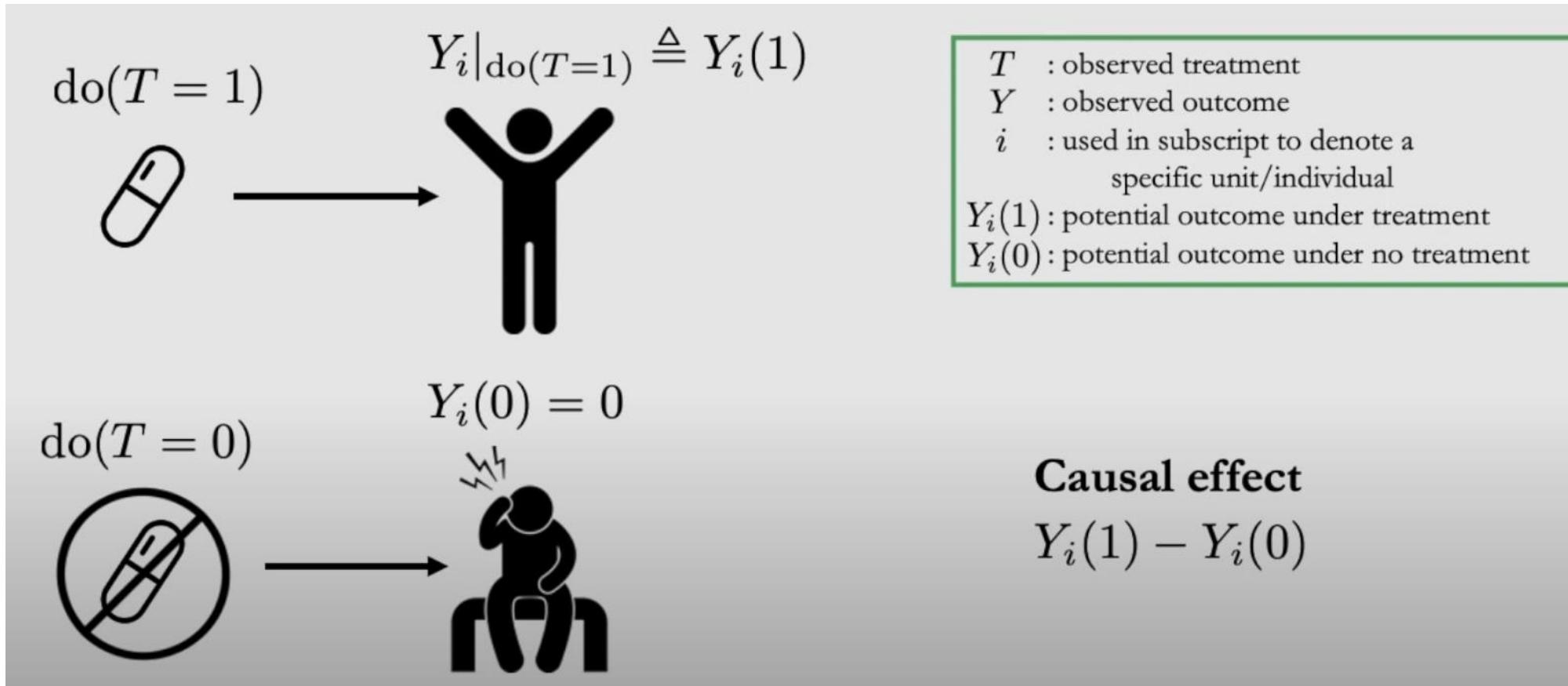
- Causal inference: inferring the effect of a treatment (policy) on some outcome



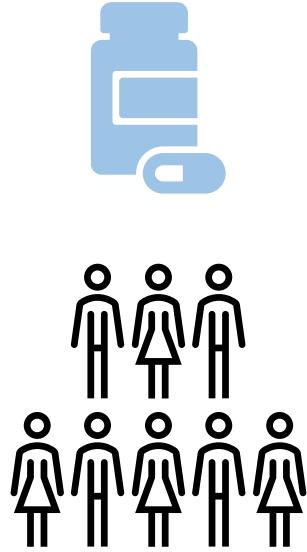
*Credit to Brady Neal (Causal Inference online class)*

# Potential Outcome Framework

- Also called **counterfactual outcome framework**
- ITE (Individual Treatment Effects):  $\tau_i = Y_i(1) - Y_i(0)$
- CATE (Conditional Average Treatment Effects ):  $\tau(x) = E[Y_i(1) - Y_i(0)|X_i = x]$

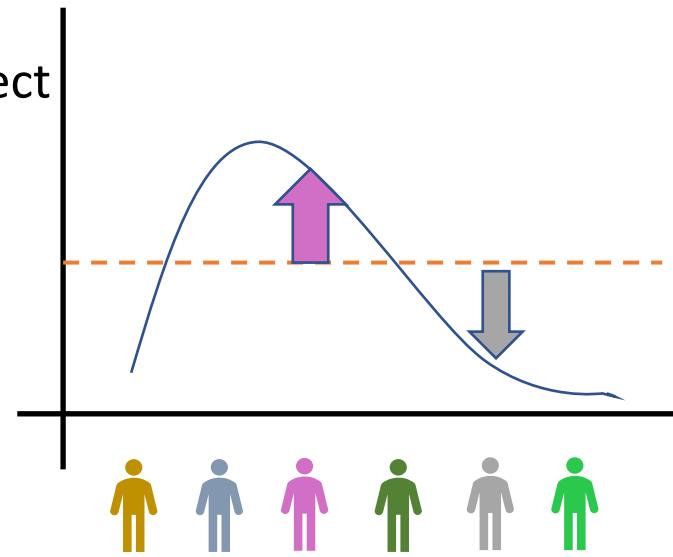


# Heterogeneous Treatment Effects (HTE)



Study population in a clinical trial or an observational study

Individualized treatment effect



Average treatment effect

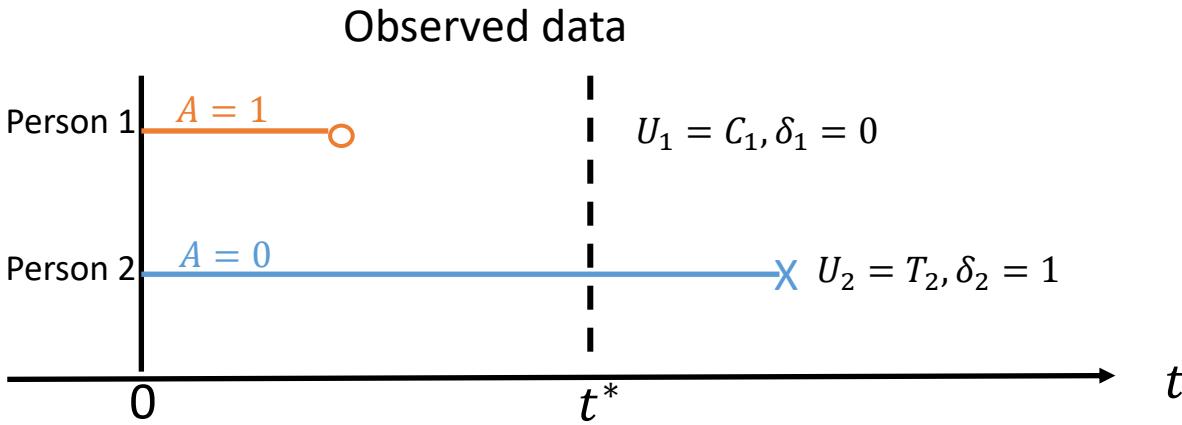
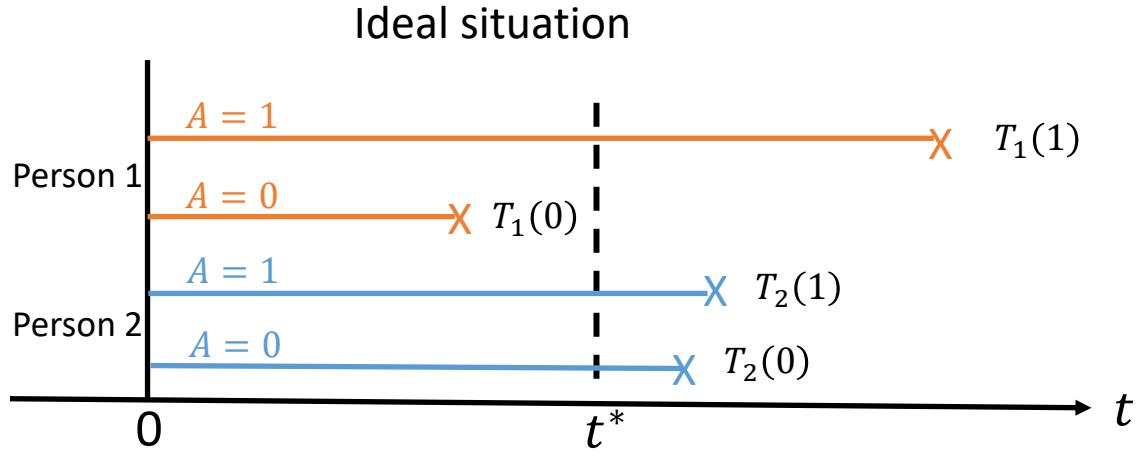
Questions of interests for **survival outcomes**:

- How much increase of the survival probability after the heart surgery?
- How much increase of the life expectancy after the chemotherapy for the lung cancer?

# Notation

- $A$ : binary treatment,  $A \in \{0,1\}$
- $T$ : survival time;  $T(1), T(0)$ : counterfactual survival times
- $C$ : censoring time
- $U = \min\{T, C\}$ : observed time
- $\delta = I(T < C)$ : event indicator
- $X$ : covariates
- $i$  subscript: denote individual  $i$

# Problem Setup with Survival Outcomes



# CATE Definition for Survival Outcomes

- On survival probability scale:

$$\begin{aligned}\tau(x) &= \mathbb{E}[I(T(1) > t^*) - I(T(0) > t^*) | X = x] \\ &= \mathbb{E}[I(T > t^*) | X = x, A = 1] - \mathbb{E}[I(T > t^*) | X = x, A = 0]\end{aligned}$$

- On restricted mean survival time (RMST) scale:

$$\begin{aligned}\tau(x) &= \mathbb{E}[\min(T(1) \wedge t^*) - \min(T(0) \wedge t^*) | X = x] \\ &= \mathbb{E}[\min(T, t^*) | X = x, A = 1] - \mathbb{E}[\min(T, t^*) | X = x, A = 0]\end{aligned}$$

# Assumptions

1. Consistency:  $T = AT(1) + (1 - A)T(0)$  ,  
 $C = AC(1) + (1 - A)C(0)$ ;
2. Unconfoundedness:  $(T(0), T(1)) \perp\!\!\!\perp A | X$  ,  $(C(0), C(1)) \perp\!\!\!\perp A | X$
3. Population Overlap:  $e(x) := P(A = 1 | X = x) \in (0,1)$  ;
4. Non-informative censoring:  $T(a) \perp C(a) | \{X, A = a\}$

## Part II

### 2.2 Deep learning approaches for estimating CATE with survival outcomes

# Two Perspectives for Estimating CATE

$$\begin{aligned}\tau(x) &= \mathbb{E}[I(T(1) > t^*) - I(T(0) > t^*)|X = x] \\ &= \mathbb{E}[I(T > t^*)|X = x, A = 1] - \mathbb{E}[I(T > t^*)|X = x, A = 0] \\ &= S_1(t^*|x) - S_0(t^*|x)\end{aligned}$$

Indirectly target on  $\tau(x)$

Estimate individualized survival function under each treatment arm, then calculate the difference.

Directly target on  $\tau(x)$

$I(T_i(1) > t^*) - I(T_i(0) > t^*)$  : individualized treatment effect (ITE).

$\mathcal{M}(I(T_i(1) > t^*) - I(T_i(0) > t^*)) \sim X$

Deep learning can be used for learning the shared covariate space well between two treatment arms.

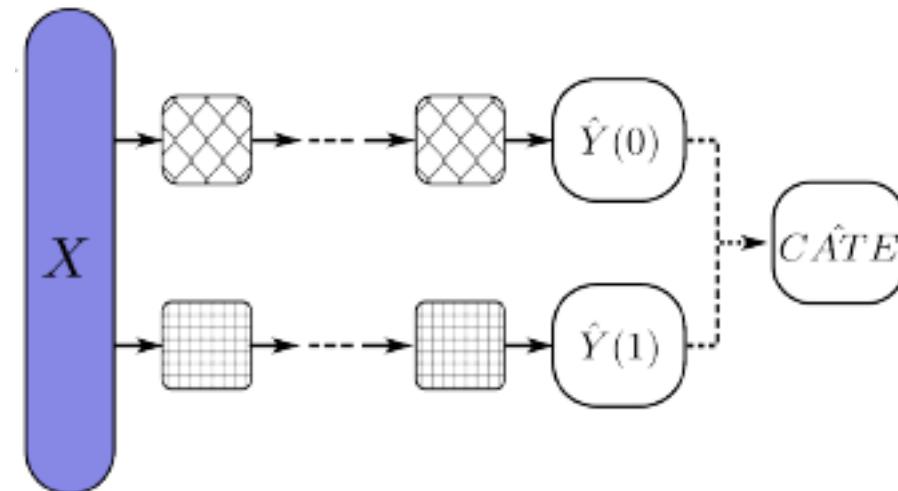
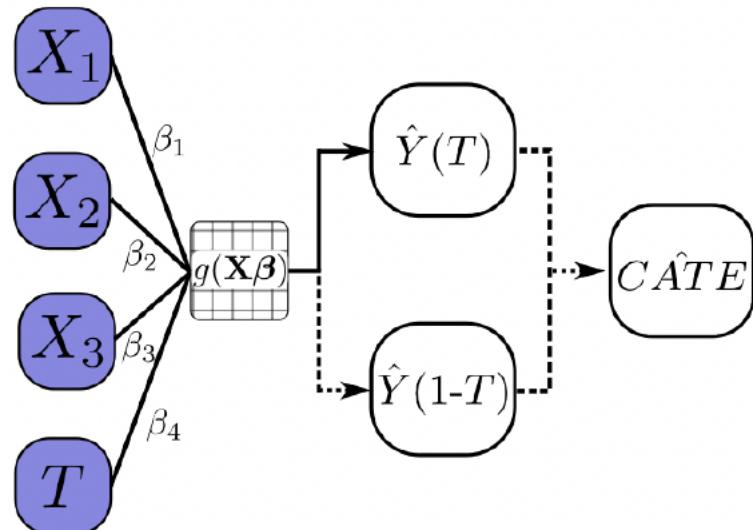
Deep learning can be used for estimating conditional survival probabilities.

(Conditional survival probabilities are nuisance parameters.)

# Indirectly Target on $\tau(x)$ : Representation Learning

## Outcome modeling approach:

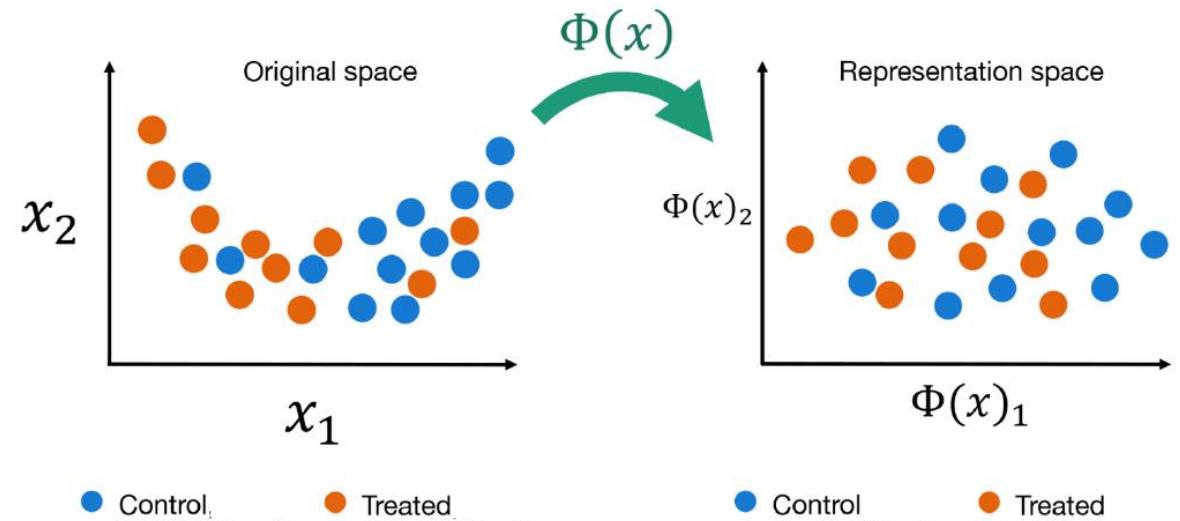
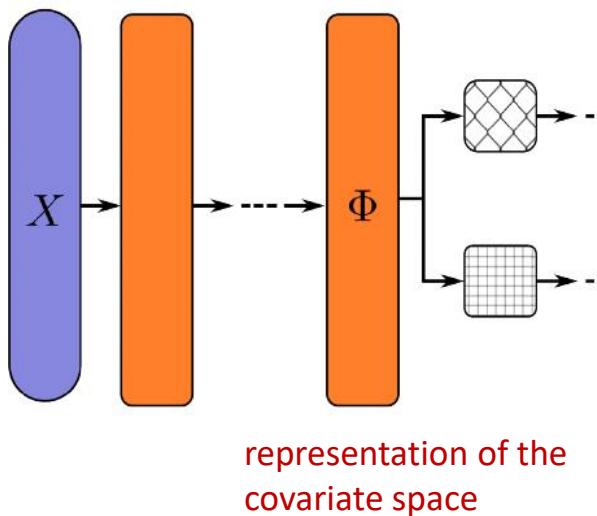
- A regression network without hidden layers; corresponds to generalized linear models (GLM).
- Deep outcome modeling



$$\text{Loss function: } L(Y, h(X, A)) = \text{MSE}(A_i, h_1(X_i, 1) + (1 - A_i)(Y_i, h_0(X_i, 0)))$$

where  $h_a(X, A)$ : outcome regression model on treatment  $A = a$

## Representation learning approach/multi-task learning:



$$\arg \min_{h, \Phi} \frac{1}{N} \sum_{t=1}^N (Y_t - (T_t(Y_t, \underbrace{h_1(\Phi(X_t), 1)}_{\hat{Y}_t(1)}) + (1 - T_t)(Y_t, \underbrace{h_0(\Phi(X_t), 0)}_{\hat{Y}_t(0)}))^2 + \lambda \underbrace{\mathcal{R}(h)}_{L_2}$$

where  $h_a(X, A)$ : outcome regression model on treatment  $A = a$

# Example of Representation Learning

- Aim to bound PEHE (Precision in Estimation of Heterogeneous Effect):  $\epsilon_{PEHE}(f) = \int_{\mathcal{X}} (\hat{\tau}_f(x) - \tau(x))^2 p(x) dx,$
- Factual loss and counterfactual loss:  $\epsilon_F(h, \Phi) = \int_{\mathcal{X} \times \{0,1\}} l_{\{h, \Phi\}}(x, a)p(x, a)dxda$   
 $\epsilon_{CF}(h, \Phi) = \int_{\mathcal{X} \times \{0,1\}} l_{\{h, \Phi\}}(x, a)p(x, 1-a)dxda$
- Bound counterfactual loss:  $\epsilon_{\{CF\}}(h, \Phi) \leq (1-\mu)\epsilon_F^{\{a=1\}}(h, \Phi) + \mu\epsilon_F^{\{a=0\}}(h, \Phi) + B_\Phi \cdot IPM_G(p_\Phi^{\{a=1\}}, p_\Phi^{\{a=0\}})$

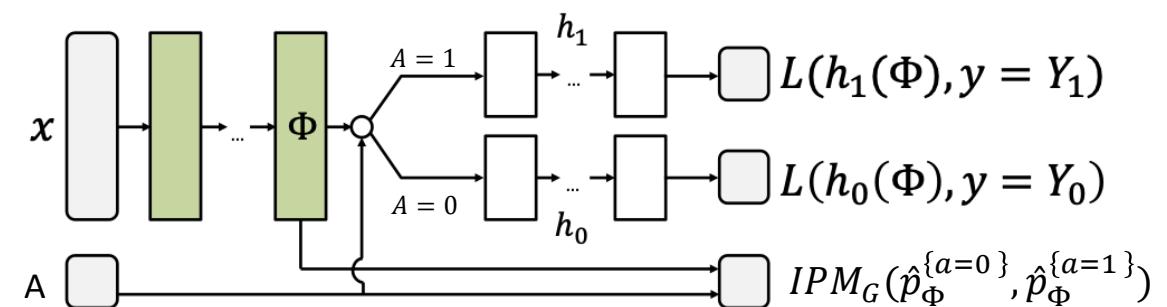
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## Estimating individual treatment effect: generalization bounds and algorithms

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Uri Shalit <sup>\*1</sup> Fredrik D. Johansson <sup>\*2</sup> David Sontag <sup>2,3</sup>

Proceedings of the 34th International Conference on Machine Learning 2017



$$IPM_G(p, q) := \sup_{g \in G} \left| \int_S g(s)(p(s) - q(s)) ds \right|$$

# Representation Learning for Survival Outcomes

- survITE (Curth et. al, 2021)

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## SurvITE: Learning Heterogeneous Treatment Effects from Time-to-Event Data

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35th Conference on Neural Information Processing Systems (NeurIPS 2021).

- BITES (Schrod et. al, 2022)

Bioinformatics, 38, 2022, 80–87  
<https://doi.org/10.1093/bioinformatics/btac221>  
ISCB/ISMB 2022



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## BITES: balanced individual treatment effect for survival data

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S. Schrod<sup>1,\*</sup>, A. Schäfer<sup>2</sup>, S. Solbrig<sup>2</sup>, R. Lohmayer<sup>3</sup>, W. Gronwald<sup>4</sup>, P. J. Oefner<sup>4</sup>,  
T. Beißbarth<sup>1</sup>, R. Spang<sup>5</sup>, H. U. Zacharias<sup>6,7</sup>, and M. Altenbuchinger<sup>1,\*</sup>

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# survITE (on discretized time)

- Discretize survival times:  $T_d = \{1, \dots, T_{max}\}$
- Target parameters:
  - Hazard function:  $\lambda^a(t^*|x) = P(T = t^*|T \geq t, do(A = a), X = x)$
  - Survival function:  $S^a(t^*|x) = P(T > t^*|do(A = a), X = x) = \prod_{t \leq t^*} [1 - \lambda^a(t^*|x)]$
- Define counting process  $N_T(t)$  and  $N_C(t)$ 
  - $N_T(t) = I(U \leq t, \delta = 1), N_C(t) = I(U \leq t, \delta = 0)$
  - Let  $N_T(0) = N_C(0) = 0$
  - $Y(t) = I(N_T(t) = 1 \cap N_T(t - 1) = 0)$ : an event occurs exactly at time  $t$
- Conditional hazard function:
$$\begin{aligned}\lambda(t^*|a, x) &= P(U = t^*, \delta = 1 | U \geq t^*, A = a, X = x) \\ &= P(Y(t^*) = 1 | N_T(t^* - 1) = N_C(t^* - 1) = 0, A = a, X = x)\end{aligned}$$

# Three Types of Covariates Shifts

- Confounding/treatment selection bias
- Censoring bias
- Event-induced shifts

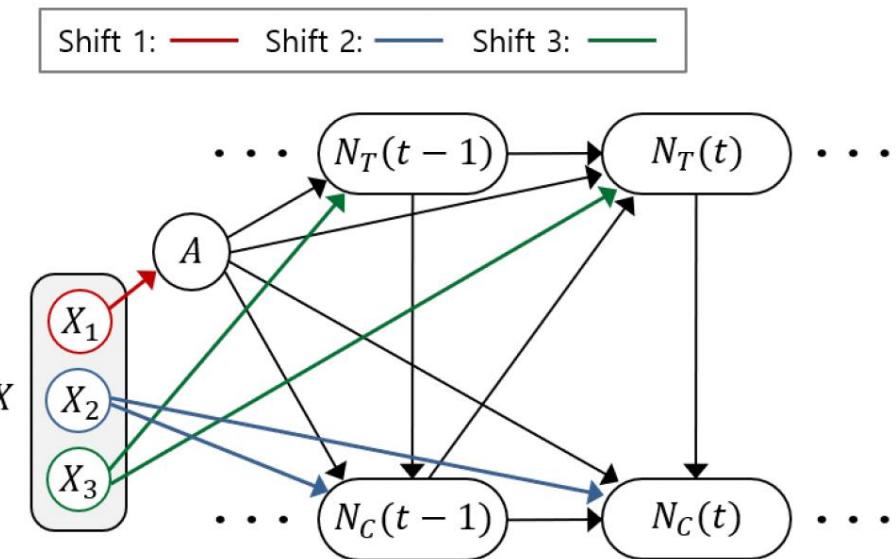


Figure 1: The assumed underlying DAG. Covariates  $X$  can be split into (possibly overlapping) subsets  $X_1$ ,  $X_2$  and  $X_3$ , determining treatment selection, informative censoring, and event times, respectively.

# SurvITE Architecture

$$\mathcal{L}_{target}(\theta_\phi, \theta_h) = \mathcal{L}_{risk}(\theta_\phi, \theta_h) + \beta \mathcal{L}_{ipm}(\theta_\phi) \quad (6)$$

where  $\theta_h = \{\theta_{h_{a,\tau}}\}_{a \in \{0,1\}, \tau \in \mathcal{T}}$ , and  $\beta > 0$  is a hyper-parameter. The pseudo-code of SurvITE, the details of how to obtain  $Wass(\cdot, \cdot)$  and how we set  $\beta$  can be found in Appendix D.

$$\mathcal{L}_{risk}(\theta_\phi, \theta_h) = \frac{1}{t_{max}} \sum_{t=1}^{t_{max}} \sum_{i: \tilde{\tau}_i \geq t} n_{1,t}^{-1} a_i \ell(y_i(t), h_{1,t}(\Phi(x_i))) + n_{0,t}^{-1} (1-a_i) \ell(y_i(t), h_{0,t}(\Phi(x_i))),$$

$$\mathcal{L}_{ipm}(\theta_\phi) = \sum_{a \in \{0,1\}} \sum_{t=1}^{t_{max}} Wass(\{\Phi(x_i)\}_{i=1}^n, \{\Phi(x_i)\}_{i: \tilde{\tau}_i \geq t, a_i=a}),$$

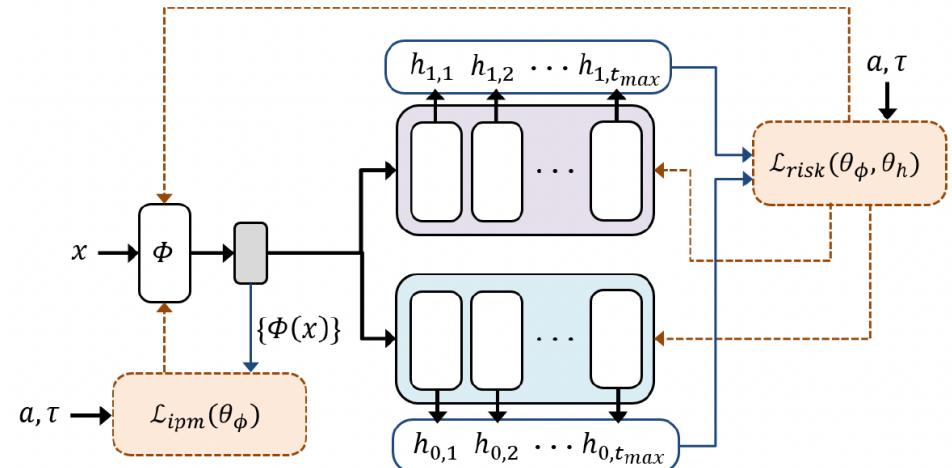
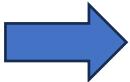


Figure 2: SurvITE architecture.

# Data Format for survITE

$X$	$A$	$U$	$\delta$
$x_1$	1	3	0
$x_2$	1	2	1
$x_3$	0	1	1
$x_4$	0	1	0
$x_5$	1	3	1
$x_6$	0	2	1



$\hat{\lambda}^a(1 x)$		
$X$	$A$	$\gamma(1)$
$x_1$	1	0
$x_2$	1	0
$x_3$	0	1
$x_4$	0	0
$x_5$	1	0
$x_6$	0	0

$\hat{\lambda}^a(2 x)$		
$X$	$A$	$\gamma(2)$
$x_1$	1	0
$x_2$	1	1
$x_3$	-	-
$x_4$	-	-
$x_5$	1	0
$x_6$	0	1

$\hat{\lambda}^a(3 x)$		
$X$	$A$	$\gamma(3)$
$x_1$	1	0
$x_2$	-	-
$x_3$	-	-
$x_4$	-	-
$x_5$	1	1
$x_6$	-	-

# Directly Target on $\tau(x)$ : Meta-learners

- Two major steps
  - Step 1: Estimate nuisance parameters and construct ITEs or pseudo ITEs
  - Step 2: Regress constructed ITEs or pseudo ITEs on the covariates
- Two popular approaches for estimating CATE in continuous or binary outcomes
  - X-learner (Kunzel et. al, 2019, *PNAS*)
  - R-learner (Nie and Wager, 2021, *Biometrika*)

# X-learner

- For a continuous outcome  $Y$

Step 1:

$$\begin{aligned}\hat{h}_0 &= \mathcal{M}_0(Y \sim X) \\ \hat{h}_1 &= \mathcal{M}_1(Y \sim X)\end{aligned}$$

← Outcome regression

$$\begin{aligned}Y_1^* &= Y - \hat{h}_0(X), A = 1 \\ Y_0^* &= \hat{h}_1(X) - Y, A = 0\end{aligned}$$

← Create Pseudo ITE

$Y_a^*$  has ITE interpretation:  
Difference between the observed  
outcome and predicted  
counterfactual.

Step 2:

$$\begin{aligned}\hat{\tau}_1(x) &= \mathcal{M}_1^\tau(Y_1^* \sim X) \\ \hat{\tau}_0(x) &= \mathcal{M}_0^\tau(Y_0^* \sim X)\end{aligned}$$

← Group-specific CATE estimator

$$\hat{\tau}(x) = e(x) \hat{\tau}_0(x) + [1 - e(x)] \hat{\tau}_1 \quad \leftarrow \text{Final CATE estimator}$$

- For survival outcomes (e.g., survival probability scale)

Step 1:

$$\begin{aligned}\hat{S}_0(t^*|x) &= \mathcal{M}_0((U, \delta) \sim X) \\ \hat{S}_1(t^*|x) &= \mathcal{M}_1((U, \delta) \sim X)\end{aligned}$$

$\leftarrow \mathcal{M}_a$  can be a NN-based survival model

$$\begin{aligned}Y_1^* &= I(T > t^*) - \hat{S}_0(t^*|x), A = 1 \\ Y_0^* &= \hat{S}_1(t^*|x) - I(T > t^*), A = 0\end{aligned}$$

$\leftarrow$  Pseudo ITE

Step 2:

$$\begin{aligned}\hat{\tau}_1(x) &= \mathcal{M}_1^\tau(Y_1^* \sim X) \\ \hat{\tau}_0(x) &= \mathcal{M}_0^\tau(Y_0^* \sim X)\end{aligned}$$

$$\hat{\tau}(x) = e(x) \hat{\tau}_0(x) + [1 - e(x)] \hat{\tau}_1$$

- For survival outcomes (e.g., survival probability scale)

Step 1:

$$\begin{aligned}\hat{S}_0(t^*|x) &= \mathcal{M}_0((U, \delta) \sim X) \\ \hat{S}_1(t^*|x) &= \mathcal{M}_1((U, \delta) \sim X)\end{aligned}$$

$\leftarrow \mathcal{M}_a$  can be a NN-based survival model

$$\begin{aligned}Y_1^* &= I(T > t^*) - \hat{S}_0(t^*|x), A = 1 \\ Y_0^* &= \hat{S}_1(t^*|x) - I(T > t^*), A = 0\end{aligned}$$

Pseudo ITE

$I(T > t^*)$  cannot be observed for those who censored before  $t^*$ .

Step 2:

$$\begin{aligned}\hat{\tau}_1(x) &= \mathcal{M}_1^\tau(Y_1^* \sim X) \\ \hat{\tau}_0(x) &= \mathcal{M}_0^\tau(Y_0^* \sim X)\end{aligned}$$

$$\hat{\tau}(x) = e(x) \hat{\tau}_0(x) + [1 - e(x)] \hat{\tau}_1$$

$\mathcal{M}_a^\tau$ : weighted pseudo ITE regression  $\frac{1}{n_a^O} \sum_{i=1}^{n_a^O} w_i^C [Y_a^* - \tau_a(x)] 2$

$w_i^C$ : inverse probability censoring weighting  $\frac{1}{P(C > \min(T, t^*) | X=x)}$ , which needs to be estimated in step 1.

# R-learner

- For continuous outcome  $Y$ :

- Motivated by Robinson decomposition:  $Y_i - E[Y_i|X_i = x] = [A_i - e(X_i)]\tau(X_i) + \epsilon_i$ , where  $E[\epsilon_i|X_i, A_i] = 0$ .

- CATE can be solved by minimizing the objective function:

$$\min_{\tau} \frac{1}{n} \sum_{i=1}^n \{[Y_i - h(X_i)] - [A_i - e(X_i)]\tau(X_i)\}^2$$

- Re-arrange the objective function:

$$\min_{\tau} \frac{1}{n} \sum_{i=1}^n [A_i - e(X_i)]^2 \underbrace{\{[Y_i - h(X_i)]/[A_i - e(X_i)] - \tau(X_i)\}^2}_{w^A}$$

- Step 1:

- $\hat{h}(X) = \mathcal{M}(Y \sim X)$  ← Outcome regression
- $Y^* = \frac{[Y - \hat{h}(X)]}{[A - \hat{e}(X)]}$  ← Create Pseudo outcome
- $w^A = [A - \hat{e}(X)]^2$  ← Method-specific weight

- Step 2:

$$\min_{\tau} \frac{1}{n} \sum_{i=1}^n [A_i - \hat{e}(X_i)]^2 \{[Y_i - \hat{h}(X_i)]/[A_i - \hat{e}(X_i)] - \tau(X_i)\}^2$$

- For survival outcome:

- Step 1:

- $\hat{S}(X) = \mathcal{M}((U, \delta) \sim X)$   $\leftarrow \mathcal{M}$  can be a NN-based survival model  
or  $\hat{S}(X) = \hat{e}(X)\hat{S}_1(X) + [1 - \hat{e}(X)]\hat{S}_0(X)$

- $Y^* = [\mathbf{I}(T > t^*) - \hat{S}(X)]/[A - \hat{e}(X)]$
- $w^A = [A - \hat{e}(X)]^2$

- Step 2:

$$\min_{\tau} \frac{1}{n^o} \sum_{i=1}^{n^o} w_i^C w_i^A \{[\mathbf{I}(T > t^*) - \hat{S}(X_i)]/[A_i - \hat{e}(X_i)] - \tau(X_i)\}^2$$

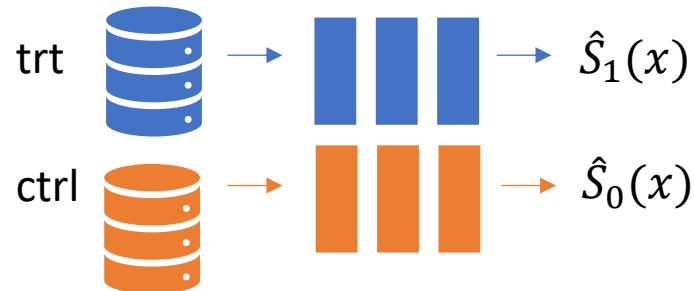
↑  
inverse probability censoring weighting  $\frac{1}{P(C>\min(T,t^*)|X=x)}$

Remark: Using NN to learn conditional survival functions can yield better performance in predicting CATE.

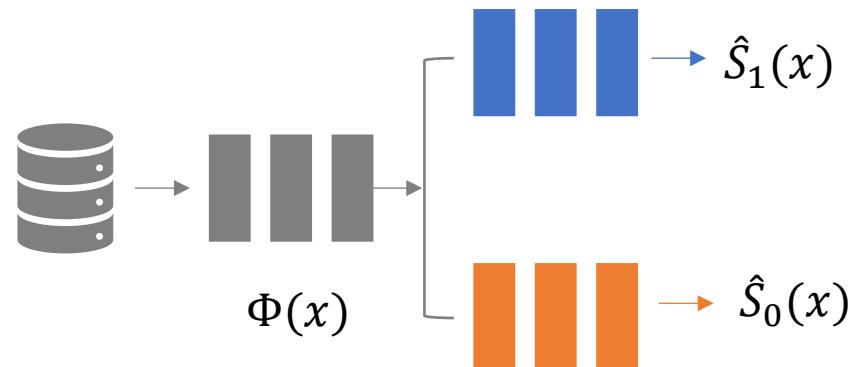
# More Complicated NN Blocks

- What we did so far:

Learning outcome regression models separately for each treatment group



- Adding shared blocks to learn representations of  $X$ :



# Example Codes

- Xlearner\_simu.ipynb
- Rlearner\_simu.ipynb
- survIETE\_simu\_TF2.ipynb

## Part II

*Case Study 3: Individualized Treatment Effects of AREDS formula in delaying Progression to late-AMD*

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### A Meta-Learner Framework to Estimate Individualized Treatment Effects for Survival Outcomes

Volume 22, Issue 4 (2024), pp. 505–523

Na Bo  Yue Wei  Lang Zeng  All authors (5) 

<https://doi.org/10.6339/24-JDS1119>

<https://doi.org/10.6339/24-JDS1119>

# Application on AREDS

## AREDS:

- Treatment Arm:
  - *Placebo*
  - Antioxidants (Vitamin C + Vitamin E + beta-carotene)
  - Zinc (zinc oxide + cupric oxide)
  - *Antioxidants + Zinc (AREDS)*
- $X$ : age, smoking status, sex, education, baseline AMD severity scale, **686 SNPs**
  - 46 SNPs identified to be associated with treatment efficacy (**CE4 SNPs**)
  - 640 SNPs reported to be associated with AMD progression (**prognostic SNPs**).
- $N = 806$  (balanced design)
- $\tau(x; t^* = 5)$ : difference of progression-free probability at 5 years



## AREDS2 (external validation data):

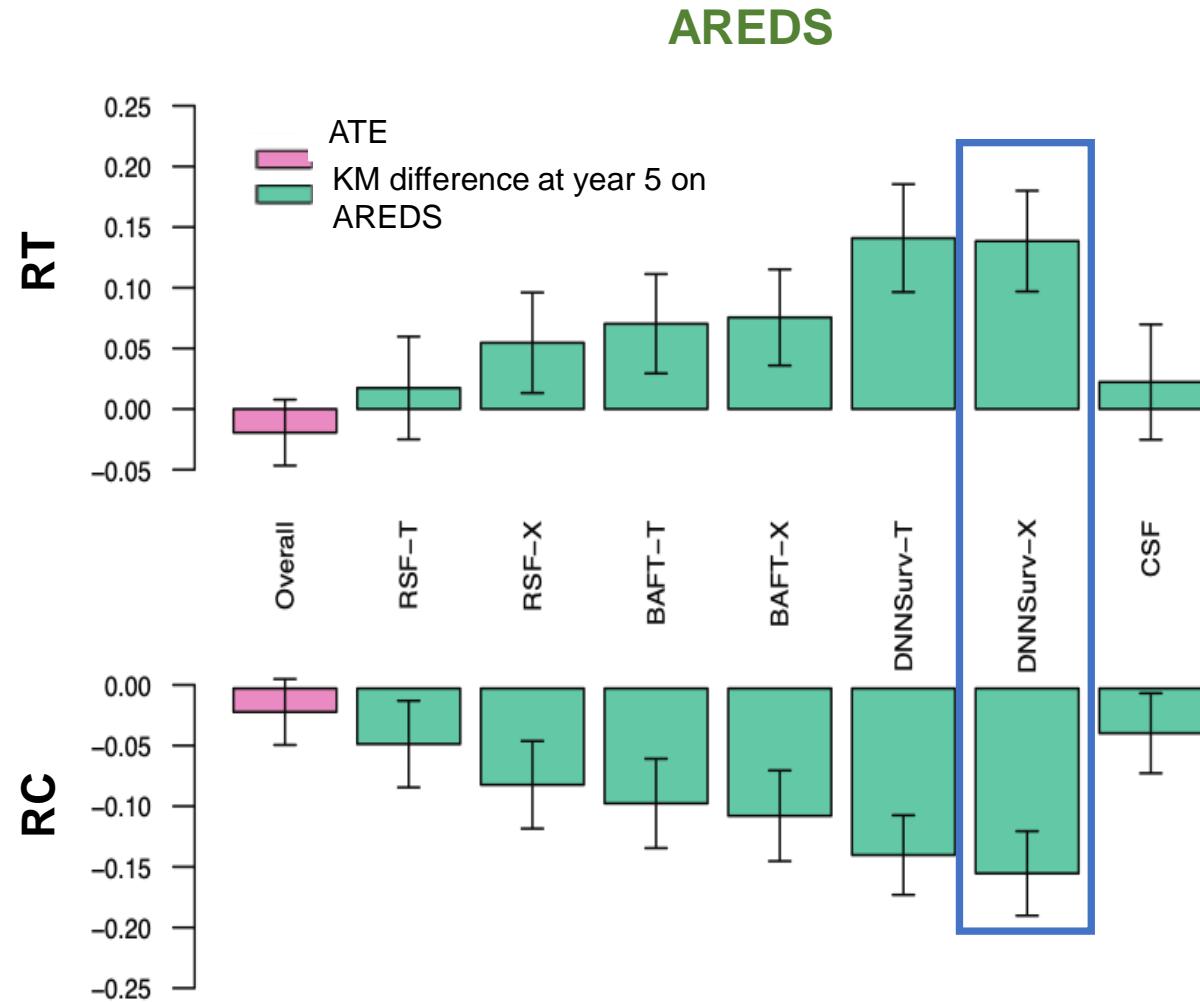
- Treatment Arm:
  - *AREDS*<sup>®</sup>
  - Modification 1 of *AREDS*<sup>®</sup>
  - Modification 2 of *AREDS*<sup>®</sup>
  - *AREDS2*
- $N = 110$  (*AREDS* arm only)

# Estimated ITEs in RT and RC Groups

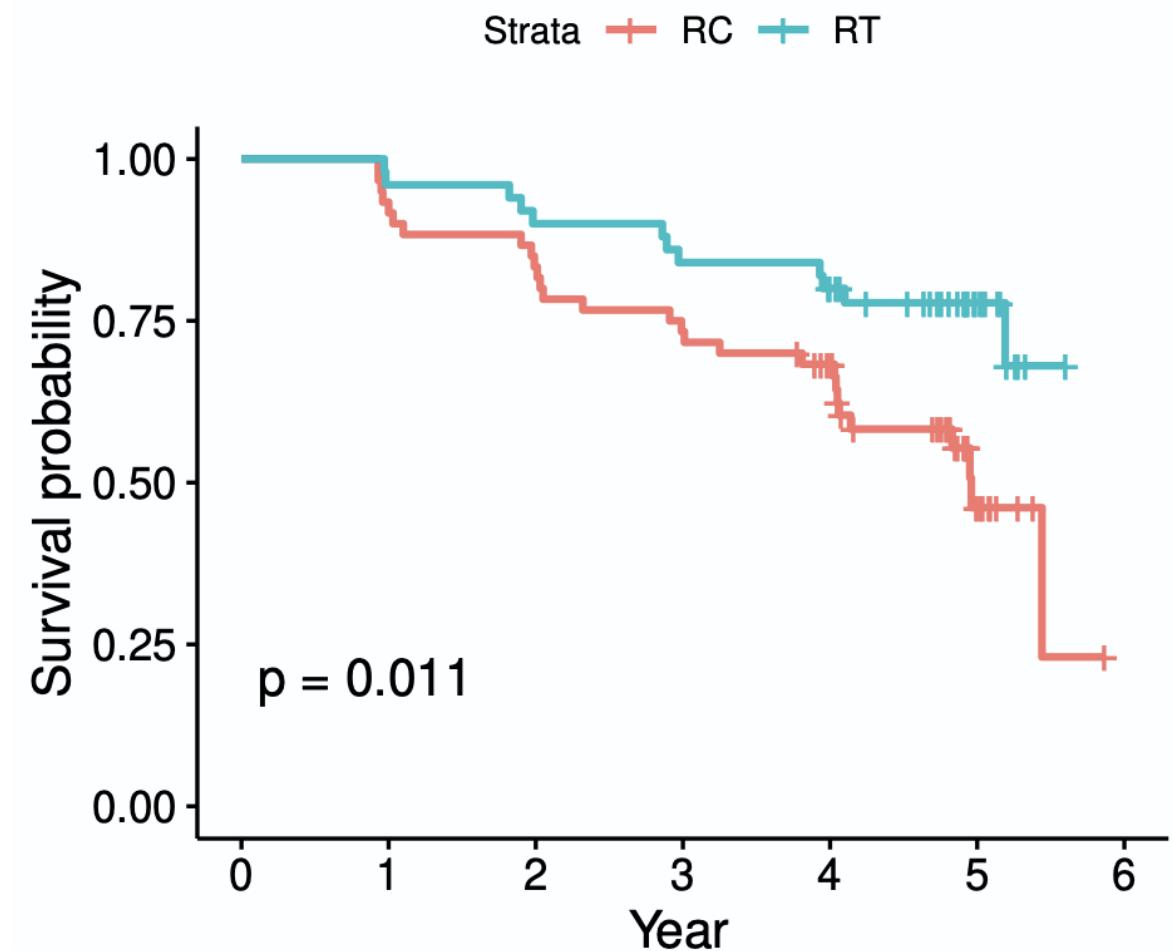
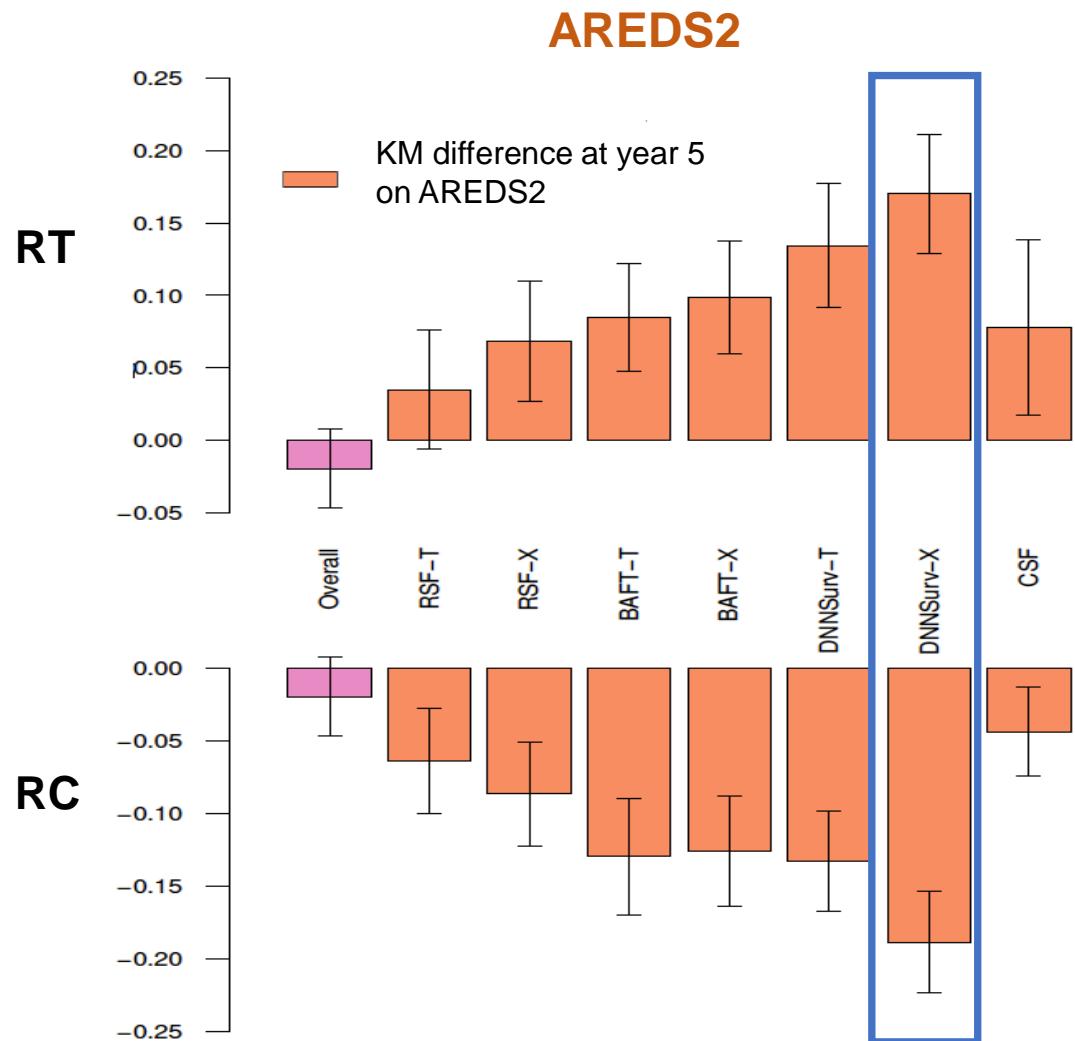
$\hat{\tau}(x; t^*) > 0$ : recommended for treatment (**RT**).

$\hat{\tau}(x; t^*) \leq 0$ : recommended for placebo (**RC**).

Calculate **mean treatment difference** using Kaplan Meier (KM) estimator between two arms at year 5 in RT and RC separately.



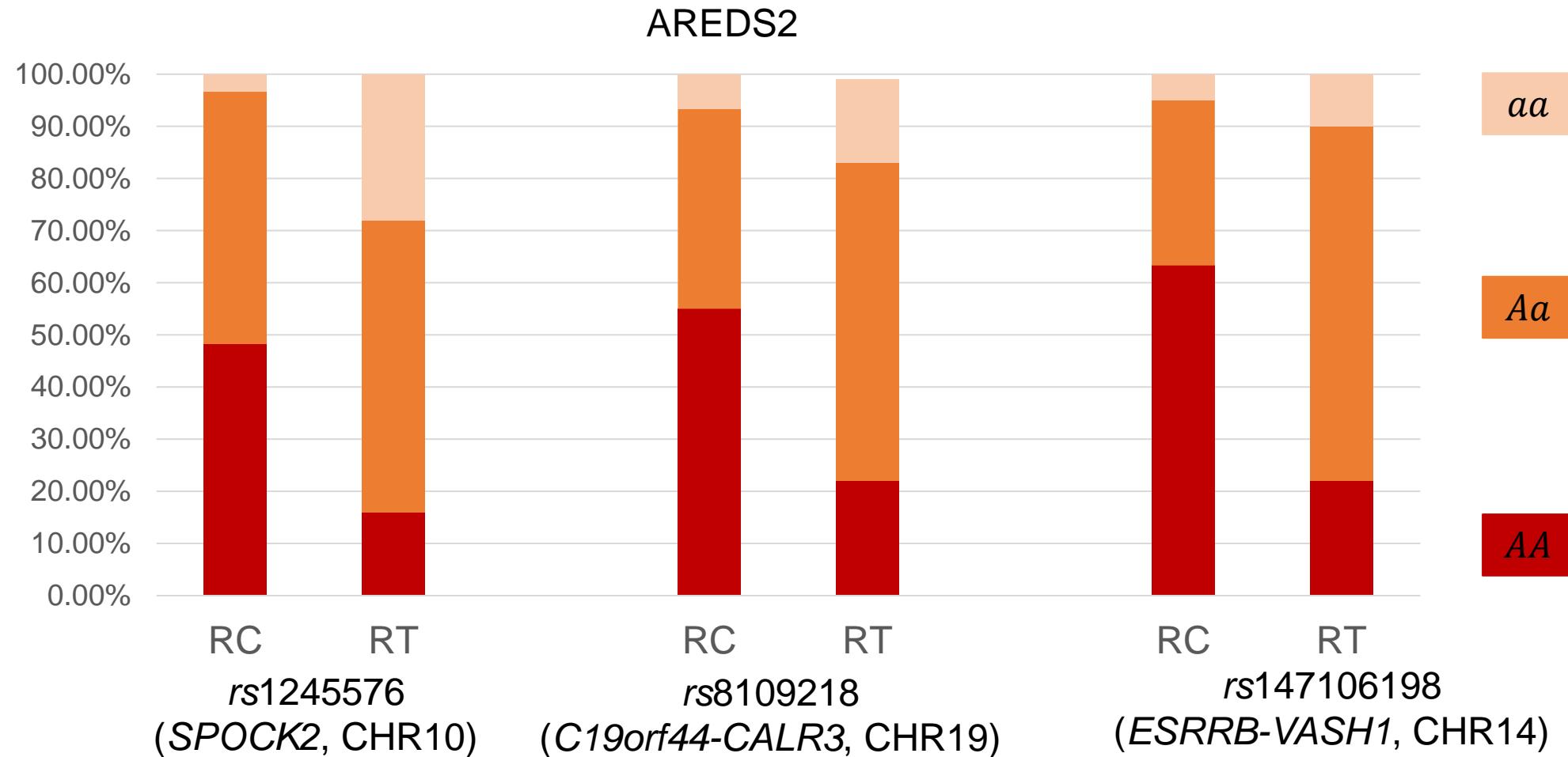
# External Validation on AREDS2



The Kaplan Meier curves of RT and RC cohorts in AREDS2 where the treatment recommendation rule is based on the D-X result on AREDS data.

# Importance Features

- Applied a post-hoc Boruta algorithm after dichotomizing predicted ITEs using D-X.
- Identified 17 SNPs, mainly from CHR10, 14 and 19.



# Thank You!

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